

Performance Portability of the Chapel Language on Diverse Architectures

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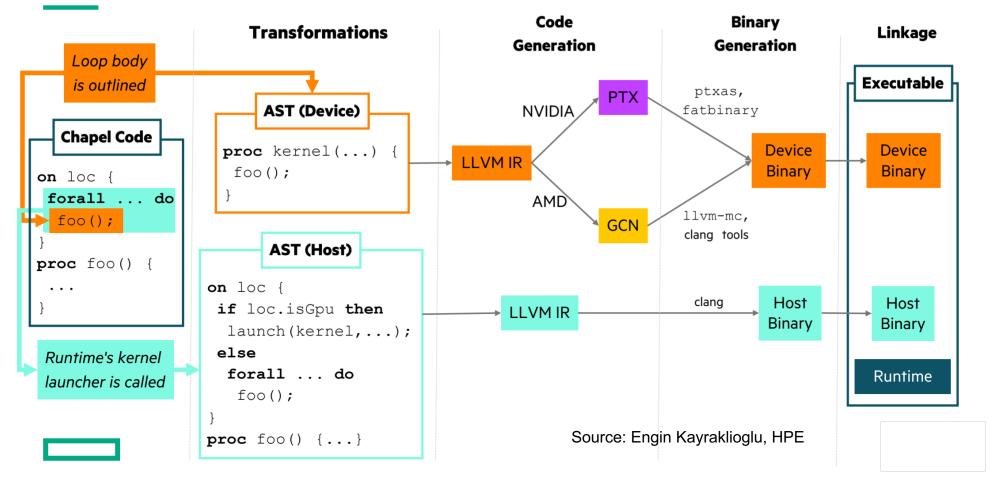


Chapel on Heterogeneous Architectures



Single-source compilation to multiple targets through LLVM

COMPILATION TRAJECTORY



Performance Portability

- Application code should run on many different hardware platforms ...
 - (without requiring rewriting for each new platform)
- ... and achieve acceptable performance on each platform
 - (without platform-specific optimizations)
- \bullet Pennycook, Sewall, and Lee's metric $\mathbf{\Psi}$: harmonic mean of efficiency on each platform
 - Architectural efficiency e.g. fraction of peak FLOP/s
 - Application efficiency e.g. inverse speedup versus fastest version
 - $-\Psi$ = 0 if code doesn't run on all platforms
- How well does Chapel support development of performance-portable application codes compared to more widely-used programming models like OpenMP and Kokkos?



Mini-apps

- We created new Chapel implementations of three mini-apps developed by the University of Bristol's High Performance Computing group
- These miniapps have been used extensively to compare parallel programming models and already have idiomatic implementations in OpenMP, Kokkos, CUDA, and HIP.
 - BabelStream: streaming memory access
 - miniBUDE: numerically intensive molecular dynamics
 - TeaLeaf: memory-intensive stencil PDE solver
- Not included in this study:
 - multi-device
 - distributed memory
 - programmer productivity



BabelStream

 An update of McCalpin's Stream memory bandwidth benchmark, comprising:

Kernel	Function	Load/Store	FLOP
Сору	C = A	2	0
Add	C = A + B	3	1
Mul	$B = \alpha * C$	2	1
Triad	$A = B + \alpha * C$	3	2 (1 FMA)
Nstream (PRK)	$A += B + \alpha * C$	4	3 (1 FMA)
Dot	$x = A \cdot B$	2	2 (1 FMA)

• We measure BabelStream version 5.0 triad with 228 64-bit FP elements

https://github.com/milthorpe/BabelStream



BabelStream Triad Implementations

```
chapel proc triad() {
    forall i in vectorDom do
        A[i] = B[i] + scalar * C[i];
    }
}
```

```
const streamLocale = if useGPU
    then here.gpus[deviceIndex]
    else here;
on streamLocale do {
    const vectorDom = 0..#arraySize;
    var A, B, C: [vectorDom] eltType = noinit;
}
```

