

# Course Projects

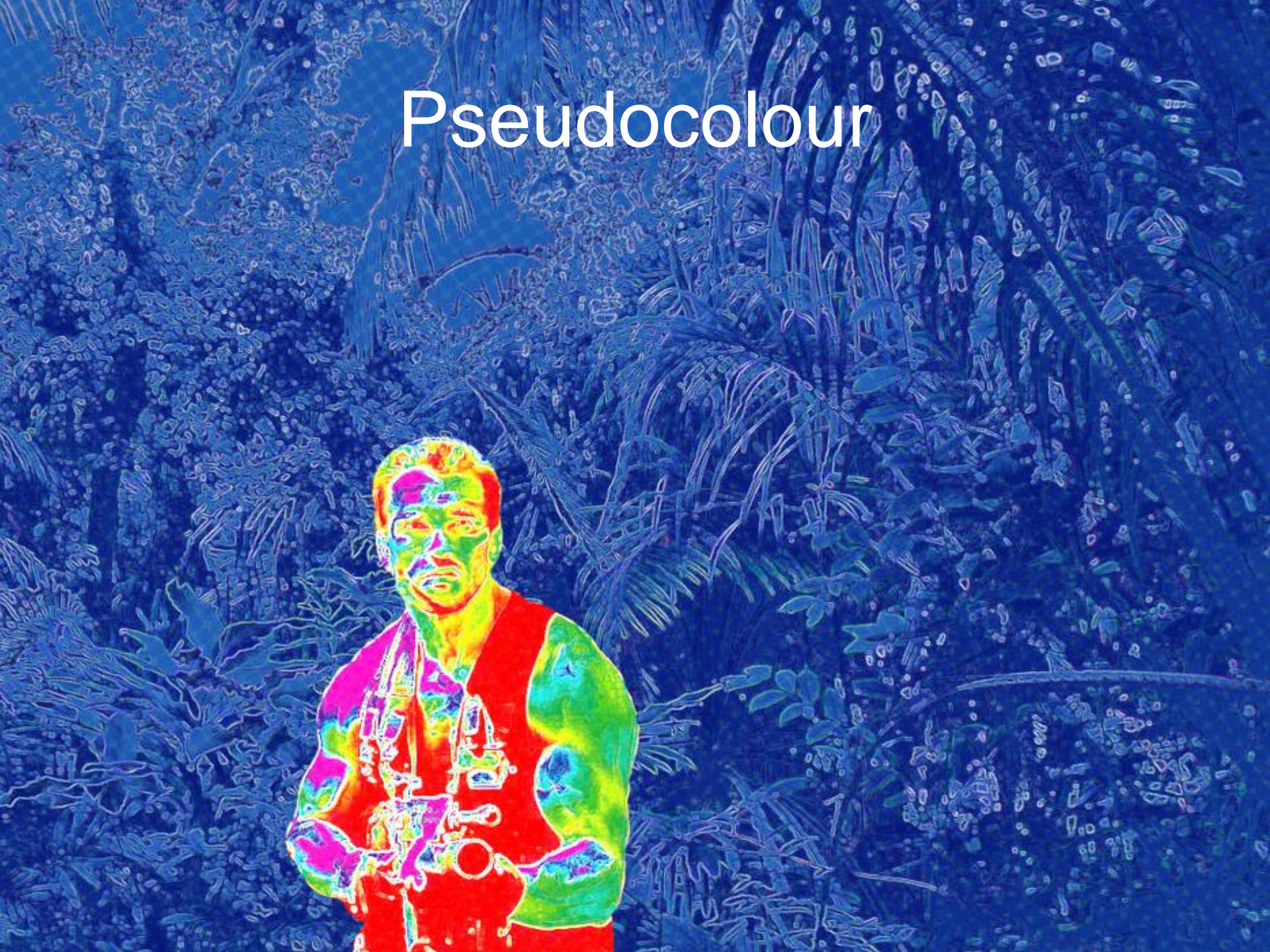
Computer Vision 23/24

***Miguel Coimbra, Hélder Oliveira***

Stuff we can do



# Pseudocolour





# Colour Slicing



# Chroma Key







Colour Edge Detectors



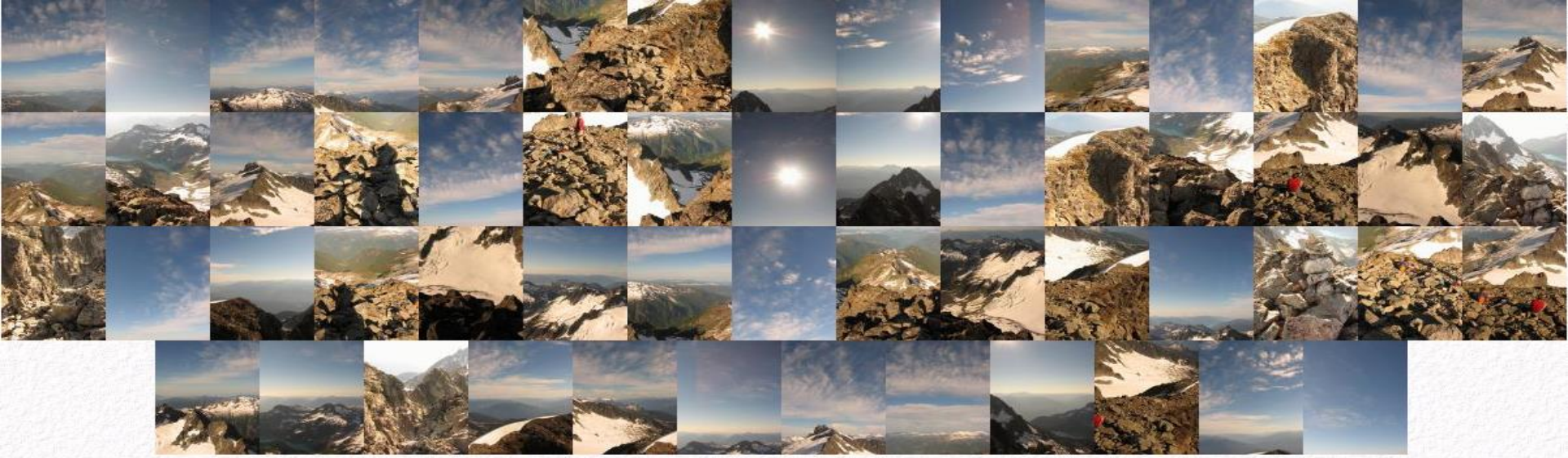
X-Rate o

Tavollow 3pgo



Motion Quantification

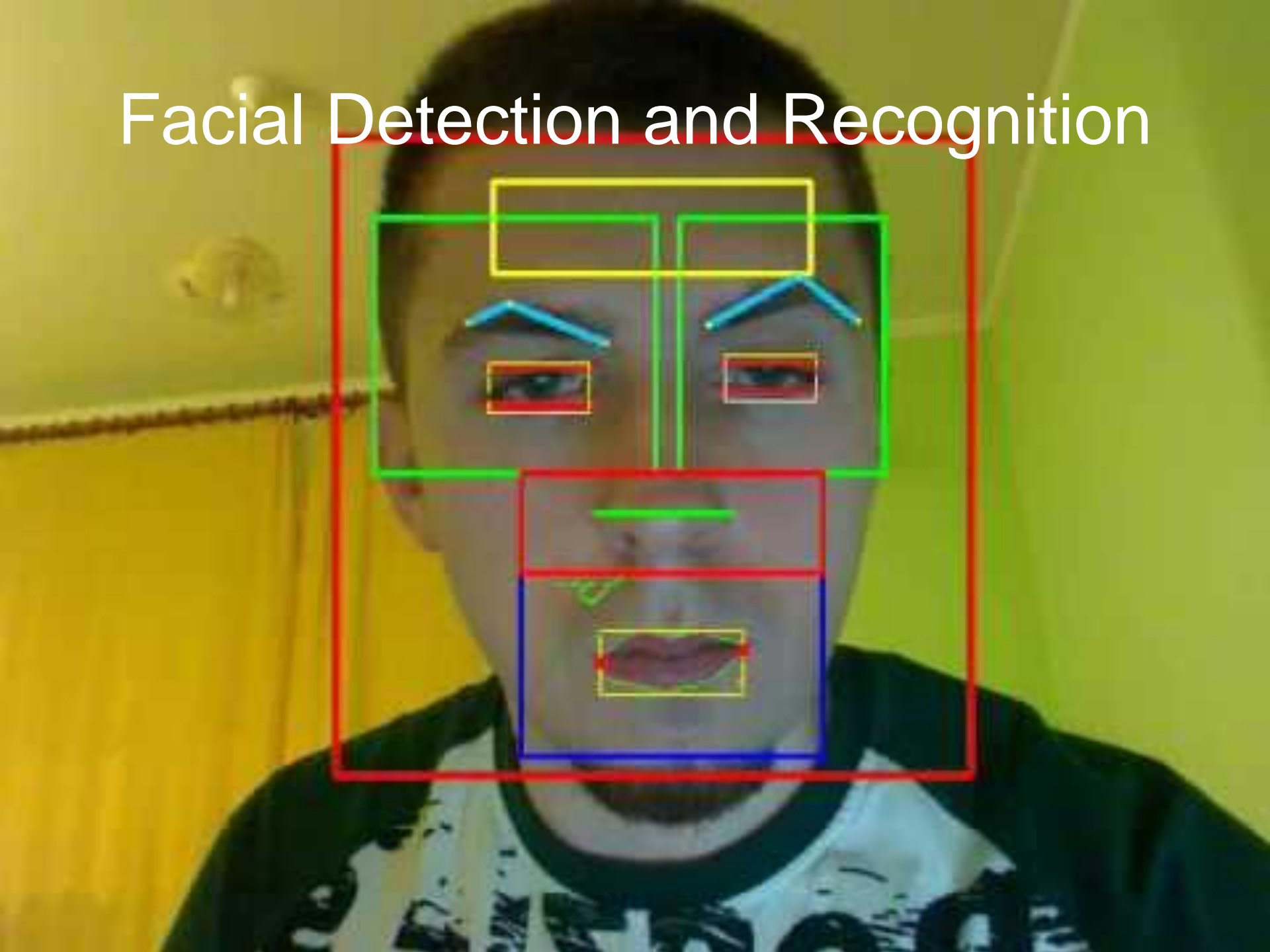




Mosaicing



# Facial Detection and Recognition

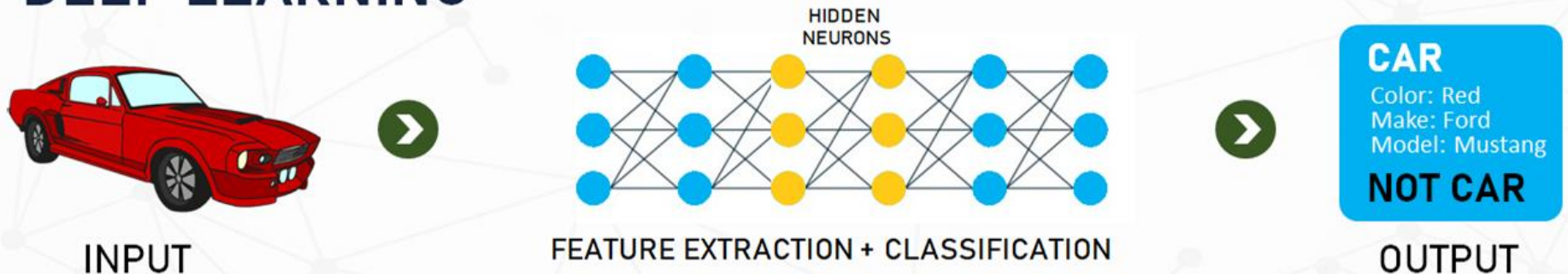


# Deep Learning Ford Mustang Classifiers

## MACHINE LEARNING



## DEEP LEARNING







# Segment Cats & Dogs

## Other Computer Vision Tasks

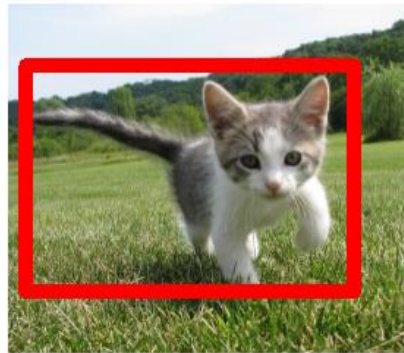
**Semantic Segmentation**



GRASS, CAT,  
TREE, SKY

No objects, just pixels

**Classification  
+ Localization**



CAT

Single Object

**Object  
Detection**



DOG, DOG, CAT

Multiple Object

**Instance  
Segmentation**



DOG, DOG, CAT

This image is CC0 public domain

Fei-Fei Li & Justin Johnson & Serena Yeung

Lecture 11 - 17 May 10, 2017

Source [http://cs231n.stanford.edu/slides/2017/cs231n\\_2017\\_lecture11.pdf](http://cs231n.stanford.edu/slides/2017/cs231n_2017_lecture11.pdf)



