

# Foundations of Machine Learning (ECE 5984)

- Linear Regression and Gradient Descent -

## **Eunbyung Park**

**Assistant Professor** 

School of Electronic and Electrical Engineering

Eunbyung Park (silverbottlep.github.io)

# Supervised Learning

# Setup

$$D = \left\{ \left( x^{(i)}, y^{(i)} \right) \right\}$$

 $x^{(i)}$  is the input (feature) vector of the  $i^{th}$  sample

 $y^{(i)}$  is the label (target) of the  $i^{th}$  sample

$$x \sim X, y \sim Y$$

$$h: X \to Y$$

Regression – continuous target variable Classification – discrete target variable

# Setup • Example

input

target

Living Area (sqft)	Price (\$)
2000	400K
1500	330K
3700	600K

## Setup

• We would like to learn a function  $h \in H$ , that minimize the loss function L

$$h = \operatorname{argmin}_{h \in H} L(h)$$

- *H* is the hypothesis class
  - neural networks, linear models, ...
- *L* is the loss function
  - Zero-one loss, squared loss, ...

### Loss

Zero-one loss

$$L_{0/1} = \frac{1}{|D|} \sum_{(x,y) \in D} \delta_{h(x) \neq y}, \quad \text{where } \delta_{h(x) \neq y} = \begin{cases} 1, & h(x) \neq y \\ 0, & \text{otherwise} \end{cases}$$

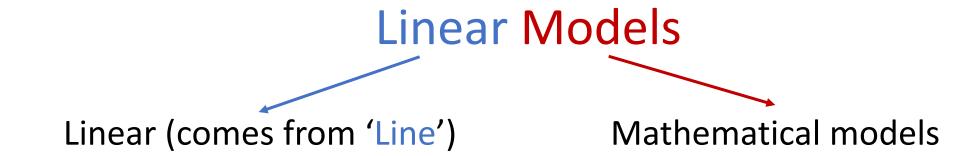
Squared loss (L2 loss)

$$L_{sq} = \frac{1}{|D|} \sum_{(x,y) \in D} (h(x) - y)^2$$

#### Generalization

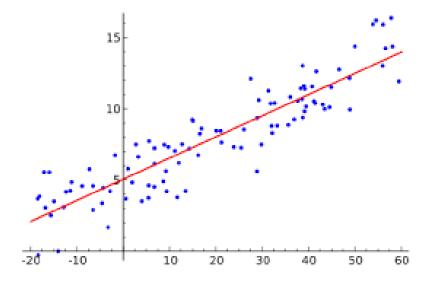
- Machine learning is about 'prediction' to the unseen data
- We split the data into three subsets,  $D_{\mathrm{train}}$ ,  $D_{\mathrm{val}}$ ,  $D_{\mathrm{test}}$ 
  - Training (Learning) on  $D_{\mathrm{train}}$ ,  $D_{\mathrm{val}}$
  - Testing (Evaluation) on  $D_{\mathrm{test}}$

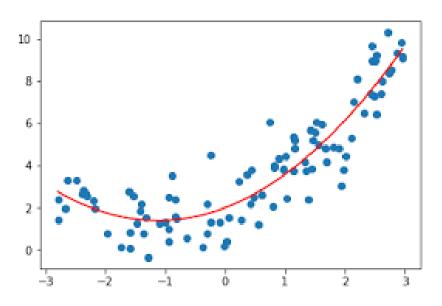
## Linear Models



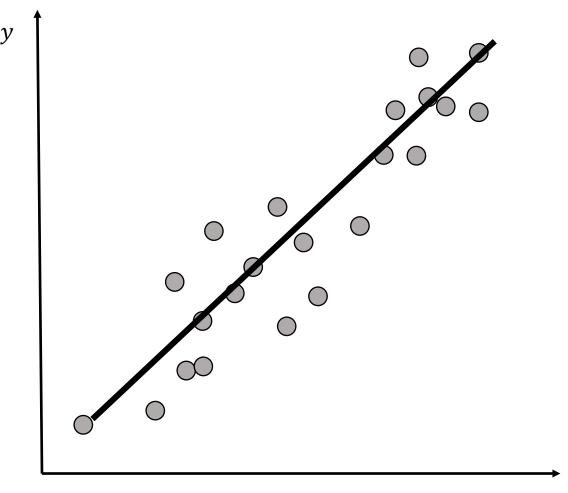
## Regression

- Regression is a (statistical) method of fitting curves through data points
- The term "regression" was coined by Francis Galton in the 19<sup>th</sup> century to describe a biological phenomenon.
  - The taller the parents, the taller the children, but shorter than their parents
  - The shorter the parents, the shorter the children, but taller than their parents
  - "regression to the mean"

