

Soft Robotics Toolkit: Assessment Proposal

Introduction

Our proposed learning goals encompass three domains: technical knowledge, design thinking, and socio-emotional learning. In developing our learning goals, we focused on how to develop effective assessments for teachers while still enabling creativity, imagination, and self-expression for learners. For our formative assessment, we propose a design journal students work on throughout the project; our summative assessment is an open-ended application project accompanied by a final gallery walk.

Learning Goals

By the end of the lesson, students should achieve the following learning goals:

- Create a soft gripper tool that uses tendon and pneumatic actuation methods
- Develop their understanding of soft robotics as well as its implications in their daily lives and the lives of others
- Independently use design thinking strategies/the engineering design process to create their own version of a soft gripper actuator
- Build confidence in themselves as individuals capable of effective STEAM work and as team members in a collaborative engineering environment

Students today will enter ever-shifting job markets: the World Economic Forum's *Future of Jobs Report* states that, in the next 10 years, "a non-negligible share of newly created jobs will be in wholly new occupations, or existing occupations undergoing significant transformations in terms of their content and skills requirements." The report also highlighted "robotics specialists" as a role growing in demand (World Economic Forum, 2020). Recognizing that inherent identification with STEAM fields may not be available to all students, our assessment suggestions incorporate opportunities for all students to identify themselves as tinkerers, designers, and creators for their communities.

We also prioritized design thinking as a means of developing social-emotional learning: not only will students gain a firsthand understanding of the engineering design process, but they will also develop collaboration skills, self-directedness, and communication abilities. We are emphasizing process-based over product-based assessment, as outcomes may be undetermined, open to further iteration, or misrepresentative of holistic learning (Graham, 2019). We see this in museum spaces as well. The Children's Museum of Pittsburgh (Wardrip & Brahms, 2015) emphasizes learning *practices* over learning outcomes as seen in Figure 1, allowing for results to be undetermined and spontaneous and understanding that process is just as important as the result. Similarly, the Tinkering Studio at the Exploratorium (2017) provides educators with a framework centered on outcomes gained from learning *experiences* over tangible results (Figure

2). Finally, feedback as part of the cyclical nature of designing empowers students to have an “ongoing critical dialogue” (Pollock et al., 2015) with peers and programs; the studying of computer science itself also enables student-self directedness because of the instant feedback programs and products can provide (Brennan, 2021).

Formative Assessment: Design Journals

To meet the broad span of our learning goals and learner experiences, we designed an assessment that would evaluate not just the learner's final product, but their collective learning process. For our formative assessment, we decided on a design journal that students complete throughout the curriculum (Figure 3). Depending on the day, the journal prompts may be reflective or interactive and individual or collaborative. The built-in variety allows for the assessment of the variety of learning goals while serving different types of learners and needs throughout the curriculum. For example, earlier in the curriculum when students are building their technical knowledge, students might be asked to explain what an actuator is to a friend or family member. After building the autonomous gripper, however, students may benefit more from individual reflection and do a rose (what worked?), thorn (what was a challenge?), and bud (what new ideas sprung up?) activity. The different activities are designed around principles to assess student self-directed learning, which states that assessment should recognize the individuality of the learner, illuminate the learning process, engage multiple perspectives, and cultivate the capacity for personal judgment (Brennan et al., 2021). Additional design journal prompts (Figure 4) and sample slides can be found in the appendix (Figures 5-9).

Beyond assessment, the design journals also serve students by furthering their learning. Reflection is a key component of learning as it turns experiences into understanding. (Ellis et al., 2014) This is especially critical for hands-on and open-ended learning like soft robotics, where the ability to build does not always mean the ability to explain or transfer knowledge. Furthermore, reflection fosters meta-cognition skills that enable learners to become more flexible, growth-oriented learners (Boser, 2018). The growth mindset is fostered through the design journal with repeated prompts throughout the curriculum and activities that ask learners to look back and reflect on their newly gained understanding.

Summative Assessment: Application Project & Gallery Walk

Our framework also suggests the integration of a project-based summative assessment. While summative assessments generally aim to evaluate student learning through high stakes (Carnegie Mellon University, n.d.), we imagine a final project that focuses on the quality of the application and the depth of the process, rather than the evaluation of knowledge gains. Namely, we designed the project to challenge the learners’ contextual and technical understanding of soft robotics, help individual learners realize their potential roles in a collaborative STEAM environment, develop design thinking skills, and reconnect to their social and emotional growth.

