

Chapel: Data Parallelism







Data vs. Task Parallelism (Our Definitions)

Data Parallelism:

- parallelism is driven by collections of data
 - data aggregates (arrays)
 - sets of indices (ranges, domains)
 - other user-defined collections
- e.g., "for all elements in array A ..."

Task Parallelism:

- parallelism is expressed in terms of distinct computations
- e.g., "create a task to do foo() while another does bar()"

(Of course, data parallelism is executed using tasks and task parallelism typically operates on data, so the line can get fuzzy at times...)







"Hello World" in Chapel: a Data Parallel Version

Data Parallel Hello World





Outline



- Domains and Arrays
 - Rectangular Domains and Arrays
 - Iterations and Operations
- Other Domain Types
- Reductions and Scans
- Jacobi Iteration Example





Domains



Domain: A first-class index set

- A fundamental Chapel concept for data parallelism
- Domains may optionally be distributed



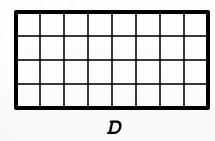






```
config const m = 4, n = 8;
```

var D: **domain**(2) =
$$\{1..m, 1..n\}$$
;





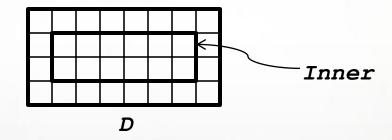




```
config const m = 4, n = 8;

var D: domain(2) = {1..m, 1..n};

var Inner: subdomain(D) = {2..m-1, 2..n-1};
```





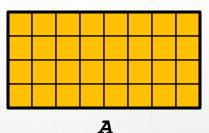
Domains Define Arrays

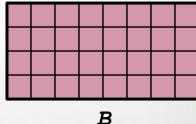


Syntax

```
array-type:
  [ domain-expr ] elt-type
```

- Semantics
 - Stores an elt-type for each index in domain-expr
- Example





Earlier example, revisited

```
var A: [1..3, 1..5] real; // [1..3, 1..5] creates an
                          // anonymous domain
```

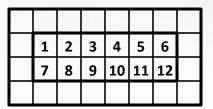




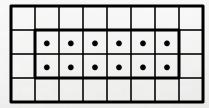
Domain Iteration



- For loops (discussed already)
 - Execute loop body once per domain index, serially



- Forall loops
 - Executes loop body once per domain index, in parallel
 - Loop must be *serializable* (executable by one task)



Loop variables take on const domain index values



Other Forall Loops



Forall loops also support...

A shorthand notation:

$$[(i,j) in D] A[i,j] = i + j/10.0;$$

• Expression-based forms:

1.1	1.2	1.3	1.4	1.5	1.6	1.7	1.8
2.1	2.2	2.3	2.4	2.5	2.6	2.7	2.8
3.1	3.2	3.3	3.4	3.5	3.6	3.7	3.8
4.1	4.2	4.3	4.4	4.5	4.6	4.7	4.8

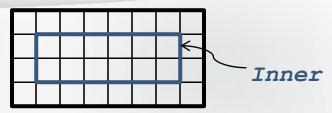
A



Domain Algebra

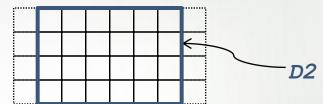


Domain values support...

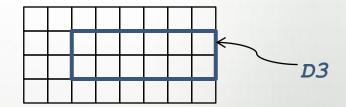


Methods for creating new domains

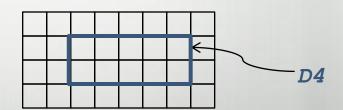
$$var$$
 D2 = Inner.expand(1,0);



$$var$$
 D3 = Inner.translate(0,1);



Intersection via Slicing



Range operators (e.g., #, by, align)

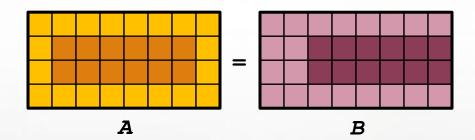








Indexing into arrays with domain values results in a sub-array expression (an "array slice")