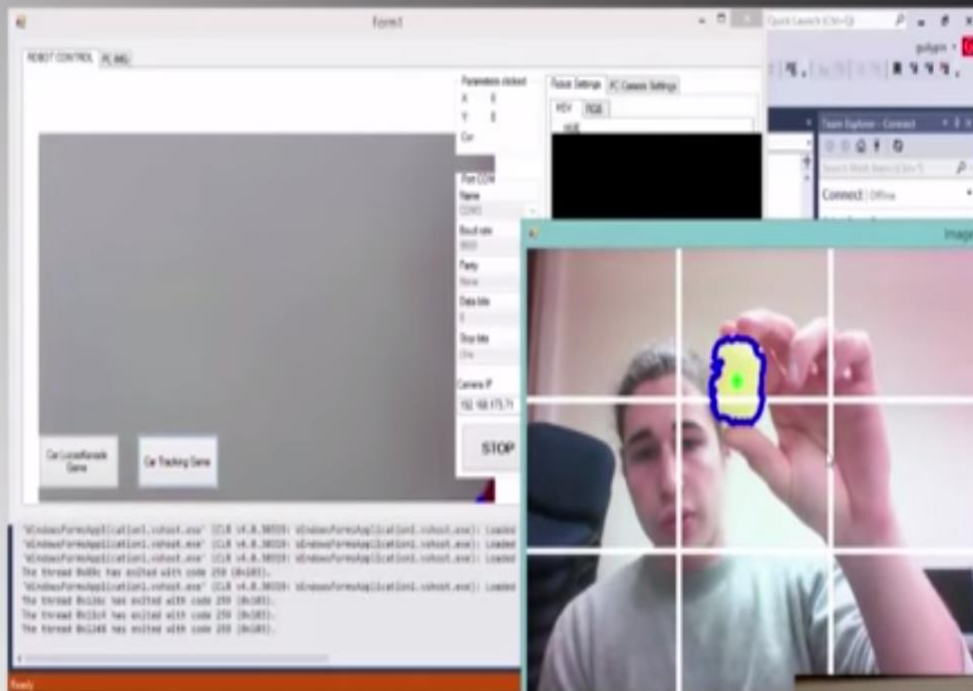


Generate AI Images

Stuff your colleagues did



# Demonstration: Self-Driving Robot





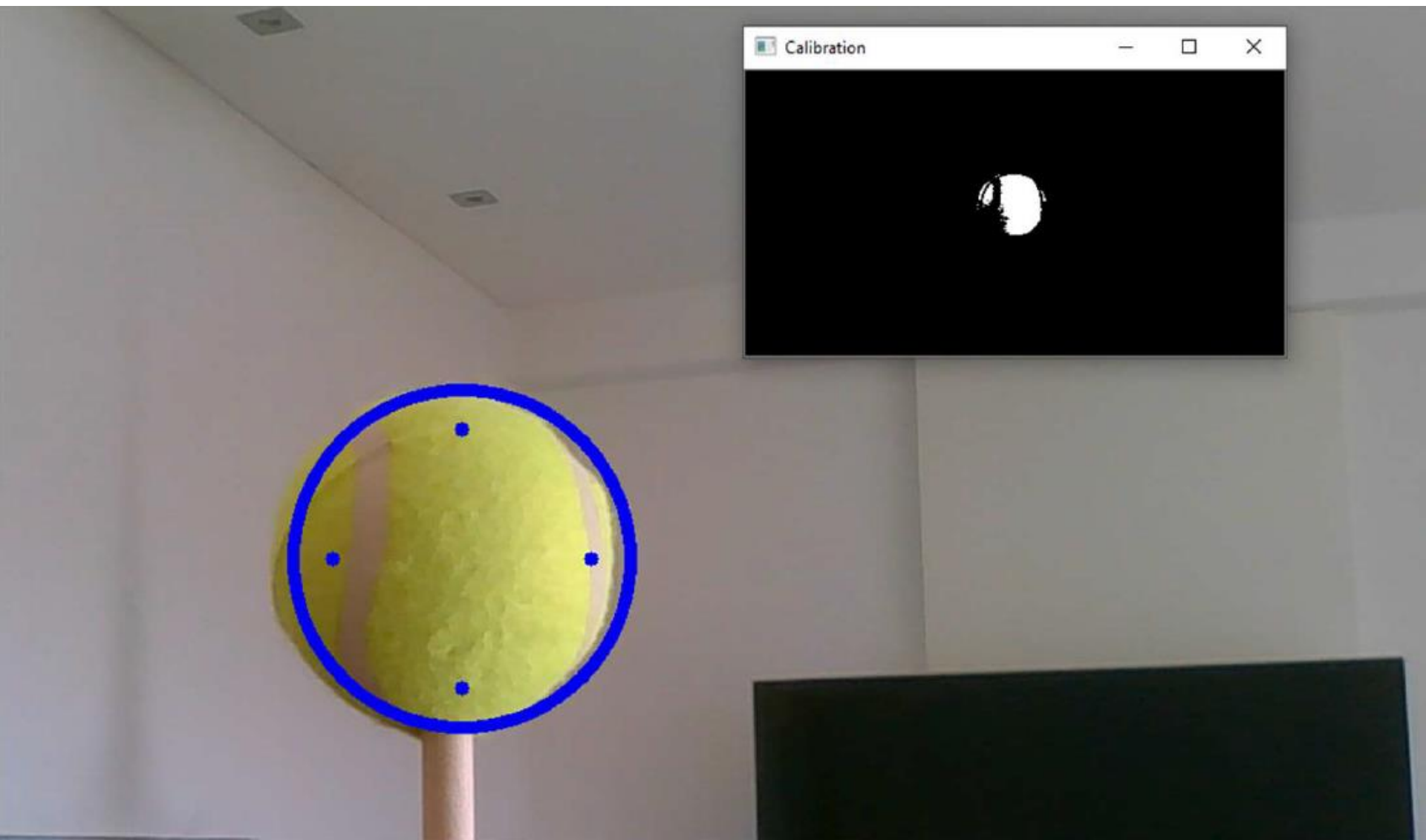
<https://www.youtube.com/watch?v=csuS2ibPVtU>

