

# CHAPEL LULESH

Episodes IV, V, and VI

SC12: November 14<sup>th</sup>, 2012

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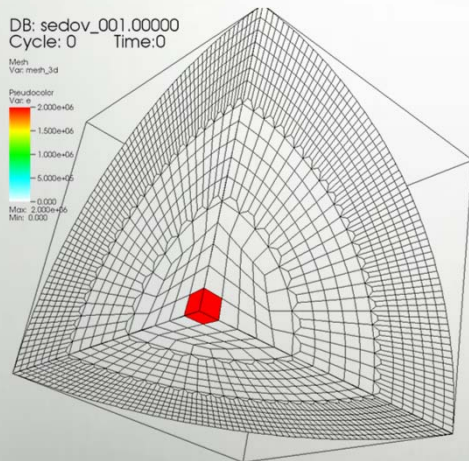


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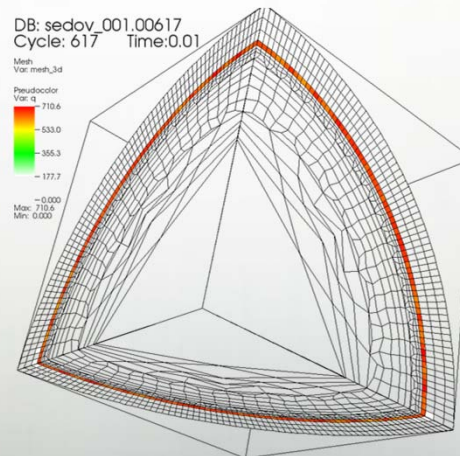


## LULESH:

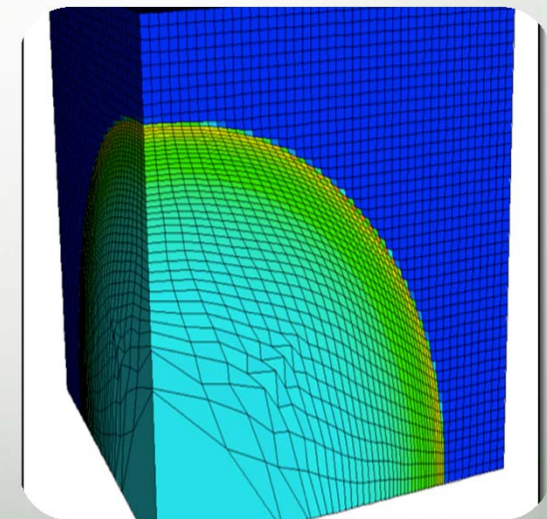
- Livermore Unstructured Lagrangian Explicit Shock Hydrodynamics challenge problem
- developed by LLNL under DARPA UHPC
- serves as a proxy app for key computation patterns
- <https://computation.llnl.gov/casc/ShockHydro/>



user: keasler  
Thu Apr 12 11:56:04 2012



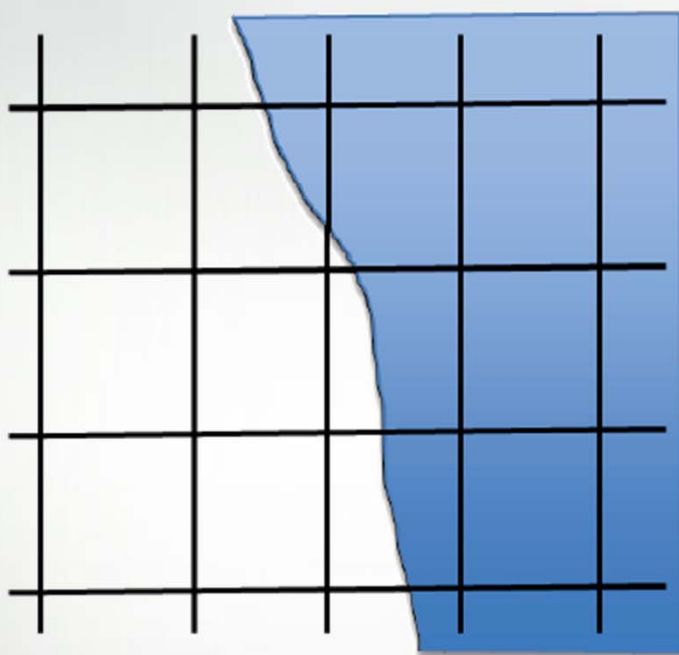
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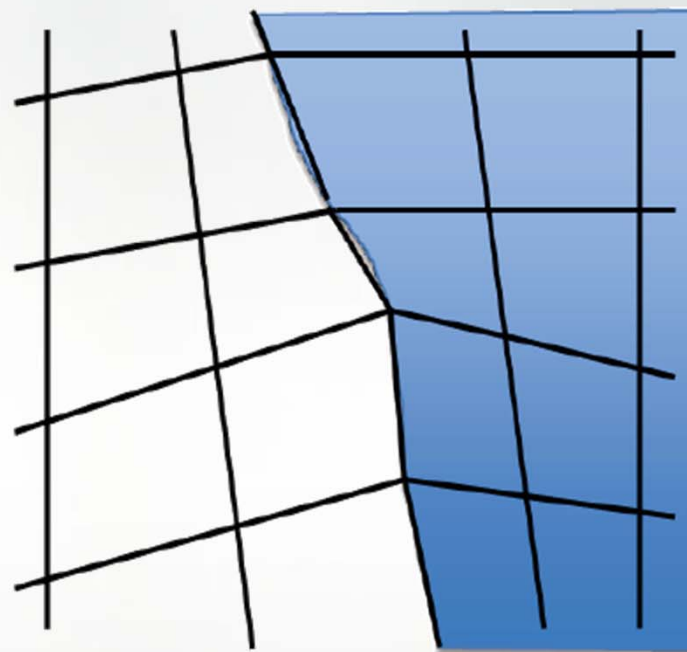
pictures courtesy of Rob Neely, Bert Still, Jeff Keasler, LLNL



