Questions:

Q1: What is "source the environment" ?

A1: It means to tell your system what ROS is and where it is.

Q2: What are nodes and edges of ROS 2 system?

A2: Nodes represent processes and edges represent communication.

Q3: Can publisher keep sending messages even with no subscriber?

A3: Yes

Q4: What is the function of message type?

A4: It must match with the message type of the topic, otherwise they are not speaking the same language.

Q5: Does one publisher only have one subscriber?

A5: No, there can be multiple subscribers to the same publisher.

Feedback:

From my perspective, I feel this lab material is very well-written and easy to follow. I don't encounter any difficult parts that I have trouble with. If I have to name one part that is a little difficult to understand, it may be the setting to source the environment.