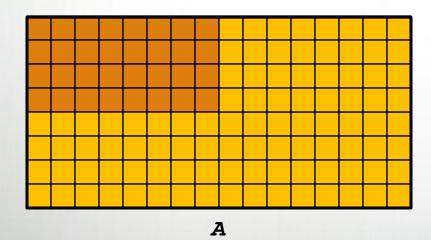
Array Reallocation

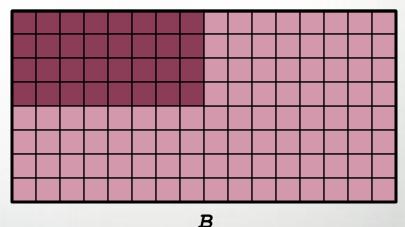


Reassigning a domain logically reallocates its arrays

array values are preserved for common indices

$$D = \{1..2*m, 1..2*n\};$$





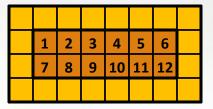


Array Iteration

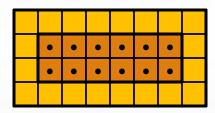


Array expressions also support for and forall loops

for a in A[Inner] do ...



forall a in A[Inner] do ...



Array loop indices refer to array elements (can be modified)

forall
$$(a_{i,j})$$
 in zip (A, D) do $a = i + j/10.0$;

Note that forall loops support zippered iteration, like for-loops

1.1	1.2	1.3	1.4	1.5	1.6	1.7	1.8
2.1	2.2	2.3	2.4	2.5	2.6	2.7	2.8
3.1	3.2	3.3	3.4	3.5	3.6	3.7	3.8
4.1	4.2	4.3	4.4	4.5	4.6	4.7	4.8





Array Indexing



 Arrays can be indexed using variables of their domain's index type (tuples) or lists of integers

```
var i = 1, j = 2;
var ij = (i,j);

A[ij] = 1.0;
A[i, j] = 2.0;
```

Array indexing can use either parentheses or brackets

$$A(ij) = 3.0;$$

 $A(i, j) = 4.0;$





Array Arguments and Aliases

Arrays are passed by reference by default

```
proc zero(X: []) { X = 0; }
zero(A[Inner]); // zeroes the inner values of A
```

Formal array arguments can reindex actuals

```
proc f(X: [1..b,1..b]) { ... } // X uses 1-based indices
f(A[lo..#b, lo..#b]);
```

Array alias declarations provide similar functionality

```
var InnerA => A[Inner];
var InnerA1: [1..n-2,1..m-2] => A[2..n-1,2..m-1];
```





Promoting Functions and Operators

Functions/operators expecting scalars can also take...

...arrays, causing each element to be passed in

...domains, causing each index to be passed in

Multiple arguments promote using zippered iteration





Data Parallelism is Implicit



- forall loops are implemented using multiple tasks
 - ditto for operations that are equivalent to foralls
 - details depend on what is being iterated over
- many times, this parallelism can seem invisible
 - for this reason, Chapel's data parallelism can be considered implicitly parallel
 - it also tends to make the data parallel features easier to use and less likely to result in bugs as compared to explicit tasks





How Much Parallelism?



By default*, controlled by three config variables:

--dataParTasksPerLocale=#

- Specify # of tasks to execute forall loops
- Current Default: number of processor cores

--dataParlgnoreRunningTasks=[true|false]

- If false, reduce # of forall tasks by # of running tasks
- Current Default: true

--dataParMinGranularity=#

- If > 0, reduce # of forall tasks if any task has fewer iterations
- Current Default: 1

^{*}Default values can be overridden for specific domains/arrays





Outline



- Domains and Arrays
- Other Domain Types
 - Strided
 - Sparse
 - Associative
 - Opaque
- Reductions and Scans
- Jacobi Iteration Example

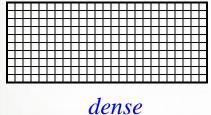


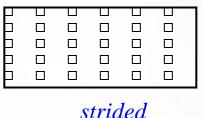


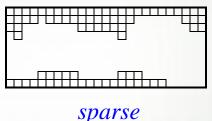


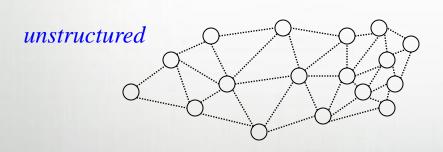
Chapel supports several domain types...

```
var OceanSpace = {0..#lat, 0..#long},
   AirSpace = OceanSpace by (2,4),
   IceSpace: sparse subdomain(OceanSpace) = genCaps();
```

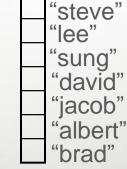








associative



var Vertices: domain(opaque) = ..., People: domain(string) = ...;





Chapel Array Types

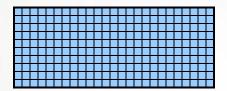


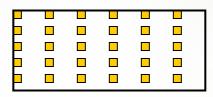
All domain types can be used to declare arrays...

