

# An Overview of Chapel: a productive parallel programming language

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Cray, Inc.

KIISE-KOCSEA HPC SIG Joint Workshop @ SC'12

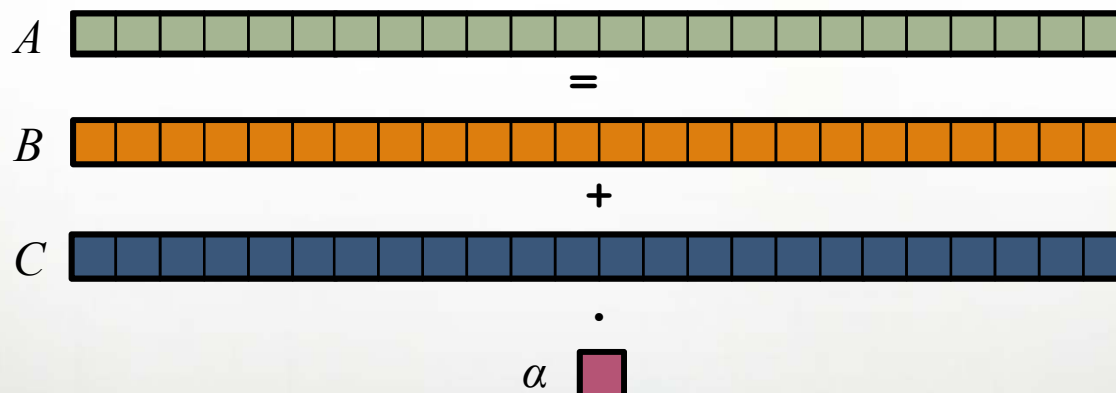


# STREAM Triad: a trivial parallel computation

**Given:**  $m$ -element vectors  $A, B, C$

**Compute:**  $\forall i \in 1..m, A_i = B_i + \alpha \cdot C_i$

**In pictures:**

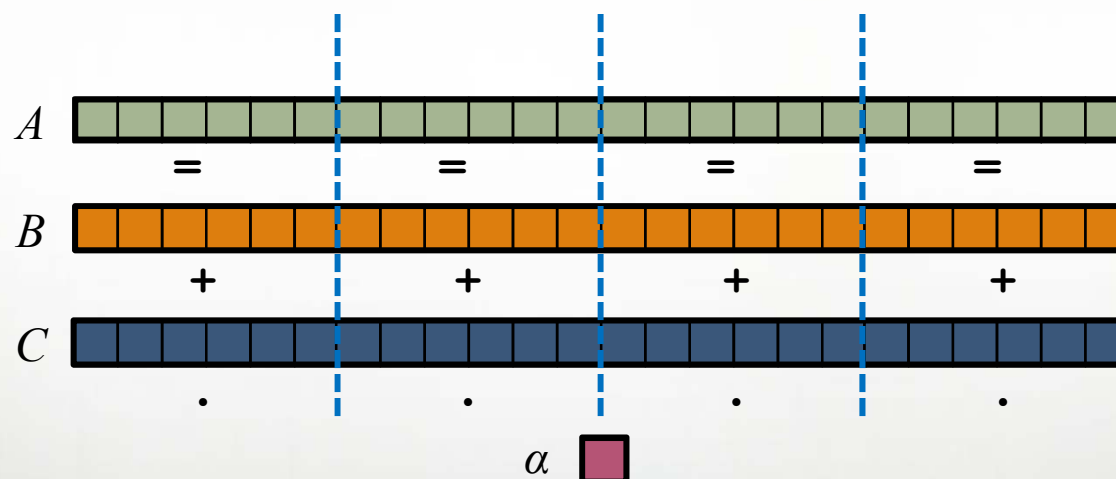


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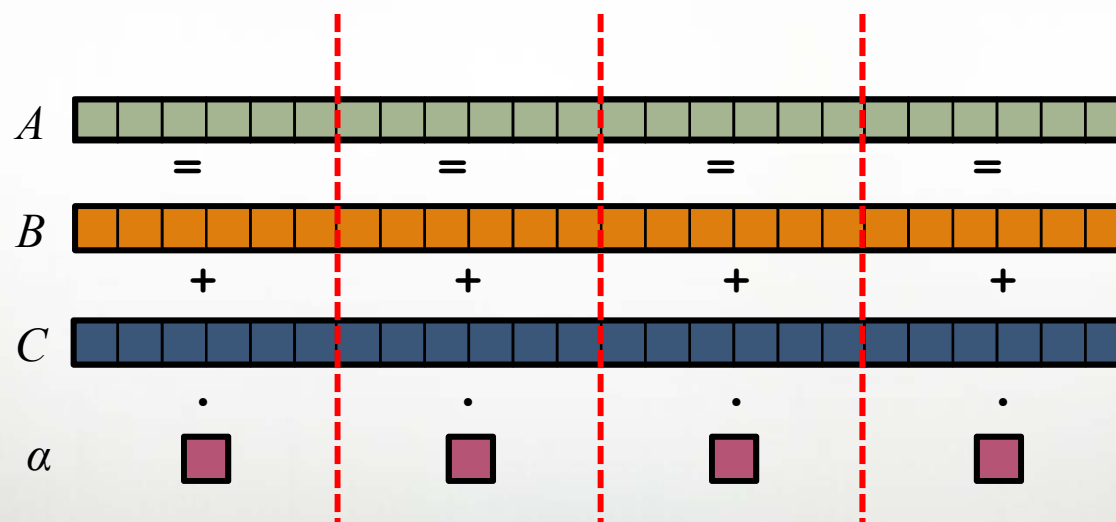


# STREAM Triad: a trivial parallel computation

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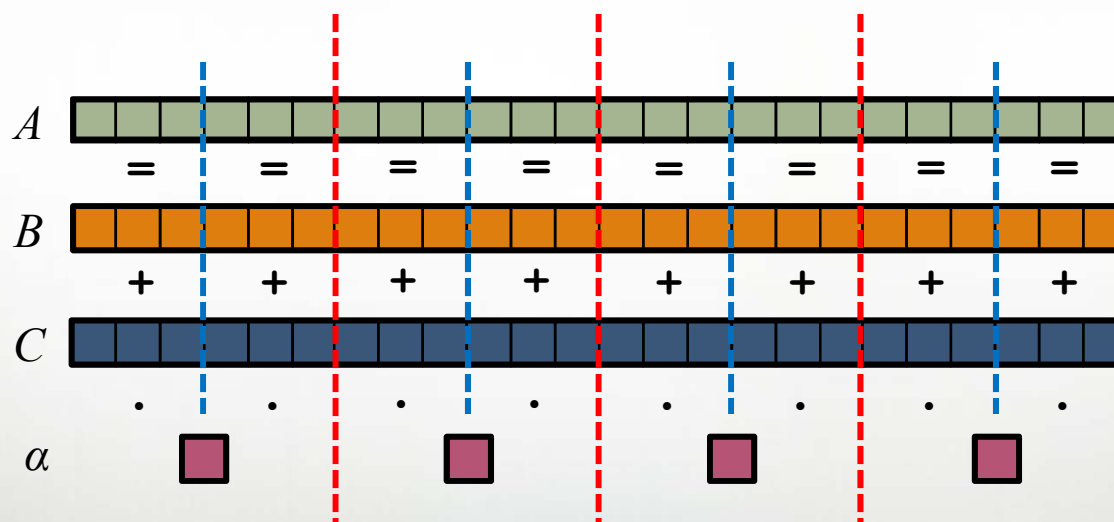