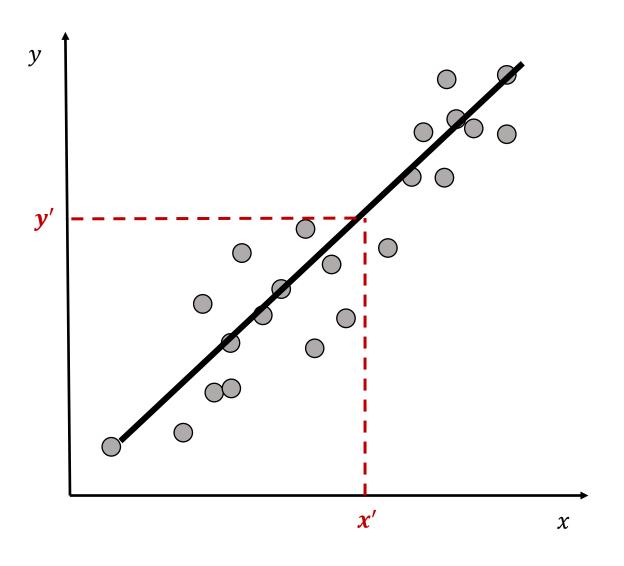




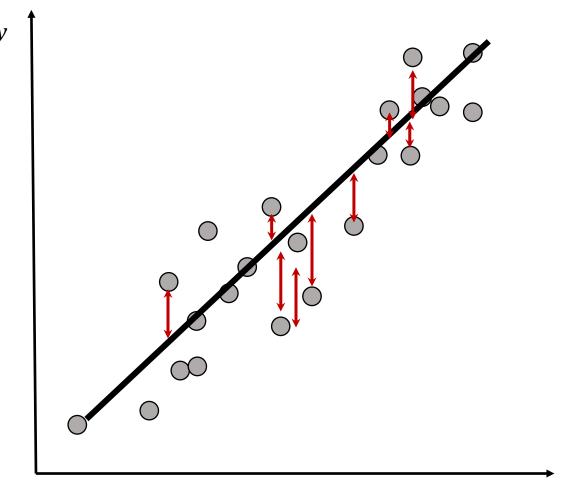
JMPer Cable Summer 98: Why is it called Regression? (jhsph.edu)



• Fitting a *line* that explains the data



- Fitting a *line* that explains the data
- Given a new data x', predict y'



• Fitting a line that explains the data  $\{(x^{(i)}, y^{(i)})\}$ 

$$f(x) = wx$$

- What is the best line?
  - A line that is close to all data points 'on average'
  - Mean squared error (MSE) loss

$$w^* = \underset{w}{\operatorname{arg\,min}} \frac{1}{2} \sum_{i=1}^{N} (y^{(i)} - wx^{(i)})^2$$

$$L(w) = \frac{1}{2} \sum_{i=1}^{N} (y^{(i)} - wx^{(i)})^{2}$$

$$w^* = \underset{w}{\operatorname{arg min}} L(w)$$

- The least squares method
  - L2 Loss function
- N and  $\{(x^{(i)}, y^{(i)})\}$  are constants (given), and only w is 'unknown'
- We are going to find w that minimizes the loss function L(w)
- Then, how?

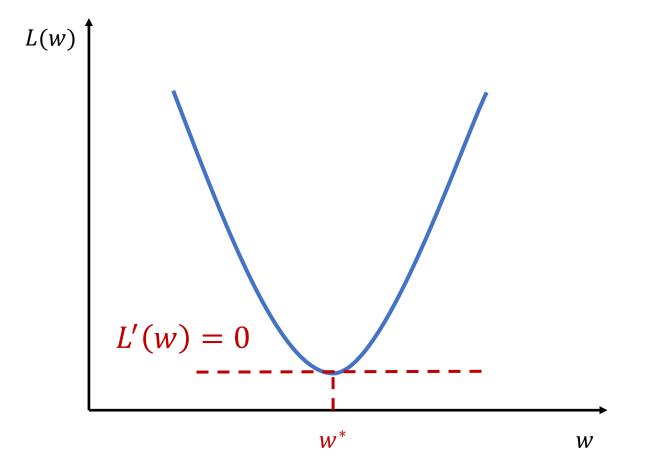
$$L(w) = \frac{1}{2} \sum_{i=1}^{N} (y^{(i)} - wx^{(i)})^{2}$$

$$L(w) = \frac{1}{2} \sum_{i=1}^{N} (y^{(i)} - wx^{(i)})^2 = \frac{1}{2} \sum_{i=1}^{N} (y^{(i)})^2 + w^2(x^{(i)})^2 - 2wx^{(i)}y^{(i)}$$

$$= \frac{1}{2} \left( \sum_{i=1}^{N} (x^{(i)})^{2} \right) w^{2} + \left( \sum_{i=1}^{N} x^{(i)} y^{(i)} \right) w + \frac{1}{2} \left( \sum_{i=1}^{N} (y^{(i)})^{2} \right)$$

L(w) is a quadradic function How to minimize a quadratic function?

- Minimizing a quadratic function
  - Take a derivative, and set it to zero



Does it have a solution?

If so, is it the unique solution?

$$L(w) = \frac{1}{2} \sum_{i=1}^{N} (y^{(i)} - wx^{(i)})^{2}$$

$$L(w) = \frac{1}{2} \sum_{i=1}^{N} (y^{(i)} - wx^{(i)})^{2}$$

$$L'(w) = \frac{dL(w)}{dw} = \sum_{i=1}^{N} (y^{(i)} - wx^{(i)})x^{(i)} = 0$$

$$w^* = \frac{\sum_{1}^{N} x^{(i)} y^{(i)}}{\sum_{1}^{N} (x^{(i)})^2}$$

# Multivariable Calculus

#### Derivative

- The rate of change of a function with respect to a variable
- f'(x) > 0, what does it mean?
- f'(x) < 0, what does it mean?

$$f'(x) = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$

#### Partial Derivative

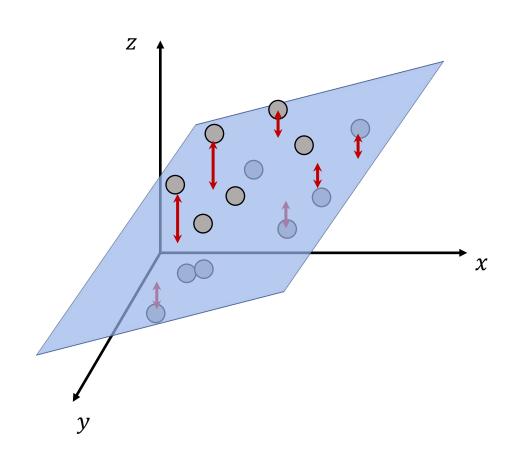
- A partial derivative of a function of several variables is its derivative with respect to one of those variables, with the others held constant
- It represents the instantaneous rates of change of the function f w.r.t one of its variables
  - $\frac{\partial f}{\partial x_i}$ : how much f changes as  $x_i$  change while fixing other components at any given point

$$\frac{\partial f}{\partial x}(x_0, y_0) = \lim_{h \to 0} \frac{f(x_0 + h, y_0) - f(x_0, y_0)}{h}$$

