# Some Notes on Proof Theory and Elements of Ordinal Analysis

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## 1 Provable Recursion in $I\Delta_0(\exp)$

 $\mathbf{I}\Delta_0(\exp)$  is a theory in first-order logic in the language:

$$\{=, 0, S, P, +, \dot{-}, \cdot, exp_2\}$$

where S and P are successor and precessor functions respectively. Further, we will denote S(x) and P(x) as x+1 and x-1 respectively.  $2^x$  stands for  $exp_2(x)$ .

The non-logical axioms of  $I\Delta_0(\exp)$  are the following list:

• 
$$x + 1 \neq 0$$
  
•  $0 - 1 = 0$   
•  $x + 0 = x$   
•  $x + 0 = x$   
•  $x - 0 = x$   
•  $x - 0 = 0$   
•  $x + 1 = y + 1 \rightarrow x = y$   
•  $(x + 1) - 1 = x$   
•  $x + (y + 1) = (x + y) + 1$   
•  $x - (y + 1) = x - y - 1$   
•  $x \cdot (y + 1) = x \cdot y + x$ 

 $\bullet$   $2^{x+1} = 2^x + 2^x$ 

along with the bounded induction scheme:

$$B(0) \land \forall x (B(x) \to B(x+1)) \to \forall x B(x)$$

where B is a  $\Delta$ -formula, that is a formula one of the following forms (with bounded quantifiers only):

• 
$$B = \forall x < tP(x) \equiv \forall x (x < t \rightarrow P(x))$$

• 
$$B = \exists x < tP(x) \equiv \exists x (x < t \land P(x))$$

A  $\Sigma_1$ -formula is a formula of the form:

$$\exists \vec{x} B(\vec{x})$$

where  $B(\vec{x}) \in \Delta_0$ .

•  $2^0 = 1$ 

**Lemma 1.1.**  $I\Delta_0(\exp)$  proves (the universal closures of):

1. 
$$x = 0 \lor x = (x - 1) + 1$$

2. 
$$x + (y + z) = (x + y) + z$$

3. 
$$x \cdot (y \cdot z) = (x \cdot y) \cdot z$$

4. 
$$x \cdot (y+z) = x \cdot y + x \cdot z$$

5. 
$$x + y = y + x$$

6. 
$$x \cdot y = y \cdot x$$

7. 
$$x \dot{-}(y+z) = (x \dot{-}y) \dot{-}z$$

8. 
$$2^{x+y} = 2^x \cdot 2^y$$

Proof.

- 1. This is self-evident.
- 2. If z = 0, then x + y = x + y. If z = z' + 1, then, by applying the IH and the relevant axioms:

$$(x + (y + (z' + 1))) = (x + ((y + z') + 1)) = (x + (y + z')) + 1 = ((x + y) + z') + 1 = (x + y) + (z' + 1)$$

3. If z = 0, then  $x \cdot (y \cdot 0) = (x \cdot y) \cdot 0$ . If z = z' + 1, then:

$$x \cdot (y \cdot (z'+1)) = x \cdot (y \cdot z'+y) = x \cdot (y \cdot z') + x \cdot y = (x \cdot y) \cdot z' + x \cdot y = (x \cdot y) \cdot (z'+1)$$

4. The rest of the cases are shown by induction on z. Consider the exponentiation law. If y=0, then

$$2^{x+0} = 2^x = 0 + 2^x = 2^x \cdot 0 + 2^x = 2^x \cdot (0+1) = 2^x \cdot 2^0$$

If y = y' + 1, then:

$$2^{x+(y'+1)} = 2^{(x+y')+1} = 2^x \cdot 2^y + 2^x \cdot 2^y = 2^x \cdot 2^{y+1}$$

**Lemma 1.2.**  $I\Delta_0(\exp)$  proves (the universal closures of):

- 1.  $\neg x < 0$
- $2. \ x \le 0 \leftrightarrow x = 0$
- 3.  $0 \le x$
- 4.  $x \leq x$

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5. x < x + 1
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6. 
$$x < y + 1 \leftrightarrow x \le y$$

7. 
$$x \le y \leftrightarrow x < y \lor x = y$$

8. 
$$x \le y \land y \le z \rightarrow x \le z$$

9. 
$$x < y \land y < z \rightarrow x < z$$

10. 
$$x \le y \lor y < x$$

11. 
$$x < y \to x + z < y + z$$

12. 
$$x < y \to x \cdot (z+1) < y \cdot (z+1)$$

13. 
$$x < 2^x$$

14. 
$$x < y \rightarrow 2^x < 2^y$$

*Proof.* Straightforward induction.

