

Foundations of Machine Learning (ECE 5984)

- Support Vector Machine -

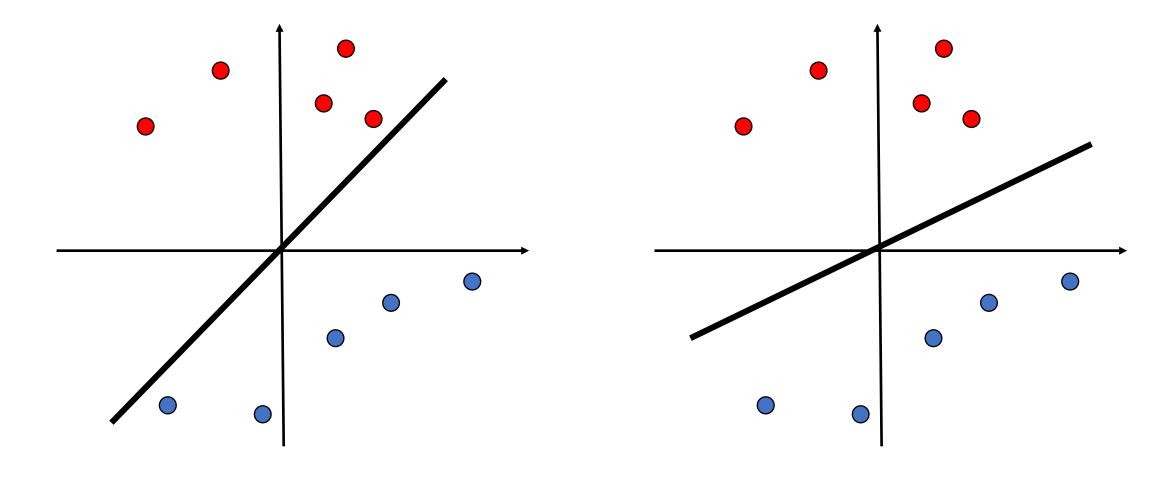
Eunbyung Park

Assistant Professor

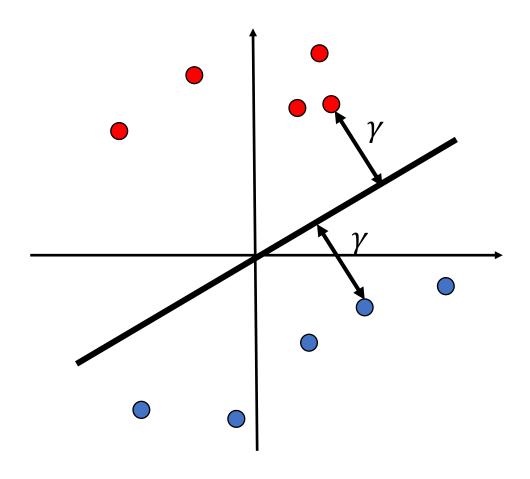
School of Electronic and Electrical Engineering

Eunbyung Park (silverbottlep.github.io)

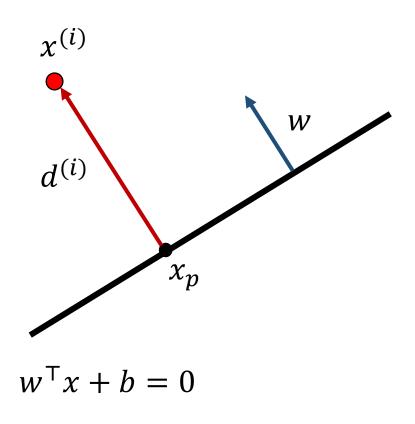
What is the best separating hyperplane?