## Gradient

 The gradient stores all the partial derivative information of a multivariable function

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix}$$



$$z = w_2 x + w_1 y$$

$$L(w_1, w_2) = \frac{1}{2} \sum_{i=1}^{N} (z^{(i)} - w_2 x^{(i)} - w_1 y^{(i)})^2$$

$$z = w_2 x + w_1 y$$

$$L(w_1, w_2) = \frac{1}{2} \sum_{i=1}^{N} (z^{(i)} - w_2 x^{(i)} - w_1 y^{(i)})^2$$

$$w_1 = \frac{\sum_{i=1}^{N} y^{(i)} z^{(i)} - w_2 \sum_{i=1}^{N} x^{(i)} y^{(i)}}{\sum_{i=1}^{N} (y^{(i)})^2}$$

$$\frac{\partial L}{\partial w_1} = \sum_{i=1}^{N} \left( z^{(i)} - w_2 x^{(i)} - w_1 y^{(i)} \right) (-y^{(i)}) = 0 \qquad w_2 = \frac{\sum_{i=1}^{N} x^{(i)} z^{(i)} - w_1 \sum_{i=1}^{N} x^{(i)} y^{(i)}}{\sum_{i=1}^{N} (x^{(i)})^2}$$

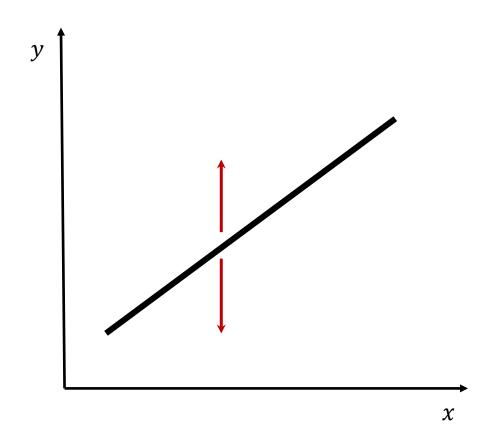
$$w_2 = \frac{\sum_{i=1}^{N} x^{(i)} z^{(i)} - w_1 \sum_{i=1}^{N} x^{(i)} y^{(i)}}{\sum_{i=1}^{N} (x^{(i)})^2}$$

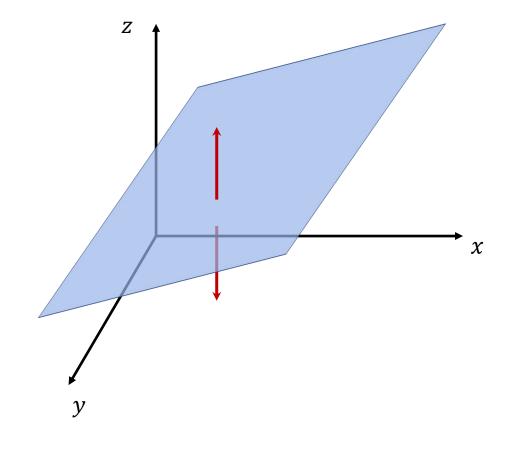
$$\frac{\partial L}{\partial w_2} = \sum_{i=1}^{N} (z^{(i)} - w_2 x^{(i)} - w_1 y^{(i)})(-x^{(i)}) = 0$$

# Bias term and Higher Dimension

$$y = w_1 x + w_0$$

$$z = w_2 x + w_1 y + w_0$$





# Linear Algebra Review

# **Basic Concepts**

$$4x_1 - 5x_2 = -13$$
  
$$-2x_1 + 3x_2 = 9$$

$$A = \begin{bmatrix} 4 & -5 \\ -2 & 3 \end{bmatrix}, \qquad b = \begin{bmatrix} -13 \\ 9 \end{bmatrix}$$

$$Ax = b$$

## **Basic Notation**

$$A \in \mathbb{R}^{m \times n}$$

$$x \in \mathbb{R}^n$$

#### **Inner Products**

$$x, y \in \mathbb{R}^n$$

$$x^{\mathsf{T}}y \in \mathbb{R}$$

$$\begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \sum_{i=1}^n x_i y_i$$

## **Outer Products**

$$x, y \in \mathbb{R}^n$$

$$xy^{\top} \in \mathbb{R}^{n \times n}$$

## Matrix Vector Products

$$A \in \mathbb{R}^{m \times n}$$

$$x \in \mathbb{R}^n$$

$$Ax \in$$

### **Matrix Matrix Products**

$$AB \in$$

$$A \in \mathbb{R}^{m \times n}$$

$$B \in \mathbb{R}^{n \times p}$$

#### **Matrix Matrix Products**

- Associative
  - (AB)C = A(BC)
- Distributive
  - A(B+C) = AB + AC
- Not commutative
  - $AB \neq BA$

# Identity Matrix and Diagonal Matrices

$$AI = A = IA$$

$$D = diag(d_1, d_2, ..., d_n) =$$

# The Transpose

$$(A^{\mathsf{T}})_{ij} = A_{ji}$$

$$(A^{\mathsf{T}})^{\mathsf{T}} = A$$
$$(AB)^{\mathsf{T}} = B^{\mathsf{T}}A^{\mathsf{T}}$$
$$(A+B)^{\mathsf{T}} = A^{\mathsf{T}} + B^{\mathsf{T}}$$