# STREAM Triad: a trivial parallel computation

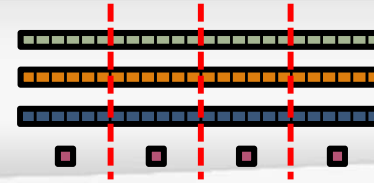
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**Compute:**  $\forall i \in 1..m, A_i = B_i + \alpha \cdot C_i$

**In pictures, in parallel (distributed memory multicore):**



# STREAM Triad: MPI



## MPI

```
#include <hpcc.h>
```

```
static int VectorSize;  
static double *a, *b, *c;
```

```
int HPCC_StarStream(HPCC_Params *params) {  
    int myRank, commSize;  
    int rv, errCount;  
    MPI_Comm comm = MPI_COMM_WORLD;  
  
    MPI_Comm_size( comm, &commSize );  
    MPI_Comm_rank( comm, &myRank );  
  
    rv = HPCC_Stream( params, 0 == myRank );  
    MPI_Reduce( &rv, &errCount, 1, MPI_INT, MPI_SUM,  
        0, comm );  
  
    return errCount;  
}
```

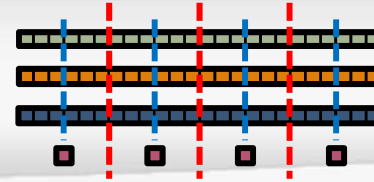
```
int HPCC_Stream(HPCC_Params *params, int doIO) {  
    register int j;  
    double scalar;  
  
    VectorSize = HPCC_LocalVectorSize( params, 3,  
        sizeof(double), 0 );  
  
    a = HPCC_XMALLOC( double, VectorSize );  
    b = HPCC_XMALLOC( double, VectorSize );  
    c = HPCC_XMALLOC( double, VectorSize );
```

```
    if (!a || !b || !c) {  
        if (c) HPCC_free(c);  
        if (b) HPCC_free(b);  
        if (a) HPCC_free(a);  
        if (doIO) {  
            fprintf( outFile, "Failed to allocate memory  
(%d).\n", VectorSize );  
            fclose( outFile );  
        }  
        return 1;  
    }
```

```
    for (j=0; j<VectorSize; j++) {  
        b[j] = 2.0;  
        c[j] = 0.0;  
    }  
  
    scalar = 3.0;
```

```
    for (j=0; j<VectorSize; j++)  
        a[j] = b[j]+scalar*c[j];  
  
    HPCC_free(c);  
    HPCC_free(b);  
    HPCC_free(a);  
  
    return 0;  
}
```

# STREAM Triad: MPI+OpenMP



## MPI + OpenMP

```
#include <hpcc.h>
#ifdef _OPENMP
#include <omp.h>
#endif

static int VectorSize;
static double *a, *b, *c;

int HPCC_StarStream(HPCC_Params *params) {
    int myRank, commSize;
    int rv, errCount;
    MPI_Comm comm = MPI_COMM_WORLD;

    MPI_Comm_size( comm, &commSize );
    MPI_Comm_rank( comm, &myRank );

    rv = HPCC_Stream( params, 0 == myRank );
    MPI_Reduce( &rv, &errCount, 1, MPI_INT, MPI_SUM,
        0, comm );

    return errCount;
}

int HPCC_Stream(HPCC_Params *params, int doIO) {
    register int j;
    double scalar;

    VectorSize = HPCC_LocalVectorSize( params, 3,
        sizeof(double), 0 );

    a = HPCC_XMALLOC( double, VectorSize );
    b = HPCC_XMALLOC( double, VectorSize );
    c = HPCC_XMALLOC( double, VectorSize );
```

```
    if (!a || !b || !c) {
        if (c) HPCC_free(c);
        if (b) HPCC_free(b);
        if (a) HPCC_free(a);
        if (doIO) {
            fprintf( outFile, "Failed to allocate memory
(%d).\n", VectorSize );
            fclose( outFile );
        }
        return 1;
    }
```

```
#ifdef _OPENMP
#pragma omp parallel for
#endif
for (j=0; j<VectorSize; j++) {
    b[j] = 2.0;
    c[j] = 0.0;
}

scalar = 3.0;
```

```
#ifdef _OPENMP
#pragma omp parallel for
#endif
for (j=0; j<VectorSize; j++)
    a[j] = b[j]+scalar*c[j];

    HPCC_free(c);
    HPCC_free(b);
    HPCC_free(a);

    return 0;
}
```

# STREAM Triad: MPI+OpenMP vs. CUDA

## MPI + OpenMP

```
#include <hpcc.h>
#ifdef _OPENMP
#include <omp.h>
#endif

static int VectorSize;
static double *a, *b, *c;

int HPCC_StarStream(HPCC_Params *params) {
    int myRank, commSize;
    int rv, errCount;
    MPI_Comm comm = MPI_COMM_WORLD;

    MPI_Comm_size( comm, &commSize );
    MPI_Comm_rank( comm, &myRank );

    rv = HPCC_Stream( params, 0 == myRank );
    MPI_Reduce( &rv, &errCount, 1, MPI_INT, MPI_SUM, 0, comm );

    return errCount;
}

int HPCC_Stream(HPCC_Params *params, int doIO) {
    register int j;
    double scalar;

    VectorSize = HPCC_LocalVectorSize( params, 3, sizeof(double), 0 );

    a = HPCC_XMALLOC( double, VectorSize );
    b = HPCC_XMALLOC( double, VectorSize );
    c = HPCC_XMALLOC( double, VectorSize );

    if (!a || !b || !c) {
        if (c) HPCC_free(c);
        if (b) HPCC_free(b);
        if (a) HPCC_free(a);
        if (doIO) {
            fprintf( outFile, "Failed to allocate memory (%d).\n", VectorSize );
            fclose( outFile );
        }
        return 1;
    }

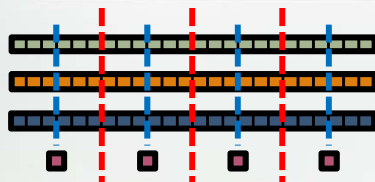
#ifdef _OPENMP
#pragma omp parallel for
#endif
    for (j=0; j<VectorSize; j++) {
        b[j] = 2.0;
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    }

    scalar = 3.0;

#ifdef _OPENMP
#pragma omp parallel for
#endif
    for (j=0; j<VectorSize; j++)
        a[j] = b[j]+scalar*c[j];

    HPCC_free(c);
    HPCC_free(b);
    HPCC_free(a);

    return 0;
}
```