• Maximize the distance to the closest data points from both classes

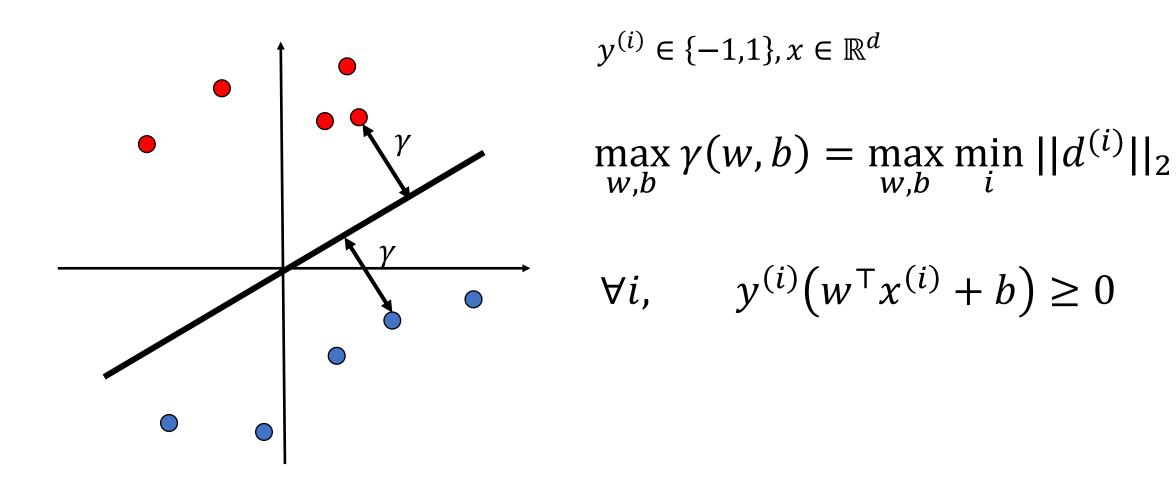


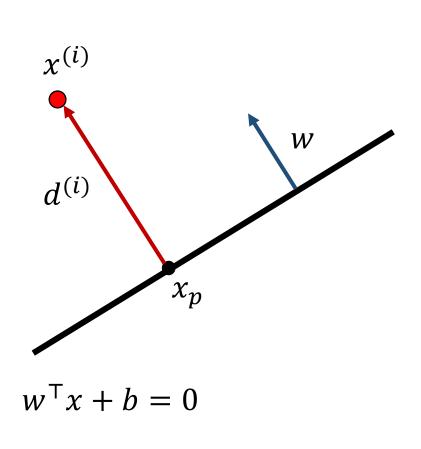
• Margin: the smallest distance across all points in dataset



$$\gamma(w,b) = \min_{i} ||d^{(i)}||_2$$

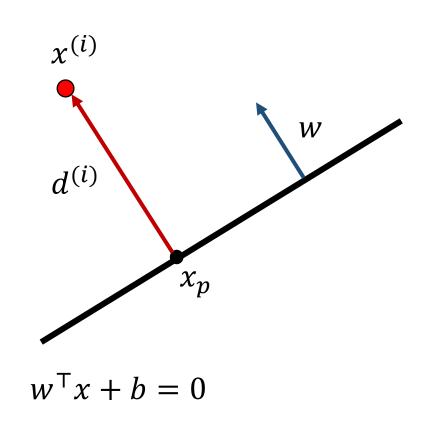
Maximize the distance to the closest data points from both classes





$$d^{(i)} = \alpha w$$

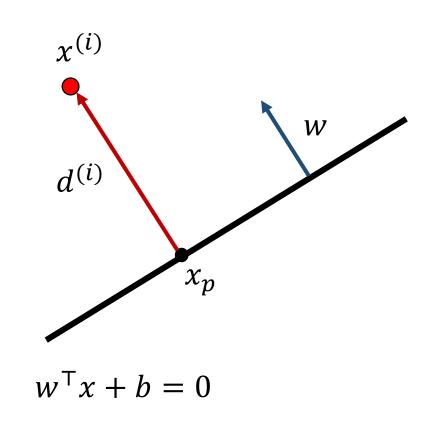
$$||d^{(i)}||_2 = \sqrt{d^{(i)}}^{\mathsf{T}} d^{(i)} = \sqrt{\alpha^2 w^{\mathsf{T}} w} = |\alpha| \sqrt{w^{\mathsf{T}} w}$$



$$d^{(i)} = \alpha w$$

 $x_p = x^{(i)} - d^{(i)}$
 $w^{\mathsf{T}} x_p + b = w^{\mathsf{T}} (x^{(i)} - \alpha w) + b = 0$

$$\alpha = \frac{w^{\mathsf{T}} x^{(i)} + b}{w^{\mathsf{T}} w}$$



$$\begin{split} & d^{(i)} = \alpha w \\ & x_p = x^{(i)} - d^{(i)} \\ & w^\top x_p + b = w^\top \big(x^{(i)} - \alpha w \big) + b = 0 \\ & \alpha = \frac{w^\top x^{(i)} + b}{w^\top w} \\ & ||d^{(i)}||_2 = \sqrt{d^{(i)}}^\top d^{(i)} = \sqrt{\alpha^2 w^\top w} = |\alpha| \sqrt{w^\top w} \end{split}$$