#### Norms

$$||x||_2 = \sqrt{\sum_{i=1}^n x_i^2} = \sqrt{x^\top x}$$

$$||x||_1 = \sum_{i=1}^n |x_i|$$
  $||x||_{\infty} = \max_i |x_i|$ 

$$||x||_p = \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}} \qquad ||A||_F = \sqrt{\sum_{i=1}^n A_{ij}^2} = \sqrt{\operatorname{tr}(A^{\mathsf{T}}A)}$$

# Linear Independence and Rank

• A set of vectors  $\{x_1, x_2, ..., x_n\} \subset \mathbb{R}^m$  is said to be *linearly independent* if no vector can be represented as a linear combination of the remaining vectors

$$x_n = \sum_{i=1}^{n-1} \alpha_i x_i \qquad \text{(linearly dependent)}$$

Geometrical interpretation

# Linear Independence and Rank

- The *column rank* of a matrix  $A \in \mathbb{R}^{m \times n}$  is the largest number of *columns* that constitute a linearly independent set
- The *row rank* of a matrix  $A \in \mathbb{R}^{m \times n}$  is the largest number of *rows* that constitute a linearly independent set
- For any matrix  $A \in \mathbb{R}^{m \times n}$  the *column rank* is equal to the *row rank*, so both quantities are referred to collectively as the *rank of A*.
- For  $A \in \mathbb{R}^{m \times n}$ , rank $(A) \leq \min(m, n)$ . If rank $(A) = \min(m, n)$ , then A is said to be *full rank*

# The Inverse of a Square Matrix

- The inverse of a square matrix
  - Non-square matrices do not have inverses by definition
  - $A^{-1}$  may not exist: non-invertiable or singular (not full rank)

$$A^{-1}A = I = AA^{-1}$$

$$(A^{-1})^{-1} = A$$
  
 $(AB)^{-1} = B^{-1}A^{-1}$   
 $(A^{-1})^{\top} = (A^{\top})^{-1} = A^{-\top}$ 

- For standard linear system, Ax = b,  $x = A^{-1}b$
- What if A is not square?

# Orthogonal Matrices

• If all its columns are orthogonal to each other and are normalized

$$x^{\mathsf{T}}y = 0$$
 (orthogonal) 
$$\|x\|_2 = 1$$
 (normalized) 
$$U^{\mathsf{T}}U = I = UU^{\mathsf{T}}$$
 (orthogonal) 
$$U^{\mathsf{T}} = U^{-1}$$

#### **Quadratic Forms**

• Given a square matrix  $A \in \mathbb{R}^{n \times n}$  and a vector  $x \in \mathbb{R}^n$ , the scalar value  $x^T A x$  is a quadratic form

$$x^{\mathsf{T}} A x = \sum_{i=1}^{n} x_i (A x)_i = \sum_{i=1}^{n} x_i \left( \sum_{j=1}^{n} A_{ij} x_j \right) = \sum_{i=1}^{n} \sum_{j=1}^{n} A_{ij} x_i x_j$$

#### Positive Semidefinite Matrices

- A symmetric matrix  $A \in \mathbb{S}^n$  is positive definite (PD), a.k.a  $\mathbb{S}^n_{++}$ 
  - $x^T A x > 0$ , for all non-zero vectors  $x \in \mathbb{R}^n$
- A symmetric matrix  $A \in \mathbb{S}^n$  is positive semidefinite (PSD), a.k.a  $\mathbb{S}^n_+$ 
  - $x^T A x \ge 0$ , for all non-zero vectors  $x \in \mathbb{R}^n$
- A symmetric matrix  $A \in \mathbb{S}^n$  is negative definite (ND)
  - $x^T A x < 0$ , for all non-zero vectors  $x \in \mathbb{R}^n$
- A symmetric matrix  $A \in \mathbb{S}^n$  is seminegative definite (ND)
  - $x^T A x \leq 0$ , for all non-zero vectors  $x \in \mathbb{R}^n$
- A symmetric matrix  $A \in \mathbb{S}^n$  is *indefinite* 
  - If there exists  $x, y \in \mathbb{R}^n$  such that  $x^T A x > 0$  and  $y^T A y \leq 0$

#### Positive Semidefinite Matrices

- Positive definite matrices (or negative definite) are always full rank, invertible
- Prove by contradiction

$$a_j = \sum_{i \neq j} x_i a_i$$
 (linearly dependent)

If 
$$x_i = -1$$
, then  $Ax = 0$ , so  $x^T Ax = 0$ 

#### **Gram Matrix**

- For any matrix  $A \in \mathbb{R}^{m \times n}$ , gram matrix is symmetric
- And, always positive semidefinite

$$G = A^{\mathsf{T}} A$$

$$x^{\mathsf{T}}Gx = \sum_{i=1}^{n} \sum_{j=1}^{n} G_{ij} x_i x_j = \sum_{i=1}^{n} \sum_{j=1}^{n} a_i^{\mathsf{T}} a_j x_i x_j = \sum_{i=1}^{n} \sum_{j=1}^{n} (x_i a_i)^{\mathsf{T}} (x_j a_j)$$
$$= \left( \sum_{i=1}^{n} x_i a_i \right)^{\mathsf{T}} \left( \sum_{j=1}^{n} x_j a_j \right) = \left\| \sum_{i=1}^{n} x_i a_i \right\|^2 \ge 0$$