## CUDA

```
#define N 2000000

int main() {
    float *d_a, *d_b, *d_c;
    float scalar;

    cudaMalloc((void**)&d_a, sizeof(float)*N);
    cudaMalloc((void**)&d_b, sizeof(float)*N);
    cudaMalloc((void**)&d_c, sizeof(float)*N);

    dim3 dimBlock(128);
    dim3 dimGrid(N/dimBlock.x );
    if( N % dimBlock.x != 0 ) dimGrid.x+=1;

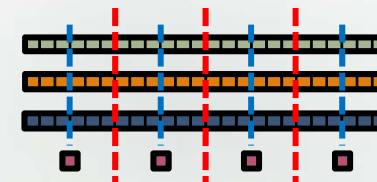
    set_array<<<dimGrid,dimBlock>>>(d_b, .5f, N);
    set_array<<<dimGrid,dimBlock>>>(d_c, .5f, N);

    scalar=3.0f;
    STREAM_Triad<<<dimGrid,dimBlock>>>(d_b, d_c, d_a, scalar, N);
    cudaThreadSynchronize();

    cudaFree(d_a);
    cudaFree(d_b);
    cudaFree(d_c);
}

__global__ void set_array(float *a, float value, int len) {
    int idx = threadIdx.x + blockIdx.x * blockDim.x;
    if (idx < len) a[idx] = value;
}

__global__ void STREAM_Triad( float *a, float *b, float *c,
                             float scalar, int len) {
    int idx = threadIdx.x + blockIdx.x * blockDim.x;
    if (idx < len) c[idx] = a[idx]+scalar*b[idx];
}
```





# STREAM Triad: MPI+OpenMP vs. CUDA

## MPI + OpenMP

```
#include <hpcc.h>
#ifdef _OPENMP
#include <omp.h>
#endif

static int VectorSize;
static double *a, *b, *c;

int HPCC_StarStream(HPCC_Params *params) {
    int myRank, commSize;
    int rv, errCount;
    MPI_Comm comm = MPI_COMM_WORLD;

    MPI_Comm_size( comm, &commSize );
    MPI_Comm_rank( comm, &myRank );

    rv = HPCC_Stream( params, 0 == myRank );
    MPI_Reduce( &rv, &errCount, 1, MPI_INT, MPI_SUM, 0, comm );

    return errCount;
}

int HPCC_Stream(HPCC_Params *params, int doIO) {
    register int j;
    double scalar;

    VectorSize = HPCC_LocalVectorSize( params, 3, sizeof(double), 0 );

    a = HPCC_XMALLOC( double, VectorSize );
    b = HPCC_XMALLOC( double, VectorSize );
    c = HPCC_XMALLOC( double, VectorSize );

    if (!a || !b || !c) {
        if (c) HPCC_free(c);
        if (b) HPCC_free(b);
        if (a) HPCC_free(a);
        if (doIO) {
            fprintf( outFile, "Failed to allocate memory (%d).\n", VectorSize );
            fclose( outFile );
        }
        return 1;
    }

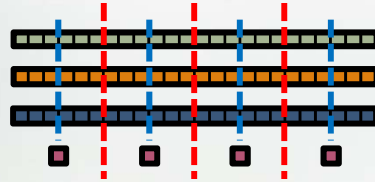
#ifdef _OPENMP
#pragma omp parallel for
#endif
    for (j=0; j<VectorSize; j++) {
        b[j] = 2.0;
        c[j] = 0.0;
    }

    scalar = 3.0;

#ifdef _OPENMP
#pragma omp parallel for
#endif
    for (j=0; j<VectorSize; j++)
        a[j] = b[j]+scalar*c[j];

    HPCC_free(c);
    HPCC_free(b);
    HPCC_free(a);

    return 0;
}
```



## CUDA

```
#define N      2000000

int main() {
    float *d_a, *d_b, *d_c;
    float scalar;

    cudaMalloc((void**)&d_a, sizeof(float)*N);
    cudaMalloc((void**)&d_b, sizeof(float)*N);
    cudaMalloc((void**)&d_c, sizeof(float)*N);

    dim3 dimBlock(128);
    if( N % dimBlock.x != 0 ) dimGrid.x+=1;

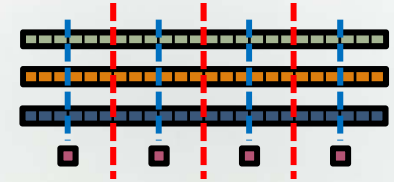
    set_array<<<dimGrid,dimBlock>>>(d_b, .5f, N);
    set_array<<<dimGrid,dimBlock>>>(d_c, .5f, N);

    scalar=3.0f;
    STREAM_Triad<<<dimGrid,dimBlock>>>(d_b, d_c, d_a, scalar, N);
    cudaThreadSynchronize();

    cudaFree(d_a);
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__global__ void set_array(float *a, float value, int len) {
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__global__ void STREAM_Triad( float *a, float *b, float *c,
                             float scalar, int len) {
    int idx = threadIdx.x + blockIdx.x * blockDim.x;
    if (idx < len) c[idx] = a[idx]+scalar*b[idx];
}
```



*HPC suffers from too many distinct notations for expressing parallelism and locality*

# STREAM Triad: Chapel

## MPI + OpenMP

```
#include <hpcc.h>
#ifdef _OPENMP
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#endif

static int VectorSize;
static double *a, *b, *c;

int HPCC_StarStream(HPCC_Params *params)
{
    int myRank, commSize;
    int rv, errCount;
    MPI_Comm comm = MPI_COMM_WORLD;

    MPI_Comm_size(comm, &commSize);
    MPI_Comm_rank(comm, &myRank);

    rv = HPCC_Stream(params, 0 == myRank);
    MPI_Reduce(&rv, &errCount, 1, MPI_INT, 0, comm);

    return errCount;
}
```

```
int HPCC_Stream(HPCC_Params *params,
    register int j;
    double scalar;

    VectorSize = HPCC_LocalVectorSize(params);

    a = HPCC_XMALLOC(double, VectorSize);
    b = HPCC_XMALLOC(double, VectorSize);
    c = HPCC_XMALLOC(double, VectorSize);

    if (!a || !b || !c) {
        if (c) HPCC_free(c);
        if (b) HPCC_free(b);
        if (a) HPCC_free(a);
        if (doIO) {
```

```
scalar = 3.0;

#ifdef _OPENMP
#pragma omp parallel for
#endif
for (j=0; j<VectorSize; j++)
    a[j] = b[j]+scalar*c[j];

HPCC_free(c);
HPCC_free(b);
HPCC_free(a);

return 0;
}
```

