FAA-Based Queues and Flat Combining

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FAA-Based Queues

Fetch-And-Add

 FAA(address, delta) - атомарно увеличивает значение на delta и возвращает старое значение

- FAA гораздо лучше масштабируется, чем CAS-loop
 - ведь всегда успешен!

Modern queues use Fetch-And-Add

Fast Concurrent Queues for x86 Processo PPOPP'13

Blavatnik School of Computer Science, Tel Aviv University

Conventional wisdom in designing concurrent data structures Convenuonal wisdom in designing concurrent data structures is to use the most powerful synchronization primitive, namely os ou use me most poweriui synchronization primitive, namely compare-and-awap (CAS), and to avoid contended hot spots. compare-and-awap (CAS), and to avoid contended not spots.

In building concurrent FIFO queues, this reasoning has led rein ounting concurrent FIFQ queues, rins reasoning has searchers to propose combining-based concurrent queues. earcners to propose comoning-based concurrent queues.
This paper takes a different approach, showing how to real-take. tus paper taxes a unierent approach, snowing now to rety one fetch-and-add (F&A), a less powerful primitive that is available on v&A arrosecure to construct a sample of the feet of the construction of the feet of the f on x86 processors, to construct a nonblocking (lock-free) linearization anie concurrent FIFO queue winen, uespie me rech oeing a con-tended hot spot, outperforms combining-based implementations by tenera not spot, outperforms combining based implementations by $1.5 \times 10.25 \times 10.000$ in all concurrency levels on an 1.5×10.000 in all concurrency levels on an 1.5×10.000 in the spot of t multicore processors, in both single-processor and multi-processor

Categories and Subject Descriptors

D.1.3 [Programming Techniques]: Concurrent Programming: E.1 [Data Structures]: Lists,

concurrent queue, nonblocking algorithm, fetch-and-

	SW
compare	_
and-Swar	depr
LUSC	der
yes	
Synchroniz dominant r	ation pri nulticore
	yes yes

that largely causes the poor i hot spot, not just the synchry Observing this distinction on most commercial multic universal primitives CAS (LL/SC). While in theory) in a wait-free manner [D] and in practice vendors d However, there is an inter ture, which dominates th ports various theoretical erty for our purpose is t Consider, for exam In shows the di

PPoPP'16

A Wait-free Queue as Fast as Fetch-and-Add

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Concurrent data structures that have fast and predictable performance are of critical importance for harnessing the power of multicore processors, which are now ubiquitous. Although wait-free objects, whose operations complete in a bounded number of steps, were devised more than two decades ago, wait-free objects that can deliver scalable high performance are still rare.

In this paper, we present the first wait-free FIFO queue based on fetch-and-add (FAA). While compare-and-swap (CAS) based non-blocking algorithms may perform poorly due to work wasted by CAS failures, algorithms that coordinate using FAA, which is guaranteed to succeed, can in principle perform better under high contention. Along with FAA, our queue uses a custom epoch-based scheme to reclaim memory; on x86 architectures, it requires no extra memory fences on our algorithm's typical execution path. An empirical study of our new FAA-based wait-free FIFO queue under high contention on four different architectures with many hardware threads shows that it outperforms prior queue designs that lack a wait-free progress guarantee. Surprisingly, at the highest level of contention, the throughput of our queue is often as high as that of a microbenchmark that only performs FAA. As a result, our fast waitfree queue implementation is useful in practice on most multi-core systems today. We believe that our design can serve as an example of how to construct other fast wait-free objects.

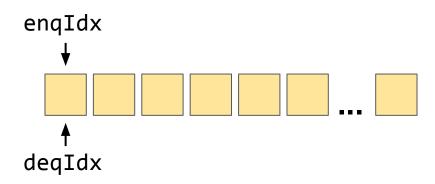
either blocking or non-blocking. Blocking data structures include at least one operation where a thread may need to wait for an operation by another thread to complete. Blocking operations can introduce a variety of subtle problems, including deadlock, livelock, and priority inversion; for that reason, non-blocking data structures

There are three levels of progress guarantees for non-blocking data structures. A concurrent object is:

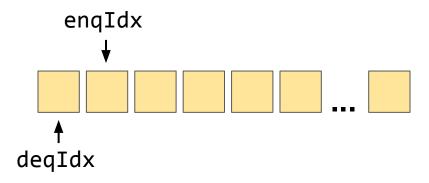
- obstruction-free if a thread can perform an arbitrary operation on the object in a finite number of steps when it executes in
- lock-free if some thread performing an arbitrary operation on the object will complete in a finite number of steps, or
- wait-free if every thread can perform an arbitrary operation on