- CPU: loop is decomposed into chunks to be executed by worker threads
- GPU: compiled to PTX (NVIDIA) or GCN (AMD) for each threads to compute a triad of elements; compiler generates host-side code for kernel launch and synchronization

```
template <class T>
void CUDAStream<T>::triad()
{
    triad_kernel<<<array_size/TBSIZE, TBSIZE>>>
        (d_a, d_b, d_c);
    check_error();
    cudaDeviceSynchronize();
    check_error();
}
```

```
template <typename T>
   __global__ void triad_kernel(T * a, const T * b,
const T * c)
{
   const T scalar = startScalar;
   const int i = blockDim.x * blockIdx.x +
threadIdx.x;
   a[i] = b[i] + scalar * c[i];
}
```

BabelStream Triad Implementations (2)

Kokkos

```
template <class T>
void KokkosStream<T>::triad()
{
   Kokkos::View<T*> a(*d_a);
   Kokkos::View<T*> b(*d_b);
   Kokkos::View<T*> c(*d_c);

   const T scalar = startScalar;
   Kokkos::parallel_for(array_size, KOKKOS_LAMBDA (const long index)
   {
      a[index] = b[index] + scalar*c[index];
   });
   Kokkos::fence();
}
```

BabelStream Triad Implementations (3)

OpenMP

```
template <class T>
void OMPStream<T>::triad()
  const T scalar = startScalar;
#ifdef OMP TARGET GPU
  int array_size = this->array_size;
 T *a = this->a;
 T *b = this->b;
 T *c = this->c;
  #pragma omp target teams distribute parallel for simd
#else
 #pragma omp parallel for
#endif
  for (int i = 0; i < array size; i++)</pre>
   a[i] = b[i] + scalar * c[i];
 #if defined(OMP_TARGET_GPU) && defined(_CRAYC)
 // If using the Cray compiler, the kernels do not block, so this update forces
  // a small copy to ensure blocking so that timing is correct
  #pragma omp target update from(a[0:0])
  #endif
```

Experimental Platforms

	Processor	Sockets	Cores	Clock GHz	FP TFLOP/s	Mem BW GB/s	STREAM Balance*
	Intel Skylake	2	8	3.70	1.89	256.0	59.2
ODU	Intel Cascade Lake	2	24	4.00	6.14	287.3	171.1
	Intel Sapphire Rapids	2	52	3.80	12.65	614.4	164.7
CPU -	AMD Rome	2	64	3.00	6.14	409.6	120.0
	AMD Milan	2	32	3.68	3.77	409.6	73.6
	ARM ThunderX2	2	28	2.20	0.99	341.2	23.1
Ĺ	IBM POWER9	2	21	3.50	1.18	340.0	27.8
	NVIDIA P100	1	56	1.19	4.76	549.1	69.4
	NVIDIA V100	1	80	1.30	7.83	897.0	69.9
GPU -	NVIDIA A100	1	108	1.07	9.75	1935.0	40.3
	AMD MI60	1	64	1.20	7.37	1024.0	57.6
	AMD MI100	1	120	1.00	11.54	1229.0	75.1
L	- AMD MI250X	1	110	1.00	23.94	1600.0	119.7



Experimental Configuration

	Processor	Operating System	GPU Driver Version	Compiler
	Intel Skylake	Ubuntu 20.04.6		clang 17.0.6
	Intel Cascade Lake	Ubuntu 22.04.3		clang 17.0.1
	Intel Sapphire Rapids	Ubuntu 22.04.3		clang 17.0.1
CPU -	AMD Rome	Ubuntu 22.04.3		clang 17.0.6
	AMD Milan	Ubuntu 22.04.3		clang 17.0.6
	ARM ThunderX2	CentOS Stream 8		clang 17.0.2
	IBM POWER9	CentOS 8.3		gcc 10.2
	NVIDIA P100	Ubuntu 20.04.6	525.147.05	nvcc 11.5
	NVIDIA V100	Ubuntu 22.04.3	550.54.15	nvcc 12.3
CDII	NVIDIA A100	Ubuntu 22.04.3	555.42.02	nvcc 12.3
GPU -	AMD MI60	Ubuntu 22.04.3	6.3.6	hipcc 5.4.3
	AMD MI100	Ubuntu 22.04.3	5.15.0-15	hipcc 5.4.3
	AMD MI250X	SUSE LES 15.4	6.3.6	hipcc 5.4.3