In efforts to design an equitable form of assessment, the project begins with an open-ended, individual prompt of brainstorming a novel soft robotics project. Nemiro, Larriva, and Jawaharlal (2015) suggest that “open-ended, challenging tasks that ask students to solve real-world problems” are ideal for encouraging a creative climate in a robotics classroom (p. 87). The loose nature of the prompt enables learners to approach the project from each individual’s unique perspective and skillset and potentially build intrinsic motivation within learners through self-developed project ideas (Castek et al., 2019). Once the learners have presented these ideas to their peers, they will be given the opportunity to form small groups (3-5 people) to design and fabricate a functional soft robotics project. For example, one group of learners may think of the project from a more conceptual lens and ideate an application of the soft robotics actuators in a new context, another group may tackle a functioning, incremental development of the soft gripper, and another group may create an expressive art project that incorporates pneumatic, silicone actuators. Based on the consensus of the learners, the facilitators might also provide sources to find existing applications of soft robotics for additional scaffolding.

Learners will also be prompted to document their design process in their design journals, including anything that is not included in their final prototype. The documentation of the design process will assist learners in reflecting on their journey to becoming soft robotics technologists. Specifically, it will help students understand the iterative design cycle that is foundational to technological development (Nemiro et al., 2015). This documentation will go hand in hand with the design journal prompts to help connect the design project to our reflective probing questions.

Finally, once the projects have been developed into a prototype, the students will present their work in a “gallery walk.” According to The Teacher Toolkit, a gallery walk is a “discussion technique [that] allows students to be actively engaged as they [...] share ideas and respond to meaningful questions, documents, images, problem-solving situations, or texts” (Education Service Center Region 13, n.d.). The gallery walk is designed to help presenters develop their oral and visual communication abilities and prompt listeners to extend their peer’s work through critique, feedback, and further ideation. We hope that the exposure of many different projects and ideas will foster an environment for divergent thinkers to explore the “adjacent possible” (Johnson, 2010, as cited by Graham, 2019).

Denise Fabella, denisefabella@gse.harvard.edu

Chan Pham, chanpham@gse.harvard.edu

Daniel Noh, dnoh@gse.harvard.edu

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Appendix

Model Learning Practices

MAKESHOP Learning Practices	
MAKESHOP Learning Practice	Practice Description
Inquire	Learners' openness and curious approach to the possibilities of the context through exploration and questioning of its material properties.
Tinker	Learners' purposeful play, testing, risk taking, and evaluation of the properties of materials, tools, and processes.
Seek & Share Resources	Learners' identification, pursuit/recruitment, and sharing of expertise with others; includes collaboration and recognition of one's own not-knowing and desire to learn.
Hack & Repurpose	Learners harnessing and salvaging of materials, tools and processes to modify, enhance, or create a new product or process; includes disassociating object property from familiar use.
Express Intention	Learners' discovery, evolution, and refinement of personal identity and interest areas through determination of short and long term goals; includes learners' responsive choice, negotiation, and pursuit of goals alone and with others.
Develop Fluency	Learners' development of comfort and competence with diverse tools, materials, and processes; developing craft.
Simplify to Complexify	Learners' demonstration of understanding of materials and processes by connecting and combining component elements to make new meaning.