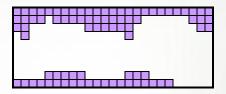
var Ocean: [OceanSpace] real,

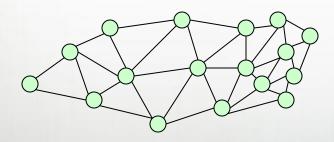
Air: [AirSpace] real,

IceCaps[IceSpace] real;









var Weight: [Vertices] real,



Age: [People] int;

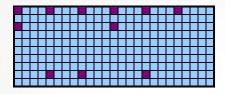


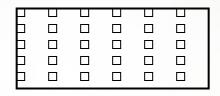
Iteration

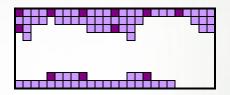


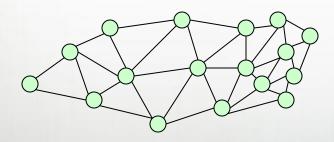
...to iterate over index sets...

forall ij in AirSpace do
Ocean[ij] += IceCaps[ij];









forall v in Vertices do
Weight[v] = numEdges[v];



forall p in People do
Age[p] += 1;

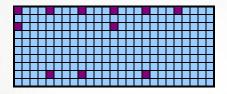


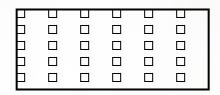
Slicing

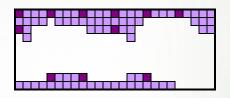


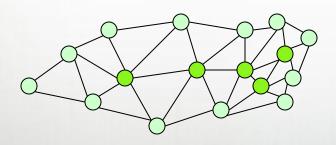
...to slice arrays...

Ocean[AirSpace] += IceCaps[AirSpace];











...Vertices[Interior]...

...People[Interns]...



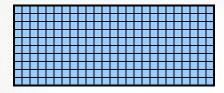


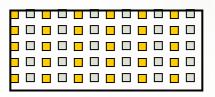
Reallocation

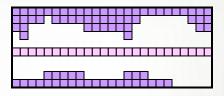


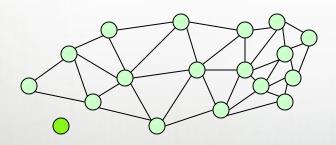
...and to reallocate arrays

```
AirSpace = OceanSpace by (2,2);
IceSpace += genEquator();
```











newnode = Vertices.create();

People += "vass";

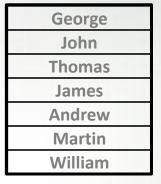






Associative Domains and Arrays by Example

```
var Presidents: domain(string) =
      {"George", "John", "Thomas",
       "James", "Andrew", "Martin"};
Presidents += "William";
var Age: [Presidents] int,
    Birthday: [Presidents] string;
Birthday["George"] = "Feb 22";
forall president in President do
  if Birthday[president] == today then
    Age[president] += 1;
```



Presidents



Birthday

Age



Outline



- Domains and Arrays
- Other Domain Types
- Reductions and Scans
- Jacobi Iteration Example





Reductions



Syntax

```
reduce-expr:
reduce-op reduce iterator-expr
```

- Semantics
 - Combines argument values using reduce-op
 - Reduce-op may be built-in or user-defined

Examples

```
total = + reduce A;
bigDiff = max reduce [i in Inner] abs(A[i]-B[i]);
(minVal, minLoc) = minloc reduce zip(A, D);
```



Scans



Syntax

```
scan-expr:
scan-op scan iterator-expr
```

- Semantics
 - Computes parallel prefix over values using scan-op
 - Scan-op may be any reduce-op
- Examples

```
var A, B, C: [1..5] int;
A = 1;
B = + scan A;
B[3] = -B[3];
C = min scan B;
// C: 1 1 -3 -3 -3
```







- Built-in
 - +, *, &&, ||, &, |, ^, min, max
 - minloc, maxloc
 - Takes a zipped pair of values and indices
 - Generates a tuple of the min/max value and its index
- User-defined
 - Defined via a class that implements a standard interface
 - Compiler generates code that calls these methods



