Danish Faraaz Syed

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Summary

A focused student working on establishing myself as an expert in robotics. I am continuously updating myself on various skills every day.

Skills

ROS	OpenCV	Matlab	Arduino	Gazebo
Python	C++	С	Siemens NX	Solidworks
Ansys	AutoCAD	CREO	Tensorflow	Keras

Projects

1. ROS Based Autonomous robot with OpenCV

January 2019 - April 2019

- Capstone year project during my Bachelors. ROS is run on Raspberry Pi 3 of the robot
- A robot that can navigate through obstacles and plan its next path based on the shape it detects
- 2. Design and Development of a Robotics Toolbox in Matlab

August 2019 - December 2019

- Inspired by the Robotics toolbox of Peter Corke. Had more functionalities including workspace plotting, differential kinematics and so on.
- Each teammate worked on a different aspect of the toolbox and it was finally put together using Matlab App Designer.
- 3. Control and Stability of a Planar Quadrotor model

August 2019 - December 2019

- Designed and simulated the effects of four different controls namely LQR, Closed-loop feedback, Observer-based feedback and PID control
- Non-linear dynamic equations were converted to state-space form and linearized about hoverconditions.
- 4. Contaminant detection and water sampling using drone, SRP

August 2019 - Present

- Used combination of SURF features and modified CMT tracker in OpenCV for detection and tracking of trash on a lake.
- Annotated and labelled the ground truth using Matlabs Ground Truth Labeller App. Compared different tracker outputs including the modified CMT with the ground truth using precision and recall metrics.
- Implemented Kalman Filter with the detection on OpenCV for better inputs to the visual control. Used ZMQ to publish and subscribe to data.

Education

•	Masters in Robotics and Autonomous Systems	CGPA - (3.67/4.0)	Arizona State University, USA	2019-2021
•	Bachelor of Mechanical Engineering	CGPA - (8.77/10)	Anna University, India	2015-2019

Research Experience

- Graduate research assistant at Robotics and Intelligent System (RISE) Lab, Arizona State University August 2019 Present
- Thesis on Vision based control at RISE Lab, Arizona State University

Starting on October 2020

Relevant links

- GitHub https://github.com/DanishFaraaz
- Portfolio/ Personal https://danishfaraaz.github.io/
- Matlab/ Python projects https://skill-lync.com/profiles/Danish-Faraaz-814

Achievements

- Awarded "Best Outgoing Student Award" in the Department of Mechanical Engineering for the batch of 2015-2019.
- Recipient of New American University (Namu) scholarship for my first year at Arizona State University.

Languages – English (Expert), Urdu (Native), Tamil (Expert), Hindi (Expert)