Figure 1
Pittsburgh Children's Museum Learning Practices

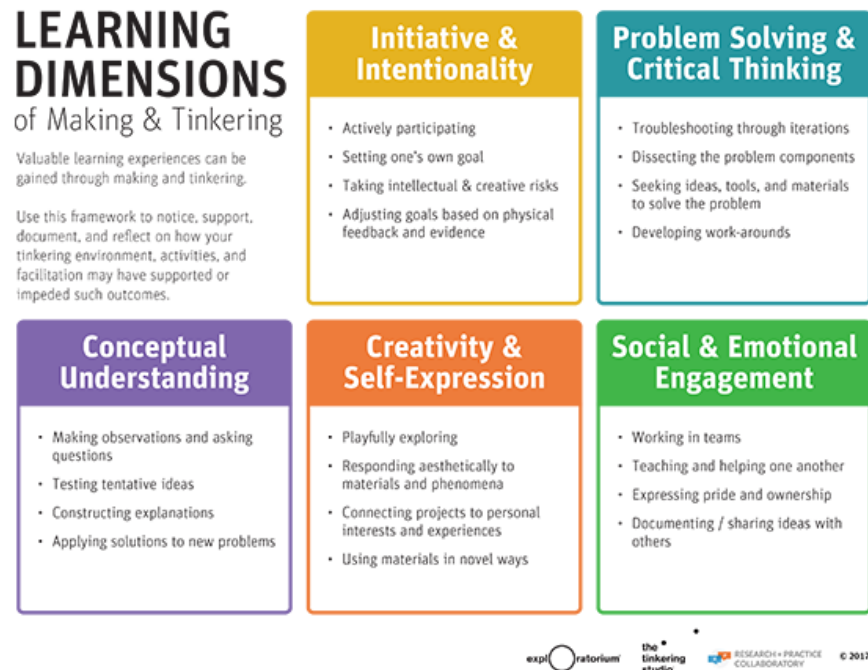


Figure 2
Exploratorium Learning Dimensions

Soft Robotics Curriculum

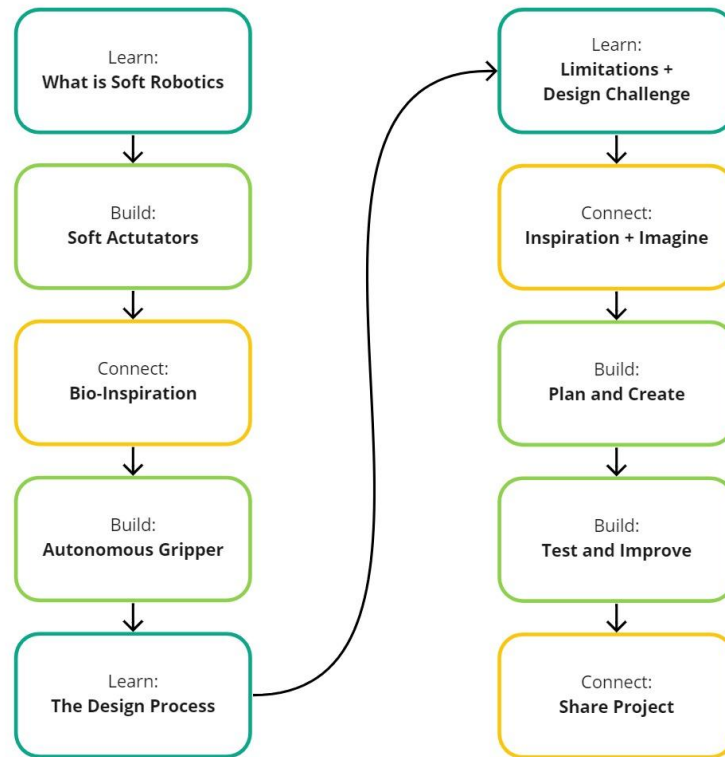


Figure 3
Our Understanding of the Curriculum

Additional Design Journal Prompts

Lesson	Journal Prompt	Learning Goals Assessed
Introduction (1)	Create a mindmap of words, a drawing, and/or questions you have around soft robotics.	Understanding of soft robotics
Bio-Inspiration (3)	Looking at nature, what is something you would want to build using soft robotics? Wild and crazy ideas encouraged!	Inspiration from nature, ideating
Understanding the Problem (7)	Pair up with a classmate and find a limitation of their robot. What did you find? How did you find it?	Collaboration, debugging skills
Gathering Inspiration (8)	With your new understanding of soft robotics, look back at your response on day 3. How would you approach building that idea? What, if anything, would you change?	Inspiration from nature, ideating, iterating, understanding of soft robotics, growth mindset
Share Project (13)	Explain your final project to a friend or family member. Look back at day 2 when you explained what an actuator is. How has your understanding changed?	Understanding of soft robotics, presentation skills, confidence in STEM, identify formation, growth mindset

