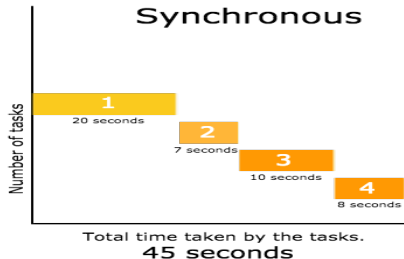


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Apr 17th, 2024



Recalling Topics on Parallel Programming

- ➊ Introduction
- ➋ Parallel Programming Models
- ➌ Parallel Architectures
- ➍ Synchronization
- ➎ Message Passing
- ➏ Parallel Constructs and Techniques
- ➐ Languages and runtime systems for parallel programming
- ➑ Performance Issues

Introduction

- Why Parallelism?
- Dimensions of parallel programming
- Design and Verification of Parallel programs

Why parallelism?

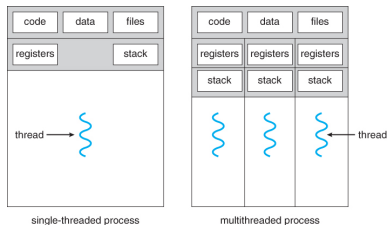
- Physical limits of sequential processor speed
- Natural parallelism in some applications
- System software
- Intrinsic interest

Dimensions of Parallelism

- Processes and threads
- Programming Models
- Concurrent \times parallel \times distributed
- Parallel and distributed systems
- Parallel architectures
- Languages and runtime
- Performance metrics

Processes and Threads

- Process → workspace
- Thread → same workspace as parent process
- Process (logical) != processor (physical hardware)
- Process is an abstraction of a processor
- Von Neumann model → one control flow
- concurrent program → 1+ flow



https://www.cs.uic.edu/~jbell/CourseNotes/OperatingSystems/4_Threads.html

Processes and Threads

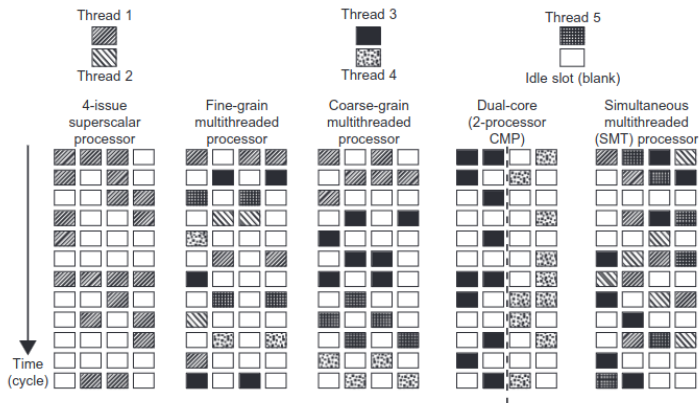


FIGURE 1.6

Five micro-architectures in modern CPU processors, that exploit ILP and TLP supported by multicore and multithreading technologies.

<https://cutepooji.files.wordpress.com/2017/01/>

Programming Models

- Define interface used by the programmer
- Parallelism, communication, synchronization etc
- Examples: sequential, shared/centralized memory, message passing

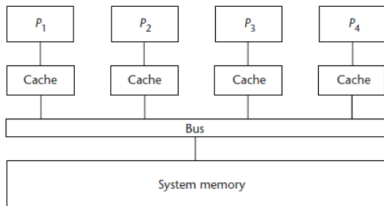
Concurrent x Parallel x Distributed

- Concurrent: 1+ control flow
- Parallel: concurrent with shared memory
- Distributed: concurrent with message passing

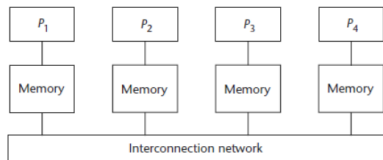
Parallel and Distributed Systems

- Parallel: hardware with just one memory space
- Distributed: multiple memories
- It is possible to run distributed programs in parallel systems and vice-versa

Shared memory

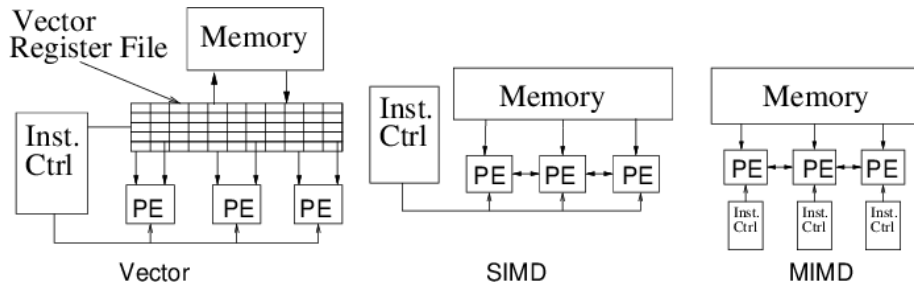


Distributed memory



Parallel Architectures

Most common: **SIMD** and **MIMD**



https://www.researchgate.net/publication/4049051_Universal_mechanisms_for_data-parallel_architectures/

figures?lo=1

- Languages: special syntax, side effects and implicit context, type verification, threads, exception handling etc
- Compilers: makes the programming model simpler
- Library: easy to modify, use with existing languages, use with several languages

Amdahl's Law:

- Speedup $s = \frac{T(1)}{T(p)}$
- Total work $c = T_s + T_p = T(1)$
- $T(p) = T_s + \frac{T_p}{p}$
- $s = \frac{(T_s + T_p)}{(T_s + \frac{T_p}{p})} = \frac{c}{(T_s + \frac{T_p}{p})} \rightarrow \frac{c}{T_s} \text{ when } p \rightarrow \inf$

Design and Verification of parallel programs

- Important: guarantee liveness and safety
 - **Liveness**: good things eventually happen
 - **Safety**: bad things never happen!
- Examples of liveness: no process waits forever, the program terminates
- Examples of safety: mutual exclusion, no buffer overflow

Most common parallel programming models

- Sequential
- Shared memory
- Message passing
- SPMD vs. MPMD or data parallelism vs. task parallelism

Other programming models

- Linda
- Actors
- Dataflow
- Logic
- Functional
- Constraints

Sequential programming model

- The simplest of all...
- Parallelism implemented by the compiler or by the system

```
for i = 1 to N  
  a[i] = 1
```

- e.g.: HPF and other Fortran versions (compiler); some declarative languages (runtime)

Shared memory model

- More complex, but close to sequential
- Parallelism implemented by the programmer with constructs and calls to functions provided by a language or by the system software
- Synchronization is needed
- Transparent communication (implemented in sw or hw)
- e.g: C#, Java (language), OpenMP (runtime, library), PFS (file system, OS)

Shared memory model

```
doall i = 1 to N
    a[i] = 1

for j = 1 to NPROCS-1
    fork(compute,j)
compute(0)

lock(mutex)
    x = x + 1
unlock(mutex)
```