

Homework-III

Chapter 3 Problems

3.3 3.13 3.14 3.18 3.26 3.43

Matlab Simulation

3.46, 3.49, 3.51, 3.53

3.3 Find the Laplace $X(s)$ given that $x(t)$ is

- (a) $2tu(t-4)$
- (b) $5\cos t \delta(t-2)$
- (c) $e^{-t}u(t-\tau)$
- (d) $\sin 2t u(t-\tau)$

$$(a) \quad 2t \cdot u(t-4)$$

$$\mathcal{L}\{2t \cdot u(t-4)\}$$

$$= \int_0^{\infty} 2t \cdot u(t-4) e^{-st} dt$$

$$= \int_4^{\infty} 2t e^{-st} dt$$

$$\frac{1}{s} \frac{d}{ds} u = 2t, \quad du = 2dt$$

$$\frac{1}{s} \frac{d}{ds} v = e^{-st} dt, \quad v = \frac{1}{-s} e^{-st}$$

$$= uv \Big|_4^{\infty} - \int_4^{\infty} v du$$

$$= 2t \frac{1}{-s} e^{-st} \Big|_4^{\infty} + \frac{2}{s} \int_4^{\infty} e^{-st} dt$$

$$= 0 - \frac{8}{s} e^{-4s} + \frac{2}{s} \left(\frac{1}{-s} e^{-st} \Big|_4^{\infty} \right)$$

$$= \frac{8}{s} e^{-4s} + \left(\frac{2}{s} \left(0 - \frac{1}{s} e^{-4s} \right) \right)$$

$$= \frac{8}{s} e^{-4s} + \frac{2}{s^2} e^{-4s}$$

$$= e^{-4s} \left(\frac{8}{s} + \frac{2}{s^2} \right)$$

$$(b) \quad 5 \cos t \delta(t-2)$$

$$\mathcal{L}\{f(t)\}$$

$$= \int_0^{\infty} \cos t \delta(t-2) e^{-st} dt$$

$$= \underline{5 \cos 2 e^{-2s}}$$

$$(d) \quad \sin 2t \cdot u(t-\tau)$$

$$= \sin(2(t-\tau)) u(t-\tau)$$

$$= \sin(2(t-\tau) + 2\tau) u(t-\tau)$$

$$= (\sin 2(t-\tau) \cos 2\tau + \cos 2(t-\tau) \sin 2\tau) u(t-\tau)$$

$$\mathcal{L}\{f(t)\}$$

$$= \mathcal{L}\{\sin 2(t-\tau) \cos 2\tau\} + \mathcal{L}\{\cos 2(t-\tau) \sin 2\tau\}$$

$$= e^{-s\tau} \frac{2}{s^2 + 2^2} \cos 2\tau + e^{-s\tau} \frac{s}{s^2 + 2^2} \sin 2\tau$$

$$= \underline{\frac{e^{-s\tau}}{s^2 + 4} (2 \cos 2\tau + s \sin 2\tau)}$$

$$(c) \quad e^{-t} u(t-\tau)$$

$$\int_0^{\infty} e^{-t} u(t-\tau) e^{-st} dt$$

$$= \int_0^{\infty} e^{-(1+s)t} u(t-\tau) dt$$

$$= \frac{1}{-(1+s)} e^{-(1+s)t} \Big|_{\tau}^{\infty}$$

$$= \underline{\frac{1}{s+1} e^{-(1+s)\tau}}$$

Find the inverse Laplace transform for

$$(a) \quad X(s) = \frac{3s+1}{s^2+2s+5}$$

$$(b) \quad Y(s) = \frac{3s+7}{s^2+3s+2}$$

$$(c) \quad Z(s) = \frac{s^2-8}{s^2-4}$$

$$(d) \quad H(s) = \frac{12}{(s+2)^2}$$

(a)