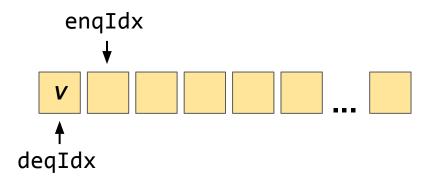
the object in a finite number of steps. Wait-freedom is the strongest progress guarantee; it rules out the possibility of starvation for all threads. Wait-free data structures are particularly desirable for mission critical applications that have real-time constraints, such as those used by cyber-physical systems.

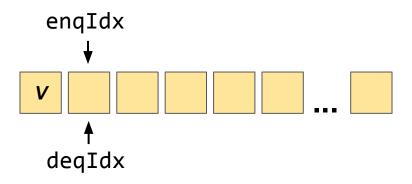
Although universal constructions for wait-free objects have existed for more than two decades [11], practical wait-free algorithms are hard to design and considered inefficient with good reason. For example, the fastest wait-free concurrent queue to date, designed by Fatourouto and Kallimanis [7], is orders of magnitude slower than the best performing lock-free queue, LCRQ, by Morrison and Afek [19]. General methods to transform lock-free objects into

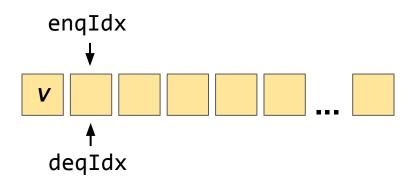


Бесконечный массив и указатели для enqueue и dequeue. Сначала увеличиваем индекс, потом пишем/читаем

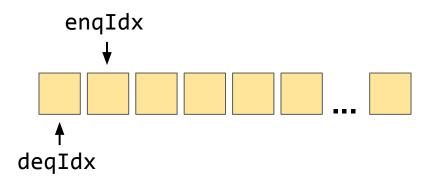


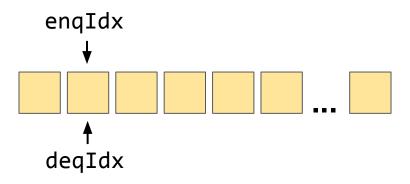


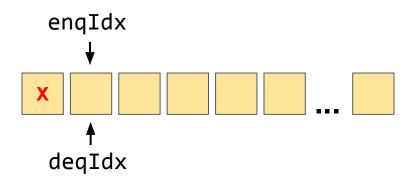




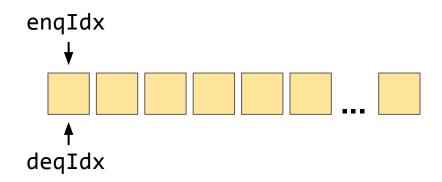
А если dequeu придёт читать раньше, чем произошла запись?







Пометим ячейку как "сломанную", обе операции начнутся заново

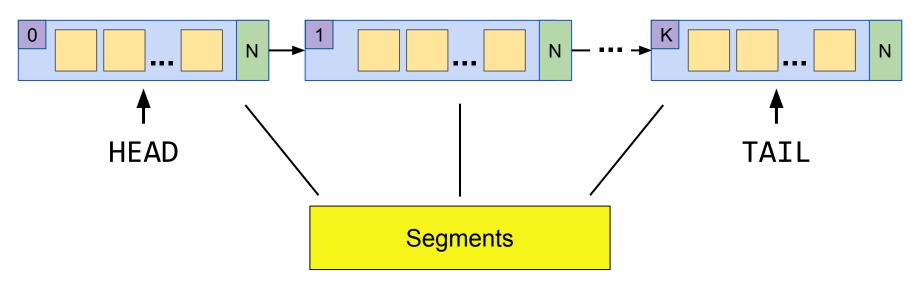


```
fun enqueue(x: T) = while (true) {
  val enqIdx = FAA(&enqIdx, 1)
  if (CAS(&data[enqIdx], null, x))
    return
}
```

```
enqIdx
                       deqIdx
                                         fun dequeue() = while (true) {
                                           if (isEmpty()) return null
                                           val deqIdx = FAA(&deqIdx, 1)
fun enqueue(x: T) = while (true) {
                                           val res = SWAP(&data[deqIdx], BROKEN)
 val engIdx = FAA(\&engIdx, 1)
  if (CAS(&data[engIdx], null, x))
                                           if (res == null) continue
    return
                                           return res
                                         fun isEmpty(): Boolean = deqIdx >= enqIdx
```