 $= \frac{|w^{\mathsf{T}}x^{(i)} + b|}{w^{\mathsf{T}}w} \sqrt{w^{\mathsf{T}}w} = \frac{|w^{\mathsf{T}}x^{(i)} + b|}{||w||_2}$

$$\max_{w,b} \gamma(w,b) = \max_{w,b} \min_{i} \frac{|w^{T}x^{(i)} + b|}{||w||_{2}}$$

$$= \max_{w,b} \frac{1}{||w||_2} \min_i |w^{\mathsf{T}} x^{(i)} + b|$$

s.t.
$$\forall i$$
, $y^{(i)}(w^{\mathsf{T}}x^{(i)} + b) \ge 0$

s.t.
$$\forall i$$
, $y^{(i)}(w^{\mathsf{T}}x^{(i)}+b) \geq 0$

$$\max_{w,b} \gamma(w,b) = \max_{w,b} \min_{i} \frac{|w^{T}x^{(i)} + b|}{||w||_{2}}$$

s.t.
$$\forall i$$
, $y^{(i)}(w^{\mathsf{T}}x^{(i)}+b) \geq 0$

$$= \max_{w,b} \frac{1}{||w||_2} \min_i |w^{\mathsf{T}} x^{(i)} + b|$$

s.t.
$$\forall i$$
, $y^{(i)}(w^{\mathsf{T}}x^{(i)}+b) \geq 0$

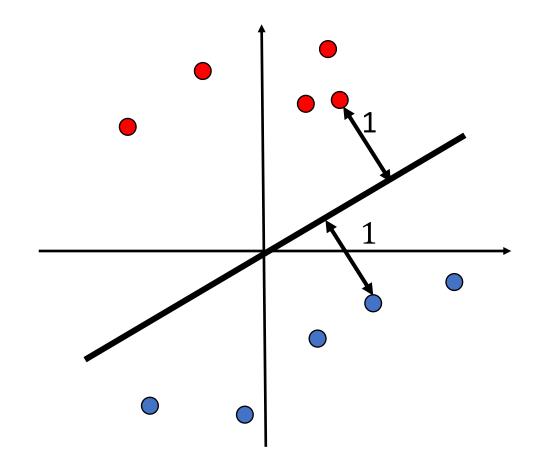
$$\to \max_{w,b} \frac{1}{||w||_2}$$

$$\rightarrow \max_{w,b} \frac{1}{||w||_2}$$
 $s.t. \min_{i} |w^{T}x^{(i)} + b| = 1$

(not same w and q, but will be 'same' decision boundary)

Scale Invariant Property of Hyperplane

- Multiply something both side does not change hyperplane!
- We are going to find w,b that makes the margin 1!



$$w^{\mathsf{T}}x + b = 0$$

$$a \cdot (w^{\mathsf{T}}x + b) = a \cdot 0$$

$$\max_{w,b} \gamma(w,b) = \max_{w,b} \min_{i} \frac{|w^{\top} x^{(i)} + b|}{||w||_{2}}$$

s.t.
$$\forall i$$
, $y^{(i)}(w^{\top}x^{(i)} + b) \ge 0$

$$= \max_{w,b} \frac{1}{||w||_2} \min_i |w^{\mathsf{T}} x^{(i)} + b|$$

s.t.
$$\forall i$$
, $y^{(i)}(w^{\mathsf{T}}x^{(i)}+b) \geq 0$

$$\to \max_{w,b} \frac{1}{||w||_2}$$

$$s.t \quad \min_{i} \left| w^{\mathsf{T}} x^{(i)} + b \right| = 1$$

(not same w and q, but will be 'same' decision boundary)