# Linear Regression (High-dim)

# Linear Algebra

- Linear algebra comes to the rescue!
- Problem setup

$$D = \left\{ \left( x^{(1)}, y^{(1)} \right), \dots, \left( x^{(N)}, y^{(N)} \right) \right\}$$

$$x^{(i)} \in \mathbb{R}^d, y^{(i)} \in \mathbb{R}, w \in \mathbb{R}^d$$

$$X \in \mathbb{R}^{N \times d}, Y \in \mathbb{R}^N$$

$$L(w) = \frac{1}{2} (Xw - Y)^{\mathsf{T}} (Xw - Y)$$
$$= \frac{1}{2} \sum_{i=1}^{N} (w^{\mathsf{T}} x^{(i)} - y^{(i)})^{2}$$

$$X \qquad w \qquad - \qquad Y \qquad = \qquad (Xw - Y) \in \mathbb{R}^N$$

# Linear Algebra

- Linear algebra comes to the rescue!
- Problem setup

$$D = \left\{ \left( x^{(1)}, y^{(1)} \right), \dots, \left( x^{(N)}, y^{(N)} \right) \right\}$$
$$x^{(i)} \in \mathbb{R}^d, y^{(i)} \in \mathbb{R}, w \in \mathbb{R}^d$$
$$X \in \mathbb{R}^{N \times d}, Y \in \mathbb{R}^N$$

$$L(w) = \frac{1}{2}(Xw - Y)^{\mathsf{T}}(Xw - Y)$$

# Linear Algebra

- Linear algebra comes to the rescue!
- Problem setup

$$D = \{(x^{(1)}, y^{(1)}), ..., (x^{(N)}, y^{(N)})\}$$

$$x^{(i)} \in \mathbb{R}^{d}, y^{(i)} \in \mathbb{R}, w \in \mathbb{R}^{d}$$

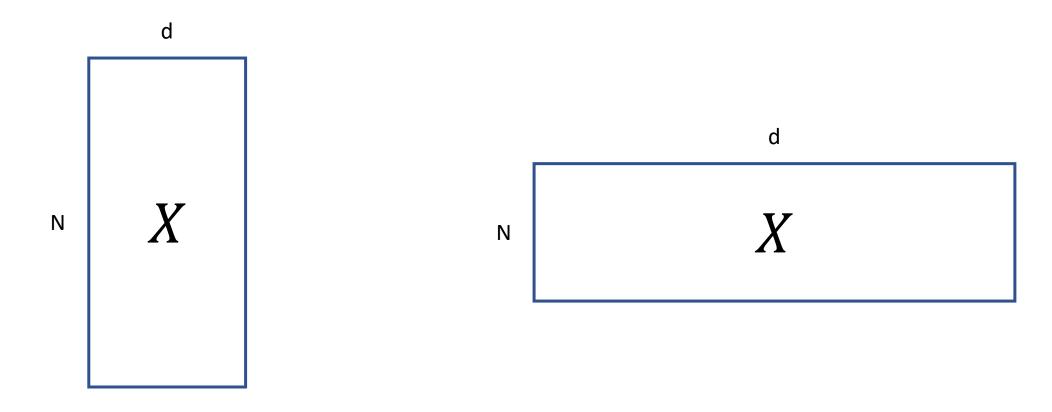
$$X \in \mathbb{R}^{N \times d}, Y \in \mathbb{R}^{N}$$

$$L(w) = \frac{1}{2}(Xw - Y)^{\mathsf{T}}(Xw - Y)$$

$$= \frac{1}{2} \sum_{i=1}^{N} (w^{\mathsf{T}}x^{(i)} - y^{(i)})^{2}$$

$$w^{*} = (X^{\mathsf{T}}X)^{-1}Y^{\mathsf{T}}X = (X^{\mathsf{T}}X)^{-1}X^{\mathsf{T}}Y$$
(pseudo-inverse)
$$(normal equation)$$

#### Overdetermined vs Underdetermined



(over-determined)

(under-determined)

# What's Wrong with It?

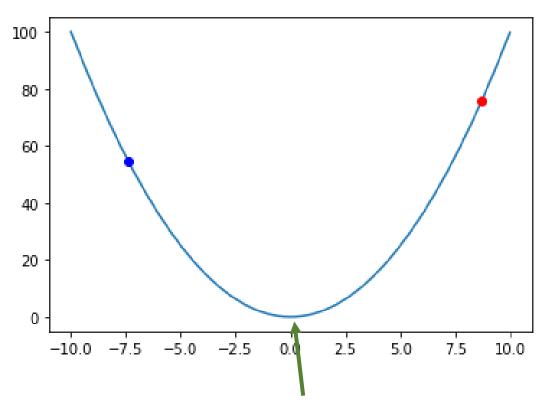
$$w^* = (X^\mathsf{T} X)^{-1} X^\mathsf{T} Y$$

- 1. Invertible?
- 2. When d is large?
- 3. Accuracy?