Figure 4
Additional Design Journal Prompts

Sample Design Journal Pages



Figure 5
Design Journal Cover

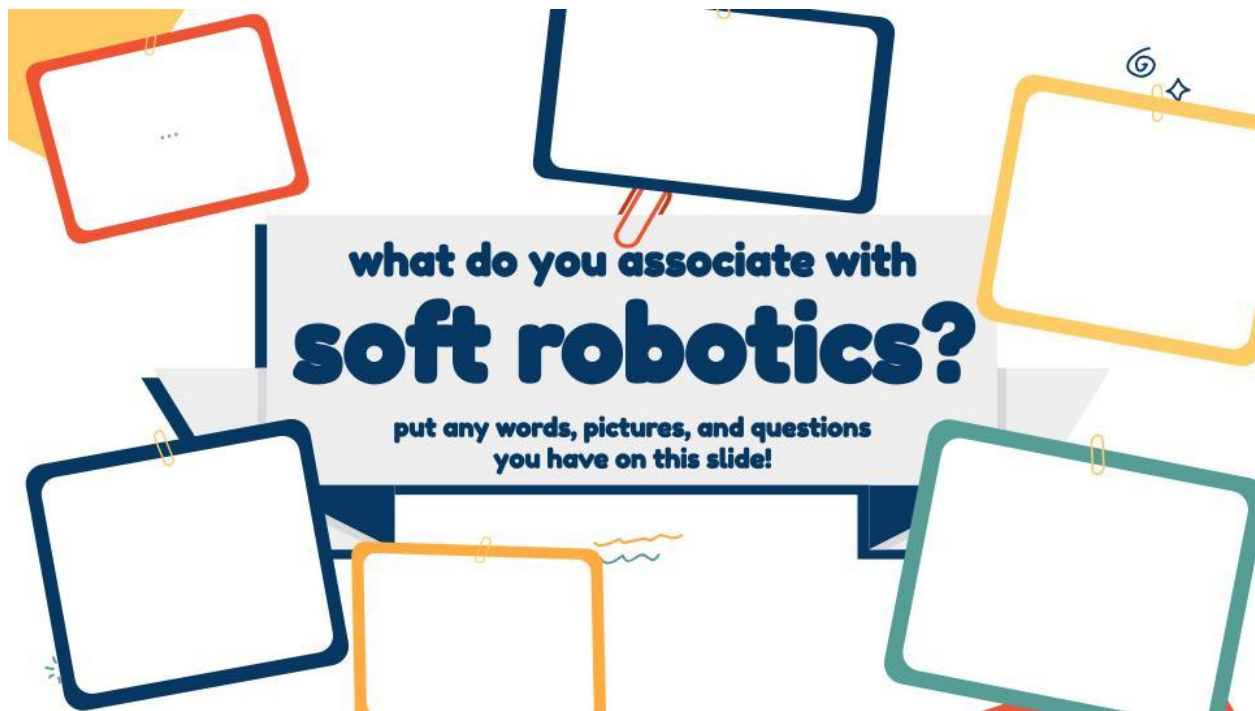


Figure 6
Introduction (1) Slide

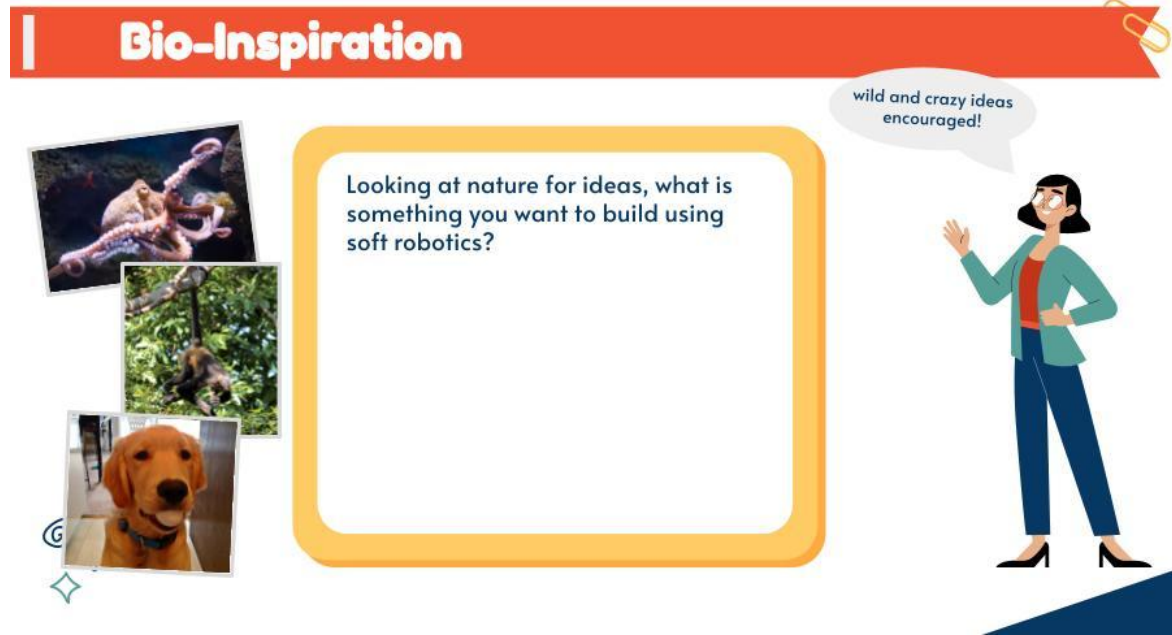


Figure 7
Bio-inspiration (3) Slide



Figure 8
Final Project Notepad (repeating throughout journal)

Understanding the Problem

Pair up with a classmate and explore limitations of each other's robots!

Your peer's robot

Current limitations:

-
-
-

Your robot

Current limitations:

-
-
-



Figure 9
Understanding the Problem (7) Slides

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