# Eulerian vs. Lagrangian Meshes



Eulerian mesh  
(grid stays fixed)



Lagrangian mesh  
(grid adapts to materials)

Image Source: LULESH specification, LLNL-TR-490254  
<https://computation.llnl.gov/casc/ShockHydro/>



# Episode IV

## A New Hope

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# LULESH Co-Design History: Cray/LLNL

**Apr 2011:** LLNL expresses interest in Chapel at Salishan

- made us aware of the LULESH benchmark

**Summer 2011:** Cray intern ports LULESH to Chapel

- *caveat:* used structured mesh to represent data arrays



# Episode V

## Chapel Strikes Back

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**Nov 2011:** Chapel team tunes LULESH for single-node performance

**Dec 2011:** Chapel team visits LLNL (talk, tutorial, 1-on-1 sessions)

**Mar 2012:** Jeff Keasler (LLNL) visits Cray to pair-program

- in one afternoon, converted from structured to unstructured mesh
- impact on code minimal (mostly in declarations) due to:
  - domains/arrays/iterators
  - rank-independent features



# Episode VI

## Return of the Salishan

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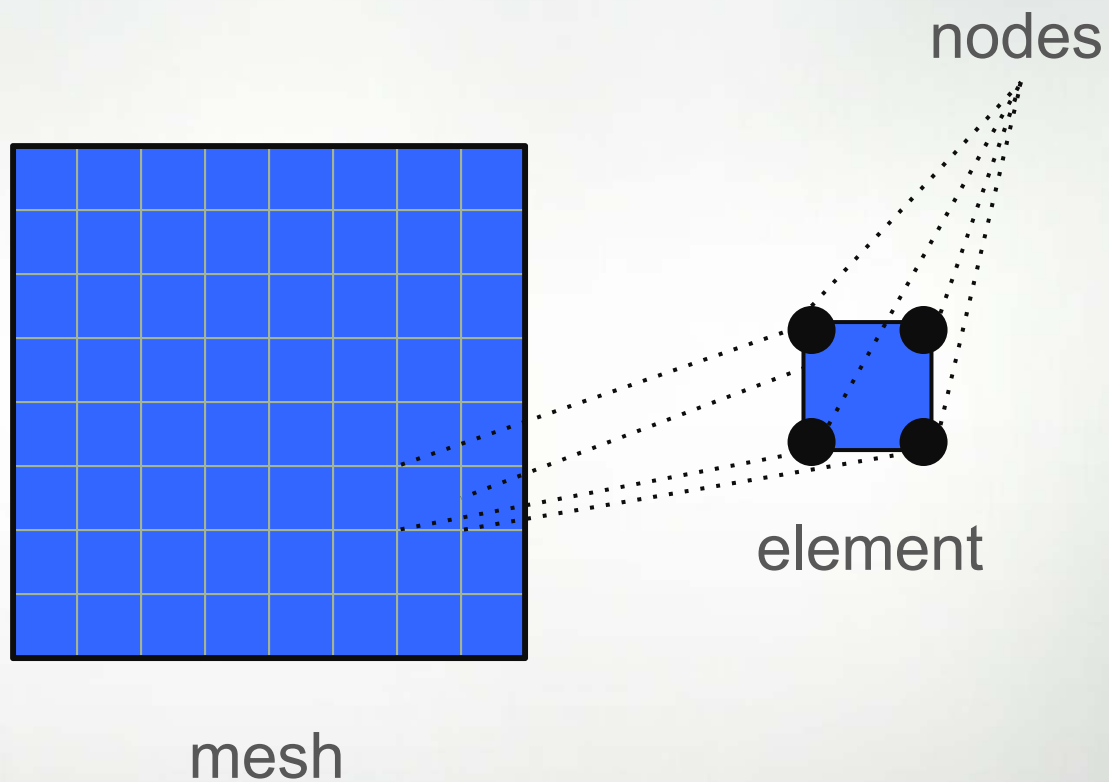
**Apr 2012:** LLNL reports on collaboration at Salishan