## Chapel

```
config const m = 1000,
    alpha = 3.0;
```

```
const ProblemSpace = {1..m} dmapped ...;
```

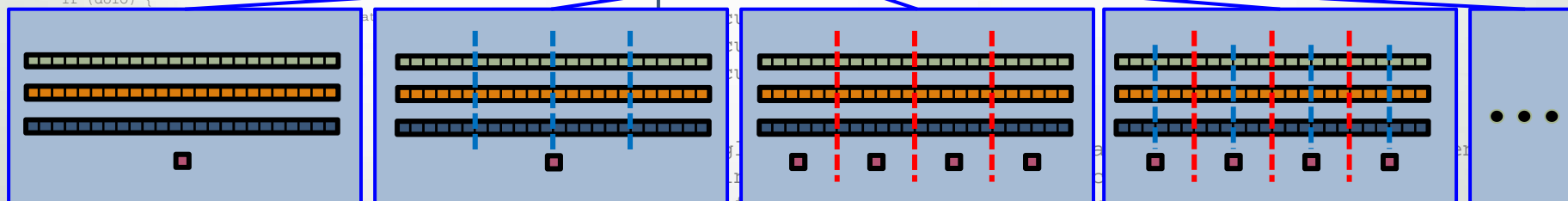
```
var A, B, C: [ProblemSpace] real;
```

```
B = 2.0;
```

```
C = 3.0;
```

```
A = B + alpha * C;
```

the special sauce



```
__global__ void STREAM_Triad( float *a, float *b, float *c,
    float scalar, int len) {
    int idx = threadIdx.x + blockIdx.x * blockDim.x;
    if (idx < len) c[idx] = a[idx]+scalar*b[idx];
}
```

# STREAM Triad: Chapel

## MPI + OpenMP

```
#include <hpcc.h>
#ifdef _OPENMP
#include <omp.h>
#endif

static int VectorSize;
static double *a, *b, *c;

int HPCC_StarStream(HPCC_Params *params,
    int myRank, commSize;
    int rv, errCount;
    MPI_Comm comm = MPI_COMM_WORLD;

    MPI_Comm_size( comm, &commSize );
    MPI_Comm_rank( comm, &myRank );

    rv = HPCC_Stream( params, 0 == myRank );
    MPI_Reduce( &rv, &errCount, 1, MPI_INT,
        0, comm );

    return errCount;
}

int HPCC_Stream(HPCC_Params *params,
    register int j;
    double scalar;

    VectorSize = HPCC_LocalVectorSize( params );

    a = HPCC_XMALLOC( double, VectorSize );
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    c = HPCC_XMALLOC( double, VectorSize );

    if (!a || !b || !c) {
        if (c) HPCC_free(c);
        if (b) HPCC_free(b);
        if (a) HPCC_free(a);
        if (doIO) {
            scalar =
        }
    }
    #ifdef _OPENMP
    #pragma omp
    #endif
    for (j=0; j<VectorSize; j++)
        a[j] = b[j] + alpha * c[j];

    HPCC_free(a);
    HPCC_free(b);
    HPCC_free(c);

    return 0;
}
```

## Chapel

```
config const m = 1000,
    alpha = 3.0;

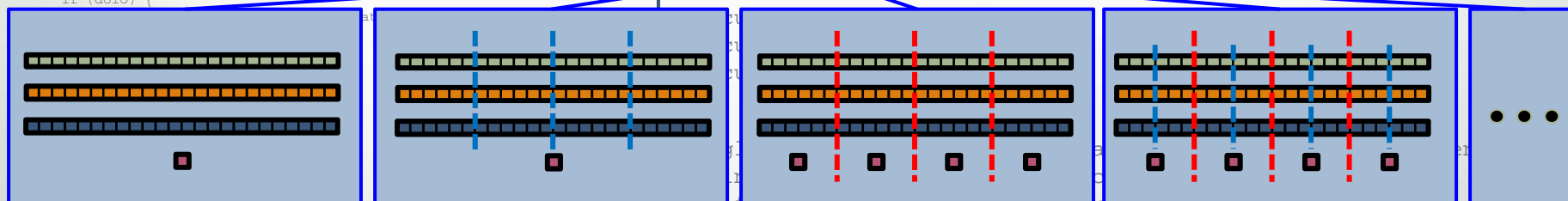
const ProblemSpace = {1..m} dmapped ...;

var A, B, C: [ProblemSpace] real;

B = 2.0;
C = 3.0;

A = B + alpha * C;
```

the special sauce



Philosophy: Good language design can tease details of locality and parallelism away from an algorithm, permitting the application scientist and HPC expert to each focus on their strengths.

# Outline

- ✓ Motivation
- Chapel Background and Themes
  - Tour of Chapel Concepts
  - Project Status

# What is Chapel?

- An emerging parallel programming language
  - Design and development led by Cray Inc.
    - in collaboration with academia, labs, industry
  - Initiated under the DARPA HPCS program
- **Overall goal:** Improve programmer productivity
  - Improve the **programmability** of parallel computers
  - Match or beat the **performance** of current programming models
  - Support better **portability** than current programming models
  - Improve the **robustness** of parallel codes
- A work-in-progress

# Chapel's Implementation

- Being developed as open source at SourceForge
- Licensed as BSD software
- **Target Architectures:**
  - Cray architectures
  - multicore desktops and laptops
  - commodity clusters
  - systems from other vendors
  - *in-progress:* CPU+accelerator hybrids, manycore, ...

# Motivating Chapel Themes

- 1) General Parallel Programming
- 2) Global-View Abstractions
- 3) Multiresolution Design
- 4) Control over Locality/Affinity
- 5) Reduce HPC  $\leftrightarrow$  Mainstream Language Gap

# Motivating Chapel Themes

- 1) General Parallel Programming
- 2) Global-View Abstractions
- 3) Multiresolution Design
- 4) Control over Locality/Affinity
- 5) Reduce HPC  $\leftrightarrow$  Mainstream Language Gap



# 1) General Parallel Programming

Recall from our STREAM example..

Style of HW Parallelism	Programming Model	Unit of Parallelism
Inter-node	MPI	executable
Intra-node/multicore	OpenMP	iteration/task
GPU/accelerator	CUDA	SIMD function/task

# 1) General Parallel Programming

With a unified set of concepts...