$$\mathcal{L}^{-1}\left\{\frac{3s+1}{s^2+2s+5}\right\} = \mathcal{L}^{-1}\left\{\frac{3(s+1)-2}{(s+1)^2+2^2}\right\}$$

$$= \mathcal{L}^{-1}\left\{3 \cdot \frac{s+1}{(s+1)^2+2^2} - \frac{2}{(s+1)^2+2^2}\right\}$$

$$= \underline{3e^{-t}\cos 2t - e^{-t}\sin 2t}$$

$$(b) \quad \frac{3s+7}{s^2+3s+2} = \frac{3s+7}{(s+2)(s+1)} = \frac{-1}{s+2} + \frac{4}{s+1}$$

$$\mathcal{L}^{-1}\{Y(s)\} = (-1)\mathcal{L}^{-1}\left\{\frac{1}{s+2}\right\} + 4\mathcal{L}^{-1}\left\{\frac{1}{s+1}\right\}$$

$$= \underline{-e^{-2t} + 4e^{-t}}$$

$$(c) \quad \frac{s^2-8}{s^2-4} = \frac{s^2-8}{(s+2)(s-2)} = \frac{\frac{3}{2}s+4}{(s+2)} + \frac{-\frac{1}{2}s}{(s-2)}$$

$$= \frac{3}{2} \cdot \frac{s}{s+2} + 4 \frac{1}{s+2} - \frac{1}{2} \frac{s}{s-2}$$

$$\mathcal{L}^{-1}\{Z(s)\} = \frac{3}{2}(\delta(t) - 2e^{-2t}) + 4e^{-2t} - \frac{1}{2}(\delta(t) + 2e^{2t})$$

$$= \underline{\delta(t) + e^{-2t} - e^{2t}}$$

$$(d) \quad \mathcal{L}^{-1}\left\{\frac{12}{(s+2)^2}\right\}$$

$$= 12 \mathcal{L}^{-1}\left\{\frac{1}{(s+2)^2}\right\}$$

$$= 12 \cdot e^{-2t} \mathcal{L}^{-1}\left\{\frac{1}{s^2}\right\}$$

$$= \underline{12 e^{-2t} \cdot t}$$

3.14 Find the inverse Laplace transform of the following functions:

(a) $F(s) = \frac{20(s+2)}{s(s^2+6s+25)}$

(b) $P(s) = \frac{6s^2+36s+20}{(s+1)(s+2)(s+3)}$

$$\begin{aligned}
 (a) \quad \frac{20s+40}{s(s^2+6s+25)} &= \frac{\frac{8}{5}}{s} + \frac{-\frac{8}{5}s + \frac{52}{5}}{s^2+6s+25} \\
 &= \frac{8}{5} \cdot \frac{1}{s} + \frac{-\frac{8}{5}(s+3) + \frac{96}{5}}{(s+3)^2+4^2} \\
 &= \frac{8}{5} \cdot \frac{1}{s} + \frac{-8}{5} \frac{s+3}{(s+3)^2+4^2} + \frac{19}{5} \frac{4}{(s+3)^2+4^2}
 \end{aligned}$$

$$\therefore \mathcal{L}^{-1}\{F(s)\} = \frac{8}{5} u(t) - \frac{8}{5} e^{-3t} \cos 4t + \frac{19}{5} e^{-3t} \sin 4t$$

$$\begin{aligned}
 (b) \quad \frac{6s^2+36s+20}{(s+1)(s+2)(s+3)} &= \frac{a}{s+1} + \frac{b}{s+2} + \frac{c}{s+3} \\
 &= \frac{-5}{s+1} + \frac{28}{s+2} + \frac{-17}{s+3}
 \end{aligned}$$

$$\begin{aligned}
 \mathcal{L}^{-1}\{P(s)\} &= -5 \mathcal{L}^{-1}\left\{\frac{1}{s+1}\right\} + 28 \mathcal{L}^{-1}\left\{\frac{1}{s+2}\right\} - 17 \mathcal{L}^{-1}\left\{\frac{1}{s+3}\right\} \\
 &= \underline{-5e^{-t} + 28e^{-2t} - 17e^{-3t}}
 \end{aligned}$$