**Apr 2012:** Chapel 1.5.0 release includes LULESH as an example code

**Sep-Nov 2012:** performance tuning, initial distributed sparse domains



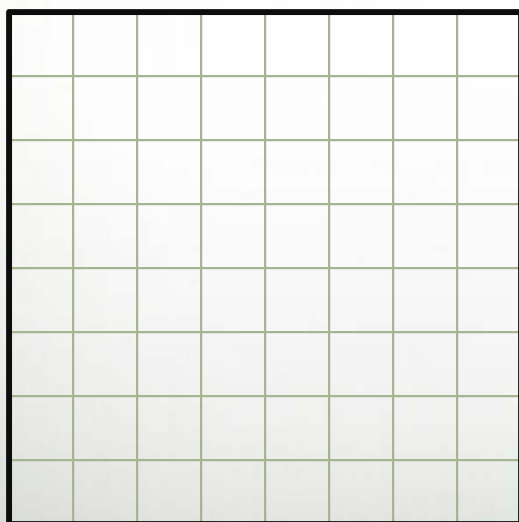
# Fundamental LULESH concepts/terminology



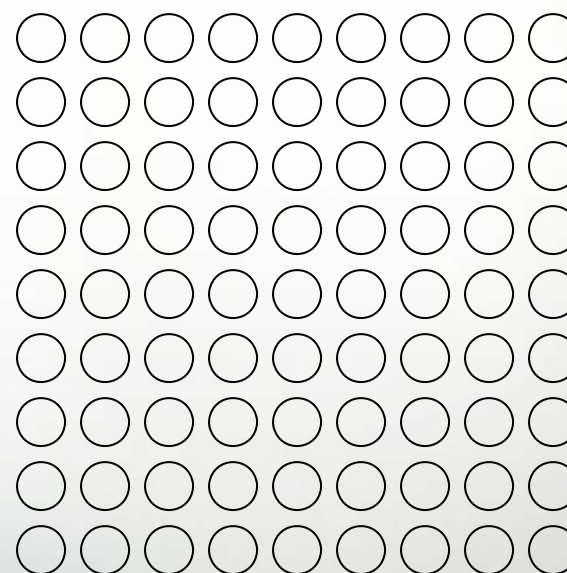
# Representation of Concepts in Chapel

- Abstract Element and Node *Domains* (Views):

```
const nodesPerEdge = elemsPerEdge+1;
const ElemSpace = {0..#elemsPerEdge, 0..#elemsPerEdge},
      NodeSpace = {0..#nodesPerEdge, 0..#nodesPerEdge};
```



*ElemSpace*

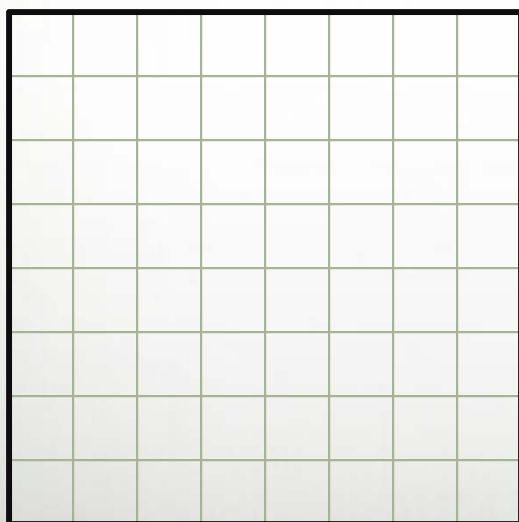


*NodeSpace*

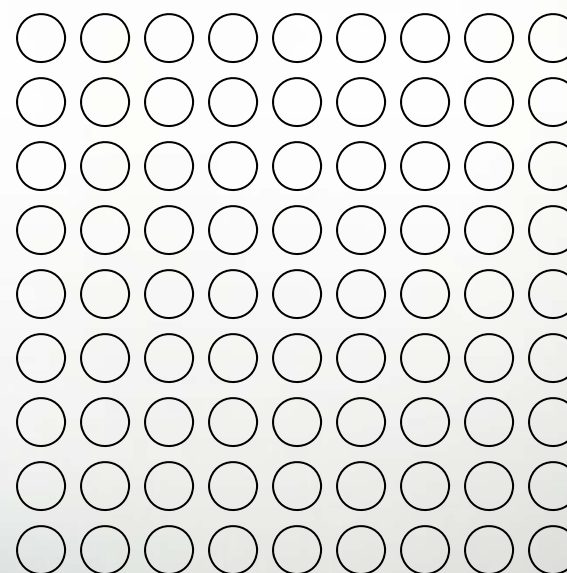
# Representation of Concepts in Chapel

- Abstract Element and Node *Domains* (Views):

```
const ElemSpace = {0..#numElems},  
      NodeSpace  = {0..#numNodes};
```