**Definition 1.1.** A function  $f: \mathbb{N}^k \to \mathbb{N}$  is provably  $\Sigma_1$  or provably recursive in an arithmetical theory if there is a  $\Sigma_1$  formula  $F(\vec{x}, y)$ , a "defining formula" of f, such that:

1. 
$$f(\vec{n}) = m$$
 iff  $\omega \models f(\vec{n}) = m$ 

2. 
$$T \vdash \exists y F(\vec{x}, y)$$

3. 
$$T \vdash F(\vec{x}, y) \land F(\vec{x}, y') \rightarrow y = y'$$

If a defining formula  $F \in \Delta_0$ , then a function f is provably bounded in T if there is a term  $t(\vec{x})$  such that  $T \vdash F(\vec{x}, y) \to y < t(\vec{x})$ .

**Theorem 1.1.** Let f be a provably recursive in T, then we can conservatively extend T by adding a new function symbol f along with the defining axiom  $F(\vec{x}, f(\vec{x}))$ .

*Proof.* Let  $\mathcal{M} \models T$ ,  $\mathcal{M}$  can be made into a model  $(\mathcal{M}, f)$  where we interpret f as the function which is uniquely determined by the second and third conditions of the definitions above. Let  $\varphi$  be a statement not involving f such that  $\varphi$  is true in  $(\mathcal{M}, f)$ , so  $\varphi$  is true in  $\mathcal{M}$  as well. By compactness T proves  $\varphi$ .

**Lemma 1.3.** Each term defines a provably bounded function of  $I\Delta_0(\exp)$ .

Proof. Let f be a function defined by some  $\mathbf{I}\Delta_0(\exp)$ -term t, that is,  $f(\vec{x}) = t(\vec{x})$ . Take  $y = t(\vec{x})$  as the defining formula for f since  $\exists y \ (y = t(\vec{x}))$  is derivable. If  $y' = t(\vec{x}) \wedge y = t(\vec{x})$ , then y = y' by transitivity. A formula  $y = t(\vec{x})$  is bounded and y = t implies y < t + 1. Thus f is provably bounded.

**Lemma 1.4.** Define  $2_k(x)$  as  $2_0(x) = x$  and  $2_{n+1}(x) = 2^{2_n(x)}$ . Then for every term  $t(x_1, \ldots, x_n)$  built up from the constants  $0, S, P, +, \dot{-}, \cdot, exp_2$  there exists  $k < \omega$  such that:

$$\mathbf{I}\Delta_0(\exp) \vdash t(x_1, \dots, x_n) < 2_k (\sum_{k=0}^n x_k)$$

*Proof.* Let t be a term constructed from subterms  $t_0$  and  $t_1$  by using one of the function constants. Assume that inductively  $t_0 < 2_{k_0}(s_0)$  and  $t_1 < 2_{k_1}(s_1)$  are both provable for some  $k_0, k_1 < \omega$ , where  $s_i$  is the sum of the variables of  $t_i$  for i = 0, 1.

Let s be the sum of all variables appearing in either  $t_0$  or  $t_1$  and let  $k = \max(k_0, k_1)$ . Then one can prove  $t_0 < 2_k(s)$  and  $t_1 < 2_k(s)$ . So one needs to show the following:

- 1.  $t_0 + 1 < 2_{k+1}(s)$
- 2.  $t_0 \dot{-} 1 < 2_k(s)$
- 3.  $t_0 \dot{-} t_1 < 2_k(s)$
- 4.  $t_0 \cdot t_1 < 2_k(s)$
- 5.  $t_0 + t_1 < 2_k(s)$
- 6.  $2^{t_0} < 2_k(s)$

So 
$$\mathbf{I}\Delta_0(\exp) \vdash t < 2_{k+1}(s)$$
.

**Lemma 1.5.** Let f be a function defined by composition:

$$f(\vec{x}) = g_0(g_1(\vec{x}), \dots, g_m(\vec{x}))$$

where  $g_0, g_1, \ldots, g_m$  are functions each of which is provably bounded in  $\mathbf{I}\Delta_0(\exp)$ . Then f is provably bounded in  $\mathbf{I}\Delta_0(\exp)$ .