...express any parallelism desired in a user's program

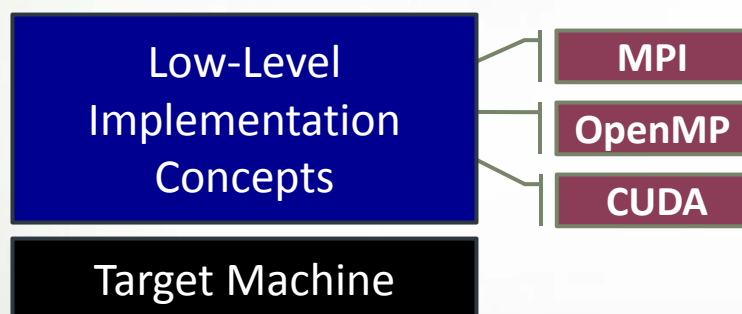
- **Styles:** data-parallel, task-parallel, concurrency, nested, ...
- **Levels:** model, function, loop, statement, expression

...target all parallelism available in the hardware

- **Types:** machines, nodes, cores, instructions

Style of HW Parallelism	Programming Model	Unit of Parallelism
Inter-node	Chapel	executable/task
Intra-node/multicore	Chapel	iteration/task
GPU/accelerator	Chapel	SIMD function/task

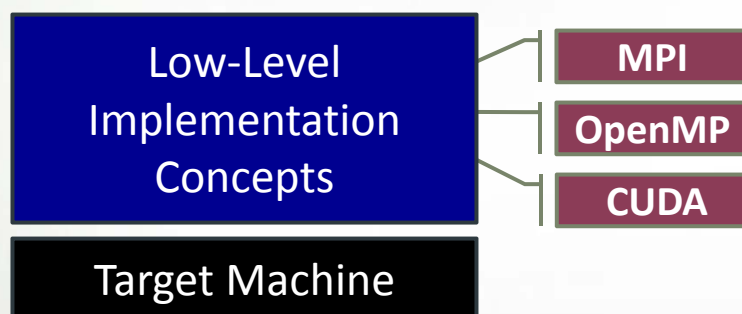
### 3) Multiresolution Design: Motivation



*“Why is everything so tedious/difficult?”*

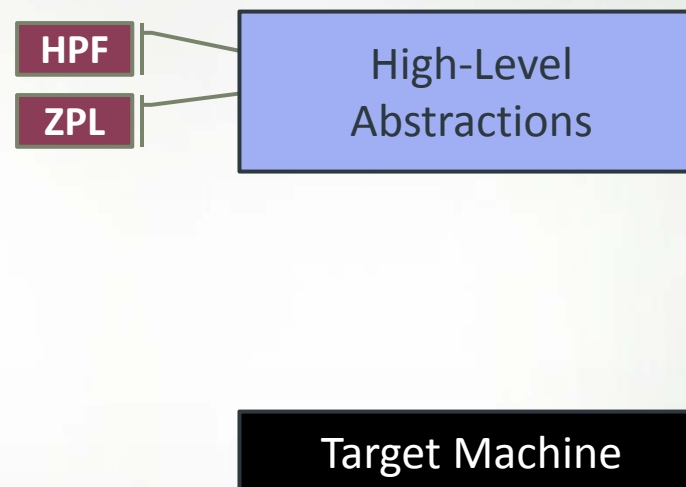
*“Why don’t my programs port trivially?”*

### 3) Multiresolution Design: Motivation



*"Why is everything so tedious/difficult?"*

*"Why don't my programs port trivially?"*



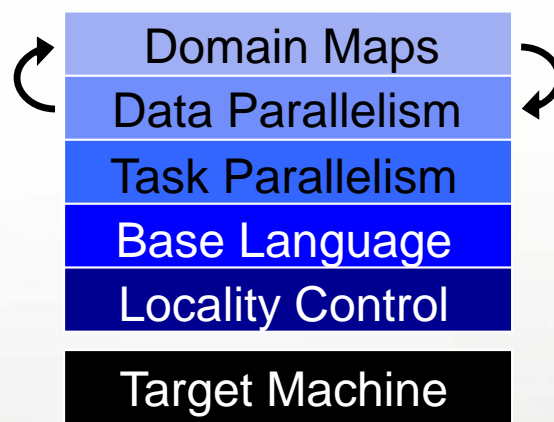
*"Why don't I have more control?"*

### 3) Multiresolution Design

**Multiresolution Design:** Support multiple tiers of features

- higher levels for programmability, productivity
- lower levels for greater degrees of control

*Chapel language concepts*

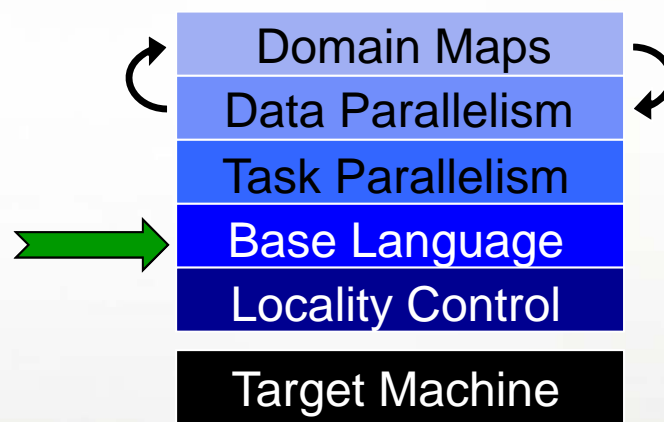


- build the higher-level concepts in terms of the lower
- permit the user to intermix layers arbitrarily

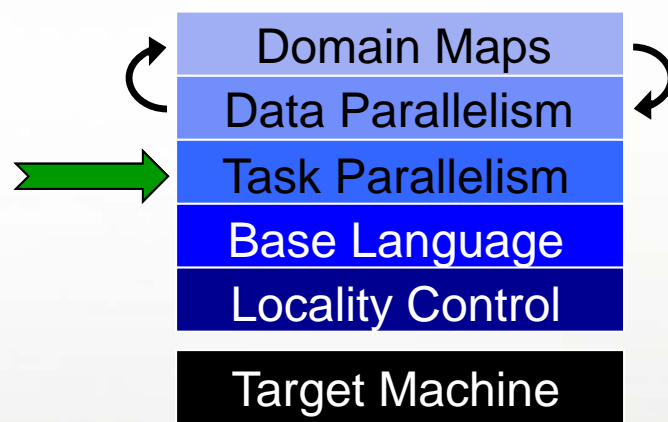
# Outline

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# Base Language Features



# Task Parallel Features





# Task Parallelism Terminology

**Task:** a unit of (parallel) work in Chapel

- All parallelism is implemented using tasks
- `main( )` is the only task when a program begins

# Begin Statements

```
begin writeln("Hello from task 0 of 4");  
begin writeln("Hello from task 1 of 4");  
begin writeln("Hello from task 2 of 4");  
begin writeln("Hello from task 3 of 4");  
writeln("All tasks done");
```

```
Hello from task 0 of 4  
All tasks done  
Hello from task 1 of 4  
Hello from task 3 of 4  
Hello from task 2 of 4
```