Outline



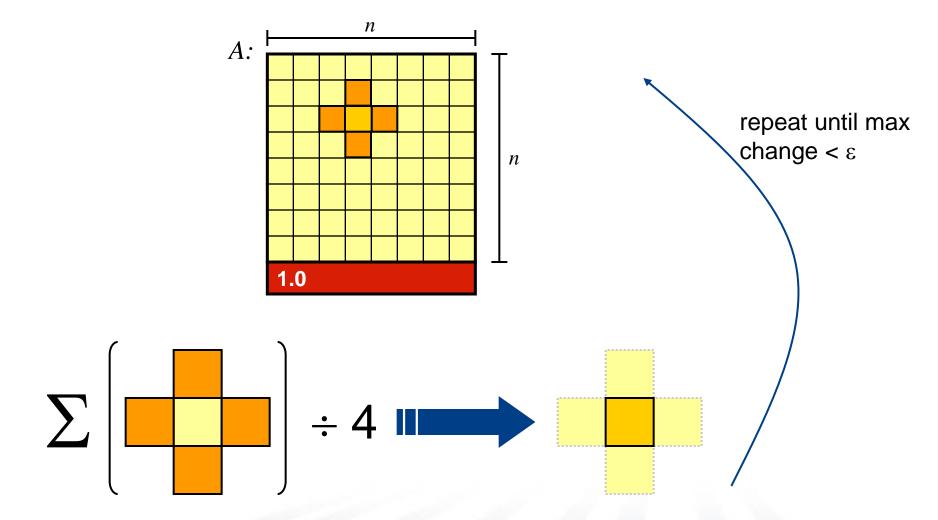
- Domains and Arrays
- Other Domain Types
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Jacobi Iteration in Pictures









```
config const n = 6,
              epsilon = 1.0e-5;
const BiqD: domain(2) = \{0..n+1, 0..n+1\},
         D: subdomain (BigD) = \{1..n, 1..n\},
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
A[LastRow] = 1.0;
do {
  [(i,j) \text{ in } D] \text{ Temp}[i,j] = (A[i-1,j] + A[i+1,j])
                            + A[i,j-1] + A[i,j+1]) / 4;
  const delta = max reduce abs(A[D] - Temp[D]);
  A[D] = Temp[D];
} while (delta > epsilon);
writeln(A);
```







```
config const n = 6,
               epsilon = 1.0e-5;
const BigD: domain(2) = \{0..n+1, 0..n+1\},
          D: subdomain (BigD) = \{1...n, 1...n\},
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
       Declare program parameters
A [Las
      const ⇒ can't change values after initialization
       config ⇒ can be set on executable command-line
                prompt> jacobi --n=10000 --epsilon=0.0001
  con
      note that no types are given; inferred from initializer
                n \Rightarrow default integer (32 bits)
 whi
                epsilon ⇒ default real floating-point (64 bits)
writeln(A);
```





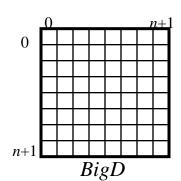


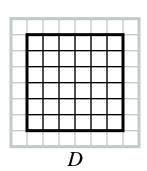
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  LastRow: subdomain(BigD) = D.exterior(1,0);
```

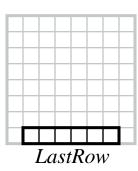
Declare domains (first class index sets)

domain(2) ⇒ 2D arithmetic domain, indices are integer 2-tuples

subdomain(P) \Rightarrow a domain of the same type as P whose indices are guaranteed to be a subset of P's







exterior ⇒ one of several built-in domain generators





4;

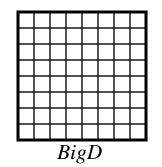


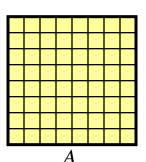
```
config const n = 6,
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const BigD: domain(2) = \{0..n+1, 0..n+1\},
         D: subdomain (BigD) = \{1...n, 1...n\},
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real; _____
A[LastRow] = 1.0;
```

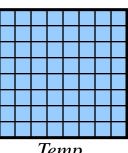
Declare arrays

var ⇒ can be modified throughout its lifetime

: [BigD] T ⇒ array of size BigD with elements of type T (no initializer) \Rightarrow values initialized to default value (0.0 for reals)







Temp





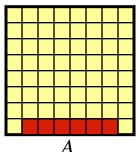
4;



