

# Assignment 2-A

## TurtleBot3 Burger Teardown

GROUP 1

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[GitHub Repository](#)

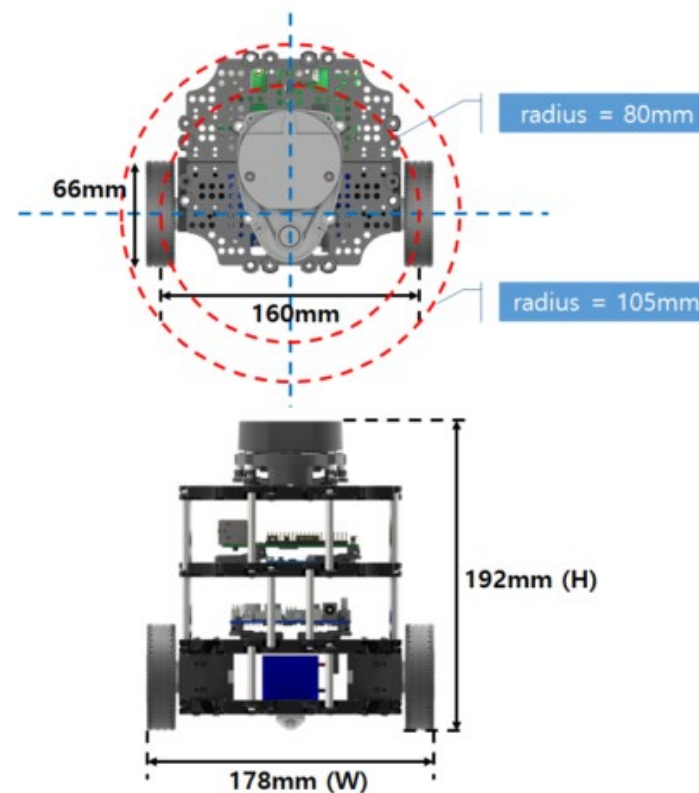



# Feature Overview

- Differential drive mechanism
- Small form factor
- Multi-mode actuators
- Multi-sensor lineups
- Affordable cost
- Open hardware
- Open firmware
- Open software
- ROS enabled

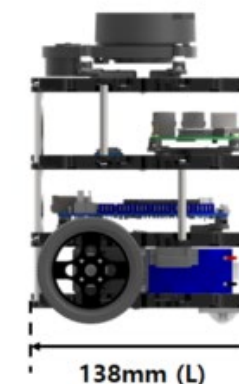


## TurtleBot3 Burger



 = 138 x 178 x 192 (L x W x H, mm)