Lock-Free Queue on Infinite Array

Michael-Scott queue of segments



Lock-Free Queue on Infinite Array

```
fun enqueue(x: T) = while (true) {
  val tail = this.tail
  val enqIdx = FAA(&tail.enqIdx, 1)
  if (enqIdx >= NODE_SIZE) {
    // try to insert new node with "x"
  } else {
    if (CAS(&tail.data[enqIdx], null, x))
      return
  }
}
```

Lock-Free Queue on Infinite Array

```
fun enqueue(x: T) = while (true) {
  val tail = this.tail
  val enqIdx = FAA(&tail.enqIdx, 1)
  if (enqIdx >= NODE_SIZE) {
    // try to insert new node with "x"
  } else {
    if (CAS(&tail.data[enqIdx], null, x))
      return
  }
}
```

```
fun dequeue(): T = while (true) {
  val head = this.head
  val deqIdx = FAA(&head.deqIdx, 1)
  if (deqIdx >= NODE_SIZE) {
    val headNext = head.next ?: return null
    CAS(&this.head, head, headNext)
    continue
  }
  val res = SWAP(&head.data[deqIdx], BROKEN)
  if (res == null) continue
  return res
}
```

Flat Combining

Какие есть способы синхронизации?

- Грубая блокировка -- просто писать, не масштабируется
- Тонкая блокировка -- сложнее, но и потенциально быстрее
- Lock-free / wait-free -- зачастую лучше, может очень хорошо масштабироваться
 - А может и нет, см. Michael-Scott Queue или Treiber Stack

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Хотим писать такой же простой код, как с грубой блокировкой, но быть существенно быстрее

Даёшь Flat Combining!

Flat Combining and the Synchronization-Parallelism **Tradeoff**

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ABSTRACT

Traditional data structure designs, whether lock-based or lock-free, provide parallelism via fine grained synchroniza-

We introduce a new synchronization paradigm based on tion among threads. coarse locking, which we call flat combining. The cost of synchronization in flat combining is so low, that having a single thread holding a lock perform the combined access requests of all others, delivers, up to a certain non-negligible concurrency level, better performance than the most effective parallel finely synchronized implementations. We use flat-combining to devise, among other structures, new linearizable stack, queue, and priority queue algorithms that greatly outperform all prior algorithms.

Categories and Subject Descriptors

D.1.3 [Concurrent Programming]: Algorithms

applications, the parts of the computation that are difficult to parallelize are those involving inter-thread communication via shared data structures. The design of effective concurrent data structures is thus key to the scalability of

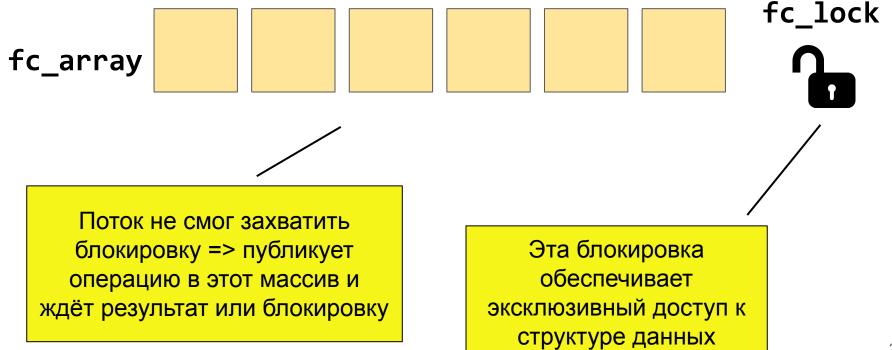
applications on multicore machines. But how does one devise effective concurrent data structures? The traditional approach to concurrent data structure design, whether lock-based or lock-free, is to provide parallelism via fine grained synchronization among threads (see for example the Java concurrency library in the Java 6.0 JDK). From the empirical literature, to date, we get a confirmation of this approach: letting threads add parallelism via hand crafted finely synchronized data structure design allows, even at reasonably low levels of concurrency, to overtake the performance of structures protected by a single global lock [4, 14, 10, 12, 7, 16].