Chapel 2.0, Kokkos 4.2.0

BabelStream Performance Portability

BabelStream v5 triad – 2²⁸ 64-bit elements

Skylake -	118	118	-	-	118	- 1600	Skylake -	46.2%
Cascade Lake	169	168	-	-	169		Cascade Lake	
Sapphire Rapids -	485	482	-	-	484	- 1400	Sapphire Rapids	79.0%
Rome -	220	219	-	1	219	- 1200	Rome -	53.6%
Milan -	198	197	ı	ı	195		Milan -	48.4%
ThunderX2	207	208	-	-	201	- 1000	ThunderX2	60.5%
POWER9	234	234	-	-	202	- 800	POWER9	68.8%
P100 -	387	419	418	-	410		P100 -	70.6%
V100 -	760	827	822	-	808	- 600	V100 -	84.7%
A100 -	1544	1679	1685	ı	1646	- 400	A100	79.8%
MI60 -	814	803	-	815	778	400	MI60 -	79.5%
MI100 -	1016	1017	1	1012	938	- 200	MI100 -	82.7%
MI250X -	1118	1244	ı	1294	1184		MI250X -	69.9%
Bandwidth (GB/s)	OpenINR	Hollos	CUDA	HIR	Chapel		Architectural efficiency	Opening

Skylake -	46.2%	46.2%	-	-	46.3%	
Cascade Lake	58.8%	58.3%	-	-	58.7%	- 80
Sapphire Rapids	79.0%	78.5%	ı	ı	78.7%	
Rome -	53.6%	53.6%	ı	ı	53.5%	
Milan -	48.4%	48.2%	ı	ı	47.6%	- 60
ThunderX2	60.5%	60.8%	1	ı	58.8%	
POWER9	68.8%	68.8%	ı	1	59.4%	
P100 -	70.6%	76.3%	76.2%	ı	74.7%	- 40
V100 -	84.7%	92.2%	91.7%	ı	90.0%	
A100 -	79.8%	86.8%	87.1%	1	85.0%	
MI60 -	79.5%	78.4%	ı	79.6%	75.9%	- 20
MI100 -	82.7%	82.8%	1	82.3%	76.3%	
MI250X -	69.9%	77.8%	ı	80.9%	74.0%	
Architectural efficiency	OpenMR	Toklos	CUDA	HR	Chapel	

Platforms	OpenMP	Kokkos	CUDA	HIP	Chapel
All platforms	64.9%	65.8%	0	0	64.0%
Supported CPUs	57.5%	57.4%	0	0	56.1%
Supported GPUs	79.1%	82.9%	84.5%	80.9%	80.0%



miniBUDE

- Proxy app created from University of Bristol BUDE protein simulator
 - calculates energy of each ligand-protein pair in different poses (position + rotation)
 - highly arithmetically intensive: FP arithmetic & trigonometric
- Kernel is triply-nested loop over proteins, ligands, poses
 - Chapel follows CUDA decomposition: 1D kernel assigning multiple poses to thread

 requires transfer of protein, ligand, and pose data to GPU; energies to host (in Chapel, these are simple array assignments)

```
const protein = context.protein;
const ligand = context.ligand;
const forcefield = context.forcefield;
const poses: [0:int(32)..<6:int(32), 0..#nposes] real(32) = context.poses[{0..<6, gpuID*nposes..#nposes}];</pre>
```



