

• Determinante :

$$\vec{\text{rot}} \vec{F} = \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz & xz & xy \end{bmatrix}$$

$$\vec{i} \cdot \begin{vmatrix} \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xz & xy \end{vmatrix} - \vec{j} \cdot \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial z} \\ yz & xy \end{vmatrix} + \vec{k} \cdot \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ yz & xz \end{vmatrix} = i(x-z) - j(y-y) + k(z-z)$$

$$\Rightarrow (0, 0, 0)$$

Portanto $\vec{\text{rot}} \vec{F} = (0, 0, 0)$