U.PORTO

VC 23/24 - Course Projects



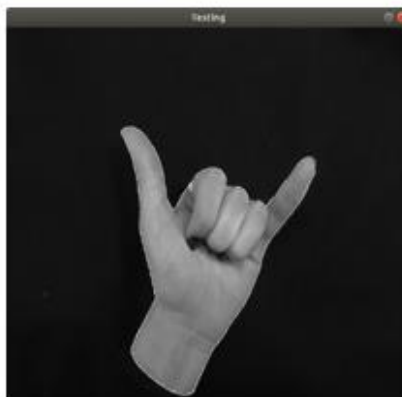
# Bubble Game



## Imagens de teste

## Segmentação da imagem

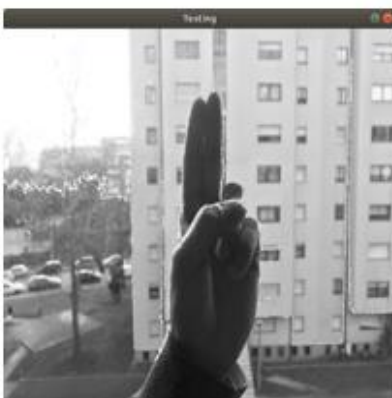
## Resultado/Tradução



# Gesture Recognition



Corresponde -> Y



Várias traduções se assemelham,  
nomeadamente:

|-> Y

|-> O

|-> U

|-> 5

|-> 5

|-> 4

|-> 3

|-> 2



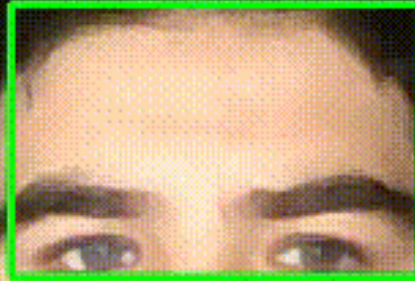
Corresponde -> O



# Heartbeat Quantification



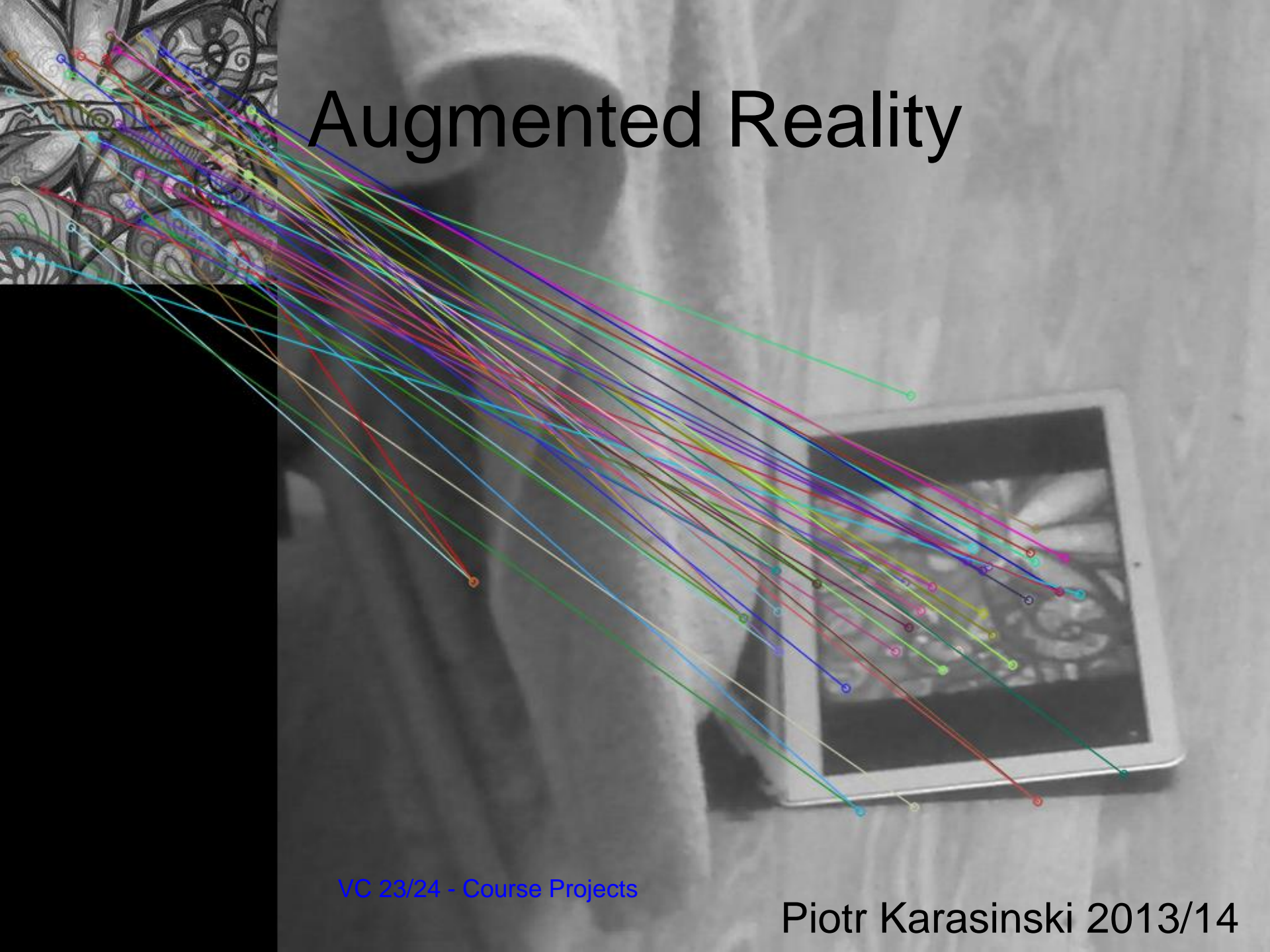
BPM: 72



(x=331, y=407) ~ R:207 G:197 B:202



# Augmented Reality



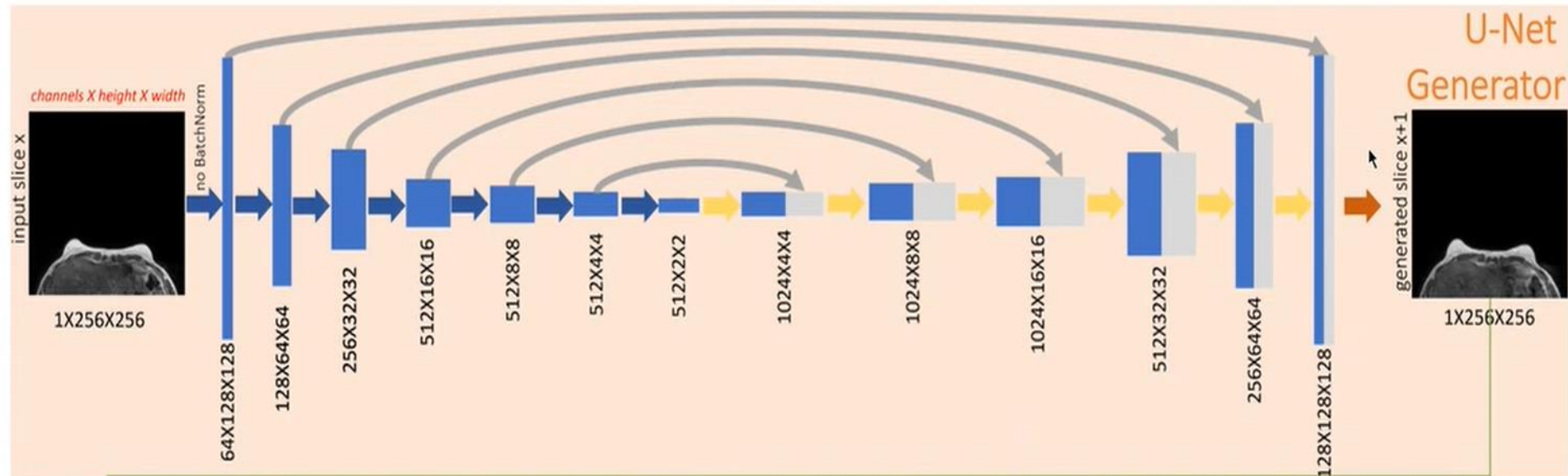




# Self-Driving System

# MODEL – pix2pix

## Generating MRI slices using GANs



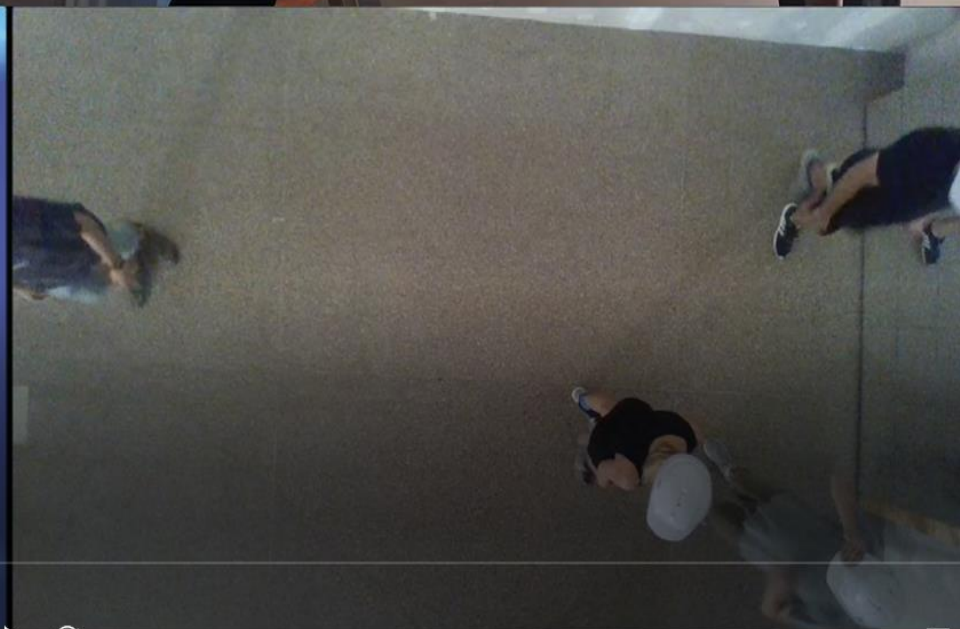
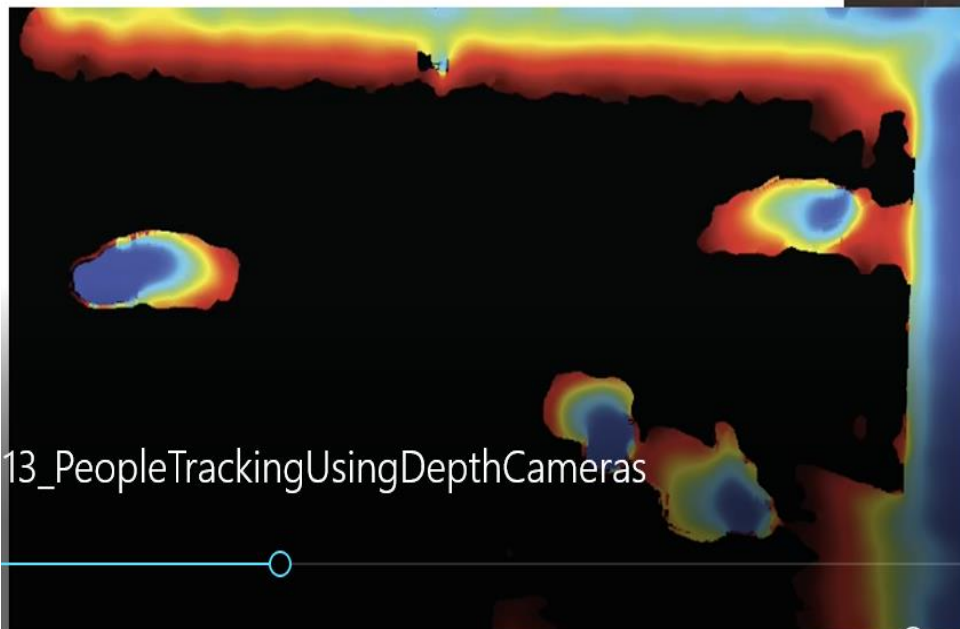
### Legend

- Conv2D 4X4, stride=2, padding=1, BatchNorm2D, LeakyReLU
- ConvTranspose2D 4X4, stride=2, padding=1, BatchNorm2D, ReLU
- ConvTranspose2D 4X4, stride=2, padding=1, Tanh
- Conv2D 3X3, stride=1, padding=1
- Concatenation along channels