# Cobegin statements

```
cobegin {  
    writeln("Hello from task 0 of 4");  
    writeln("Hello from task 1 of 4");  
    writeln("Hello from task 2 of 4");  
    writeln("Hello from task 3 of 4");  
}  
  
writeln("All tasks done");
```

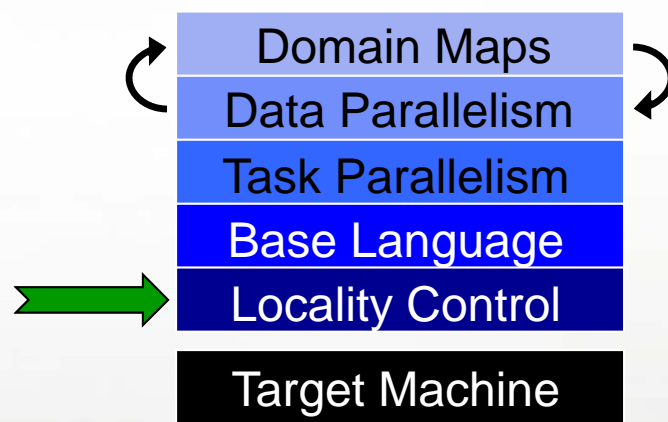
```
Hello from task 1 of 4  
Hello from task 2 of 4  
Hello from task 3 of 4  
Hello from task 0 of 4  
All tasks done
```

# Coforall Loops

```
coforall t in 0..numTasks-1 do  
  writeln("Hello from task ", t, " of ", numTasks);  
  
writeln("All tasks done");
```

```
Hello from task 2 of 4  
Hello from task 0 of 4  
Hello from task 3 of 4  
Hello from task 1 of 4  
All tasks done
```

# Locality Features



# The Locale Type

## Definition:

- Abstract unit of target architecture
- Supports reasoning about locality
- Capable of running tasks and storing variables
  - i.e., has processors and memory
- Can be queried for characteristics like amount of memory or number of cores

**Typically:** A multi-core processor or an SMP

# Controlling Locality

- Users specify the number of locales to use at program launch
  - The locale variables are available to the user in an built-in array called `Locales`
- *On-clauses* support placement of computations:

```
writeln("on locale 0");

on Locales[1] do
  writeln("now on locale 1");

writeln("on locale 0 again");
```

## Important Note #1

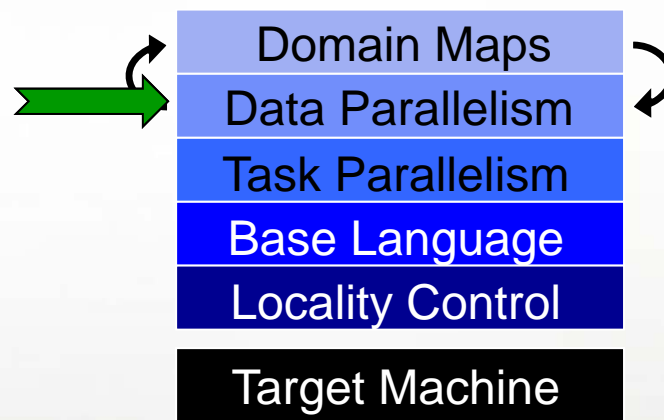
*Parallelism* and *Locality* are distinct concepts

- e.g., begin statements create tasks
  - new task will run on the current locale
- e.g., on-clauses place computation
  - no parallelism introduced

Composing these concepts can be very powerful

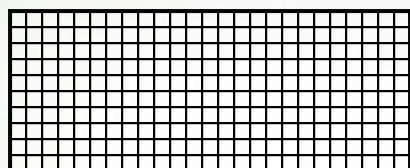


# Data Parallel Features

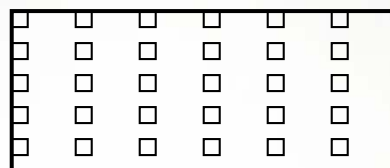


# Chapel Domain Types

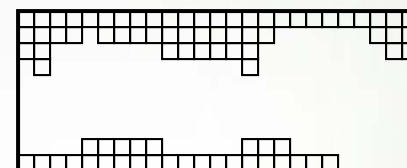
Chapel supports several types of domains (index sets) :



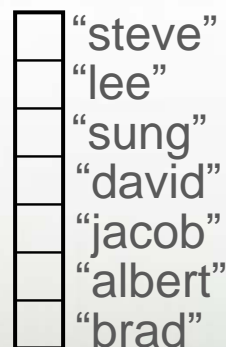
*dense*



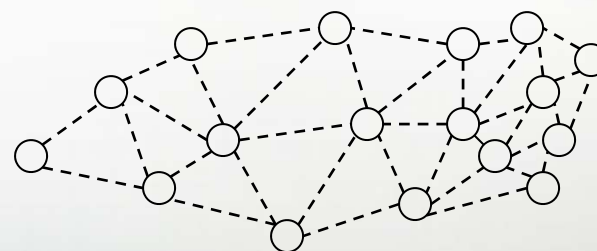
*strided*



*sparse*



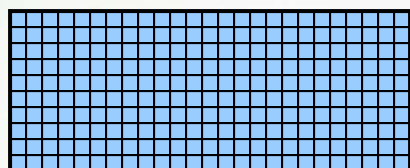
*associative*



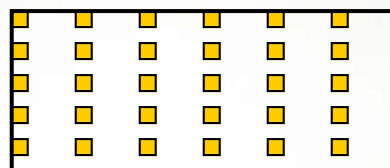
*unstructured*

# Chapel Array Types

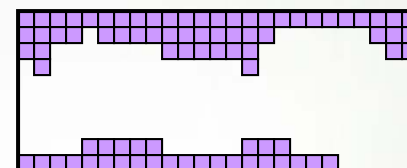
Each domain type can be used to declare arrays:



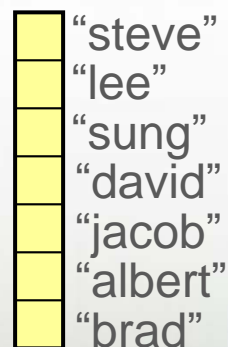
*dense*



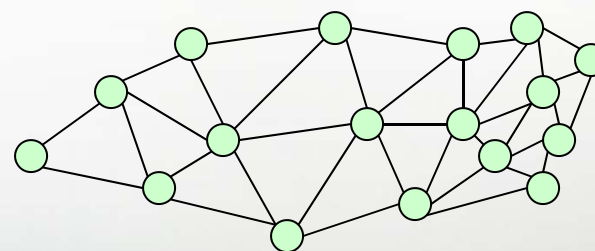
*strided*



*sparse*



*associative*



*unstructured*

# Chapel Domain/Array Operations

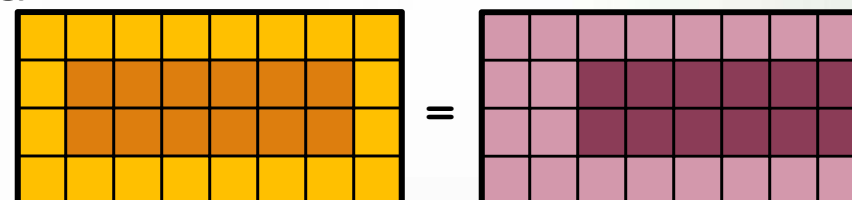
- Parallel and Serial Iteration

```
for a in A do a = 0.0;
forall (i,j) in D do A[i,j] = i + j/10.0;
```

1.1	1.2	1.3	1.4	1.5	1.6	1.7	1.8
2.1	2.2	2.3	2.4	2.5	2.6	2.7	2.8
3.1	3.2	3.3	3.4	3.5	3.6	3.7	3.8
4.1	4.2	4.3	4.4	4.5	4.6	4.7	4.8

- Array Slicing; Domain Algebra

```
A[InnerD] = B[InnerD+(0,1)];
```



- Promotion of Scalar Operators and Functions

```
A = B + alpha * C;
```

```
A = exp(B, C);
```

- And several others: indexing, reallocation, set operations, remapping, aliasing, queries, ...

## Important Note #2

Operations on arrays are the same regardless of the domain that is used to declare the arrays

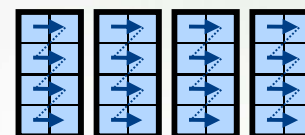
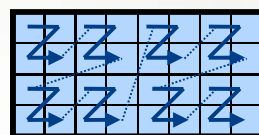
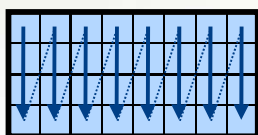
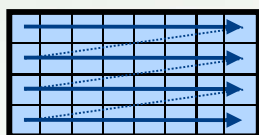
```
A = B + alpha * C;
```

- A, B, and C could be dense, strided, sparse, associative, or unstructured

# Data Parallelism Implementation Qs

## Q1: How are arrays laid out in memory?

- Are regular arrays laid out in row- or column-major order? Or...?

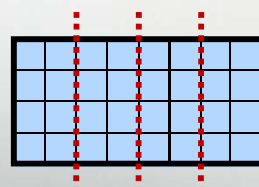
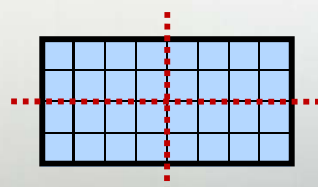
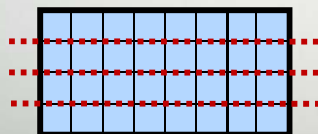


...?

- How are sparse arrays stored? (COO, CSR, CSC, block-structured, ...?)

## Q2: How are arrays stored by the locales?

- Completely local to one locale? Or distributed?
- If distributed... In a blocked manner? cyclically? block-cyclically? recursively bisected? dynamically rebalanced? ...?

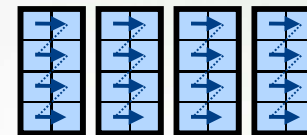
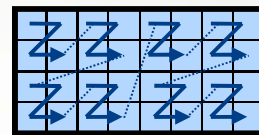
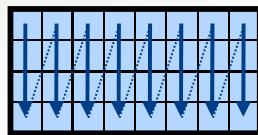
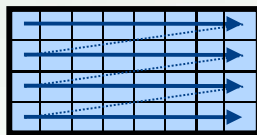


...?

# Data Parallelism Implementation Qs

## Q1: How are arrays laid out in memory?

- Are regular arrays laid out in row- or column-major order? Or...?



...?

- How are sparse arrays stored? (COO, CSR, CSC, block-structured, ...?)

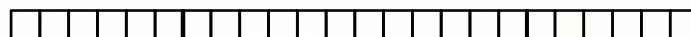
## Q2: How are arrays stored by the locales?

- Completely local to one locale? Or distributed?
- If distributed... In a blocked manner? cyclically? block-cyclically? recursively bisected? dynamically rebalanced? ...?

**A:** Chapel's *domain maps* are designed to give the user full control over such decisions

# STREAM Triad: Chapel (multicore)

```
const ProblemSpace = {1..m};
```



```
var A, B, C: [ProblemSpace] real;
```



```
A = B + alpha * C;
```

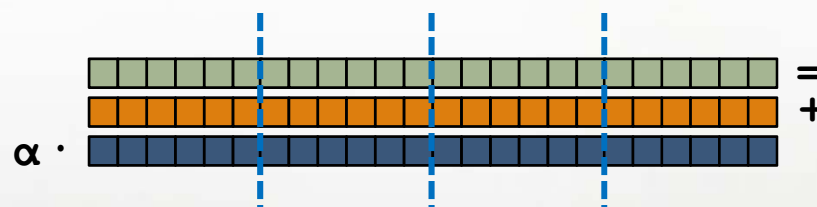


# STREAM Triad: Chapel (multicore)

```
const ProblemSpace = {1..m};
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```
var A, B, C: [ProblemSpace] real;
```

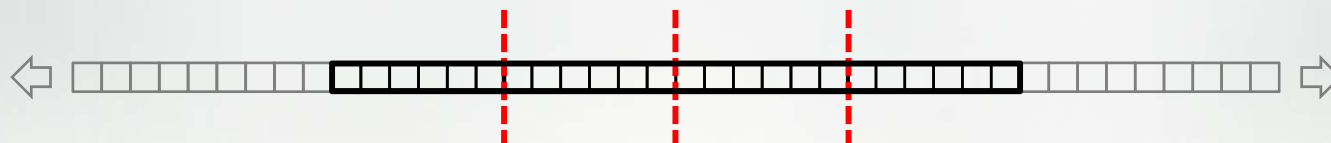


```
A = B + alpha * C;
```

No domain map specified => use default layout

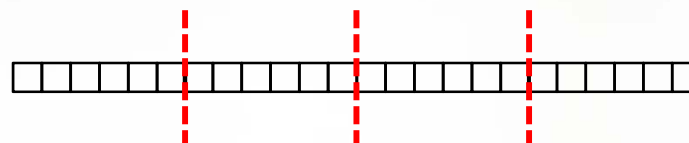
- current locale owns all indices and values
- computation will execute using local processors only

