



# Chapel: Data Parallelism





## Data vs. Task Parallelism (Our Definitions)

#### **Data Parallelism:**

- parallelism is driven by collections of data
  - data aggregates (arrays)
  - sets of indices (ranges, domains)
  - other user-defined collections
- e.g., "for all elements in array A ..."

#### **Task Parallelism:**

- parallelism is expressed in terms of distinct computations
- e.g., "create a task to do foo() while another does bar()"

(Of course, data parallelism is executed using tasks and task parallelism typically operates on data, so the line can get fuzzy at times...)







# "Hello World" in Chapel: a Data Parallel Version

#### Data Parallel Hello World

```
config const numIters = 100000;
forall i in 1..numIters do
 writeln("Hello, world! ",
          "from iteration ", i, " of ", numIters);
```





### Outline



- Domains and Arrays
  - Rectangular Domains and Arrays
  - Iterations and Operations
- Other Domain Types
- Reductions and Scans
- Jacobi Iteration Example





#### **Domains**



#### **Domain:** A first-class index set

- A fundamental Chapel concept for data parallelism
- A generalization of ZPL's region concept
- Domains may optionally be distributed

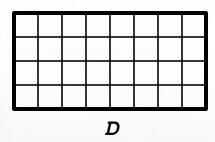








```
config const m = 4, n = 8;
```





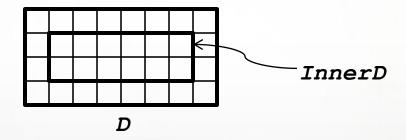
# Sample Domains



```
config const m = 4, n = 8;

var D: domain(2) = [1..m, 1..n];

var InnerD: subdomain(D) = [2..m-1, 2..n-1];
```







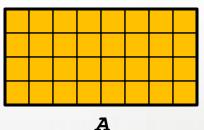
# **Domains Define Arrays**

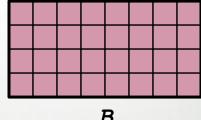


Syntax

```
array-type:
  [ domain-expr ] elt-type
```

- Semantics
  - Stores element for each index in domain-expr
- Example





Earlier example, revisited

```
var A: [1..3, 1..5] real; // [1..3, 1..5] is an
                          // anonymous domain
```



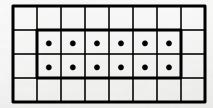
#### **Domain Iteration**



- For loops (discussed already)
  - Execute loop body once per domain index, serially

1	2	3	4	5	6	
7	8	9	10	11	12	

- Forall loops
  - Executes loop body once per domain index, in parallel
  - Loop must be *serializable* (executable by one task)



Loop variables take on const domain index values



# Other Forall Loops



### Forall loops also support...

A shorthand notation:

• Expression-based forms:

1.1	1.2	1.3	1.4	1.5	1.6	1.7	1.8
2.1	2.2	2.3	2.4	2.5	2.6	2.7	2.8
3.1	3.2	3.3	3.4	3.5	3.6	3.7	3.8
4.1	4.2	4.3	4.4	4.5	4.6	4.7	4.8

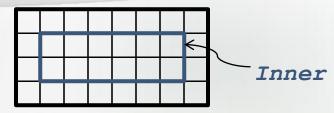
A



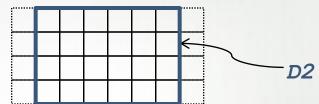
# Domain Algebra

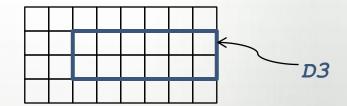


### Domain values support...



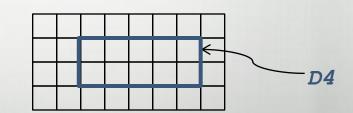
Methods for creating new domains





Intersection via Slicing

Range operators (e.g., #, by)



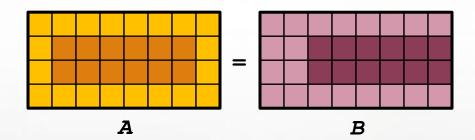








Indexing into arrays with domain values results in a sub-array expression (an "array slice")





