

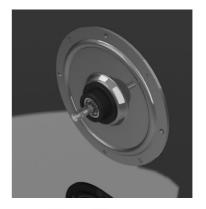


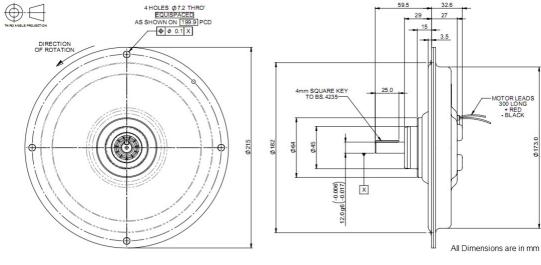
## Datasheet GPM16LR RS Pt No: 225 9591

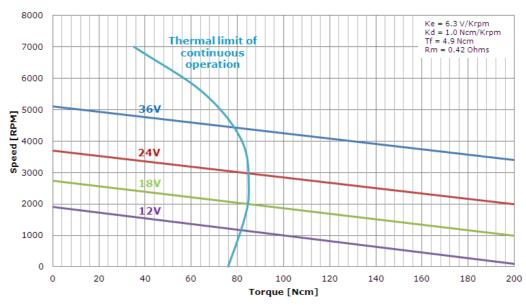
The Printed Motor Works *GP*M16LR is a totally enclosed dc motor in an ultra slim pancake profile. This pancake motor can provide a cost effective servo capability either direct drive or combined with a timing pulley/gearbox.

## **Features & Benefits**

- Ultra slim profile
- Minimum torque ripple
- Very low inertia
- High peak torques
- Zero cogging
- Ultra slow/creep capability
- Low inductance
- · EMC compatible







NOTE: The above voltages are examples, not a predefined maximum or minimum.

Due to ongoing product improvements data is subject to change without notice.

RS, Professionally Approved Products, gives you professional quality parts across all products categories. Our range has been testified by engineers as giving comparable quality to that of the leading brands without paying a premium price.



## **ENGLISH**

**Applications:** Servo mechanisms, motion control, industrial robots, CNC machining, printing machinery, logistics solutions, medical mobility, medical scanners, flight simulators, marine autopilots and high ambient temperature ventilation.

**Markets:** Industrial automation, automotive, medical, life sciences, aerospace, printing, logistics, instrumentation, test and measurement, oil & gas and offshore marine.

## **Design Modifications**

- Encoders
- Timing pulleys
- Long leads
- Tri-rated cable
- Open/kit option
- Customised shafts
- EMC suppression
- Connectors
- Rated for operation in 150°C ambient
- Mounting customisation

Performance Specifications	Symbol	Units	GPM16LR
Peak Torque	Тр	N-cm (oz-in)	730 (1034)
Rated Speed	N	RPM	3000
Rated Continuous Torque @ 25°C	T <sub>25</sub>	N-cm (oz-in)	84 (119)
Rated Power Output	Р	Watts	221
Maximum Recommended Speed	Nmax	RPM	6000
Continuous Stall Torque	Ts	N-cm (oz-in)	43.1 (61.03)
Cogging Torque	Tc	N-cm (oz-in)	0 (0)
Electrical Specifications			
Rated Terminal Voltage	Е	Volts	24
Rated Continuous Current	Ī	Amps	13.4
Peak Current	Ip	Amps	122.5
Continuous Stall Current	İs	Amps	8.0
Winding Charifications			
Winding Specifications Terminal Resistance ± 10%	Rm	Ohms	0.425
Armature Resistance ± 10%	Ra	Ohms	0.425
Back EMF Constant ± 5%	Ka Ke	V/kRPM	6.3
Torque Constant ± 5%	Kt	•	
		N-cm/Amp (oz-in/Amp) N-cm/KRPM	6 (8.5)
Viscous Damping Constant	Kd	(oz-in/KRPM)	1 (1.42)
Armature Inductance	L	μΗ	< 0.03
Temperature Coefficient of KE	С	%/°C Rise	-0.19
Number of Commutation Bars	Z		165
Mechanical Specifications			
Moment of Inertia	Jm	Kg-cm² (oz-in-sec²)	6.284 (0.089)
Average Friction Torque	Tf	N-cm (oz-in)	4.9 (6.939)
Weight	W	kg (Ibs)	2.9 (6.393)
Diameter	D	mm (In)	215 (8.465)
Length	LG	mm (In)	32.6 (1.283)
Permitted Radial Load		Kg (Ibs)	6 (13.23)
Permitted Axial Load		Kg (Ibs)	6 (13.23)
Figure of Merit			
Mechanical Time Constant	Tm	ms	73.8
Electrical Time Constant	Te	ms	<0.24
		-	-
Thermal Specifications Thermal Positions at Pated Chard	DAAD	0C //Math	1 25
Thermal Resistance at Rated Speed	RAAR	°C/Watt °C/Watt	1.25 1.9
Thermal Resistance at Stall	RAAS	°C/ watt	1.9