*ElemSpace*

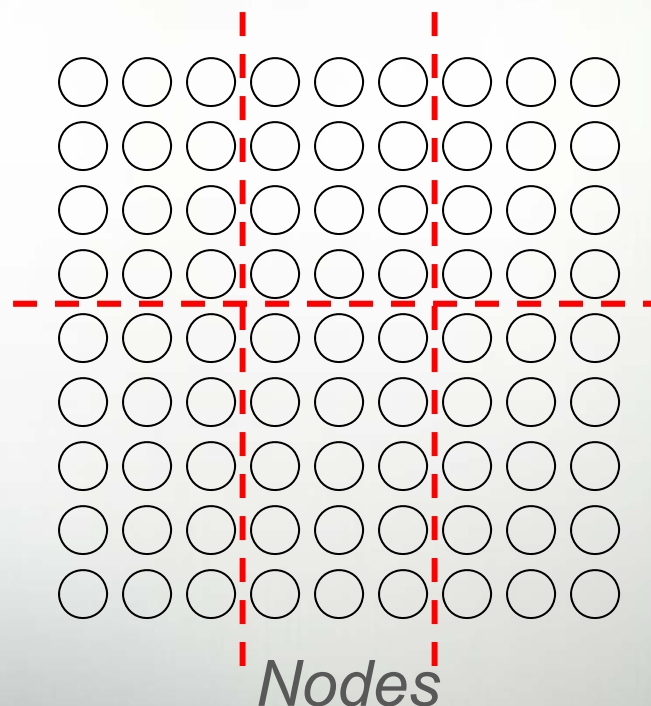
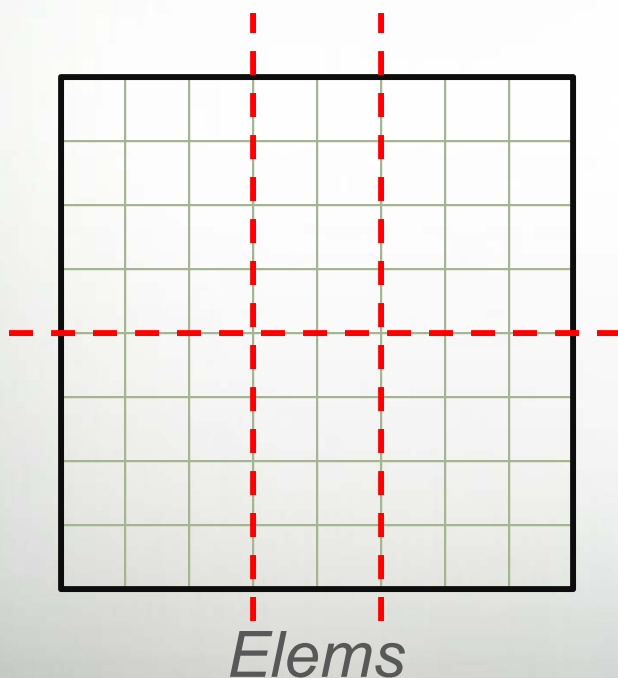