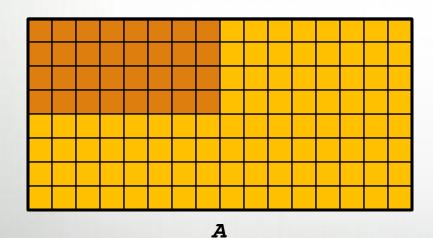
# **Array Reallocation**

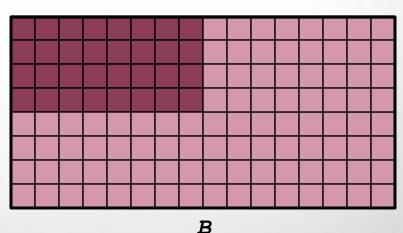


### Reassigning a domain logically reallocates its arrays

values are preserved for common indices

$$D = [1..2*m, 1..2*n];$$





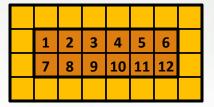


# **Array Iteration**

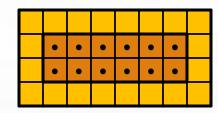


Array expressions also support for and forall loops

for a in A[InnerD] do ...



forall a in A[InnerD] do ...



Array loop indices refer to array variables (modifiable)

forall 
$$(a_{i,j})$$
 in  $(A, D)$  do  $a = i + j/10.0$ ;

Note that forall loops support zippered iteration, like for-loops

1.1	1.2	1.3	1.4	1.5	1.6	1.7	1.8
2.1	2.2	2.3	2.4	2.5	2.6	2.7	2.8
3.1	3.2	3.3	3.4	3.5	3.6	3.7	3.8
4.1	4.2	4.3	4.4	4.5	4.6	4.7	4.8





# **Array Indexing**



 Arrays can be indexed using variables of their domain's index type (e.g., tuples) or lists of integers

```
var i = 1, j = 2;
var ij = (i,j);

A[ij] = 1.0;
A[i, j] = 2.0;
```

Array indexing can use either parentheses or brackets

$$A(ij) = 3.0;$$
  
 $A(i, j) = 4.0;$ 

# **Array Arguments and Aliases**



Arrays are passed by reference by default

```
proc zero(X: []) { X = 0; }
zero(A[InnerD]); // zeroes the inner values of A
```

Formal array arguments can reindex actuals

```
proc f(X: [1..b,1..b]) { ... } // X uses 1-based indices
f(A[lo..#b, lo..#b]);
```

Array alias declarations provide similar functionality

```
var InnerA => A[InnerD];
var InnerA1: [1..n-2,1..m-2] => A[2..n-1,2..m-1];
```







## **Promoted Functions and Operators**

Functions/operators expecting scalars can also take...

...arrays, causing each element to be passed in

...domains, causing each index to be passed in

Multiple arguments promote using zipper promotion





# Data Parallelism is Implicit



- forall loops are implemented using multiple tasks
  - details depend on what is being iterated over
- so are operations that are equivalent to forall loops
  - promoted operators/functions, whole array assignment, ...
- many times, this parallelism can seem invisible
  - for this reason, Chapel's data parallelism can be considered implicitly parallel
  - it also tends to make the data parallel features easier to use and less likely to result in bugs as compared to explicit tasks



### How Much Parallelism?



# By default\*, controlled by three configuration variables:

#### --dataParTasksPerLocale=#

- Specify # of tasks to execute forall loops
- Current Default: number of processor cores

# --dataParlgnoreRunningTasks=[true|false]

- If false, reduce # of forall tasks by # of running tasks
- Current Default: true

### --dataParMinGranularity=#

- If > 0, reduce # of forall tasks if any task has fewer iterations
- Current Default: 1





### Outline



- Domains and Arrays
- Other Domain Types
  - Strided
  - Sparse
  - Associative
  - Opaque
- Reductions and Scans
- Jacobi Iteration Example

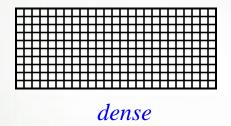


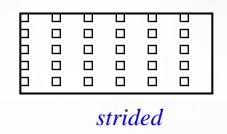


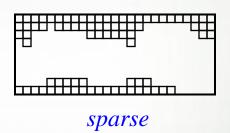


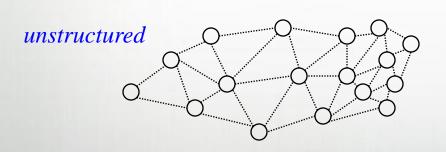
### Chapel supports several domain types...

```
var OceanSpace = [0..#lat, 0..#long],
   AirSpace = OceanSpace by (2,4),
   IceSpace: sparse subdomain(OceanSpace) = genCaps();
```









associative



var Vertices: domain(opaque) = ..., People: domain(string) = ...;



## **Chapel Array Types**

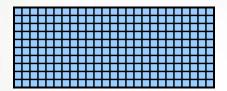


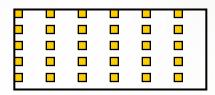
# All domain types can be used to declare arrays...