 = 1 Kg



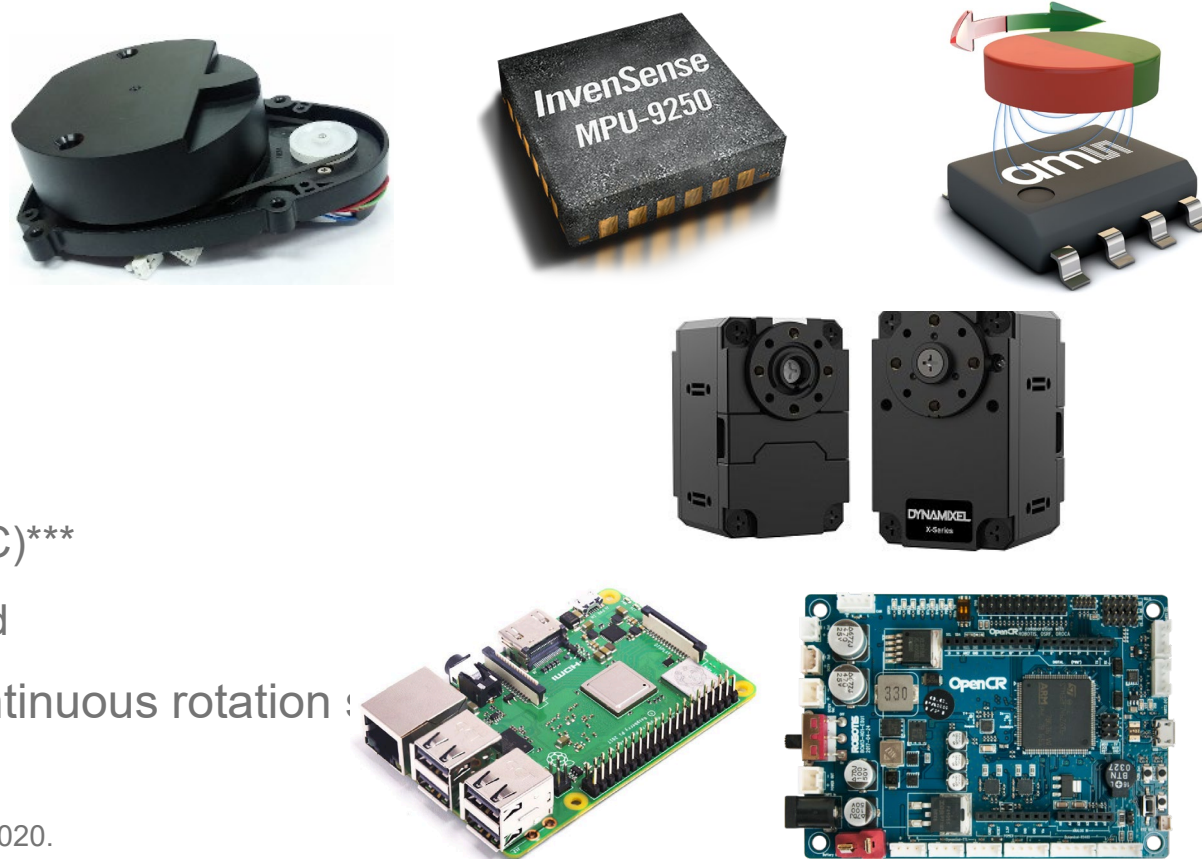
Source: [ROBOTIS Inc.](https://robotis.com)

# Existing Hardware

**Note 1:** Complete list of specifications available [here](#)

**Note 2:** The TurtleBot3 Burger provided in class has add-on [Pi Camera v2](#)

- **Battery:** 11.1 V 1800 mAh LiPo
- **Sensors:**
  - [LDS-01](#) 360° planar LiDAR\*
  - [MPU-9250](#) 9-axis IMU\*\*
  - [AS5601](#) magnetic absolute encoders
- **Computers:**
  - [Raspberry Pi 3B+](#) single board computer (SBC)\*\*\*
  - [OpenCR1.0](#) auxiliary low-level controller board
- **Actuators:** [DYNAMIXEL XL430-W250-T](#) continuous rotation :



\*[LDS-02](#) is applied since 2022.

\*\*9-axis [MPU-9250](#) IMU has been replaced with 6-axis [ICM-20648](#) IMU since 2020.

\*\*\*[Raspberry Pi 3 Model B+](#) is applied since 2019. Earlier model is equipped with [Raspberry Pi 3 Model B](#). [Raspberry Pi 4 Model B](#) is applied since 2021 September.

