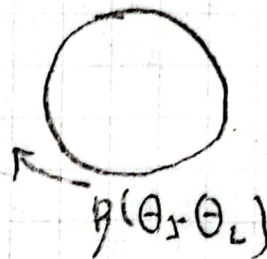
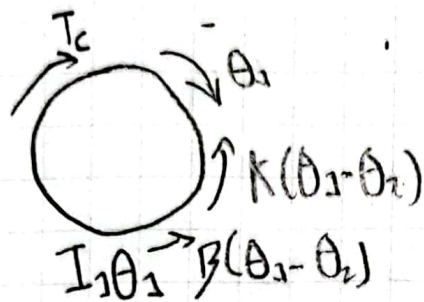
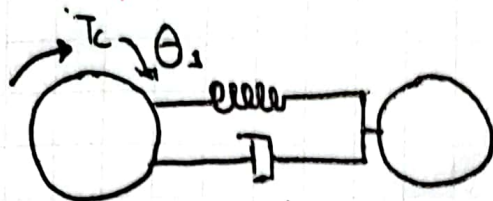


Torsion



$$① T_c - K(\theta_1 - \theta_2) - B(\dot{\theta}_1 - \dot{\theta}_2) = I_1 \ddot{\theta}_1$$

$$② I_2 \ddot{\theta}_2 = K(\theta_1 - \theta_2) + B(\dot{\theta}_1 - \dot{\theta}_2)$$

$$\hookrightarrow \ddot{\theta}_1 = \frac{T_c}{I_1} - \frac{K}{I_1}(\theta_1 - \theta_2) - \frac{B}{I_1}(\dot{\theta}_1 - \dot{\theta}_2)$$

$$\Rightarrow \frac{B\dot{\theta}_1}{I_2} - \frac{B\dot{\theta}_2}{I_2} + \frac{K\theta_1}{I_1} - \frac{K\theta_2}{I_1} = \ddot{\theta}_2$$

$$\begin{bmatrix} \dot{q}_1 \\ q_1 \\ \dot{q}_2 \\ q_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -\frac{K}{I_1} & -\frac{b}{I_1} & \frac{K}{I_1} & \frac{b}{I_1} \\ 0 & 0 & 0 & 1 \\ 0 & \frac{(K+b) - K}{I_2} & -\frac{b}{I_1} & 0 \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{bmatrix} + \begin{bmatrix} 0 \\ 1/I_1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{bmatrix}$$

$$q_1 = \theta_1, q_2 = \dot{q}_1 = \dot{\theta}_1, \\ \textcircled{q_3} = \dot{q}_2 = \ddot{q}_1 = \ddot{\theta}_1$$

$$q_3 = \theta_2, q_4 = \dot{q}_3 = \dot{\theta}_2, \\ \textcircled{q_5} = \ddot{q}_3 = \ddot{\theta}_2$$