$$\begin{aligned}
 a(s+2)(s+3) + b(s+1)(s+3) + c(s+1)(s+2) \\
 &= (a+b+c)s^2 + (5a+4b+3c)s + (6a+3b+2c) \\
 \Rightarrow \begin{cases} a+b+c=6 \\ 5a+4b+3c=36 \\ 6a+3b+2c=20 \end{cases} &\Rightarrow \begin{cases} a = 6-11 = -5 \\ b = 28 \\ c = 11-28 = -17 \end{cases}
 \end{aligned}$$

3.18 Let $F(s) = \frac{5(s+1)}{(s+2)(s+3)}$

- (a) Use the initial and final value theorems to find $f(0)$ and $f(\infty)$.
 (b) Verify your answer in part (a) by finding $f(t)$ using partial fractions.

(a) $f(0) = \lim_{s \rightarrow \infty} sF(s) = \lim_{s \rightarrow \infty} \frac{5s^2 + 5s}{s^2 + 5s + 6} = 5$

$f(\infty) = \lim_{s \rightarrow 0} sF(s) = 0$

(b) $F(s) = \frac{5(s+1)}{(s+2)(s+3)} = \frac{-5}{s+2} + \frac{10}{s+3}$

$\Rightarrow f(t) = -5e^{-2t} + 10e^{-3t}$

$\therefore f(0) = -5 + 10 = 5, f(\infty) = 0 + 0 = 0$

3.26 For each of the systems shown in Figure 3.28, use Laplace transform to find $y(t)$.

(a) $\mathcal{L}\{e^{-2t}u(t)\} = \frac{1}{s+2}$

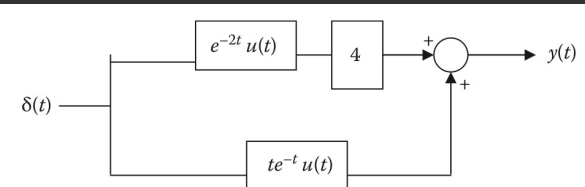
$\mathcal{L}\{4\} = 4 \cdot \frac{1}{s}$

$\mathcal{L}\{te^{-t}u(t)\} = \frac{1}{(s+1)^2}$

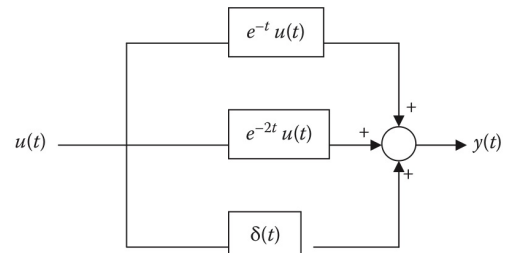
$\therefore H(s) = \frac{1}{s+2} \cdot \frac{4}{s} + \frac{1}{(s+1)^2}$
 $= \frac{4}{s(s+2)} + \frac{1}{(s+1)^2}$
 $= \frac{2}{s} + \frac{-2}{s+2} + \frac{1}{(s+1)^2}$

$Y(s) = X(s)H(s) = H(s)$

$\Rightarrow \underline{y(t) = 2u(t) - 2e^{-2t} + te^{-t}}$



(a)



(b)

FIGURE 3.28 For Problem 3.26.

(b)

$Y(s) = X(s)H(s)$

$= \frac{1}{s} \frac{1}{s+1} + \frac{1}{s} \frac{1}{s+2} + \frac{1}{s}$

$= \frac{1}{s} + \frac{-1}{s+1} + \frac{\frac{1}{2}}{s} + \frac{-\frac{1}{2}}{s+2} + \frac{1}{s}$

$\therefore \underline{y(t) = \frac{5}{2}u(t) - e^{-t} - \frac{1}{2}e^{-2t}}$

3.43 An LTI system is described by

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + 2y(t) = \frac{dx(t)}{dt} - 3x(t)$$

- (a) Determine the transfer function of the system.
(b) Obtain the impulse response of the system.