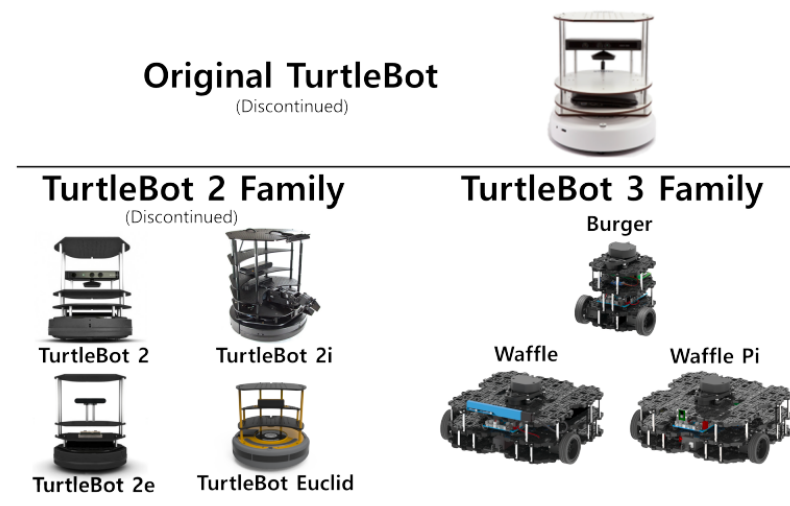
# TurtleBot Version Comparison

TurtleBot Version	Mobile Base	Battery Pack	Computer(s)	Sensor(s)	Actuator(s)	Developer(s)	Release Date
TurtleBot1	iRobot Create	3000 mAh	Asus 1215N Laptop	Gyro, MS Kinect (RGBD-Cam), Encoders	iRobot Create Robot Base Motors	Willow Garage	Nov 2010
TurtleBot2	Yujin Kobuki	2200 mAh	Asus 1215N Laptop	Gyro, MS Kinect (RGBD-Cam), Encoders	iCleo Kobuki Robot Base Motors	Yujin Robot	Oct 2012
TurtleBot3	Burger, Waffle, Waffle Pi	1800 mAh	Raspberry Pi (or Intel Joule 570x), OpenCR1.0	2D LiDAR, 9-Axis IMU, Encoders, Pi Camera (Mono-Cam), Intel RealSense RGBD-Cam	DYNAMIXEL Servo Motors	ROBOTIS, OSRF	May 2017

- **TurtleBot1:** Costs \$1400, large, less flexibility, deprecated
- **TurtleBot2:** Costs \$1500, huge, less modular, deprecated
- **TurtleBot3:** Costs \$650, small, modular, continued support

**Robotis and OSRF Announce TurtleBot 3 Smaller, Cheaper, and Modular (IEEE Spectrum, By Evan Ackerman, 12 Oct 2016)**

Source: [IEEE Spectrum](#)



Source: [TurtleBot.com](#)