*Proof.* Each  $g_i$  has a defining formula  $G_i$  and, by Lemma 1.4, there is a number  $k_i < \omega$  such that:

$$\mathbf{I}\Delta_0(\exp) \vdash \exists y < 2_{k_i}(s) \ G_i(\vec{x}, y)$$

where s is the sum of elements of  $\vec{x}$ . And for i=0 one has:

$$\mathbf{I}\Delta_0(\exp) \vdash \exists y < 2_{k_0}(s_0) \ G_0(y_1, \dots, y_m, y)$$

where  $s_0$  is the sum of  $y_1, \ldots, y_m$ .

Let  $k = \max\{k_i < \omega \mid i < m+1\}$  and let  $F(\vec{x}, y)$  be the bounded formula:

$$\exists y_1 < 2_k(s) \dots \exists y_m < 2_k(s) C(\vec{x}, y_1, \dots, y_m, y)$$

where  $C(\vec{x}, y_1, \dots, y_m, y)$  is the conjunction:

$$G_1(\vec{x}, y_1) \wedge \cdots \wedge G_m(\vec{x}, y_m) \wedge G_0(y_1, \dots, y_m, y)$$

F is clearly a defining formula for f such that  $\mathbf{I}\Delta_0(\exp) \vdash \exists y F(\vec{x}, y)$ . Moreover, each  $G_i$  is unique, so  $\mathbf{I}\Delta_0(\exp)$  also proves:

$$C(\vec{x}, y_1, \dots, y_m, y) \land C(\vec{x}, z_1, \dots, z_m, z) \rightarrow$$

$$\rightarrow \bigwedge_{j=1}^m y_j = z_j \land G_0(y_1, \dots, y_m, y) \land G_0(y_1, \dots, y_m, z) \rightarrow$$

$$\rightarrow y = z$$

so we have (by first order logic):

$$\mathbf{I}\Delta_0(\exp) \vdash F(\vec{x}, y) \land F(\vec{x}, z) \rightarrow y = z$$

Thus f is provably  $\Sigma_1$  in  $\mathbf{I}\Delta_0(\exp)$ , so the rest is to find its bounding term.  $\mathbf{I}\Delta_0(\exp)$  proves the following:

$$C(\vec{x}, y_1, \dots, y_m, y) \to \bigwedge_{j=1}^m y_j < 2_k(s) \land y < 2_k(y_1 + \dots + y_m)$$

and

$$\bigwedge_{j=1}^{m} y_j < 2_k(s) \to y_1 + \dots + y_m < 2_k(s) \cdot m$$

Put  $t(\vec{x}) = 2_k(2_k(s) \cdot m)$ , then we obtain

$$\mathbf{I}\Delta_0(\exp) \vdash C(\vec{x}, y_1, \dots, y_m, y) \to y < t(\vec{x})$$

and so

$$\mathbf{I}\Delta_0(\exp) \vdash F(\vec{x}, y) \to y < t(\vec{x})$$

**Lemma 1.6.** Suppose f is defined by bounded minimisation

$$f(\vec{n}, m) = \mu_{k < m}(g(\vec{n}, k) = 0)$$

from a function g which is provably bounded in  $\mathbf{I}\Delta_0(\exp)$ . Then f is provably bounded in  $\mathbf{I}\Delta_0(\exp)$ .

*Proof.* Let G be a defining formula for g. Let  $F(\vec{x}, z, y)$  be the bounded formula

$$y \le z \land \forall i < y \neg G(\vec{x}, i, 0) \land (y = z \lor G(\vec{x}, y, 0))$$

 $\omega \models F(\vec{n}, m, k)$  iff either k is the least number less than m such that  $g(\vec{n}, k) = 0$  or there is no such and k = m. Thus it means that k is the value of  $f(\vec{n}, m)$ , so F is a defining formula for f.