#### Derivative?

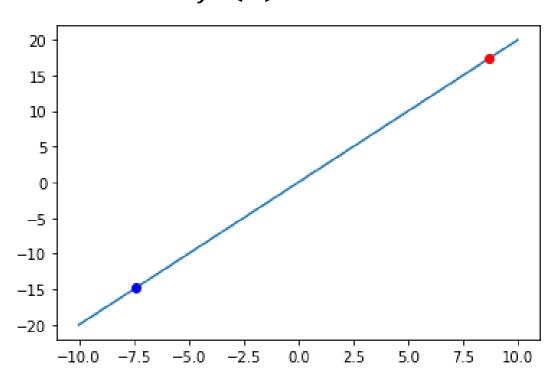
- The rate of change of a function with respect to a variable
- f'(x) > 0, what does it mean?
- f'(x) < 0, what does it mean?
- Our purpose is to minimize a function (loss function) w.r.t model parameter
  - $L(\theta)$

$$f(x) = x^2$$

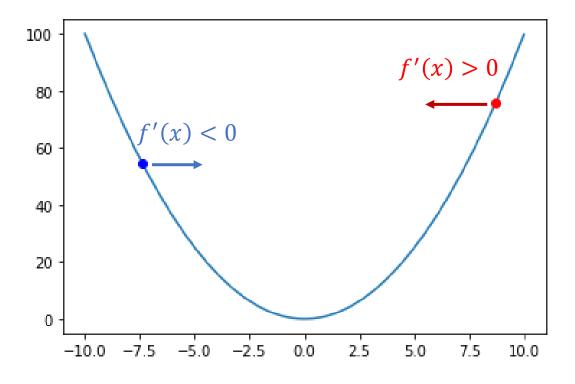


$$x^* = 0 = \arg\min_{x} f(x)$$
$$f(x^*) = 0$$

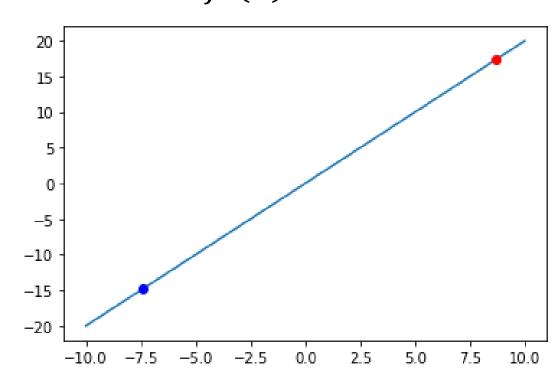
$$f'(x) = 2x$$



$$f(x) = x^2$$



$$f'(x) = 2x$$



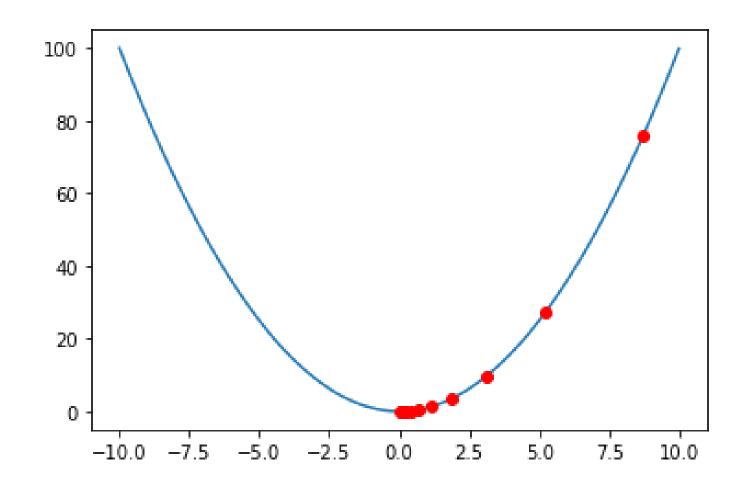
$$x \leftarrow x - \alpha f'(x)$$

$$f(x) = x^2$$

$$f'(x) = 2x$$

$$x_0 = 8.7, \alpha = 0.2$$

$$x \leftarrow x - \alpha f'(x)$$

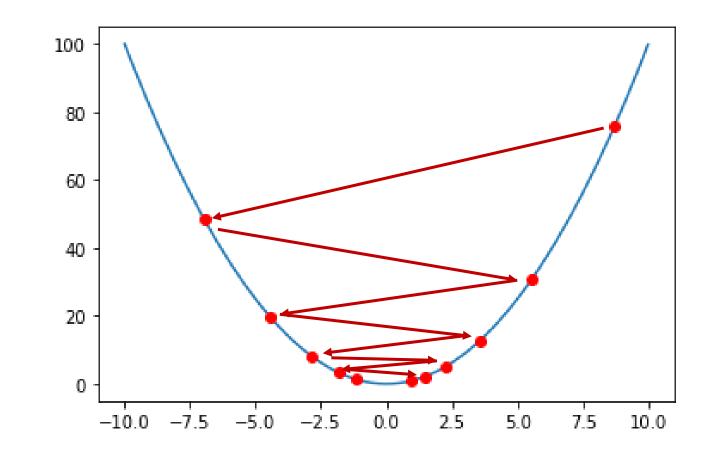


$$f(x) = x^2$$

$$f'(x) = 2x$$

$$x_0 = 8.7, \alpha = 0.9$$

$$x \leftarrow x - \alpha f'(x)$$