miniBUDE Performance Portability

miniBUDE v2 – small 'bm1' input

														1	
Skylake -	457	444	-	-	488		7000	Skylake -	24.1%	23.5%	-	-	25.7%		70
Cascade Lake -	2491	2538	-	-	1032		- 6000	Cascade Lake -		41.3%	-	-	16.8%		
Sapphire Rapids -	6710	7009	-	-	1884		0000	Sapphire Rapids -	53.1%	55.4%	-	-	14.9%		- 60
Rome -	3484	3471	-	-	3026		- 5000		56.7%	56.5%	-	-	49.2%		
Milan -	2687	2652	-	-	2771			Milan -	72.6%	71.7%	-	-	74.9%		- 50
ThunderX2 -	427	432	-	-	305		- 4000	ThunderX2 -	43.3%	43.8%	-	-	31.0%		- 40
POWER9 -	33	33	-	-	501			POWER9	2.8%	2.8%	-	-	42.5%		40
P100 -	1798	2692	2790	-	2705		- 3000	P100 -	37.8%	56.5%	57.3%	-	57.2%		- 30
V100-	4018	5720	5772	-	5735			V100 -	51.3%	73.0%	73.7%	-	73.2%		
A100-	3639	4537	5087	-	5360		- 2000	A100 -	37.3%	46.5%	52.2%	-	55.0%	.	- 20
MI60 -	4436	3554	-	3739	3610			MI60 -	60.2%	48.2%	-	50.7%	49.0%		
MI100-	4288	3554	-	3761	4739		- 1000	MI100 -	37.2%	30.8%	_	32.6%	41.1%		- 10
MI250X -	4272	3694	-	3266	4969			MI250X -	17.8%	15.4%	-	13.6%	20.8%		
Performance (GFLOP/s)	OpenMR	Loiko ^s	CUDA	HR	Chapel	_		Architectural efficiency	OpenMR	Tolkos	CUDA	HIP	Chapel	1	

Platforms	OpenMP	Kokkos	CUDA	HIP	Chapel
All platforms*	43.0%	44.8%	0	0	33.8%
Supported CPUs*	43.0%	43.1%	0	0	25.9%
Supported GPUs	43.0%	47.1%	60.2%	39.7%	53.1%



^{*} Except POWER9

TeaLeaf

- Collection of iterative sparse linear solvers, simulating heat conduction over time using five-point stencils over 2D grid
- Low arithmetic intensity = better suited to low STREAM balance
- 2D index domains: expose parallelism over both loops

```
Kokkos::parallel for(
#pragma omp target teams distribute parallel for simd
                                                                   x * y, KOKKOS_LAMBDA(const int &index) {
collapse(2)
                                                                     const int kk = index % x;
for (int jj = halo depth; jj < y - halo depth; ++jj) {</pre>
                                                                     const int jj = index / x;
  for (int kk = halo_depth; kk < x - halo_depth; ++kk) {</pre>
    const int index = kk + jj * x;
                                                                     if (kk >= halo depth
    p[index] = beta * p[index] + r[index];
                                                                      && kk < x - halo depth
                                                                      && jj >= halo depth && jj < y - halo depth) {
                                                                       p(index) = beta * p(index) + r(index);
                                                                   });
[(i,j) \text{ in Domain.expand}(-halo depth)] p[i,j] = beta * p[i,j] + r[i,j];
           https://github.com/milthorpe/TeaLeaf
```

S. McIntosh-Smith, et al., <u>Tealeaf: A mini-application to enable design-space explorations for iterative sparse linear solvers</u>. IEEE International Conference on Cluster Computing (CLUSTER), 2017.



TeaLeaf - Reductions

- Many sum reductions to compute global deltas or error metrics
 - In Chapel 2.0, these must be computed in global memory

```
var temp: [reduced_local_domain] real = noinit;
Kokkos::parallel reduce(
   x * y,
   KOKKOS_LAMBDA(const int &index, double &rrn_temp) { forall oneDIdx in reduced OneD {
      const int kk = index % x;
                                                          const ij = reduced local domain.orderToIndex(oneDIdx);
      const int jj = index / x;
                                                          u[ij] += alpha * p[ij];
     if (kk >= halo depth
                                                          r[ij] -= alpha * w[ij];
                                                                                      Chapel 2.0
      && kk < x - halo depth
                                                          temp[ij] = r[ij] ** 2;
      && jj >= halo depth
      && jj < y - halo depth) {
                                                        rrn = gpuSumReduce(temp);
       u(index) += alpha * p(index);
        r(index) -= alpha * w(index);
                                                        var rrn: real;
        rrn temp += r(index) * r(index);
                                                        forall ij in reduced local domain
                                                          with (+ reduce rrn) {
    },
                                                          u[ij] += alpha * p[ij];
    *rrn);
                                                          r[ij] -= alpha * w[ij];
                                                                                      Chapel 2.x
                                                          rrn += r[ij] ** 2;
```