Furthermore

$$\mathbf{I}\Delta_0(\exp) \vdash F(\vec{x}, z, y) \to y < z + 1$$

so  $t(\vec{x}, z) = z + 1$  can be taken as a bounding term for f. We can prove:

$$F(\vec{x}, z, y) \wedge F(\vec{x}, z, y') \wedge y < y' \rightarrow G(\vec{x}, y, 0) \wedge \neg G(\vec{x}, y, 0)$$

and similarly for interchanged y and y'. So we can prove:

$$F(\vec{x}, z, y) \land F(\vec{x}, z, y') \rightarrow \neg y < y' \land \neg y' < y$$

As far as  $y < y' \lor y' < y \lor y = y'$ , we have

$$F(\vec{x}, z, y) \wedge F(\vec{x}, z, y') \rightarrow y = y'$$

Now we have to check that  $\mathbf{I}\Delta_0(\exp) \vdash \exists y F(\vec{x}, z, y)$ . We construct such y by bounded induction on z.

1. z = 0.

 $F(\vec{x},0,0)$  is provable since  $y=0 \leftrightarrow y \leq 0$  and  $\neg i < 0$ . So  $\mathbf{I}\Delta_0(\exp) \vdash F(\vec{x},0,y)$  is provable.

2. Assume  $\exists y F(\vec{x}, z, y)$  is provable, let show that that  $\exists y F(\vec{x}, z + 1, y)$  is provable.

We can show  $y \le z \to y+1 \le z+1$  and, via  $i < y+1 \leftrightarrow i < y \lor i=y,$ 

$$\forall i < y \, \neg G(\vec{x}, i, 0) \wedge ((y = z) \wedge \neg G(\vec{x}, y, 0)) \rightarrow \forall i < y + 1 \, \neg G(\vec{x}, i, 0) \wedge y + 1 = z + 1$$

Therefore

$$F(\vec{x}, z, y) \to F(\vec{x}, z + 1, y + 1) \vee F(\vec{x}, z + 1, y)$$

and thus:

$$\exists y F(\vec{x}, z, y) \rightarrow \exists y F(\vec{x}, z + 1, y)$$

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**Theorem 1.2.** Every elementary function is provably bounded in  $I\Delta_0(\exp)$ .

*Proof.* As we know from recursion theory, the class of elementary functions can be characterised as those functions which are definable from 0, S, P,  $\cdot$ , +,  $exp_2$ ,  $\dot{-}$  and  $\cdot$  by composition and minimisation. And then we apply above lemmas.

### 1.1 Proof-theoretic Characterisation

For this section we shall be using a Tait-style formalisation of  $I\Delta_0(\exp)$ . We have the following logical rules:

$$\begin{array}{c} \overline{\Gamma, R\vec{t}, \neg R\vec{t}} \ \mathbf{Ax} \\ \\ \overline{\Gamma, A_0, A_1} \\ \overline{\Gamma, A_0 \vee A_1} \vee \\ \\ \overline{\Gamma, A_0 \wedge A_1} \\ \end{array} \vee \begin{array}{c} \underline{\Gamma, A_0} \quad \Gamma, A_1 \\ \overline{\Gamma, A_0 \wedge A_1} \wedge \\ \\ \overline{\Gamma, A_0 \wedge A_1} \end{array} \wedge \\ \\ \overline{\frac{\Gamma, A(t)}{\Gamma, \exists x A(x)}} \exists \end{array}$$

where  $R\vec{t}$  is an atomic formula and x is not free in A in the  $\forall$  rule. Here  $\Gamma$  stores all non-logical axioms of  $\mathbf{I}\Delta_0(\exp)$  along with its negations. We also have the bounded induction rule:

$$\frac{\Gamma, B(0) \qquad \Gamma, \neg B(n), B(n+1)}{\Gamma, B(t)} \, \mathbf{BInd}$$

where B is a bounded formula and t is any term.

Of course, the cut rule is admissible:

$$\frac{\Gamma, A}{\Gamma}$$
  $\frac{\Gamma, \neg A}{\Gamma}$  cut

**Definition 1.2.** Let  $\exists \vec{z}B(\vec{z})$  be a closed  $\Sigma_1$ -formula, then it is *true at m*, written as  $m \models \exists \vec{z}B(\vec{z})$ , if there exist natural numbers  $m_1, \ldots, m_l$  such that each  $m_i < m$  and  $B(\vec{m})$  is true in the standard model.

A finite set  $\Gamma$  of closed  $\Sigma_1$ -formulas is true at m, written as  $m \models \Gamma$  if at least one of them is true at m.