*NodeSpace*

# Representation of Concepts in Chapel

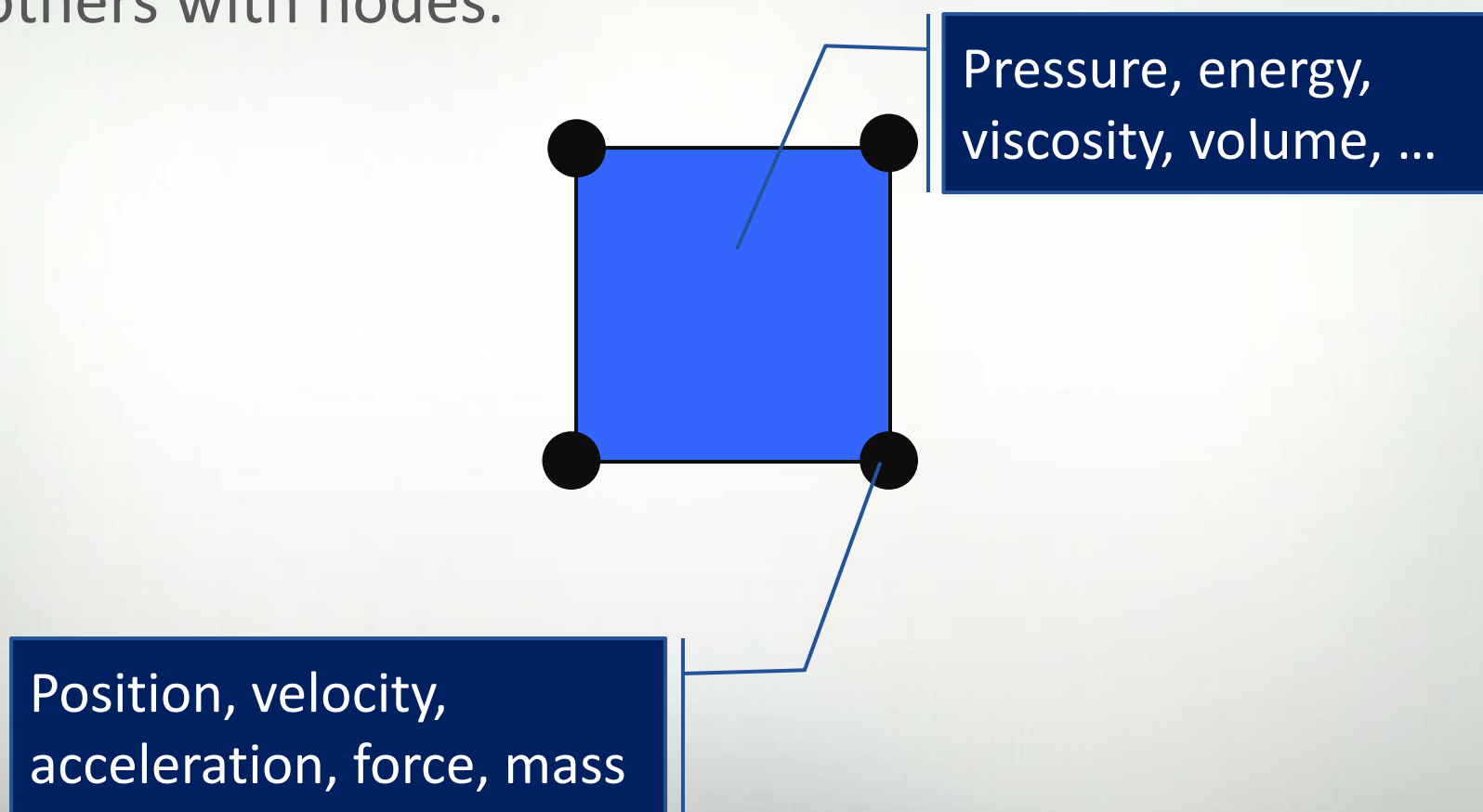
- Distributed Element/Node Domains:

```
const Elms = ElemSpace dmapped Block(ElemSpace),  
      Nodes = NodeSpace dmapped Block(NodeSpace);
```



# Element vs. Node Fields

- Some variables (*fields*) are associated with elements, others with nodes.



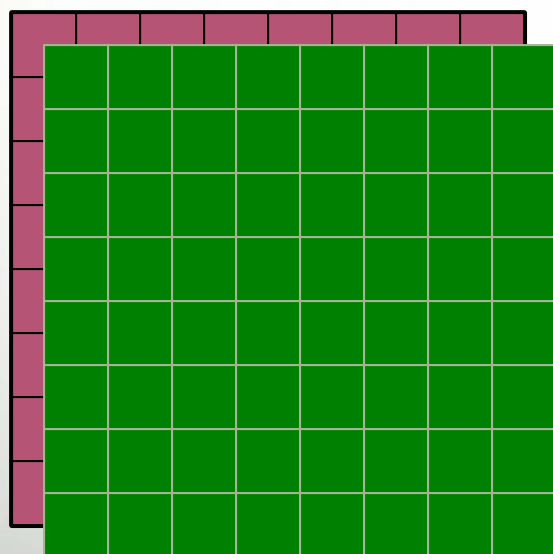


# Representation of Fields in Chapel

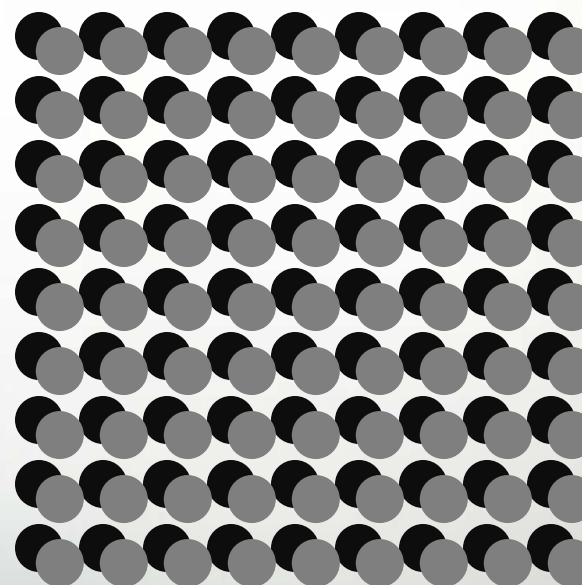
- Sample field declarations:

```
var x, y, z: [Nodes] real;
```

```
var e, p: [Elms] real;
```