$$\rightarrow \min_{w,b} ||w||_2$$

$$s.t \quad \min_{i} \left| w^{\mathsf{T}} x^{(i)} + b \right| = 1$$

$$\rightarrow \min_{w,b} w^{\mathsf{T}} w$$

$$s.t \quad \min_{i} \left| w^{\mathsf{T}} x^{(i)} + b \right| = 1$$

• The new objective

$$\min_{w,b} w^{\top} w \\ s.t \quad \min_{i} |w^{\top} x^{(i)} + b| \ge 0$$

The new objective

(a)
$$\min_{w,b} w^{\mathsf{T}} w$$

$$s. t \quad \min_{i} \left| w^{\mathsf{T}} x^{(i)} + b \right| = 1$$

(b)
$$\min_{w,b} w^{\top} w$$
 $\forall i, y^{(i)} (w^{\top} x^{(i)} + b) \ge 1$

(a)->(b): It's kind of obvious,
$$|w^{\top}x^{(i)} + b| \ge 1$$
, $y^{(i)} \in \{-1,1\}$
(b)->(a): ??

The new objective

$$\min_{w,b} w^{\mathsf{T}} w$$

$$\forall i$$
,

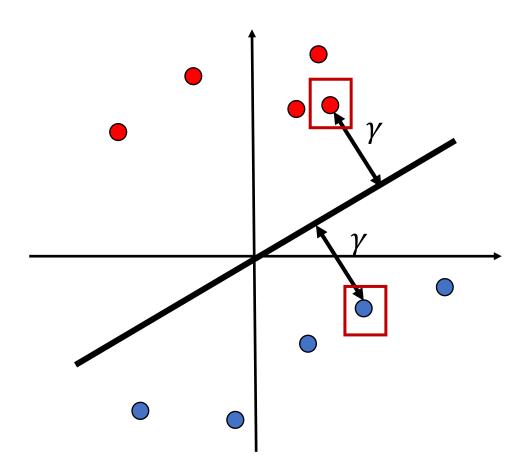
$$y^{(i)} \left(w^{\mathsf{T}} x^{(i)} + b \right) \ge 1$$

Quadratic objective

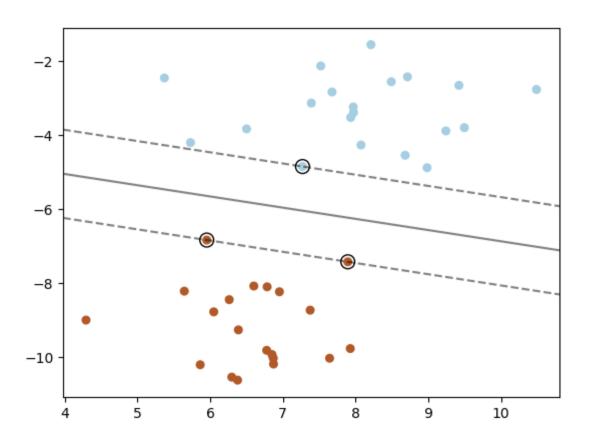
Linear constraints

- 1. Convex
- 2. We can use Quadratic Programing
 - very well established methods and softwares

Support Vectors



Decision Boundary



SVM with Soft Constraints

Non-Separable Cases

The objective with slack variables

$$\min_{w,b} w^{\mathsf{T}} w + C \sum_{i=1}^{N} \xi^{(i)} \qquad \forall i, \qquad y^{(i)} (w^{\mathsf{T}} x^{(i)} + b) \ge 1 - \xi^{(i)}$$
$$\forall i, \qquad \xi^{(i)} \ge 0$$

Unconstrained Formulation

Margin violation

$$\xi^{(i)} = \begin{cases} 1 - y^{(i)} (w^{\mathsf{T}} x^{(i)} + b), & if \ y^{(i)} (w^{\mathsf{T}} x^{(i)} + b) < 1 \\ 0, & if \ y^{(i)} (w^{\mathsf{T}} x^{(i)} + b) \ge 1 \end{cases}$$



Out of margin

$$\xi^{(i)} = \max(1 - y^{(i)}(w^{\mathsf{T}}x^{(i)} + b), 0)$$

Unconstrained Formulation

$$\min_{w,b} w^{\mathsf{T}} w + C \sum_{i=1}^{N} \max(1 - y^{(i)} (w^{\mathsf{T}} x^{(i)} + b), 0)$$

- 1. We can use gradient descent!
- 2. Is it convex?