If  $\Gamma(x_1,\ldots,x_k)$  is a finite set of  $\Sigma_1$ -formulas whose free variables occur amongst  $x_1,\ldots,x_k$ . Let  $f:\mathbb{N}^k\to\mathbb{N}$ , then  $f\models\Gamma(x_1,\ldots,x_k)$  we have  $f(\vec{n})\models\Gamma(x_1:=n_1,\ldots,x_k:=n_k)$  for each  $\vec{n}=(n_1,\ldots,n_k)$ .

#### Fact 1.1. (Persistence)

- 1. If  $m \leq m'$ , then  $m \models \exists \vec{z} B(\vec{z})$  implies  $m' \models \exists \vec{z} B(\vec{z})$ .
- 2. If  $\forall \vec{n} \in \mathbb{N}^k$   $f(\vec{n}) \leq f'(\vec{n})$ , then  $f(\vec{n}) \models \Gamma(x_1 := n_1, \dots, x_k := n_k)$  implies  $f'(\vec{n}) \models \Gamma(x_1 := n_1, \dots, x_k := n_k)$ .

**Lemma 1.7.** Let  $\Gamma(\vec{x})$  be a finite set of  $\Sigma_1$  formulas such that

$$\mathbf{I}\Delta_0(exp) \vdash \bigvee_{\gamma(\vec{x}) \in \Gamma(\vec{x})} \gamma(\vec{x}).$$

Then there is an elementary function f such that  $f \models \Gamma(\vec{x})$  and f is strongly increasing on its variables.

*Proof.* If  $\Gamma$  is provable in  $\mathbf{I}\Delta_0(exp)$ , then it is provable in the Tait-style version of  $\mathbf{I}\Delta_0(exp)$ , where all cut formulas are  $\Sigma_1$ .

If  $\Gamma$  is classically derivable from non-logical axioms  $A_1, \ldots, A_s$ , then there is a cut-free proof in the Tait calculus of  $\neg A_1, \Delta, \Gamma$ , where  $\Delta = \neg A_2, \ldots, \neg A_s$ . Let us show how to cancel  $\neg A_1$  using a  $\Sigma_1$ -cut.

If  $A_1$  is an induction axiom on some formula B, then we have a cut-free proof of:

$$B(0) \wedge \forall y (\neg B(y) \vee B(y+1)) \wedge \exists x \neg B(x), \Delta, \Gamma$$

Thus we also have cut-free proofs of  $B(0), \Delta, \Gamma, \neg B(y), B(y+1), \Delta, \Gamma$  and  $\exists x \neg B(x), \Delta, \Gamma$ . So we have

$$\cfrac{\frac{\Delta,\Gamma,B(0)}{\Delta,\Gamma,B(x)}}{\cfrac{\Delta,\Gamma,B(x)}{\Delta,\Gamma,\forall xB(x)}}\,\forall \qquad \qquad \exists x\neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma,\exists xB(x)}{\Delta,\Gamma}\, & \qquad \qquad \Box x\neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x\neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x\neg B(x),\Delta,\Gamma \\ & \qquad \qquad \Box x\neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta,\Gamma \\ \cfrac{\Delta,\Gamma}{\Delta,\Gamma} & \qquad \qquad \Box x \neg B(x),\Delta$$

We can similarly cancel each of  $\neg A_2, \ldots, \neg A_s$  and so obtain the proof of  $\Gamma$  with  $\Sigma_1$ -cuts only.

Now we choose a proof of  $\Gamma(\vec{x})$  and proceed by induction on the height of the proof and determine an elementary function f such that  $f \models \Gamma$ .

- 1. If  $\Gamma(\vec{x})$  is an axiom, then for all  $\vec{n}$   $\Gamma(\vec{n})$  contains a true atom. So for any  $f \not\models \Gamma$ . Let us choose  $f(\vec{n}) = n_1 + \cdots + n_k$ .
- 2. If  $\Gamma, B_0 \vee B_1$  is derivable, so is  $\Gamma, B_0, B_1$ . Note that  $B_0$  and  $B_1$  are both bounded. Let  $f \models \Gamma, B_0, B_1$ , then  $f \models \Gamma, B_0 \vee B_1$ .
- 3. Assume  $\Gamma, B_0 \wedge B_1$  is derivable, then  $\Gamma, B_0$  and  $\Gamma, B_1$  By the induction hypothesis we have  $f_0 \models \Gamma, B_0$  and  $f_1 \models \Gamma, B_1$ , so, by persistence, we have  $\lambda \vec{n}.f_0(\vec{n}) + f_1(\vec{n}) \models \Gamma, B_0 \wedge B_1$ .
- 4. Assume  $\Gamma, \forall y B(y)$  is derivable, then  $\Gamma, B(y)$  is derivable and y is not free in  $\Gamma$ . Since all the formulas are  $\Sigma_1, \forall x B(y)$  must be bounded, so  $B(y) = \neg(y < t) \lor B'(y)$  for some term t and for some bounded formula B'. By the induction hypothesis, assume  $f_0 \models \Gamma, \neg(y < t), B'(y)$  for some increasing elementary function  $f_0$ . Then we have:

$$f_0(\vec{n}, k) \models \Gamma(\vec{n}), \neg(k < t(\vec{n})), B'(\vec{n}, k)$$

Let g be an increasing elementary function bounding t, define

$$f(\vec{n}) = \sum_{k < q(\vec{n})} f(\vec{n}, k)$$

We have either  $f(\vec{n}) \models \Gamma(\vec{n})$  or, by persistence,  $B'(\vec{n}, k)$  is true for every  $k < t(\vec{n})$ . So  $f \models \Gamma, \forall y B(y)$  and f is elementary.

5. Assume  $\Gamma, \exists y A(y, \vec{x})$  is derivable, so  $\Gamma, A(t, \vec{x})$  is derivable for some term t. By the IH, there is elementary  $f_0$  such that for all  $\vec{n}$  one has

$$f_0(\vec{n}) \models \Gamma(\vec{n}), A(t(\vec{n}), \vec{n})$$

Then either  $f_0(\vec{n}) \models \Gamma(\vec{n})$  or else  $f_0(\vec{n})$  bounds true witnesses for all existential quantifiers in  $A(t(\vec{n}), \vec{n})$ . Choose an elementary function g which is bounding for t. Define  $f(\vec{n}) = f_0(\vec{n}) + g(\vec{n})$ , then for all  $\vec{n}$  either  $f(\vec{n}) \models \Gamma(\vec{n})$  or  $f(\vec{n}) \models \exists y A(y, \vec{n})$ .

6. Assume  $\Gamma$  comes about by the cut rule with  $\Sigma_1$  formula  $C = \exists \vec{z} B(\vec{z})$ , so the premises are  $\Gamma, \forall \vec{z} \neg B(\vec{z})$  and  $\Gamma, \exists \vec{z} B(\vec{z})$ .

Without increasing the height of a proof, we can invert all universal quantifiers in the first premise. So we have  $\neg B(\vec{z})$ . B is bounded, so the induction hypothesis can be applied to this formula to obtain an elementary function  $f_0$  such that, for all assignments  $[\vec{x} := \vec{n}]$  and  $[\vec{z} := \vec{m}]$ 

$$f_0(\vec{n}, \vec{m}) \models \Gamma(\vec{n}), \neg B(\vec{n}, \vec{m})$$

Now we apply the induction hypothesis to the second premise of the cut rule, so we have an elementary function  $f_1$  such that for all  $\vec{n}$  either  $f_1(\vec{n}) \models \Gamma(\vec{n})$  or there are fixed witnesses  $\vec{m} < f_1(\vec{n})$  such that  $B(\vec{n}, \vec{m})$  is true.

Define f the following way:

$$f(\vec{n}) = f_0(\vec{n}, f_1(\vec{n}), \dots, f_1(\vec{n}))$$

Furthermore  $f \models \Gamma$ . For otherwise there would be a tuple  $\vec{n}$  such that  $\Gamma(\vec{n})$  is not true at  $f(\vec{n})$ , so, by persistence,  $\Gamma(\vec{n})$  is not true at  $f_1(\vec{n})$ . Thus  $B(\vec{n}, \vec{m})$  is true for particular numbers  $\vec{m} < f_1(\vec{n})$ . But then  $f_0(\vec{n}, \vec{m}) < f(\vec{n})$ , so, by persistence,  $\Gamma(\vec{n})$  cannot be true at  $f_0(\vec{n}, \vec{m})$ . Thus  $B(\vec{n}, \vec{m})$  is false, so we have a contradiction.