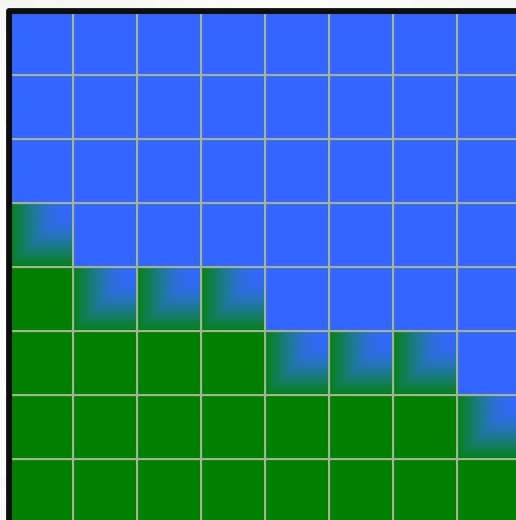
$e, p$



$x, y, z$

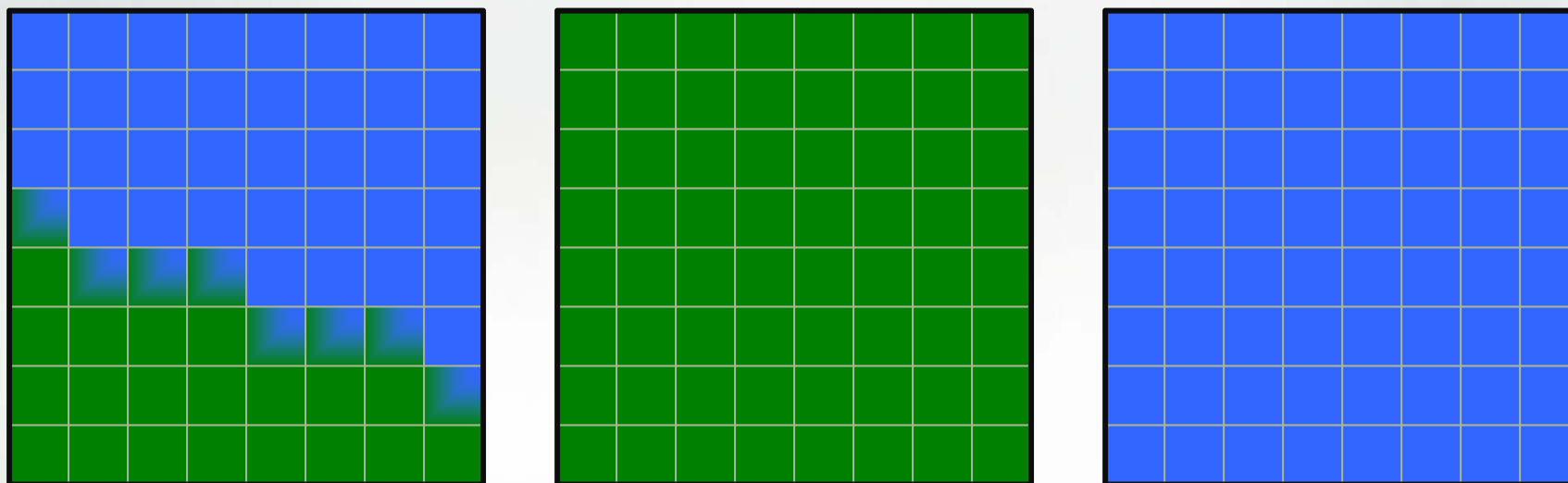
# Materials

- LULESH models the behavior of materials within the elements



not all elements will contain all materials,  
and some will contain combinations