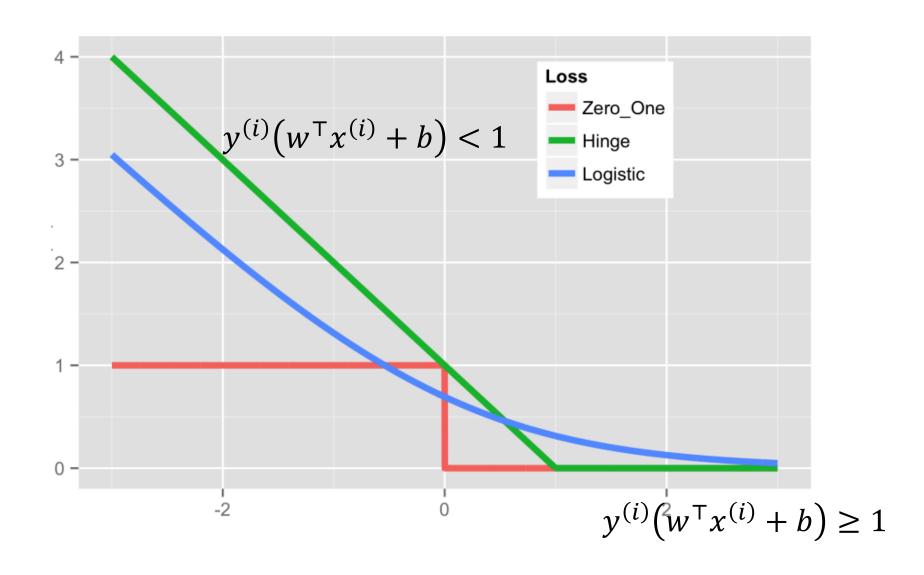
Regularization Perspective

$$\min_{w} C \sum_{i=1}^{N} \max(1 - y^{(i)}(w^{\mathsf{T}}x^{(i)} + b), 0) + w^{\mathsf{T}}w$$