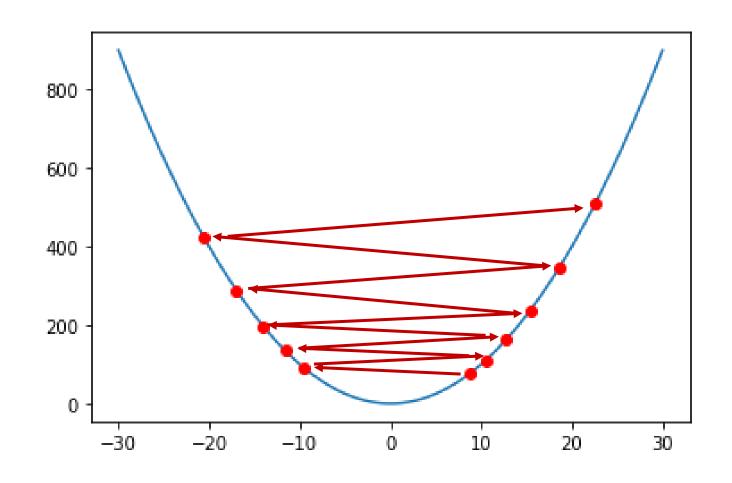


$$f(x) = x^2$$

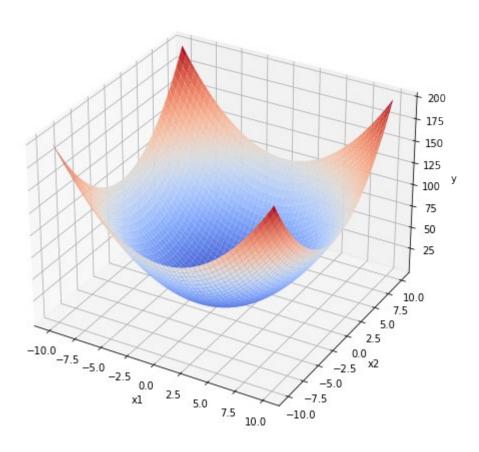
$$f'(x) = 2x$$

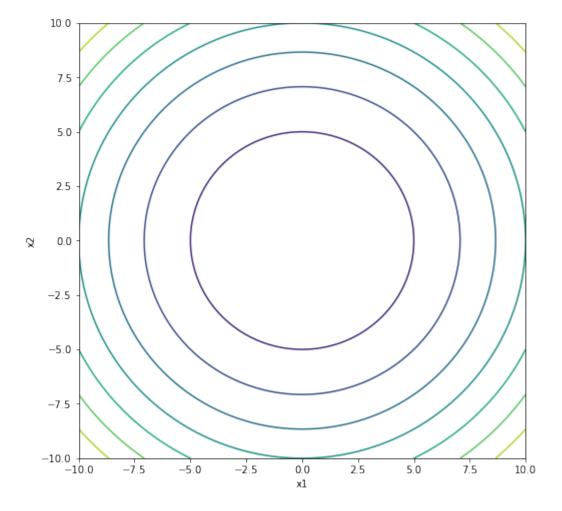
$$x_0 = 8.7, \alpha = 1.05$$

$$x \leftarrow x - \alpha f'(x)$$



$$f(x_1, x_2) = x_1^2 + x_2^2$$

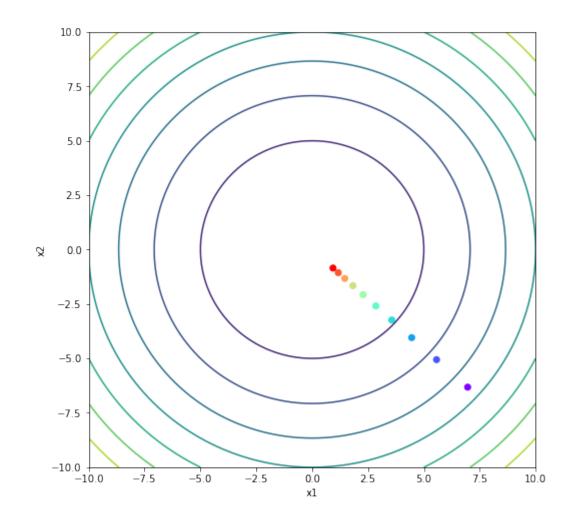




$$f(x_1, x_2) = x_1^2 + x_2^2$$

$$x_0 = [8.7, -7.9], \alpha = 0.1$$

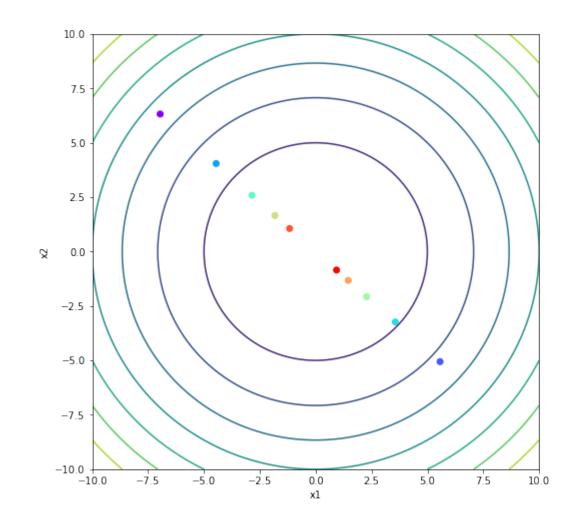
$$x \leftarrow x - \alpha \nabla f(x)$$



$$f(x_1, x_2) = x_1^2 + x_2^2$$

$$x_0 = [8.7, -7.9], \alpha = 0.9$$

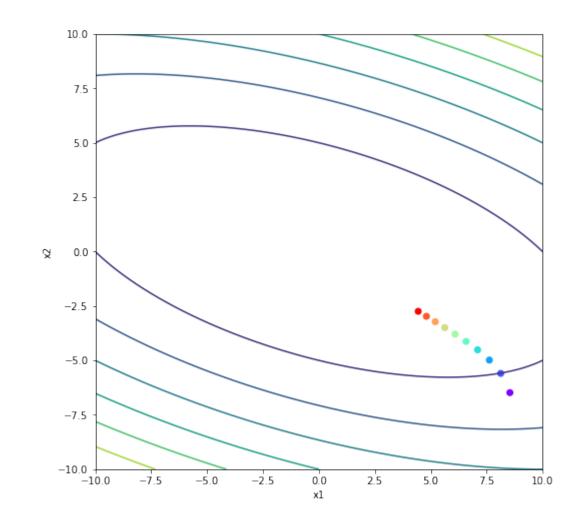
$$x \leftarrow x - \alpha \nabla f(x)$$



$$f(x_1, x_2) = 0.5x_1^2 + 2x_2^2 + x_1x_2$$

$$x_0 = [8.7, -7.9], \alpha = 0.2$$

$$x \leftarrow x - \alpha \nabla f(x)$$



### Steepest Descent

• 'The negative gradient is the direction of steepest descent'