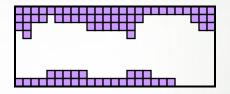
var Ocean: [OceanSpace] real,

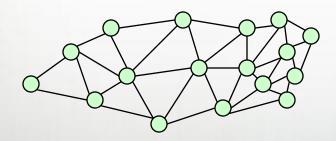
Air: [AirSpace] real,

IceCaps[IceSpace] real;









var Weight: [Vertices] real,



Age: [People] int;

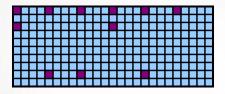


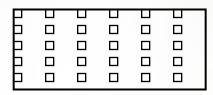
#### **Iteration**

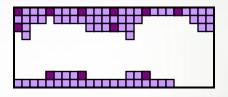


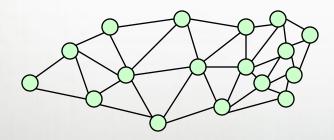
### ...to iterate over index sets...

forall ij in AirSpace do
Ocean[ij] += IceCaps[ij];









forall v in Vertices do
Weight[v] = numEdges[v];



forall p in People do
Age[p] += 1;

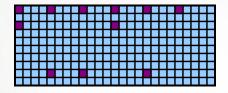


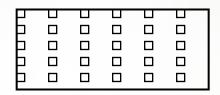
# Slicing

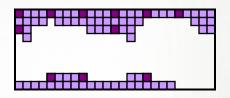


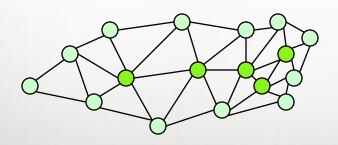
## ...to slice arrays...

Ocean[AirSpace] += IceCaps[AirSpace];











...Vertices[Interior]...

...People[Interns]...



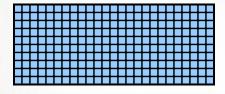


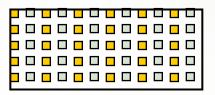
#### Reallocation

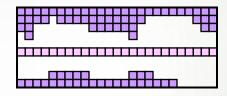


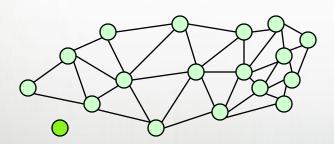
### ...and to reallocate arrays

```
AirSpace = OceanSpace by (2,2);
IceSpace += genEquator();
```











newnode = Vertices.create();





### Associative Domains and Arrays by Example

```
var Presidents: domain(string) =
      ("George", "John", "Thomas",
       "James", "Andrew", "Martin");
Presidents += "William";
var Age: [Presidents] int,
    Birthday: [Presidents] string;
Birthday["George"] = "Feb 22";
forall president in President do
  if Birthday[president] == today then
    Age[president] += 1;
```

George
John
Thomas
James
Andrew
Martin
William

#### Presidents



Birthday

Age



### Outline



- Domains and Arrays
- Other Domain Types
- Reductions and Scans
- Jacobi Iteration Example





### Reductions



### Syntax

```
reduce-expr:
reduce-op reduce iterator-expr
```

- Semantics
  - Combines argument values using reduce-op
  - Reduce-op may be built-in or user-defined

### Examples

```
total = + reduce A;
bigDiff = max reduce [i in InnerD] abs(A[i]-B[i]);
(minVal, minLoc) = minloc reduce (A, D);
```



#### Scans



### Syntax

```
scan-expr:
scan-op scan iterator-expr
```

#### Semantics

- Computes parallel prefix over values using scan-op
- Scan-op may be any reduce-op

### Examples

```
var A, B, C: [1..5] int;
A = 1;
B = + scan A;
B[3] = -B[3];
C = min scan B;
// C: 1 1 -3 -3 -3
```



# **Reduction and Scan Operators**



- Built-in
  - +, \*, &&, ||, &, |, ^, min, max
  - minloc, maxloc
    - Takes a tuple of values and indices
    - Generates a tuple of the min/max value and its index
- User-defined
  - Defined via a class that supplies a set of methods
  - Compiler generates code that calls these methods
  - Based on:

S. J. Deitz, D. Callahan, B. L. Chamberlain, and L. Snyder. *Global-view abstractions for user-defined reductions and scans*. In Proceedings of the Eleventh ACM SIGPLAN Symposium on Principles and Practices of Parallel Programming, 2006.