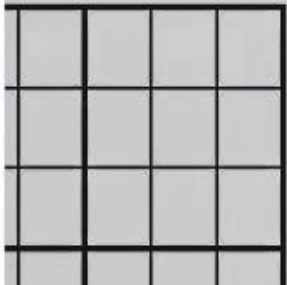
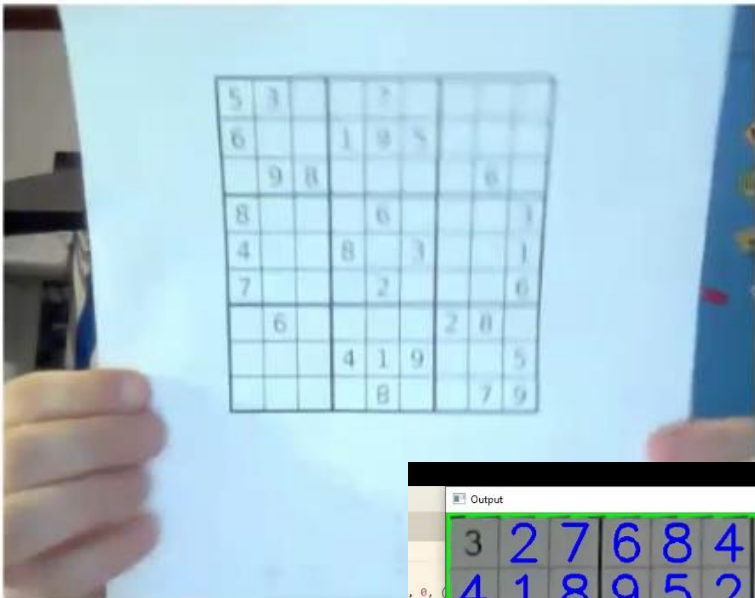
# People tracking using depth cameras

- **6 depth cameras** placed on the ceiling in a matrix
- **already collected** a dataset ~60 GB of recordings



# Sudoku Vision

## Webcam



### Control Panel

Please turn on camera and show a sudoku board to play.

Difficulty:

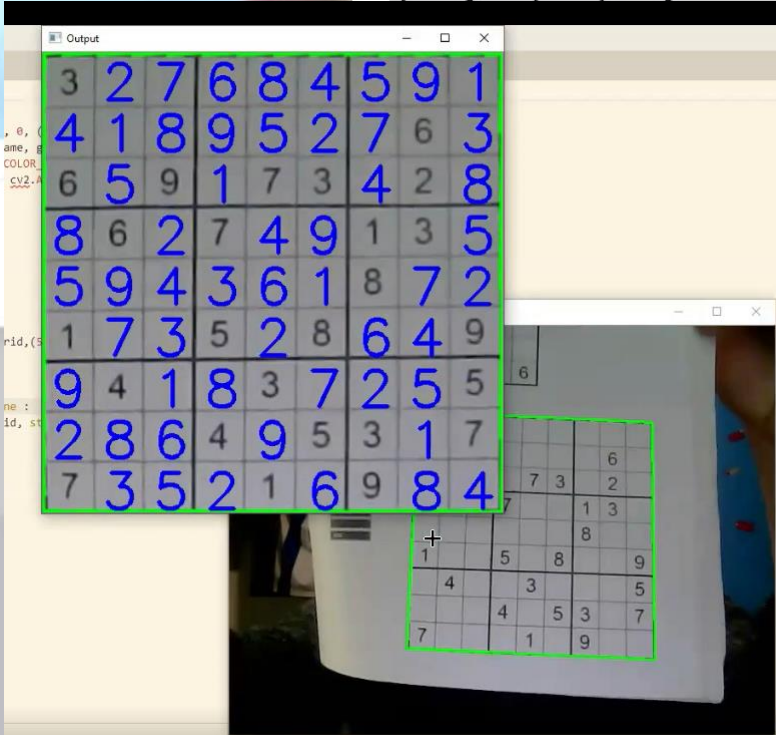
☐ Evaluate your resolution  
Activate to check your resolution as you answer the sudoku.

Erase

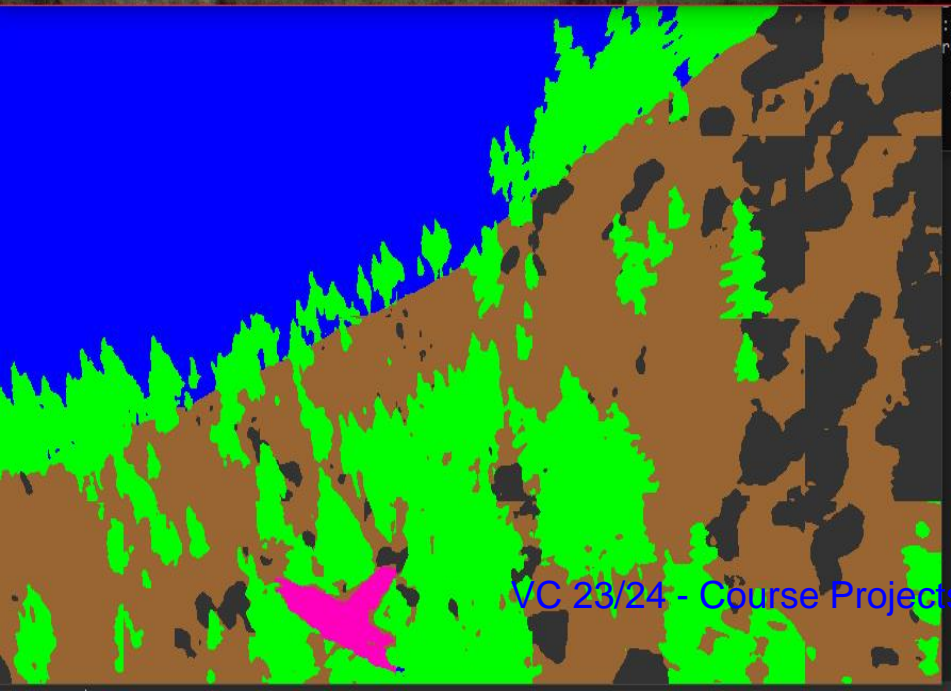
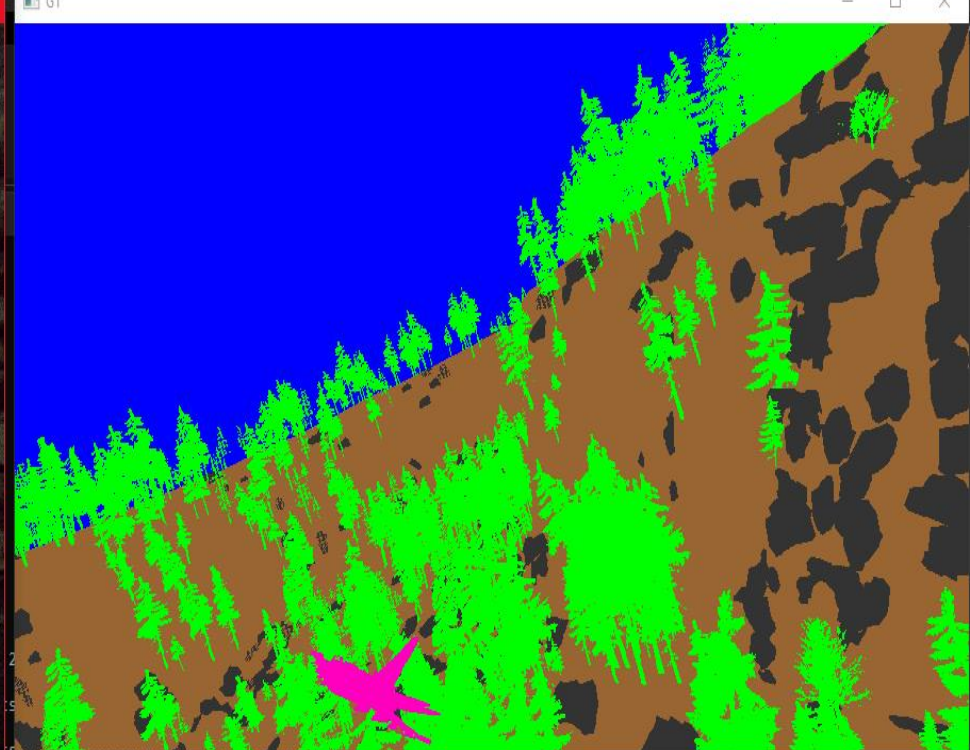
Solve