```
config const n = 6,
             epsilon = 1.0e-5;
const BigD: domain(2) = \{0..n+1, 0..n+1\},
         D: subdomain (BiqD) = \{1..n, 1..n\},
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
A[LastRow] = 1.0;
```

Set Explicit Boundary Condition

indexing by domain ⇒ slicing mechanism array expressions ⇒ parallel evaluation



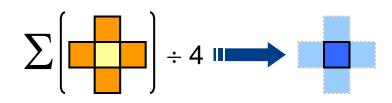






Compute 5-point stencil

 $[(i,j) \text{ in } D] \Rightarrow \text{ parallel forall expression over } D$'s indices, binding them to new variables i and j



```
[(i,j) \text{ in } D] \text{ Temp}[i,j] = (A[i-1,j] + A[i+1,j] + A[i,j-1] + A[i,j+1]) / 4;
```

```
const delta = max reduce abs(A[D] - Temp[D]);
A[D] = Temp[D];
} while (delta > epsilon);
writeln(A);
```







Compute maximum change

op reduce ⇒ collapse aggregate expression to scalar using op

Promotion: abs() and – are scalar operators, automatically promoted to work with array operands







```
config const n = 6,
              epsilon = 1.0e-5;
const BigD: domain(2) = \{0..n+1, 0..n+1\},
          D: subdomain (BiqD) = \{1..n, 1..n\},
   LastRow: subdomain(BigD) = D.exterior(1,0);
    Copy data back & Repeat until done
A [La uses slicing and whole array assignment
    standard do...while loop construct
do
  [(i,j) in D] Temp[i,j] = (A[i-1,j] + A[i+1,j])
                            + A[i,j-1] + A[i,j+1]
  const delta = max reduce abs(A[D]         Temp[D]);
  A[D] = Temp[D];
} while (delta > epsilon);
writeln(A);
```







```
config const n = 6,
            epsilon = 1.0e-5;
const BigD: domain(2) = \{0..n+1, 0..n+1\},
        D: subdomain (BiqD) = \{1..n, 1..n\},
  LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
A[LastRow] = 1.0;
                                 Write array to console
do {
 [(i,j) \text{ in } D] \text{ Temp}[i,j] = (A[i-1,j] + A[i+1,j])
                         + A[i,j-1] + A[i,j+1])
  A[D] = Temp[D];
} while (delta > epsilo
writeln(A);
```



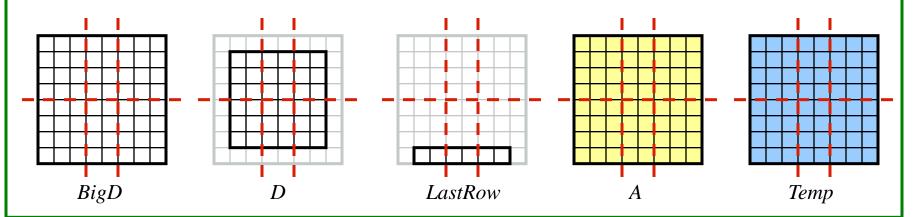




```
config const n = 6,
             epsilon = 1.0e-5;
const BigD = \{0..n+1, 0..n+1\} dmapped Block (...),
         D: subdomain (BiqD) = \{1..n, 1..n\},
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
```

With this change, same code runs in a distributed manner Domain distribution maps indices to *locales*

⇒ decomposition of arrays & default mapping of iterations to locales Subdomains inherit parent domain's distribution









```
config const n = 6,
              epsilon = 1.0e-5;
const BigD = \{0..n+1, 0..n+1\} dmapped Block (...),
         D: subdomain (BiqD) = \{1..n, 1..n\},
   LastRow: subdomain(BigD) = D.exterior(1,0);
var A, Temp : [BiqD] real;
A[LastRow] = 1.0;
do {
  [(i,j) \text{ in } D] \text{ Temp}[i,j] = (A[i-1,j] + A[i+1,j])
                            + A[i,j-1] + A[i,j+1]) / 4;
  const delta = max reduce abs(A[D] - Temp[D]);
  A[D] = Temp[D];
} while (delta > epsilon);
writeln(A);
```





Data Parallelism: Status



- Most features implemented and working correctly
- Scalar performance not optimal for higherdimensional domain/array operations
- Implementation of unstructured domains/arrays is correct but inefficient





Future Directions



 Gain more experience with unstructured (graphbased) domains and arrays





Questions?



- Domains and Arrays
 - Regular Domains and Arrays
 - Iterations and Operations
- Other Domain Types
 - Strided
 - Sparse
 - Associative
 - Opaque
- Data Parallel Operations
 - Reductions
 - Scans
- Jacobi Iteration Example