(a)

$$\mathcal{L}\{\text{LHS}\} = \mathcal{L}\{\text{RHS}\}$$

$$\Rightarrow s^2 Y(s) + 2sY(s) + 2Y(s) = sX(s) - 3X(s)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{s-3}{s^2+2s+2}$$

(b)

$$H(s) = \frac{s-3}{s^2+2s+2}$$

$$= \frac{s+1-4}{(s+1)^2 + 1^2}$$

$$= \frac{s+1}{(s+1)^2 + 1^2} - 4 \frac{1}{(s+1)^2 + 1^2}$$

$$= e^{-t} \cos t - 4e^{-t} \sin t$$

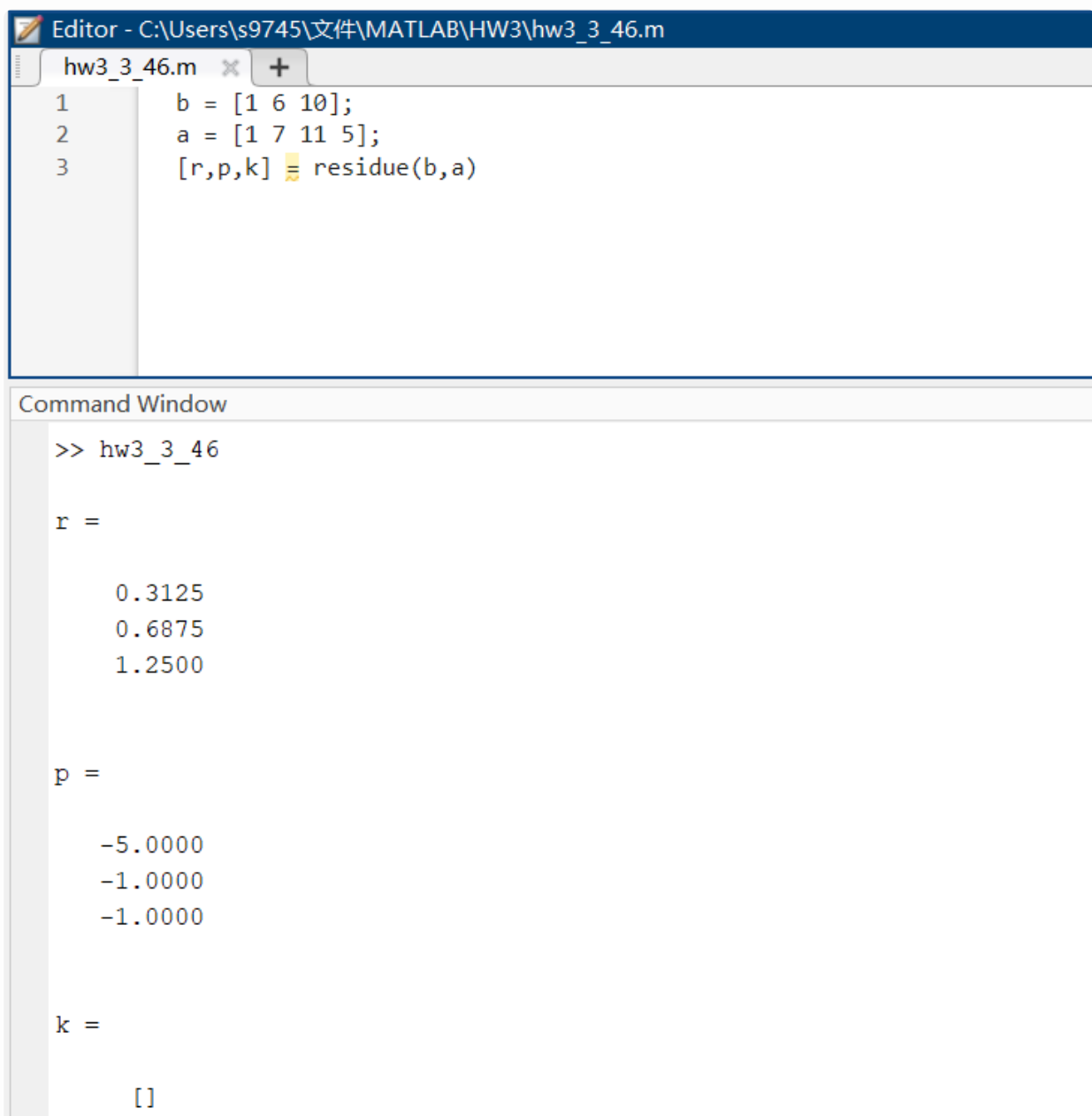
3.46

由附圖程式我們得到

$$H(s) = \frac{0.3125}{s+5} + \frac{0.6875}{s+1} + \frac{1.2500}{(s+1)^2}$$

因此

$$h(t) = 0.3125e^{-5t} + 0.6875e^{-t} + 1.2500te^{-t}$$