Next Step

**i** If you want a new sudoku just press the camera button in the header and show a new one to it.



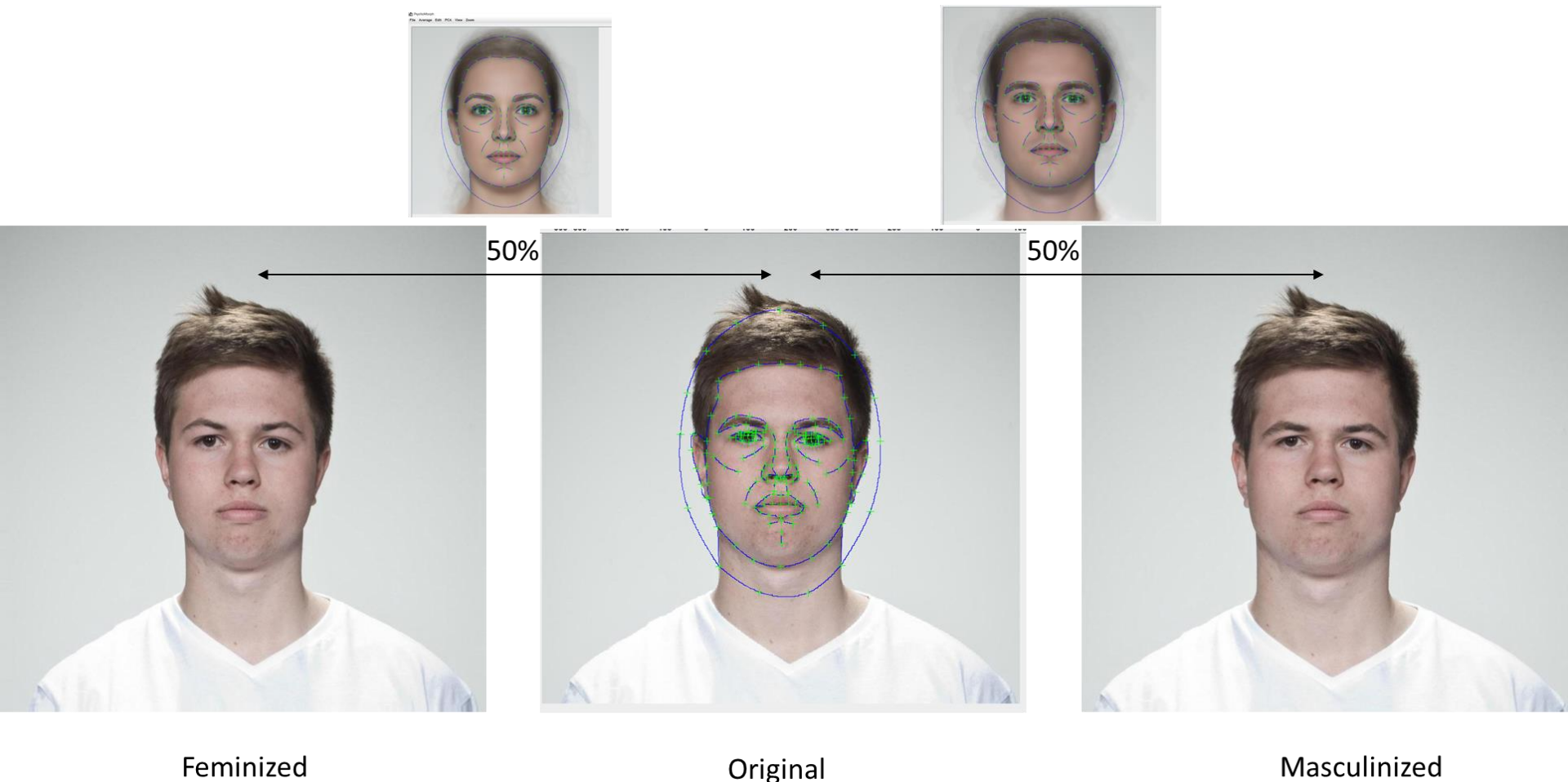




[193] This TensorFlow binary is optimized with instructions in performance-critical operations: compiler flags.