# STREAM Triad: Chapel (multilocale, blocked)

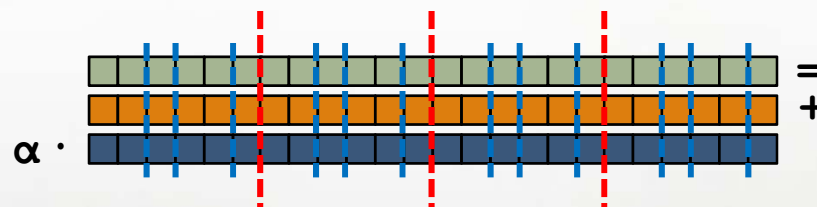


```
const ProblemSpace = {1..m}
```

```
dmapped Block(boundingBox={1..m}) ;
```

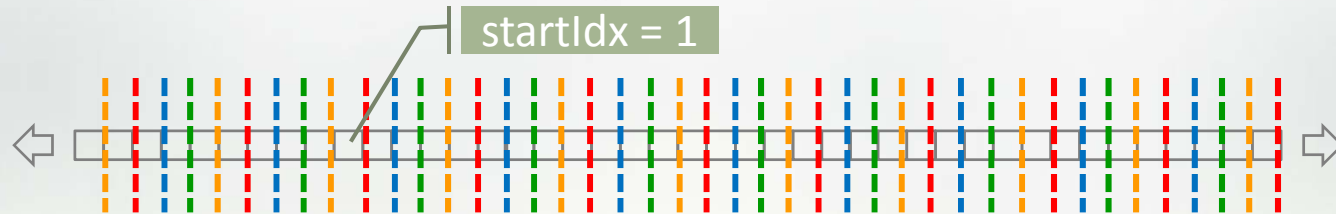


```
var A, B, C: [ProblemSpace] real;
```



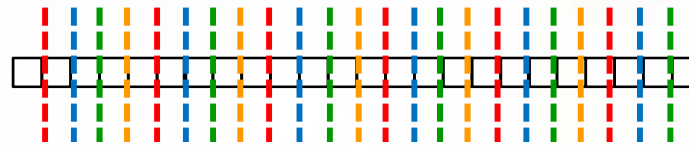
```
A = B + alpha * C;
```

# STREAM Triad: Chapel (multilocale, cyclic)

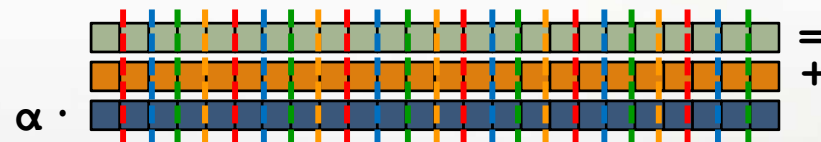


```
const ProblemSpace = {1..m}
```

```
dmapped Cyclic(startIdx=1);
```



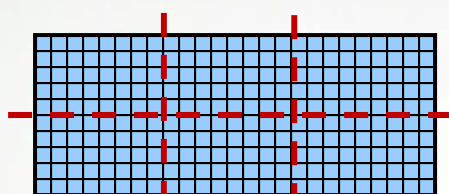
```
var A, B, C: [ProblemSpace] real;
```



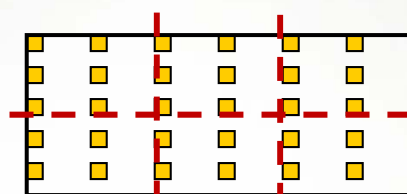
```
A = B + alpha * C;
```

## Important Note #3

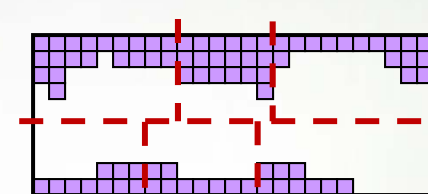
All Chapel domain types support domain maps



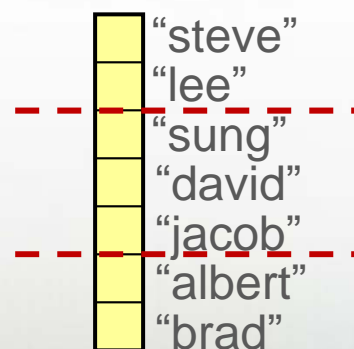
*dense*



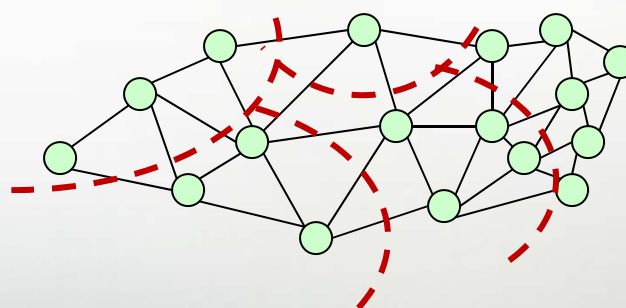
*strided*



*sparse*



*associative*



*unstructured*

# Standard Domain Maps

## Completed domain maps:

- Block, Cyclic, Replicated
- Sparse COO and CSR
- Quadratic probing associative

## In the works:

- Block-Cyclic, 2D dimensional
- Distributed associative and sparse

## More Domain Maps

Users can write their own domain maps

- GPU computations
- Dynamically load balanced domains/arrays
- Resilient data structures
- *in situ* interoperability with legacy codes
- out-of-core computations
- ...

## Summary

Chapel is a new parallel programming language aimed at drastically improving programmer productivity

- Chapel avoids locking crucial implementation decisions into the language specification
  - Separates the roles of domain scientist and HPC expert
  - Results in much cleaner, maintainable code

# Outline

- ✓ Motivation
- ✓ Chapel Background and Themes
- ✓ Tour of Chapel Concepts
- Project Status



# Implementation Status – Version 1.6.0

## **In a nutshell:**

- Most features work
- Many performance optimizations remain

## **This is a good time to:**

- Try out the language and compiler
- Give us feedback on the language
- Use Chapel for parallel programming education
- Use Chapel for non-performance-critical projects

## Some Next Steps

- Grow the set of architectures we can target effectively
- Grow the set of codes we are evaluating
- Performance optimizations
- Evolve from prototype- to production-grade

## For More Information

**Chapel project page:** <http://chapel.cray.com>

- overview, papers, presentations, language spec, ...

**Chapel SourceForge page:** <https://sourceforge.net/projects/chapel/>

- release downloads, public mailing lists, code repository, ...

### Mailing Lists:

- [chapel\\_info@cray.com](mailto:chapel_info@cray.com): contact the team
- [chapel-users@lists.sourceforge.net](mailto:chapel-users@lists.sourceforge.net): user-oriented discussion list
- [chapel-developers@lists.sourceforge.net](mailto:chapel-developers@lists.sourceforge.net): dev.-oriented discussion
- [chapel-education@lists.sourceforge.net](mailto:chapel-education@lists.sourceforge.net): educator-oriented discussion
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