# Materials

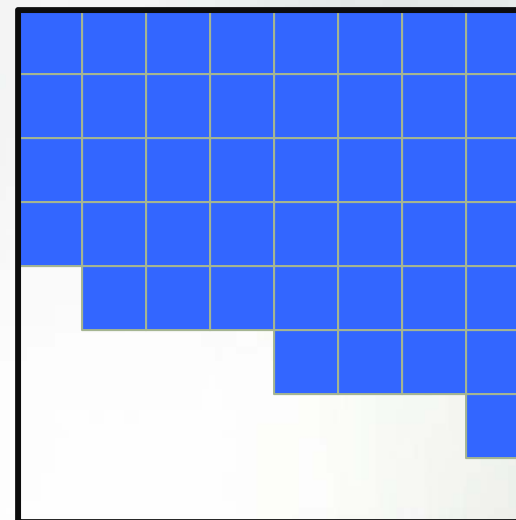
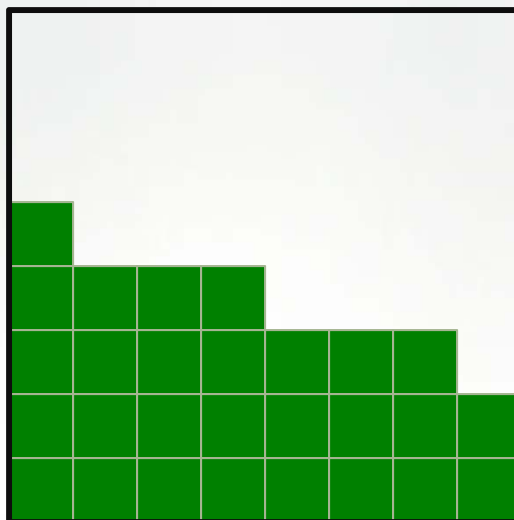
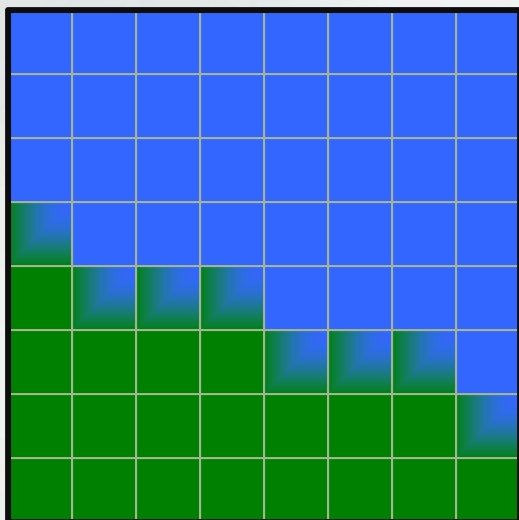


naïve approach: store all materials everywhere  
 (reasonable for LULESH, but not in practice)

```
const Mat1Elems = Elems,  

      Mat2Elems = Elems;
```

# Materials



improved approach: use sparse subdomains to  
only store materials where necessary

```
var Mat1Elems: sparse subdomain(Elems) = enumerateMat1Locs(),  
    Mat2Elems: sparse subdomain(Elems) = enumerateMat2Locs();
```

# The Physics

```

proc CalcKinematicsForElems(dxx, dyy, dzz, const dt: real) {
  // loop over all elements
  forall k in Elems {
    var b_x, b_y, b_z: 8*real,
        d: 6*real,
        detJ: real;

    //get nodal coordinates from global arrays and copy into local arrays
    var x_local, y_local, z_local: 8*real;
    localizeNeighborNodes(k, x, x_local, y, y_local, z, z_local);

    //get nodal velocities from global arrays and copy into local arrays
    var xd_local, yd_local, zd_local: 8*real;
    localizeNeighborNodes(k, xd, xd_local, yd, yd_local, zd, zd_local);
    var dt2 = 0.5 * dt; //wish this was local, too...

    local {
      //volume calculations
      const volume = CalcElemVolume(x_local, y_local, z_local);
      const relativeVolume = volume / volo.localAccess[k];
      vnew.localAccess[k] = relativeVolume;
      delv.localAccess[k] = relativeVolume - v.localAccess[k];

      //set characteristic length
      arealg.localAccess[k] = CalcElemCharacteristicLength(x_local, y_local,
                                                           z_local, volume);

      for param i in 1..8 {
        x_local[i] -= dt2 * xd_local[i];
        y_local[i] -= dt2 * yd_local[i];
        z_local[i] -= dt2 * zd_local[i];
      }

      CalcElemShapeFunctionDerivatives(x_local, y_local, z_local,
                                       b_x, b_y, b_z, detJ);

      CalcElemVelocityGradient(xd_local, yd_local, zd_local, b_x, b_y, b_z,
                              detJ, d);
    }

    // put velocity gradient quantities into their global arrays.
    dxx.localAccess[k] = d[1];
    dyy.localAccess[k] = d[2];
    dzz.localAccess[k] = d[3];
  }
}