The image shows a MATLAB Editor window with a script named `hw3_3_46.m` and a Command Window below it. The script defines the numerator `b` and denominator `a` coefficients and uses the `residue` function to find the partial fraction decomposition. The Command Window displays the results for `r`, `p`, and `k`.

```
Editor - C:\Users\s9745\文件\MATLAB\HW3\hw3_3_46.m
hw3_3_46.m x +
1      b = [1 6 10];
2      a = [1 7 11 5];
3      [r,p,k] = residue(b,a)

Command Window
>> hw3_3_46

r =

    0.3125
    0.6875
    1.2500

p =

   -5.0000
   -1.0000
   -1.0000

k =

     []
```

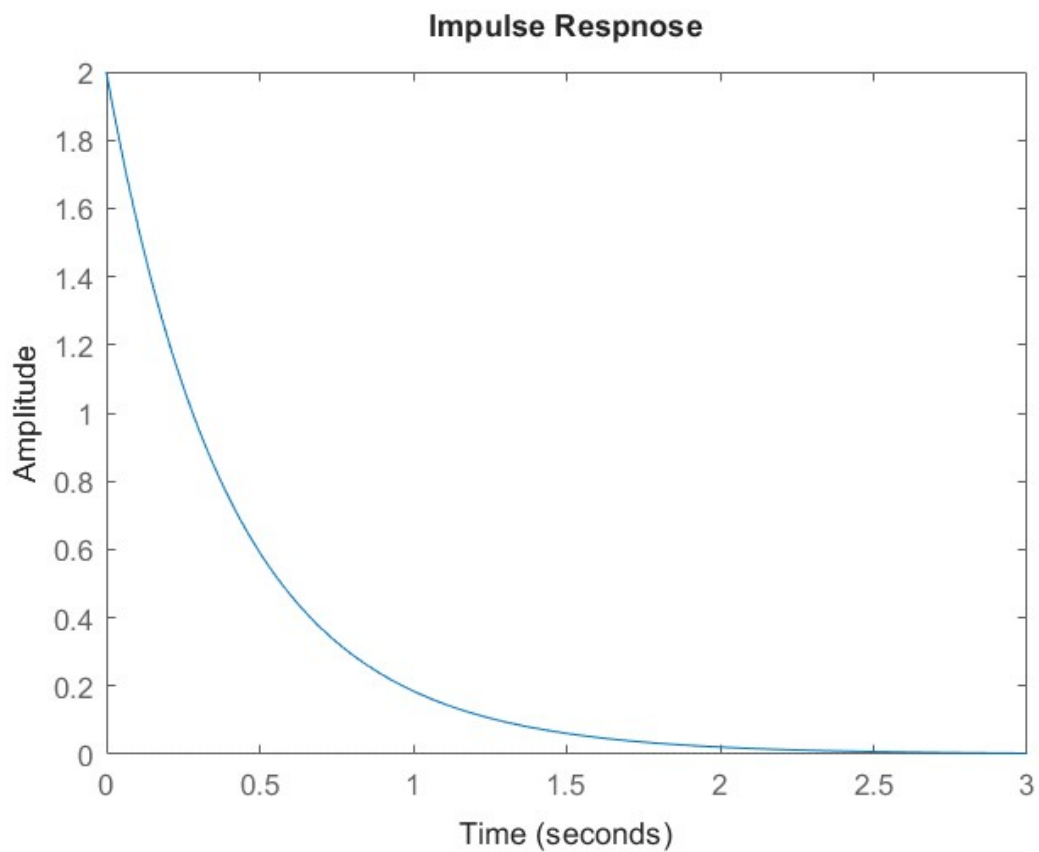
```
1 b = [1 6 10]; %分子
2 a = [1 7 11 5]; %分母
3 [r,p,k] = residue(b,a)
```