#### **Directional Derivatives**

- The gradient vector is a vector of partial derivatives
- It represents the instantaneous rates of change of the function f w.r.t one of its variables
  - $\frac{\partial f}{\partial x_i}$ : how much f changes as  $x_i$  change while fixing other components at any given point
- Directional derivative is about how much f changes as all components change together at any given point

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix}$$
(gradient)

$$\frac{\partial f}{\partial x}(x_0, y_0) = \lim_{h \to 0} \frac{f(x_0 + h, y_0) - f(x_0, y_0)}{h}$$
(partial derivative)

$$D_{u}f(x_{0}, y_{0}) = \lim_{h \to 0} \frac{f(x_{0} + u_{1}h, y_{0} + u_{2}h) - f(x_{0}, y_{0})}{h}$$

$$u = [u_{1}, u_{2}], ||u|| = 1$$
 (unit vector) (directional derivative)

# Directional Derivatives (Chain Rules)

• Given a function f(x, y) then the rate of change with respect to t along a curve x(t), y(t) is

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t}$$

• The line through  $(x_0, y_0)$  in the direction  $u = u_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + u_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  is

$$x(t) = u_1 t + x_0,$$
  $y(t) = u_2 y + y_0$ 

$$D_{\mathbf{u}}f(x,y) = \frac{\partial f}{\partial x}u_1 + \frac{\partial f}{\partial y}u_2 = \nabla f(x,y) \cdot u$$

#### **Directional Derivatives**

$$a \cdot b = ||a|| ||b|| \cos(\theta)$$

$$D_u f(x_0, y_0) = \nabla f(x_0, y_0) \cdot u = \|\nabla f(x_0, y_0)\| \|u\| \cos(\theta)$$

• When  $\theta = 0$ ,  $\cos(\theta) = 1$ ,  $D_u f$  is maximized, u is the direction of steepest ascent

$$u = \frac{\nabla f(x_0, y_0)}{\|\nabla f(x_0, y_0)\|}$$

• When  $\theta = \pi, \cos(\theta) = -1$ ,  $D_u f$  is minimized, u is the direction of steepest descent

$$u = -\frac{\nabla f(x_0, y_0)}{\|\nabla f(x_0, y_0)\|}$$

# Gradient Descent in Linear Regression (1D)

$$L(w) = \frac{1}{2} \sum_{i=1}^{N} (wx^{(i)} - y^{(i)})^{2} \qquad \frac{\partial L(w)}{\partial w} = \sum_{i=1}^{N} (wx^{(i)} - y^{(i)})x^{(i)}$$

$$w \coloneqq w - \alpha \left( \sum_{i=1}^{N} (wx^{(i)} - y^{(i)})x^{(i)} \right)$$

(descent) (step-size) (gradient)

# Gradient Descent in Linear Regression (N-D)

$$L(w) = \frac{1}{2} \sum_{i=1}^{N} (w^{\mathsf{T}} x^{(i)} - y^{(i)})^{2} \qquad \qquad \frac{\partial L}{\partial w_{k}} = \sum_{i=1}^{N} (w^{\mathsf{T}} x^{(i)} - y^{(i)}) x_{k}^{(i)}$$

$$w_k \coloneqq w_k - \alpha \left( \sum_{i=1}^{N} (w^{\mathsf{T}} x^{(i)} - y^{(i)}) x_k^{(i)} \right)$$
(descent) (step-size) (gradient)

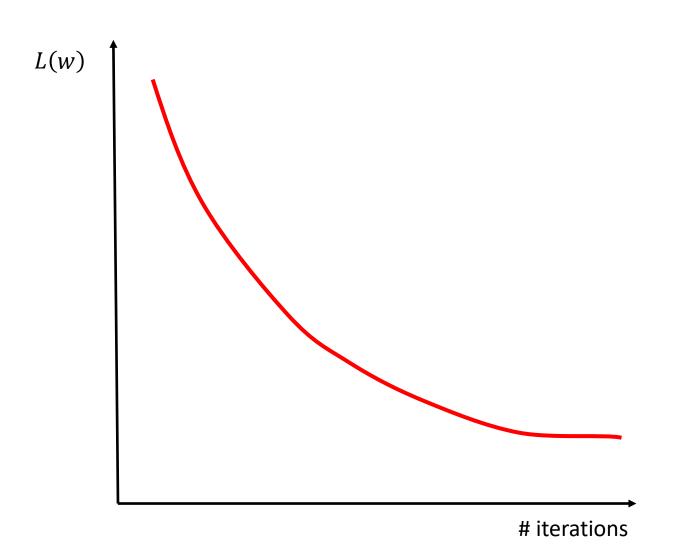
# Gradient Descent in Linear Regression (N-D)

$$L(w) = \frac{1}{2} \sum_{i=1}^{N} (w^{\mathsf{T}} x^{(i)} - y^{(i)})^{2} \qquad \frac{\partial L}{\partial w} = \sum_{i=1}^{N} (w^{\mathsf{T}} x^{(i)} - y^{(i)}) x^{(i)} = X^{\mathsf{T}} (Xw - Y)$$

$$w \coloneqq w - \alpha(X^{\mathsf{T}}(Xw - Y))$$

(descent) (step-size) (gradient)

#### **Gradient Descent in Practice**



• L(w) should decrease every iteration

• If L(w) decreases by very small amount, then it's considered as convergence