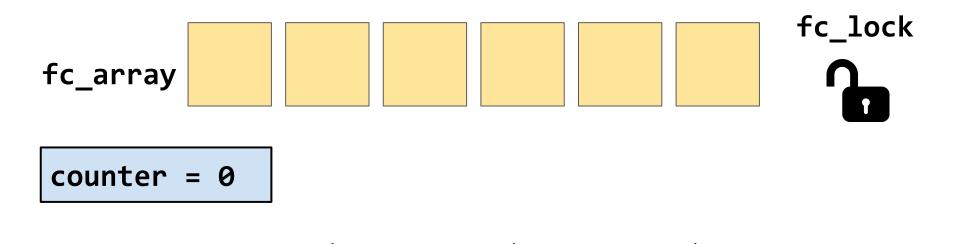
The premise of this paper is that the above assertion is wrong. That for a large class of data structures, the cutoff point (in terms of machine concurrency) at which finely synchronized concurrent implementations outperform ones in which access to the structure is controlled by a coarse ther out then we ever anticipated. The reason, as

Flat Combining -- Basic Ideas

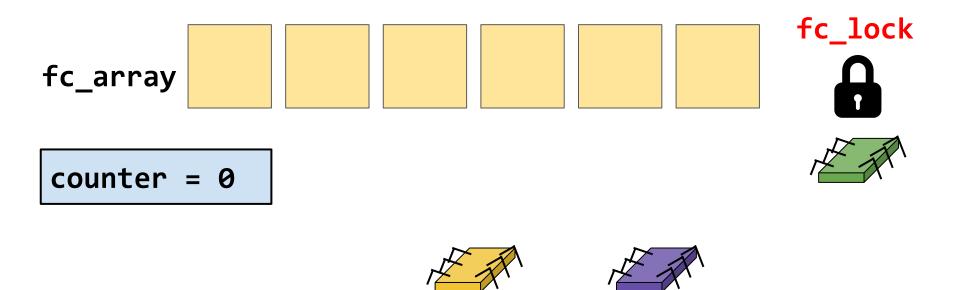
- Операции выполняются последовательно, структура данных защищена блокировкой
- 2. Поток, который держит блокировку -- комбайнер, он выполняет свою операцию и операции других потоков
- 3. Те, кто не смог взять блокировку, публикуют свои операции для комбайнера и дожидаются или результата этой операции, или блокировки (тогда этот поток становится комбайнером)



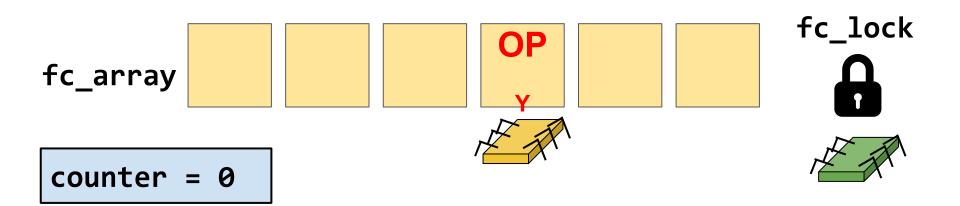




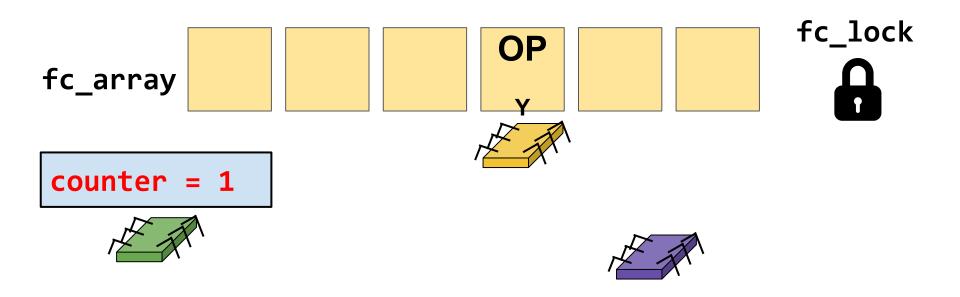
Будем делать счётчик. Три потока, никто ещё ничего не начал.