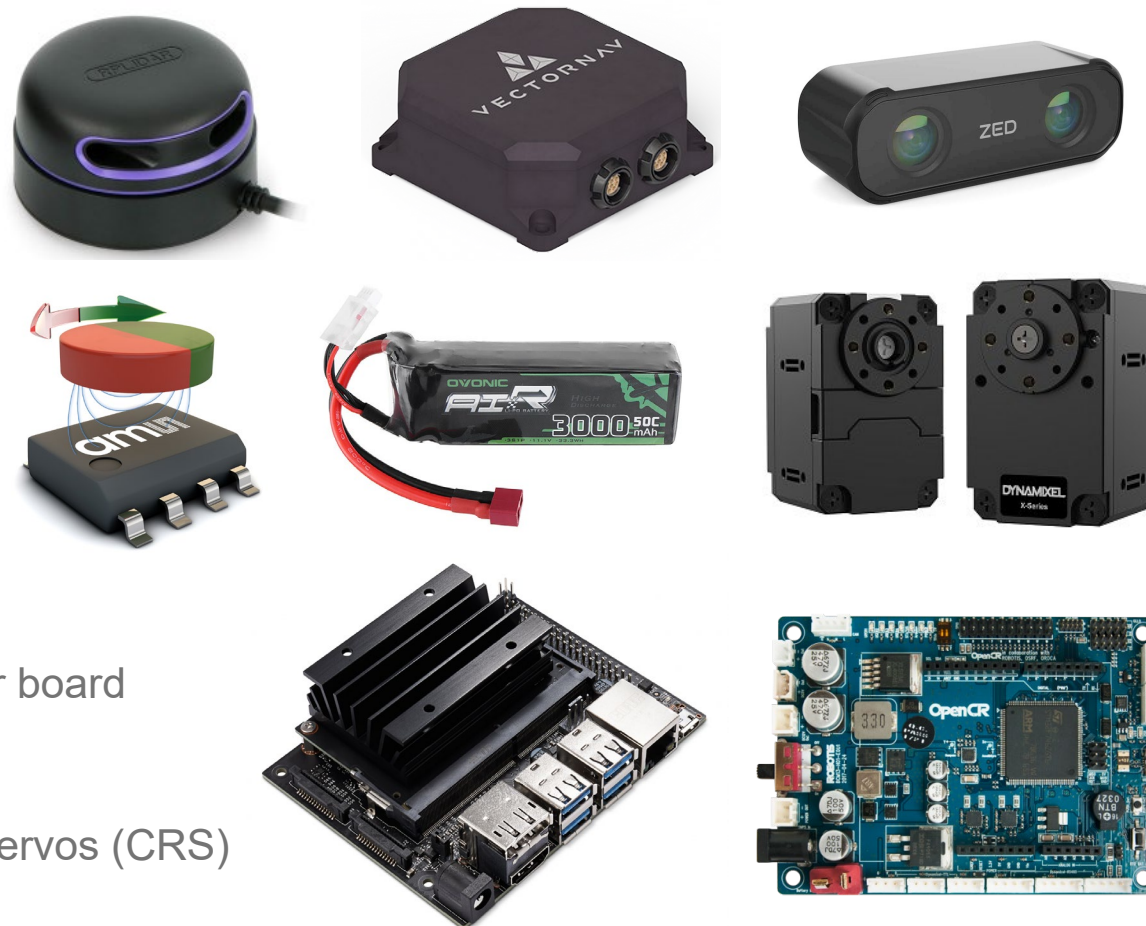


# Replacement Hardware

**Note 1:** Actuators and low-level compute need not be replaced

**Note 2:** These replacements do not consider cost constraint

- **Battery:** 11.1 V 3000 mAh 3S 50C LiPo
- **Sensors:**
  - LiDAR: RPLIDAR-A3 360° planar LiDAR
  - IMU: VN-110 9-axis IMU
  - Encoders: AS5601 magnetic absolute encoders
  - Camera: ZED X Mini RGBD camera
- **Computers:**
  - High level: Jetson Nano B01 developer kit
  - Low level: OpenCR1.0 auxiliary low-level controller board
- **Actuators:**
  - DYNAMIXEL XL430-W250-T continuous rotation servos (CRS)



# Hardware for Educational Deployment - Battery

Candidates	Voltage Rating	Current Capacity	Discharge	Form Factor	Weight	Cost
✓ <a href="#">OVONIC 3S Li-Po</a>	11.1 V	3000 mAh	50 C	105x32x28 mm	193 g	\$22.81
<a href="#">Traxxas 3S Li-Po</a>	11.1 V	5000 mAh	25 C	135x44x28 mm	354 g	\$69.95
<a href="#">OVONIC 2S Li-Po</a>	7.4 V	6200 mAh	50 C	137x46x24 mm	280 g	\$19.5
<a href="#">AES 3 Cell Li-Ion</a>	11.1 V	2600 mAh	1.6 C	69x57x18 mm	156 g	\$36.00
<a href="#">AES 6 Cell Li-Ion</a>	11.1 V	5200 mAh	1.6 C	69x57x39 mm	283 g	\$59.00