### Outline



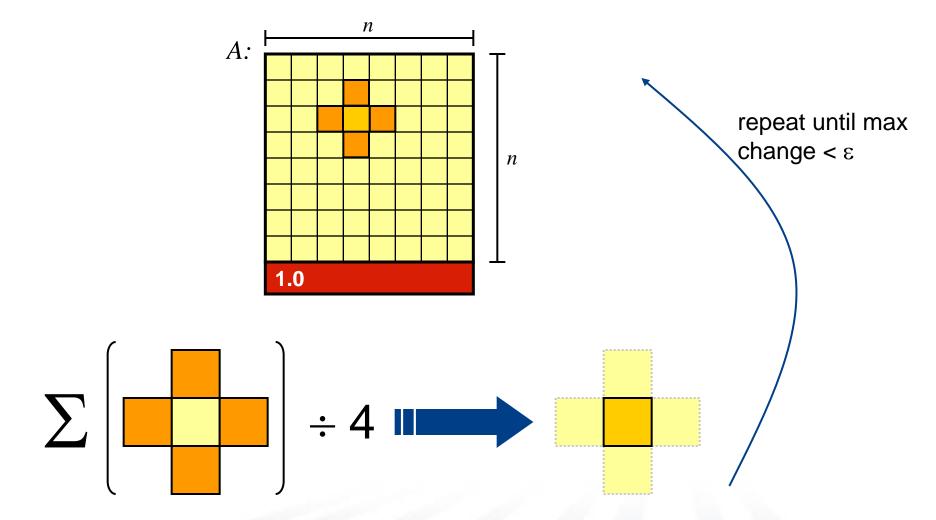
- Domains and Arrays
- Other Domain Types
- Reductions and Scans
- Jacobi Iteration Example







### **Jacobi Iteration in Pictures**









```
config const n = 6,
              epsilon = 1.0e-5;
const BigD: domain(2) = [0..n+1, 0..n+1],
         D: subdomain (BigD) = [1..n, 1..n],
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
A[LastRow] = 1.0;
do {
  [(i,j) \text{ in } D] \text{ Temp}(i,j) = (A[i-1,j] + A[i+1,j])
                            + A[i,j-1] + A[i,j+1]) / 4;
  const delta = max reduce abs(A[D] - Temp[D]);
  A[D] = Temp[D];
} while (delta > epsilon);
writeln(A);
```







```
config const n = 6,
               epsilon = 1.0e-5;
const BiqD: domain(2) = [0..n+1, 0..n+1],
          D: subdomain (BigD) = [1..n, 1..n],
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BigD] real;
       Declare program parameters
A[Las
      const ⇒ can't change values after initialization
       config ⇒ can be set on executable command-line
               prompt> jacobi --n=10000 --epsilon=0.0001
  con
      note that no types are given; inferred from initializer
               n \Rightarrow default integer (32 bits)
 whi
               epsilon ⇒ default real floating-point (64 bits)
writeln(A);
```





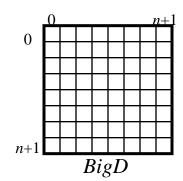


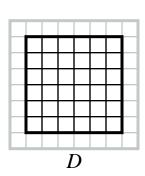
```
config const n = 6,
             epsilon = 1.0e-5;
const BigD: domain(2) = [0..n+1, 0..n+1],
         D: subdomain(BiqD) = [1..n, 1..n], —
  LastRow: subdomain(BigD) = D.exterior(1,0);
```

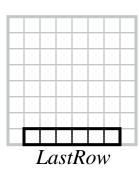
#### **Declare domains (first class index sets)**

**domain(2)** ⇒ 2D arithmetic domain, indices are integer 2-tuples

**subdomain(P)**  $\Rightarrow$  a domain of the same type as P whose indices are guaranteed to be a subset of P's







**exterior** ⇒ one of several built-in domain generators





4;

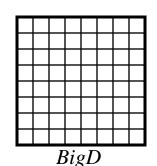


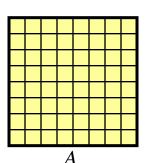
```
config const n = 6,
             epsilon = 1.0e-5;
const BigD: domain(2) = [0..n+1, 0..n+1],
         D: subdomain (BigD) = [1..n, 1..n],
  LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real; _____
```

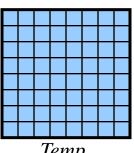
A[LastRow] = 1.0;