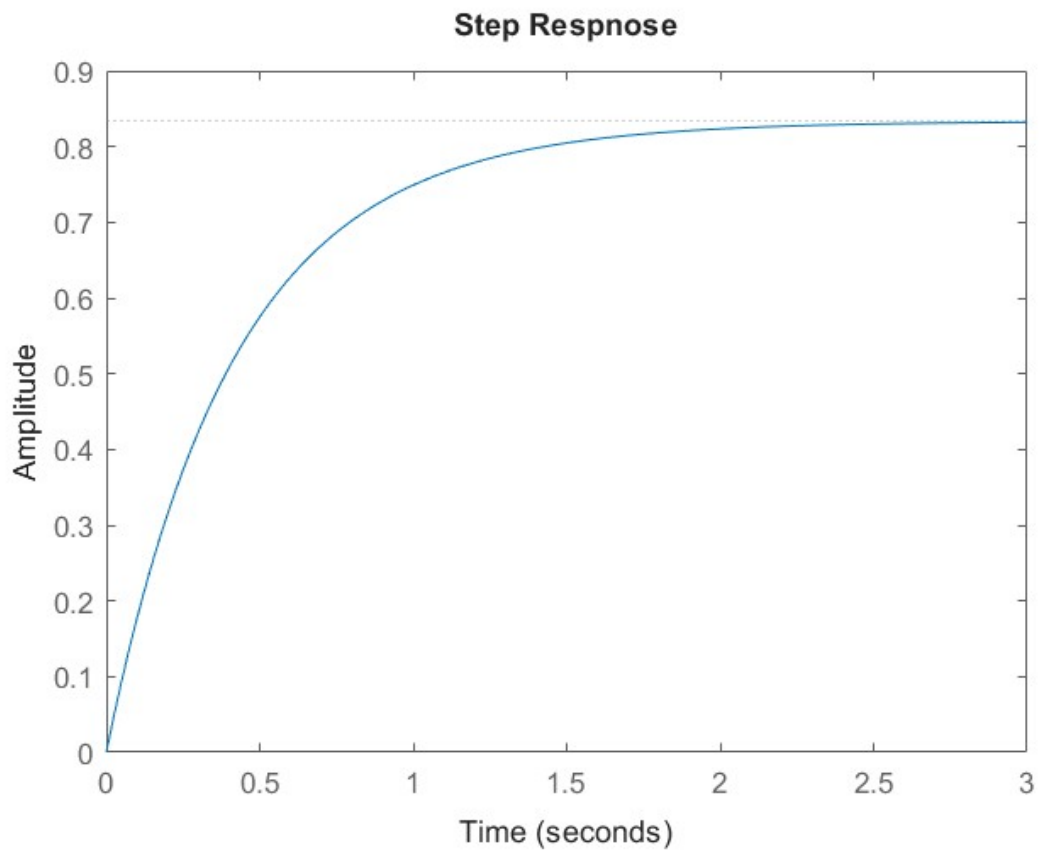
3.49

對於transfer function

$$H(s) = \frac{2s + 5}{(s + 2)(s + 3)} = \frac{2s + 5}{s^2 + 5s + 6}$$

利用以下MATLAB程式得到impulse response以及step response：





```

1 num = [2 5]; %分子係數
2 den = [1 5 6]; %分母係數
3
4 H = tf(num, den); % Transfer function
5
6 figure;
7 impulse(H);
8 title('Impulse Respnose')
9
10 figure;
11 step(H);
12 title('Step Respnose')