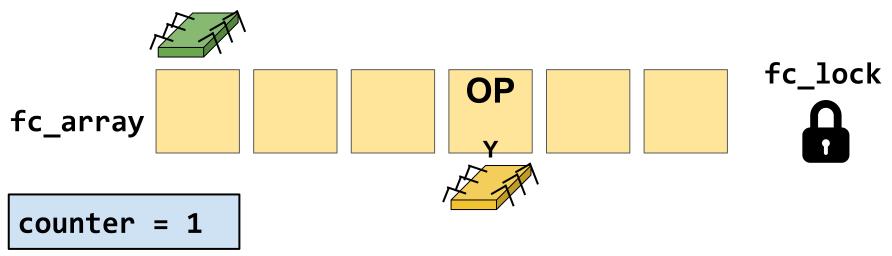
Зелёный начал операцию и успешно взял блокировку



Жёлтый не сумел захватить блокировку и опубликовал свою операцию

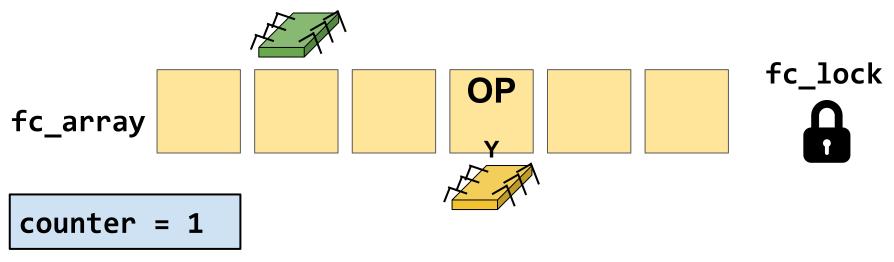


Жёлтый ждёт результат, а зелёный поменял счётчик



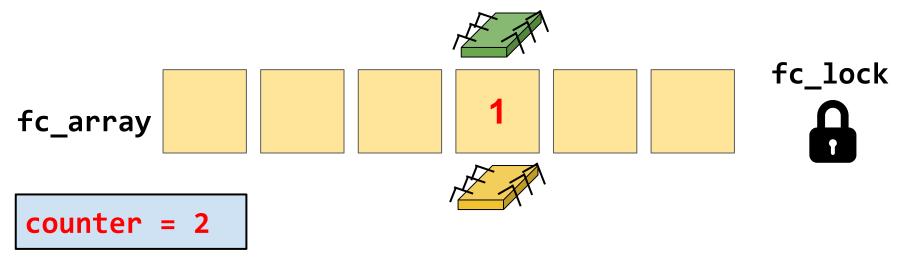


Жёлтый всё ждёт, а зелёный пошёл по массиву



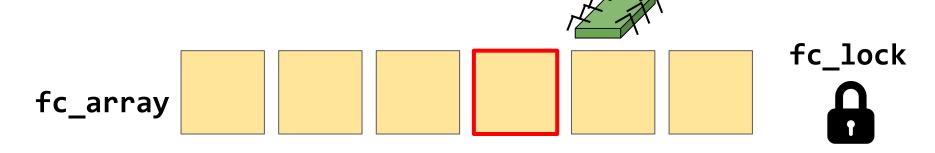


Жёлтый всё ждёт, зелёный всё идёт





Зелёный дошёл до жёлтого, ура! Выполнил операцию и записал результат в ячейку массива.

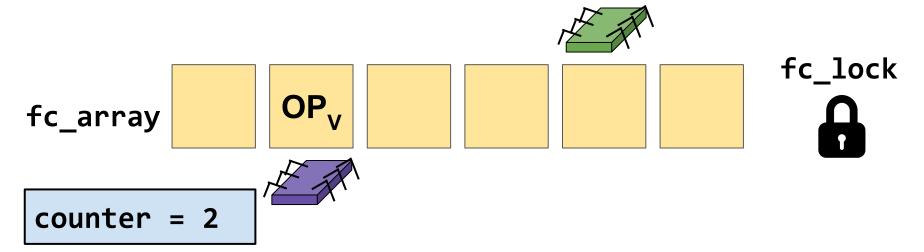


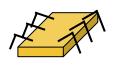
counter = 2





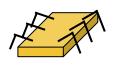
Зелёный пошёл дальше, а жёлтый вернул результат и обнулил ячейку.