TeaLeaf – Chapel Multi-Dimensional Indexing

- Using 2D indices improved readability of Chapel code and performed well on CPU platforms
- However, using 2D domains reduced GPU performance due to underutilization of available GPU cores in Chapel 2.0
 - first dimension is assigned to GPU threads
 - remaining dimensions implemented as loops inside GPU kernel
- We replaced multi-dimensional loops with 1D loop over linearized space to allow full utilization of GPU cores

```
const Domain = {0..<y, 0..<x};
forall ij in Domain {
    u[ij] = energy[ij] * density[ij];
}

const Domain = {0..<y, 0..<x};
const OneD = {0..<y*x};
foreach oneDIdx in OneD {
    const ij = local_domain.orderToIndex(oneDIdx);
    u[ij] = energy[ij] * density[ij];
}</pre>
```



TeaLeaf Performance Portability

tea_bm_5.in - 4000×4000 CG solve, 10 iters

Skylake -	491	720	-	-	466	464	
Cascade Lake -	316	471	-	-	324	324	
Sapphire Rapids -	95	239	-	-	118	116	- 4000
Rome -	149	530	-	-	165	166	
Milan -	246	770	-	-	269	265	2000
ThunderX2 -	413	864	-	-	400	403	- 3000
POWER9-	743	4781	-	-	361	360	
P100 -	281	246	177	-	2574	4133	- 2000
V100-	149	129	96	-	544	3540	
A100-	131	69	50	-	314	3430	
MI60 -	164	115	-	251	297	4911	- 1000
MI100 -	148	111	-	233	231	2310	
MI250X -	143	79	-	73	169	2034	
Runtime (s)	OpenMR	Tolkos	CUDA	HR	Chapel	Chapel ID	

							100
Skylake -	94.4%	64.4%	-	-	99.5%	100%	100
Cascade Lake	100%	67.1%	-	-	97.7%	97.7%	
Sapphire Rapids	100%	39.9%	-	-	80.5%	81.9%	- 80
Rome	100%	28.1%	-	-	90.4%	89.7%	
Milan -	100%	31.9%	-	-	91.4%	92.8%	
ThunderX2	96.9%	46.3%	-	-	100%	99.2%	- 60
POWER9	48.4%	7.5%	-	-	99.8%	100%	
P100 -	63.1%	72.0%	100%	-	6.9%	4.3%	- 40
V100 -	64.3%	74.3%	100%	-	17.6%	2.7%	
A100	38.1%	72.5%	100%	-	15.9%	1.5%	
MI60 -	70.3%	100%	-	45.9%	38.8%	2.3%	- 20
MI100 -	75.4%	100%	-	47.8%	48.1%	4.8%	
MI250X -	51.2%	93.1%	-	100%	43.4%	3.6%	
				- \oldsymbol{O}			
Application	OpeniMP	Tolkos	CUDA	HIP	Chapel	Chapel 2D	
r reprioation	000	10,	$\mathcal{O}_{\mathbf{c}}$		CA	2220	
efficiency	O '					Ch	

Platforms	OpenMP	Kokkos	CUDA	HIP	Chapel	Chapel 2D
All platforms	69.8%	37.3%	0	0	31.5%	5.7%
Supported CPUs	85.8%	25.3%	0	0	93.7%	94.0%
Supported GPUs	57.3%	83.5%	100.0%	56.9%	17.8%	2.7%



Conclusions

- \bullet Pennycook, Sewall and Lee's metric \P remains a useful lens for evaluating portable programming models and identifying areas of strength and weakness
- Performance portability of OpenMP and Kokkos continues to improve
- Chapel compares favourably for performance-portable parallel programming
 - concise code
 - (mostly) good performance across a wide range of platforms
 - easier path to multi-device, multi-node distribution
- Some issues remain with Chapel GPU code generation
 - fixing these will avoid performance pitfalls for users



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