# Hardware for Educational Deployment - LIDAR

Candidates	Range	FOV	Resolution	Sampling Rate	Scan Rate	Cost
<a href="#">ROBOTIS LDS-01</a>	0.12 - 3.5 m	360°	1°	1.8 kHz	5.0 Hz	\$196.10
<a href="#">ROBOTIS LDS-02</a>	0.16 - 8.0 m	360°	1°	2.3 kHz	5.0 Hz	\$211.38*
✓ <a href="#">Slamtec RPLIDAR A1</a>	0.15 - 12.0 m	360°	1°	8.0 kHz	10.0 Hz	\$99.00
<a href="#">Slamtec RPLIDAR A3</a>	0.20 - 25.0 m	360°	0.225°	16.0 kHz	15.0 Hz	\$599.00
<a href="#">YDLIDAR X4</a>	0.12 - 10.0 m	360°	0.645°	5.0 kHz	10.0 Hz	\$79.99
<a href="#">Hokuyo UST-10LX</a>	0.06 - 30.0 m	270°	0.125°	N/A	40.0 Hz	\$1,595.00
<a href="#">Sick TIM310</a>	0.05 - 25.0 m	270°	0.33°	N/A	15.0 Hz	\$1,503.00

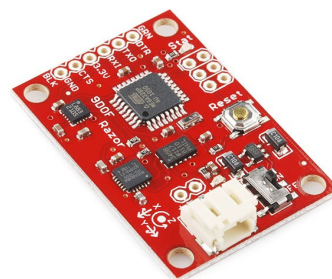
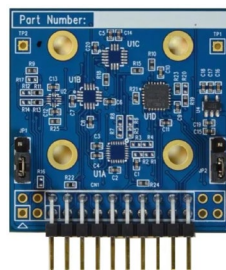
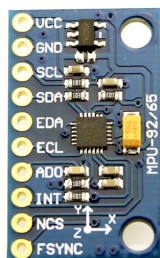
\*Exact cost data for LDS-02 is not available, value approximated by adding 25% markup to LDS-01 cost.



# Hardware for Educational Deployment - IMU



Candidates	DOF	Range	Noise Sensitivity	Form Factor	Weight	Cost
<a href="#">InvenSense MPU-9250</a>	9	$\pm 2000^\circ/\text{s}$   $\pm 16\text{ g}$   $\pm 4800\text{ }\mu\text{T}$	$0.01^\circ/\text{s}/\text{Hz}$   $300\text{ }\mu\text{g}/\text{Hz}$	15x25x3 mm	3.78 g	\$14.99
<a href="#">InvenSense ICM-20648</a>	6	$\pm 2000^\circ/\text{s}$   $\pm 16\text{ g}$	$0.015^\circ/\text{s}/\text{Hz}$   $230\text{ }\mu\text{g}/\text{Hz}$	38.1x 38.1x1.6 mm	4.45 g	\$40.00
<a href="#">SparkFun Razor IMU</a>	9	$\pm 2000^\circ/\text{s}$   $\pm 16\text{ g}$   $\pm 8\text{ G}$	$0.03^\circ/\text{s}/\text{Hz}$   $300\text{ }\mu\text{g}/\text{Hz}$	28x41x6 mm	5 g	\$124.95
<a href="#">VectorNav VN-110</a>	9	$\pm 490^\circ/\text{s}$   $\pm 15\text{ g}$   $\pm 2.5\text{ G}$	$0.001^\circ/\text{s}/\text{Hz}$   $40\text{ }\mu\text{g}/\text{Hz}$	56x56x23 mm	125 g	N/A