7. Finally suppose  $\Gamma(\vec{x})$ ,  $B(\vec{x},t)$  comes from the induction rule on a bounded formula B. The premises of the rule  $\Gamma(\vec{x})$ ,  $B(\vec{x},0)$  and  $\Gamma(\vec{x})$ ,  $\neg B(\vec{x},y)$ ,  $B(\vec{x},y+1)$ .

Let us apply the induction hypothesis to each of the premises, and then we obtain increasing elementary functions  $f_0$  and  $f_1$  such that for all  $\vec{n}$  and for all k

$$f_0(\vec{n}) \models \Gamma(\vec{n}), B(\vec{n}, 0)$$
$$f_1(\vec{n}, k) \models \Gamma(\vec{n}), \neg B(\vec{n}, k), B(\vec{n}, k+1)$$

Now let

$$f(\vec{n}) = f_0(\vec{n}) + \sum_{k < g(\vec{n})} f_1(\vec{n}, k)$$

where g is an increasing elementary function which is bounding for the term t. f is elementary and increasing, and, by persistence for  $f_0$  and  $f_1$ , we have either  $f(\vec{n}) \models \Gamma(\vec{n})$  or else  $B(\vec{n},0)$  and  $B(\vec{n},k) \rightarrow B(\vec{n},k+1)$  are true for all  $k < t(\vec{n})$ . In either case, we have  $f \models \Gamma(\vec{x}), B(\vec{x}, t(\vec{x}))$ .

**Theorem 1.3.** A number-theoretic function is elementary iff f is provably  $\Sigma_1$  in  $\mathbf{I}\Delta_0(exp)$ .

*Proof.* The only if part is in Theorem 1.2, so we show the if part only. Assume f is provably  $\Sigma_1$  in  $\mathbf{I}\Delta_0(exp)$ . Then we have a formula

$$F(\vec{x}, y) = \exists z_1 \dots \exists z_k B(\vec{x}, y, z_1, \dots, z_k)$$

which defines f and such that

$$\mathbf{I}\Delta_0(exp) \models \exists y F(\vec{x}, y)$$

By Lemma 1.7, there exists an elementary function g such that for every tuple of arguments  $\vec{n}$  there are numbers  $m_0, \ldots, m_k$  less that g(n) satisfying the bounded formula  $B(\vec{n}, m_0, m_1, \ldots, m_k)$ . Apply the elementary sequence coding:

$$h(\vec{n}) = \langle g(\vec{n}), g(\vec{n}), \dots, g(\vec{n}) \rangle$$

so that if  $m = \langle m_0, m_1, \dots, m_k \rangle$  where  $m_i < g(\vec{n})$  for each  $i \in n+1$ , so  $m < h(\vec{n})$ . As far as  $f(\vec{n})$  is the unique  $m_0$  for which there are  $m_1, \dots, m_k$  satisfying  $B(\vec{n}, m_0, \dots, m_k)$ , we define f as:

$$f(\vec{n}) = (\mu_{m < h(\vec{n})} B(\vec{n}, (m)_0, (m)_1, \dots, (m)_k))_0.$$

B is a bounded formula of  $\mathbf{I}\Delta_0(exp)$ , B is elementarily decidable. Moreover, elementary functions are closed under composition and bounded minimisation, so f is elementary.

### 2 Primitive Recursion and $I\Sigma_1$

 $\mathbf{I}\Sigma_1$  is an arithmetical theory where the induction scheme is restructed to  $\Sigma_1$  formulas.

**Lemma 2.1.** Every primitive recursion is provably recursive in  $I\Sigma_1$ .

*Proof.* We have to show represent each primitive recursive function f with a  $\Sigma_1$  formula  $F(\vec{x}, y) := \exists z C(\vec{x}, y, z)$  such that:

1. 
$$f(\vec{n}) = m \text{ iff } \omega \models F(\vec{x}, y).$$

- 2.  $\mathbf{I}\Sigma_1 \vdash \exists y F(\vec{x}, y)$ .
- 3.  $\mathbf{I}\Sigma_1 \vdash F(\vec{x}, y) \land F(\vec{x}, y') \rightarrow y = y'$ .

3  $\epsilon_0$  and Peano Arithmetic

- $\mathbf{4} \quad \mathbf{RCA}_0$
- $5 \quad \mathbf{WKL}_0$
- $\mathbf{6}$   $\mathbf{ACA}_0$
- 7 ATR
- 8  $\Pi_1^1$ -comprehension