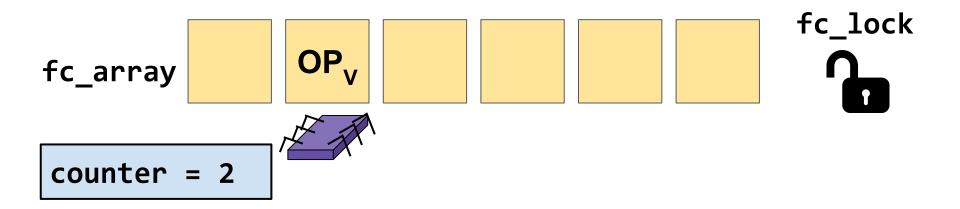




В дело вступает фиолетовый, он тоже не смог захватить блокировку и опубликовал операцию





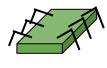






Теперь фиолетовый может захватить блокировку!







fc_array fc_lock









Теперь фиолетовый увеличивает счетчик

fc_array fc_lock

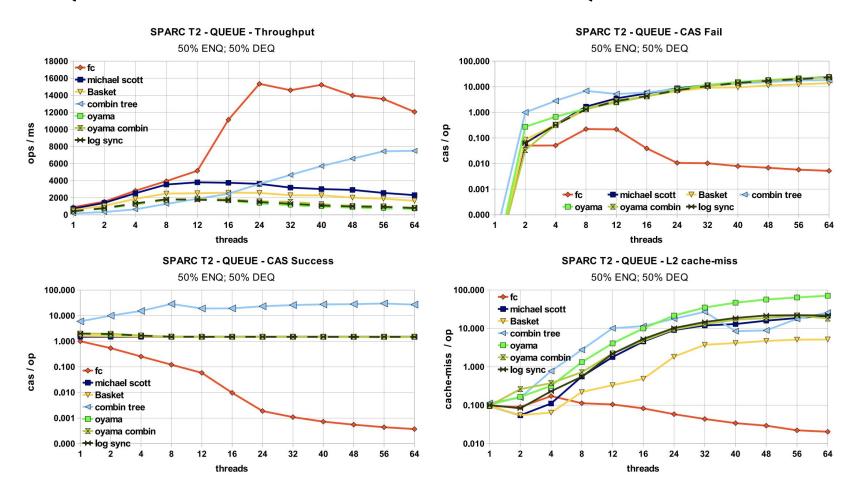
counter = 3



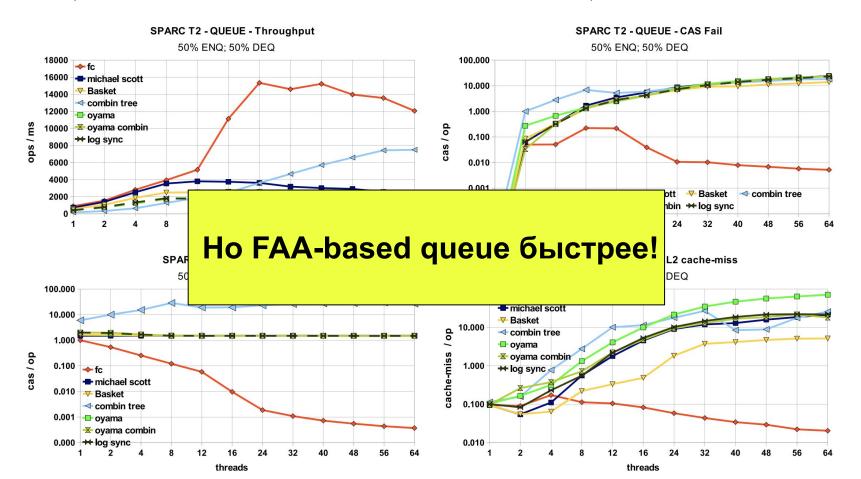


И в конце освобождает блокировку

FC Queue is Much Faster than MSQueue!



FC Queue is Much Faster than MSQueue!



Flat Combining -- когда полезен?

- Когда производительности грубой/тонкой блокировки недостаточно, а с flat combining -- OK
- Когда последовательная версия структуры данных сильно проще и быстрее (например, priority queue)
- Когда алгоритм плохо масштабируется by design (например, очередь)
- Когда алгоритм может существенно быстрее выполнять запросы пачкой, а не по-отдельности (batch processing)

Flat Combining -- какие плюсы нахаляву?

- Cache Locality -- один поток на одном ядре выполняет несколько операций, нет инвалидаций кеша
- Очень быстрая блокировка -- можем написать вот так:

```
var locked = false
fun tryLock() = CAS(&lock, false, true)
fun unlock() { locked = false }
```