#### **Declare arrays**

var ⇒ can be modified throughout its lifetime : [BigD] T ⇒ array of size BigD with elements of type T (no initializer)  $\Rightarrow$  values initialized to default value (0.0 for reals)







**Temp** 



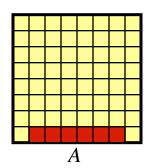


4;



#### **Set Explicit Boundary Condition**

indexing by domain ⇒ slicing mechanism array expressions ⇒ parallel evaluation





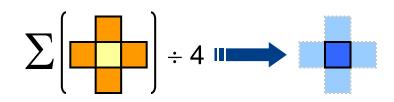




```
config const n = 6,
             epsilon = 1.0e-5;
```

#### **Compute 5-point stencil**

 $[(i,j) \text{ in } D] \Rightarrow \text{ parallel for all expression over } D$ 's indices, binding them to new variables *i* and *j* 



```
[(i,j) \text{ in } D] \text{ Temp}(i,j) = (A[i-1,j] + A[i+1,j])
                             + A[i,j-1] + A[i,j+1]) / 4;
  const delta = max reduce abs(A[D] - Temp[D]);
  A[D] = Temp[D];
} while (delta > epsilon);
writeln(A);
```







#### **Compute maximum change**

*op* reduce ⇒ collapse aggregate expression to scalar using *op* 

**Promotion:** abs() and – are scalar operators, automatically promoted to work with array operands







```
config const n = 6,
              epsilon = 1.0e-5;
const BiqD: domain(2) = [0..n+1, 0..n+1],
          D: subdomain (BiqD) = [1..n, 1..n],
   LastRow: subdomain(BigD) = D.exterior(1,0);
    Copy data back & Repeat until done
A [La uses slicing and whole array assignment
    standard do...while loop construct
do
  [(i,j) in D] Temp(i,j) = (A[i-1,j] + A[i+1,j])
                            + A[i,j-1] + A[i,j+1]
  const delta = max reduce abs(A[D]         Temp[D]);
  A[D] = Temp[D];
} while (delta > epsilon);
writeln(A);
```







```
config const n = 6,
            epsilon = 1.0e-5;
const BiqD: domain(2) = [0..n+1, 0..n+1],
        D: subdomain (BiqD) = [1..n, 1..n],
  LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
A[LastRow] = 1.0;
                                 Write array to console
do {
 [(i,j) \text{ in } D] \text{ Temp}(i,j) = (A[i-1,j] + A[i+1,j])
                        + A[i,j-1] + A[i,j+1])
  A[D] = Temp[D];
} while (delta > epsilo
writeln(A);
```

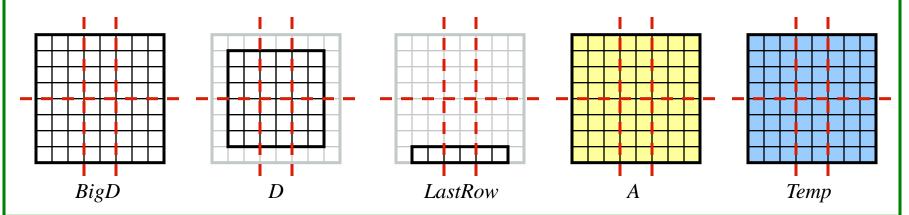






With this change, same code runs in a distributed manner Domain distribution maps indices to *locales* 

⇒ decomposition of arrays & default mapping of iterations to locales
Subdomains inherit parent domain's distribution









```
config const n = 6,
              epsilon = 1.0e-5;
const BigD = [0..n+1, 0..n+1] dmapped Block (...),
         D: subdomain (BiqD) = [1..n, 1..n],
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
A[LastRow] = 1.0;
do {
  [(i,j) \text{ in } D] \text{ Temp}(i,j) = (A[i-1,j] + A[i+1,j])
                            + A[i,j-1] + A[i,j+1]) / 4;
  const delta = max reduce abs(A[D] - Temp[D]);
  A[D] = Temp[D];
} while (delta > epsilon);
writeln(A);
```





### Data Parallelism: Status



- Most features implemented and working correctly
- Scalar performance not optimal for higherdimensional domain/array operations
- Implementation of unstructured domains/arrays is correct but inefficient





### **Future Directions**



 Gain more experience with unstructured (graphbased) domains and arrays





### **Questions?**



- Domains and Arrays
  - Regular Domains and Arrays
  - Iterations and Operations
- Other Domain Types
  - Strided
  - Sparse
  - Associative
  - Opaque
- Data Parallel Operations
  - Reductions
  - Scans
- Jacobi Iteration Example

