Some Notes on Proof Theory and Elements of Ordinal Analysis

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1 Provable Recursion in $I\Delta_0$

 $\mathbf{I}\Delta_0$ is a theory in first-order logic in the language:

$$\{=, 0, S, P, +, \dot{-}, \cdot, exp_2\}$$

where S and P are successor and precessor functions respectively. Further, we will denote S(x) and P(x) as x+1 and x-1 respectively. 2^x stands for $exp_2(x)$.

The non-logical axioms of $\mathbf{I}\Delta_0$ are the following list:

•
$$x + 1 \neq 0$$

•
$$0 \dot{-} 1 = 0$$

•
$$x + 0 = x$$

$$\bullet \ x \dot{-} 0 = x$$

$$\bullet \ x \cdot 0 = 0$$

•
$$2^0 = 1$$

•
$$x + 1 = y + 1 \rightarrow x = y$$

•
$$(x+1)\dot{-}1 = x$$

•
$$x + (y + 1) = (x + y) + 1$$

•
$$x - (y + 1) = x - y - 1$$

•
$$x \cdot (y+1) = x \cdot y + x$$

•
$$2^{x+1} = 2^x + 2^x$$

along with the bounded induction scheme:

$$B(0) \land \forall x (B(x) \rightarrow B(x+1)) \rightarrow \forall x B(x)$$

where B is a Δ -formula, that is a formula one of the following forms (with bounded quantifiers only):

•
$$B = \forall x < tP(x) \equiv \forall x (x < t \rightarrow P(x))$$

•
$$B = \exists x < tP(x) \equiv \exists x (x < t \land P(x))$$

A Σ_1 -formula is a formula of the form:

$$\exists \vec{x} B(\vec{x})$$

where $B(\vec{x}) \in \Delta_0$.

Lemma 1.1. $\mathbf{I}\Delta_0$ proves (the universal closures of):

1.
$$x = 0 \lor x = (x - 1) + 1$$

2.
$$x + (y + z) = (x + y) + z$$

3.
$$x \cdot (y \cdot z) = (x \cdot y) \cdot z$$

4.
$$x \cdot (y+z) = x \cdot y + x \cdot z$$

5.
$$x + y = y + x$$

$$6. \ x \cdot y = y \cdot x$$

7.
$$\dot{x} - (y + z) = (\dot{x} - \dot{y}) - z$$

8.
$$2^{x+y} = 2^x \cdot 2^y$$

Proof.

1. This is self-evident.

2. If z = 0, then x + y = x + y. If z = z' + 1, then, by applying the IH and the relevant axioms:

$$(x + (y + (z' + 1))) = (x + ((y + z') + 1)) = (x + (y + z')) + 1 = ((x + y) + z') + 1 = (x + y) + (z' + 1)$$

3. If z = 0, then $x \cdot (y \cdot 0) = (x \cdot y) \cdot 0$. If z = z' + 1, then:

$$x \cdot (y \cdot (z'+1)) = x \cdot (y \cdot z'+y) = x \cdot (y \cdot z') + x \cdot y = (x \cdot y) \cdot z' + x \cdot y = (x \cdot y) \cdot (z'+1)$$

4. The rest of the cases are shown by induction on z. Consider the exponentiation law. If y=0, then

$$2^{x+0} = 2^x = 0 + 2^x = 2^x \cdot 0 + 2^x = 2^x \cdot (0+1) = 2^x \cdot 2^0$$

If y = y' + 1, then:

$$2^{x+(y'+1)} = 2^{(x+y')+1} = 2^x \cdot 2^y + 2^x \cdot 2^y = 2^x \cdot 2^{y+1}$$

Lemma 1.2. $\mathbf{I}\Delta_0$ proves (the universal closures of):

1.
$$\neg x < 0$$

$$2. \ x \le 0 \leftrightarrow x = 0$$

3.
$$0 \le x$$

4.
$$x \leq x$$

5.
$$x < x + 1$$

6.
$$x < y + 1 \leftrightarrow x \le y$$

7.
$$x \le y \leftrightarrow x < y \lor x = y$$

8.
$$x \le y \land y \le z \rightarrow x \le z$$

9.
$$x < y \land y < z \rightarrow x < z$$

10.
$$x \le y \lor y < x$$

11.
$$x < y \to x + z < y + z$$

12.
$$x < y \to x \cdot (z+1) < y \cdot (z+1)$$

13.
$$x < 2^x$$

14.
$$x < y \rightarrow 2^x < 2^y$$

Proof. Straightforward induction.

Definition 1.1. A function $f: \mathbb{N}^k \to \mathbb{N}$ is provably Σ_1 or provably recursive in an arithmetical theory if there is a Σ_1 formula $F(\vec{x}, y)$, a "defining formula" of f, such that:

1.
$$f(\vec{n}) = m$$
 iff $\omega \models f(\vec{n}) = m$

2.
$$T \vdash \exists y F(\vec{x}, y)$$

3.
$$T \vdash F(\vec{x}, y) \land F(\vec{x}, y') \rightarrow y = y'$$

If a defining formula $F \in \Delta_0$, then a function f is provably bounded in T if there is a term $t(\vec{x})$ such that $T \vdash F(\vec{x}, y) \to y < t(\vec{x})$.

Theorem 1.1. Let f be a provably recursive in T, then we can conservatively extend T by adding a new function symbol f along with the defining axiom $F(\vec{x}, f(\vec{x}))$.

2 Primitive Recursion and $I\Sigma_1$

 $\mathbf{I}\Sigma_1$ is an arithmetical theory where the induction scheme is restructed to Σ_1 formulas.

Lemma 2.1. Every primitive recursion is provably recursive in $I\Sigma_1$.

Proof. We have to show represent each primitive recursive function f with a Σ_1 formula $F(\vec{x}, y) := \exists z C(\vec{x}, y, z)$ such that:

1.
$$f(\vec{n}) = m \text{ iff } \omega \models F(\vec{x}, y).$$

- 2. $\mathbf{I}\Sigma_1 \vdash \exists y F(\vec{x}, y)$.
- 3. $\mathbf{I}\Sigma_1 \vdash F(\vec{x}, y) \land F(\vec{x}, y') \rightarrow y = y'$.