# Jet Fighter Detector

# Attractiveness: What can we learn from algorithms?





# Object Detection in Autonomous Driving

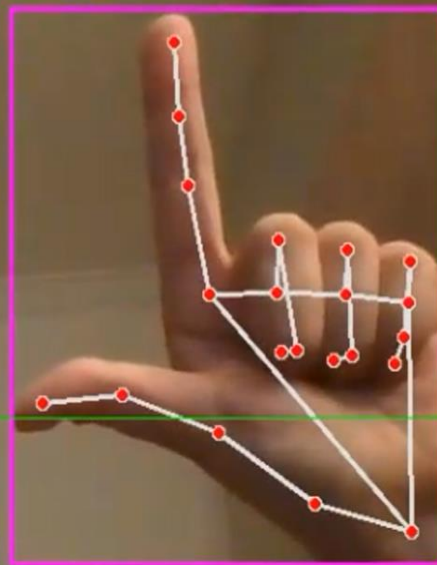


# Hand Arithmetic

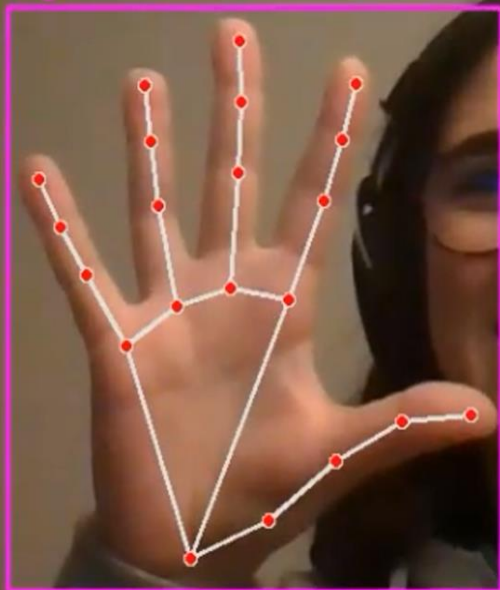
3

FPS: 10

Left



Right

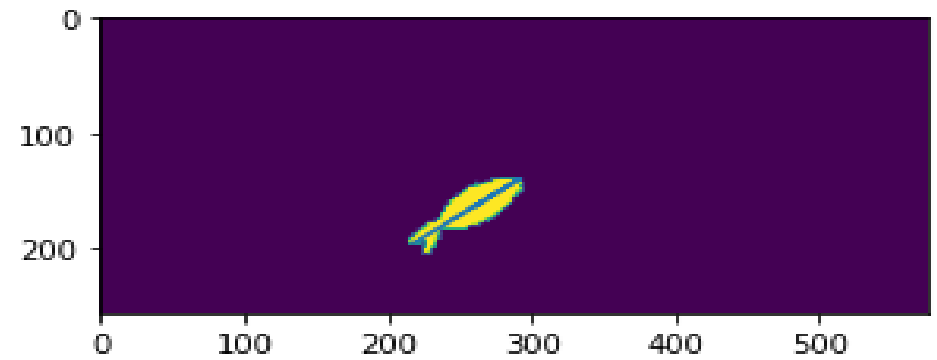
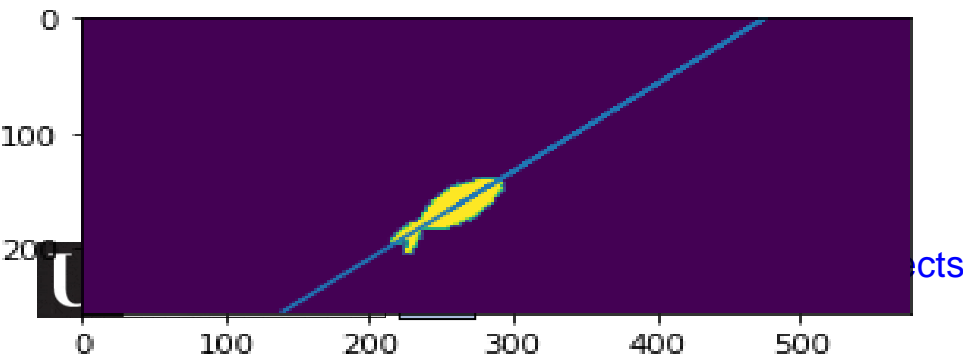
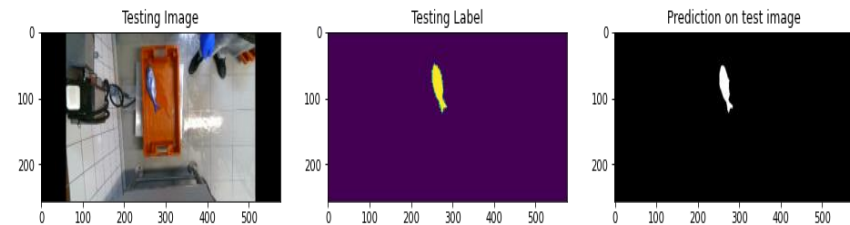
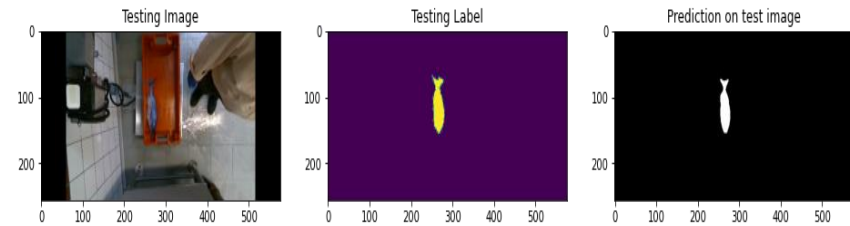
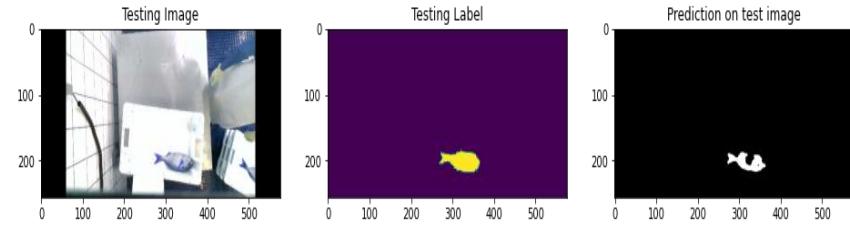
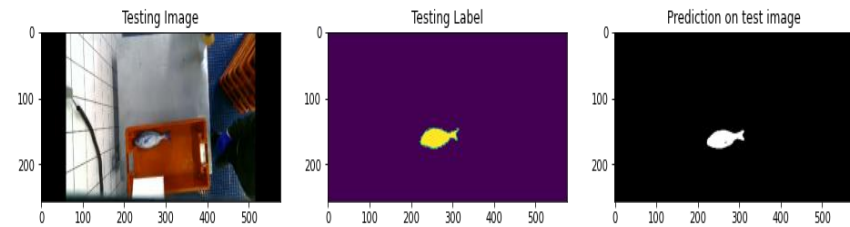


True



# Measuring Fish Size

Brenda Nogueira, 22/23



What are you going to do?