## QUICK ESTIMATION OF $\hat{M}$ , $\hat{P}$ , AND $\hat{N}$

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From before, the analytical solutions for  $\hat{M}, \hat{N}|\hat{P}$  and  $\hat{P}, \hat{N}|\hat{M}$  can be written as:

$$(1) \qquad \qquad \hat{M'}^t = \left(\sum_i w_i S_i^P S_i^{Pt}\right)^{-1} \left(\sum_i w_i S_i^P I_i^t\right)$$

$$\hat{P'}^t = \left(\sum_i w_i S_i^{Mt} S_i^M\right)^{-1} \left(\sum_i w_i S_i^{Mt} I_i\right)$$

where

$$M' = (M N)$$

$$P' = \begin{pmatrix} P \\ N \end{pmatrix}$$

$$S_i^M = (\lambda_i M S_i I_D)$$

$$S_i^P = \begin{pmatrix} \lambda_i S_i P \\ I_D \end{pmatrix}$$

By breaking the matrices of each analytical solution into components, the summation over all clusters can be removed. Taking equation (1) for example:

$$\sum_{i} w_{i} S_{i}^{P} S_{i}^{Pt} = \begin{pmatrix} \sum_{i} w_{i} \lambda_{i}^{2} S_{i} P P^{t} S_{i}^{t} & \sum_{i} w_{i} \lambda_{i} S_{i} P \\ \sum_{i} w_{i} \lambda_{i} P^{t} S_{i}^{t} & \sum_{i} w_{i} I_{D} \end{pmatrix}$$

$$= \begin{pmatrix} \sum_{i} w_{i} \lambda_{i}^{2} S_{i} P P^{t} S_{i}^{t} & \bar{S} P \\ P^{t} \bar{S}^{t} & \bar{w} I_{D} \end{pmatrix}$$

$$\sum_{i} w_{i} S_{i}^{P} I_{i}^{t} = \begin{pmatrix} \sum_{i} w_{i} \lambda_{i} S_{i} P I_{i}^{t} \\ \sum_{i} w_{i} I_{i}^{t} \end{pmatrix}$$

$$= \begin{pmatrix} \sum_{i} w_{i} \lambda_{i} S_{i} P I_{i}^{t} \\ \bar{I}^{t} \end{pmatrix}$$

where  $\bar{S} = \sum_i w_i \lambda_i S_i$ ,  $\bar{w} = \sum_i w_i$  and  $\bar{I} = \sum_i w_i I_i$ . There are two sums left in the components of the equation. From Minka we have the following identity:

$$\operatorname{Vec}(ABC) = (C^t \otimes A) \operatorname{Vec}(B)$$

$$\operatorname{Vec}\left(\sum_{i} w_{i} \lambda_{i}^{2} S_{i} P P^{t} S_{i}^{t}\right) = \left[\sum_{i} w_{i} \lambda_{i}^{2} \left(S_{i} \otimes S_{i}\right)\right] \operatorname{Vec}\left(P P^{t}\right)$$

$$= J \operatorname{Vec}\left(P P^{t}\right) \text{ by appropriate definition of } J.$$

$$\operatorname{Vec}\left(\sum_{i} w_{i} \lambda_{i} S_{i} P I_{i}^{t}\right) = \left[\sum_{i} w_{i} \lambda_{i} \left(I_{i} \otimes S_{i}\right)\right] \operatorname{Vec}\left(P\right)$$

$$= K \operatorname{Vec}\left(P\right) \text{ by appropriate definition of } K.$$

Defining the Reshape operator to be the inverse of Vec, the summation free matrices are:

$$\sum_{i} w_{i} S_{i}^{P} S_{i}^{Pt} = \begin{pmatrix} \operatorname{Reshape} (J \operatorname{Vec}(PP^{t})) & \bar{S}P \\ P^{t} \bar{S}^{t} & \bar{w} \operatorname{I}_{D} \end{pmatrix}$$

$$\sum_{i} w_{i} S_{i}^{P} I_{i}^{t} = \begin{pmatrix} \operatorname{Reshape} (K \operatorname{Vec}(P)) \\ \bar{I}^{t} \end{pmatrix}$$

Similar solutions hold for equation (2):

$$\sum_{i} w_{i} S_{i}^{M t} S_{i}^{M} = \begin{pmatrix} \operatorname{Reshape} (J^{t} \operatorname{Vec}(M^{t} M)) & \bar{S}^{t} M^{t} \\ M \bar{S} & \bar{w} \operatorname{I}_{D} \end{pmatrix} 
\sum_{i} w_{i} S_{i}^{M t} I_{i} = \begin{pmatrix} \operatorname{Reshape} (K^{t} \operatorname{Vec}(M^{t})) \\ \bar{I} \end{pmatrix}$$

so