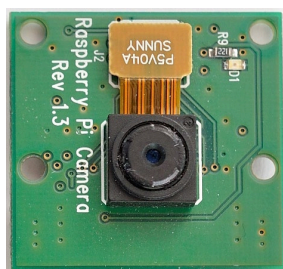




# Hardware for Educational Deployment - Camera

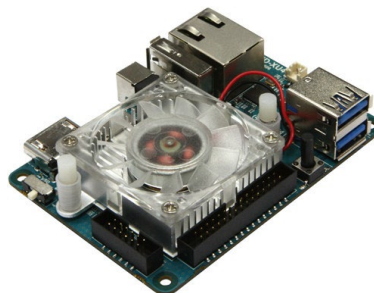
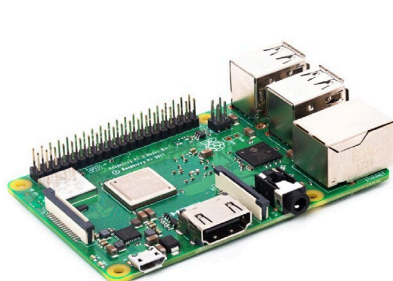
Candidates	Depth	Resolution	FOV	Frame Rate	Form Factor	Weight	Cost
<a href="#">PiCamera v1</a>	No	5 MP (2592×1944 px)	53.5°	1080p30	25x24x9 mm	3 g	\$25.00
<a href="#">PiCamera v2</a>	No	8 MP (3280 × 2464 px)	62.2°	1080p47	25x24x9 mm	3 g	\$25.00
✓ <a href="#">PiCamera v3</a>	No	11.9 MP (4608 x 2592 px)	66°	1296p56	25x24x11.5 mm	4 g	\$25.00
<a href="#">Intel RealSense D435</a>	Yes	2 MP	69°   87°	1080p30   720p90	90x25x25 mm	72 g	\$333.75
<a href="#">ZED X Mini</a>	Yes	2.3 MP	110°   120°	1200p60   1200p120	94x30x37 mm	150 g	\$549.00

**Note:** Detailed comparison of Pi camera versions is available [here](#)



# Hardware for Educational Deployment - Computer

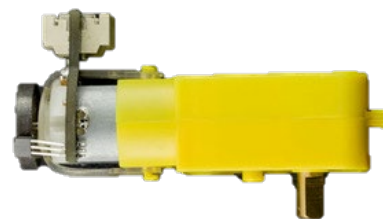
Candidates	CPU	GPU	Memory	Form Factor	Weight	Cost
<a href="#">Raspberry Pi 3B+</a>	Cortex-A53, 1.4 GHz	Videocore-IV	1GB LPDDR2	82x56x19.5 mm	50 g	\$35.00
<a href="#">Raspberry Pi 4B</a>	Cortex-A72, 1.5 GHz	VideoCore VI	1-8 GB LPDDR4	88x58x19.5 mm	46 g	\$75.00
<a href="#">Odroid XU4</a>	Cortex-A15, 2.0 GHz/ Cortex-A7, 1.3 GHz	Mali-T628 MP6	2 GB LPDDR3	83x58x20 mm	38 g	\$59.00
✓ <a href="#">NVIDIA Jetson Nano b01</a>	Cortex-A57, 1.43 GHz	128-core Maxwell	4 GB LPDDR4	100x80x29 mm	141 g	\$149.00
<a href="#">NVIDIA Jetson Xavier NX</a>	NVIDIA Carmel, 1.9 GHz	384-core Volta	8-16 GB LPDDR4x	103x90.5x31 mm	172 g	\$1999.00



# Hardware for Educational Deployment - Actuators

Candidates	Power Rating	Range	Speed	Torque	Encoder	Form Factor	Weight	Cost
<a href="#">DYNAMIXEL XL430-W250*</a>	11.1 V   1.3 A	360°	57 RPM	1.4 Nm	2048 CPR	28.5x46.5x34 mm	57.2 g	\$49.90
<a href="#">All Metal TT Motor</a>	6.0 V   1.0 A	360°	120 RPM	0.18 Nm	N/A	69.5x22x20.7 mm	39.4 g	\$5.95
✓ <a href="#">TT Motor with Encoder</a>	6.0 V   2.8 A	360°	160 RPM	0.08 Nm	1920 CPR	79.5x22x20.7 mm	50.0 g	\$7.40
<a href="#">NEMA 17 Stepper Motor</a>	12.0 V   350 mA	360°	50 RPM	0.28 Nm	N/A	58x42.3x42.3 mm	240 g	\$14.00
<a href="#">Tower-Pro MG-995</a>	6.0 V   2.8 A	170°	62.5 RPM	0.98 Nm	Internal feedback	40.7x19.7x42.9 mm	62.41 g	\$19.95

\*ROBOTIS recommends that new and existing AX series users transition to [XL430-W250](#).



# Thank You!