```

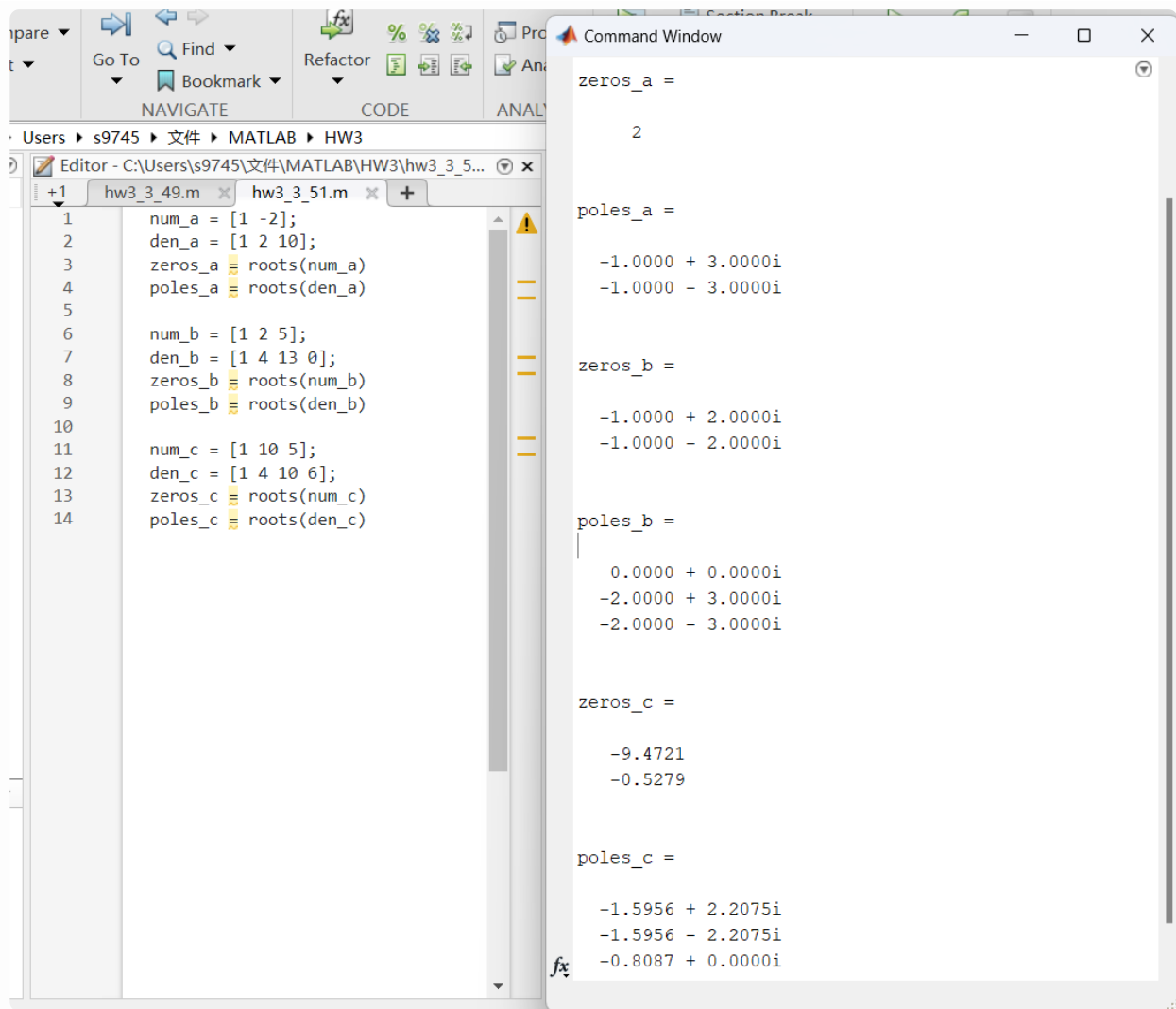
3.51

我們利用roots()來得到各自的zeros和poles，發現：

$$zeros_a = 2, poles_a = -1 \pm 3i$$

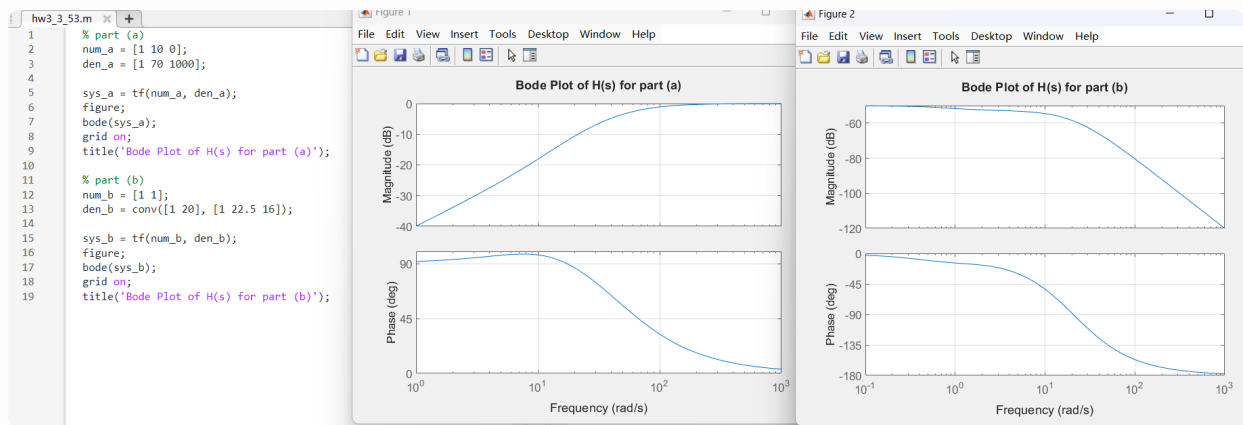
$$zeros_b = -1 \pm 2i, poles_b = -2 \pm 3i, 0$$

$$zeros_c = -9.4721, -0.5279, poles_c = -1.5956 \pm 2.2075i, -0.8087$$



```
1 num_a = [1 -2];  
2 den_a = [1 2 10];  
3 zeros_a = roots(num_a)  
4 poles_a = roots(den_a)  
5  
6 num_b = [1 2 5];  
7 den_b = [1 4 13 0];  
8 zeros_b = roots(num_b)  
9 poles_b = roots(den_b)  
10  
11 num_c = [1 10 5];  
12 den_c = [1 4 10 6];  
13 zeros_c = roots(num_c)  
14 poles_c = roots(den_c)
```

3.53



```
1 num_a = [1 10 0];
2 den_a = [1 70 1000];
3 sys_a = tf(num_a, den_a);
4 figure;
5 bode(sys_a);
6 grid on;
7 title('Bode Plot of H(s) for part (a)');
8
9
10 num_b = [1 1];
11 den_b = conv([1 20], [1 22.5 16]);
12 sys_b = tf(num_b, den_b);
13 figure;
14 bode(sys_b);
15 grid on;
16 title('Bode Plot of H(s) for part (b)');
```