Hinge Loss

L2 regularization

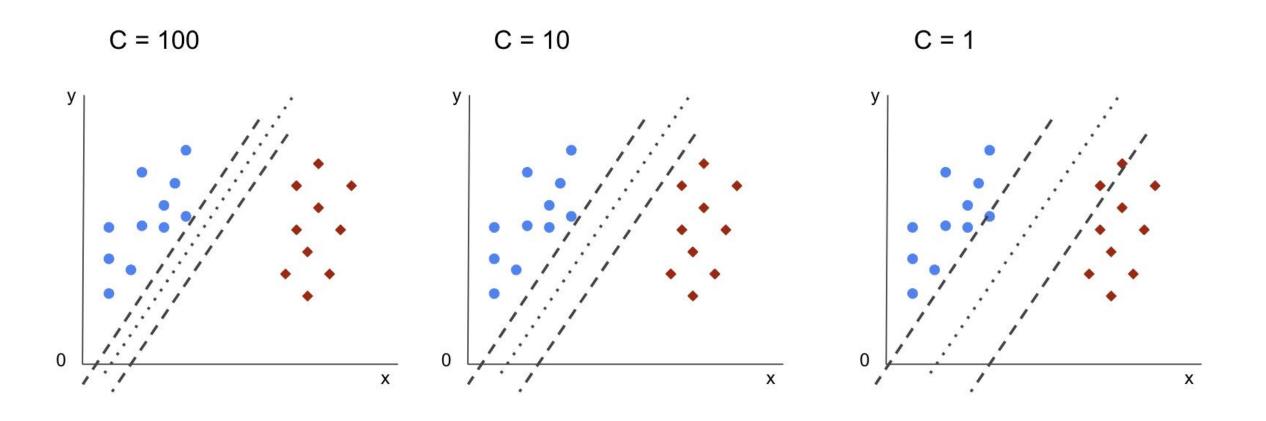
Hinge-Loss vs Log-Loss



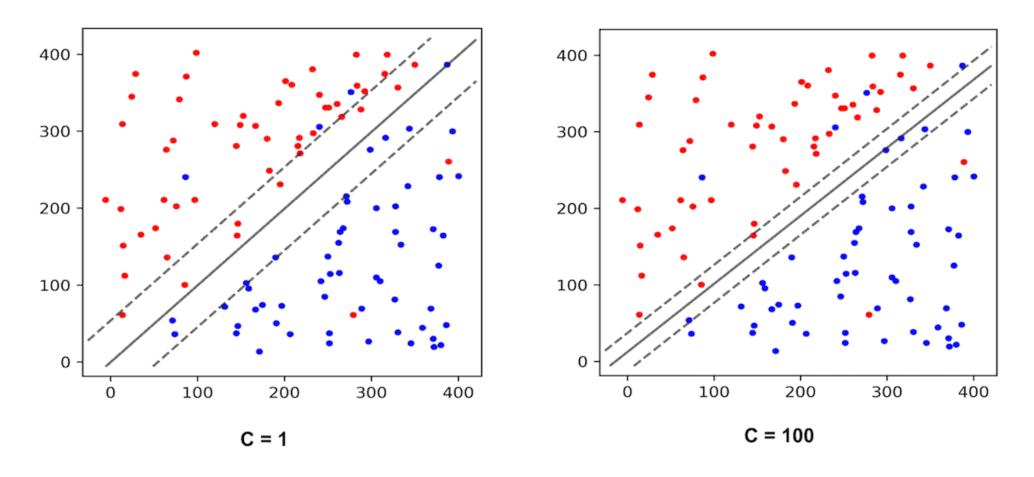
Hinge-Loss vs Log-Loss

- When the distance from the boundary is greater than or equal to 1, the loss is 0
- If the distance from the boundary is less than 1, there is a loss. At 0 distance, the loss is 1
- Correctly classified points that are outside of the margin will not affect the decision boundary
- Hinge-Loss often incur sparsity

The C Hyperparameter



The C Hyperparameter



Optimization

Subgradient Descent

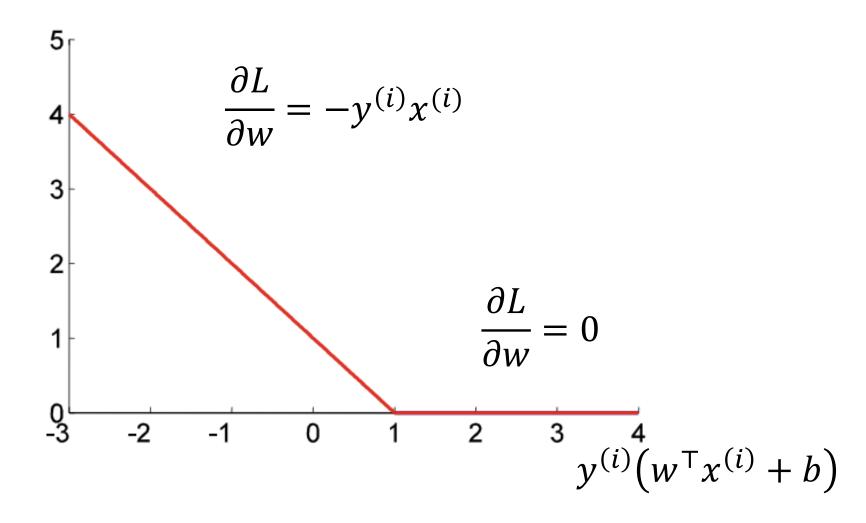
Not differentiable everywhere

$$\min_{w,b} C \sum_{i=1}^{N} \max(1 - y^{(i)}(w^{\mathsf{T}}x^{(i)} + b), 0) + w^{\mathsf{T}}w$$

$$\min_{w,b} \sum_{i=1}^{N} \max(1 - y^{(i)}(w^{\mathsf{T}}x^{(i)} + b), 0) + \lambda w^{\mathsf{T}}w$$

Subgradient Descent

Not differentiable everywhere



Subgradient Descent

Stochastic gradient descent

$$w \coloneqq w - \alpha \left(\lambda w - y^{(i)} x^{(i)} \right)$$

$$w := w - \alpha \lambda w$$

$$if \ y^{(i)}(w^{\mathsf{T}}x^{(i)} + b) < 1$$

otherwise