```



# The Physics

```

proc CalcKinematicsForElems(dxx, dyy, dzz, const dt: real) {
  // loop over all elements
  forall k in Elems {
    var b_x, b_y, b_z: 8*real,
        d: 6*real,
        detJ: real;

    //get nodal coordinates from global arrays and copy into local arrays
    var x_local, y_local, z_local: 8*real;
    localizeNeighborNodes(k, x, x_local, y, y_local, z, z_local);

    //get nodal velocities from global arrays and copy into local arrays
    var xd_local, yd_local, zd_local: 8*real;
    localizeNeighborNodes(k, xd, xd_local, yd, yd_local, zd, zd_local);
    var dt2 = 0.5 * dt; //wish this was local, too...

    local {
      //volume calculations
      const volume = CalcElemVolume(x_local, y_local, z_local);
      const relativeVolume = volume / volo.localAccess[k];
      vnew.localAccess[k] = relativeVolume;
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      //set characteristic length
      arealg.localAccess[k] = CalcElemCharacteristicLength(x_local, y_local,
                                                           z_local, volume);

      for param i in 1..8 {
        x_local[i] -= dt2 * xd_local[i];
        y_local[i] -= dt2 * yd_local[i];
        z_local[i] -= dt2 * zd_local[i];

        shapeFunctionDerivatives(x_local, y_local, z_local,
                                  b_x, b_y, b_z, detJ);
        CalcElemVelocityGradient(xd_local, yd_local, zd_local, b_x, b_y, b_z,
                                 detJ, d);
      }

      // put velocity gradient quantities into their global arrays.
      dxx.localAccess[k] = d[1];
      dyy.localAccess[k] = d[2];
      dzz.localAccess[k] = d[3];
    }
  }
}

```

Representation-  
Independent Physics!





## LULESH in Chapel

- physics code (all but ~25 lines) unchanged when switching...
  - ...from 3D regular- vs. 1D irregular-mesh
  - ...from dense vs. sparse materials elements representation
- great demonstration of domain maps, rank independent syntax
- LLNL application scientists notably impressed



## Why We <3 LULESH

- Access to expert knowledge for a code that people actually care about
  - Tips on performance tuning
- Feedback on the language
- Ideas for new sparse data structures
- New challenges to the language



# Episode VII

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# The Next Steps: PERFORMANCE

- LULESH-specific
  - tuples
  - array-of-structs vs. struct-of-arrays
- General
  - Reductions
    - ~50% of the per cycle time at 64 locales
  - Communication optimizations
    - aggregation
    - overlap
    - floating point atomics (when AMOs not available)



## Will there be an Episode VII?

- LULESH-specific **[NOT FUNDED]**
  - tuples
  - array-of-structs vs. struct-of-arrays
- General **[POTENTIALLY FUNDED]**
  - Reductions
    - ~50% of the per cycle time at 64 locales
  - Communication optimizations
    - aggregation
    - overlap
    - floating point atomics (when AMOs not available)



# Benchmark Sources

## LULESH:

- in Chapel release: `$CHPL_HOME/examples/benchmarks/lulesh/`
- In Subversion tree:
  - Elegant version:
    - <https://chapel.svn.sourceforge.net/svnroot/chapel/trunk/test/release/examples/benchmarks/lulesh/>
  - Performance studies version:
    - <https://chapel.svn.sourceforge.net/svnroot/chapel/trunk/test/studies/lulesh/bradc/lulesh-dense.chpl>

(Recipes for compiler/execution/environment options for our performance results available by request)





## Chapel at SC12 (see [chapel.cray.com/events.html](http://chapel.cray.com/events.html) for details)

- ✓ **Sun:** Chapel tutorial (8:30am)
- ✓ **Mon:** 3<sup>rd</sup> Annual Chapel Users Group (CHUG) Meeting
- ✓ **Tues:** HPC Challenge BoF (12:15pm)
- ✓ **Wed:** Chapel Lightning Talks BoF (12:15pm)
- ✓ **Wed:** Chapel talk at KISTI booth (~3-4pm)
- ✓ **Wed:** HPCS BoF (5:30pm)
- **Wed:** Proxy Applications for Exascale BoF (5:30pm)
- **Thurs:** HPC Educators Forum on Chapel (1:30pm)



# Resources For After Today

**Chapel project page:** <http://chapel.cray.com>

- overview, papers, presentations, language spec, ...

**Chapel SourceForge page:** <https://sourceforge.net/projects/chapel/>

- release downloads, public mailing lists, code repository, ...

## IEEE TCSC Blog Series:

- [\*Myths About Scalable Parallel Programming Languages\*](#)

## Mailing Lists:

- [chapel\\_info@cray.com](mailto:chapel_info@cray.com): contact the team
- [chapel-users@lists.sourceforge.net](mailto:chapel-users@lists.sourceforge.net): user-oriented discussion list
- [chapel-developers@lists.sourceforge.net](mailto:chapel-developers@lists.sourceforge.net): dev.-oriented discussion
- [chapel-education@lists.sourceforge.net](mailto:chapel-education@lists.sourceforge.net): educator-oriented discussion
- [chapel-bugs@lists.sourceforge.net](mailto:chapel-bugs@lists.sourceforge.net)/[chapel\\_bugs@cray.com](mailto:chapel_bugs@cray.com) : public/private bug forum

