worksheet 07

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1 Worksheet 07

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1.0.1 Topics

• Density-Based Clustering

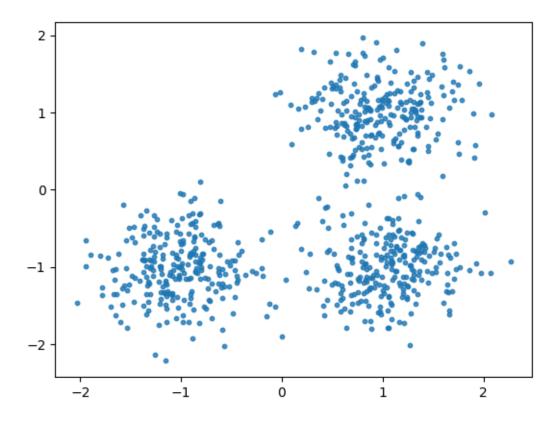
1.0.2 Density-Based Clustering

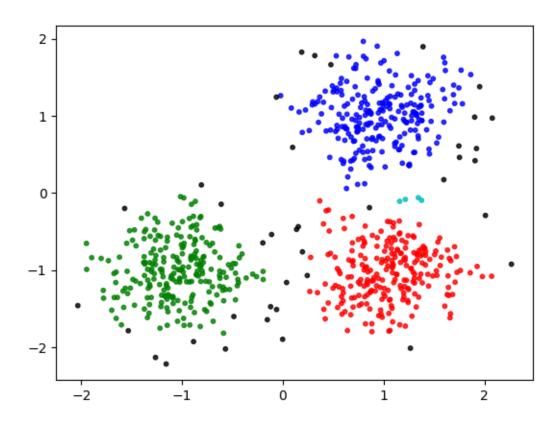
Follow along with the live coding of the DBScan algorithm.

```
[5]: import numpy as np
     import matplotlib.pyplot as plt
     import sklearn.datasets as datasets
     centers = [[1, 1], [-1, -1], [1, -1]]
     X, _ = datasets.make_blobs(n_samples=750, centers=centers, cluster_std=0.4,
                                 random_state=0)
     print(X)
     plt.scatter(X[:,0],X[:,1],s=10, alpha=0.8)
     plt.show()
     class DBC():
         def __init__(self, dataset, min_pts, epsilon):
             self.dataset = dataset
             self.min_pts = min_pts
             self.epsilon = epsilon
             self.assignments = [-1 for x in range(len(self.dataset))]
         def dbscan(self):
             11 11 11
             returns a list of assignments. The index of the
             assignment should match the index of the data point
```

```
in the dataset.
      cluster_id = 0 #changed cluster num to cluster id cause it makes more_
⇔sense to me
      for i in range(len(self.dataset)):
          if not self.is_unassigned(i) :
               continue
          if self.is_core_point(i):
               #start building new cluster
               self.make_cluster(i, cluster_id=cluster_id)
               cluster_id += 1
      return self.assignments
  def is_core_point(self, i):
      return len(self.get_neigborhood(i)) >= self.min_pts
  def is_unassigned(self, i):
      return self.assignments[i] == -1
  def get_neigborhood(self, i):
      neighborhood = []
      for j in range(len(self.dataset)):
          if i != j and self.distance(i, j) <= self.epsilon:</pre>
               neighborhood.append(j)
      return neighborhood
  def get_unassigned_neigborhood(self, i):
      neighborhood = self.get_neigborhood(i)
      return [point for point in neighborhood if self.is_unassigned(point)]
  def distance(self, i, j):
      return np.linalg.norm(self.dataset[i] - self.dataset[j])
  def make_cluster(self, i, cluster_id):
      self.assignments[i] = cluster_id
      neighbors_queue = self.get_unassigned_neigborhood(i) #maybe get a stack_
⇔or a double ended queue
      while len(neighbors_queue) > 0:
```

```
next_pt = neighbors_queue.pop()
            if not self.is_unassigned(next_pt): #Todo: Make this a function and ⊔
 ⇔improve data structure
                continue
            self.assignments[next_pt] = cluster_id #Note: border points will be_
 ⇔assigmend to the cluster in a last come last serve basis
            if self.is_core_point(next_pt):
                #self.assignments[next_pt] = cluster_id
                neighbors_queue += self.get_unassigned_neigborhood(next_pt)
        return
clustering = DBC(X, 3, .2).dbscan()
colors = np.array([x for x in 'bgrcmykbgrcmykbgrcmykbgrcmyk'])
colors = np.hstack([colors] * 200)
plt.scatter(X[:, 0], X[:, 1], color=colors[clustering].tolist(), s=10, alpha=0.
 ⇔8)
plt.show()
[[ 0.84022039    1.14802236]
[-1.15474834 -1.2041171 ]
[ 0.67863613  0.72418009]
[ 0.26798858 -1.27833405]
[-0.88628813 -0.30293249]
[ 0.60046048 -1.29605472]]
```





1.1 Challenge Problem

Using the code above and the template provided below, create the animation below of the DBScan algorithm.

```
[6]: from IPython.display import Image
Image(filename="dbscan_2.gif", width=500, height=500)
```

[6]: <IPython.core.display.Image object>

Hints:

- First animate the dbscan algorithm for the dataset used in class (before trying to create the above dataset)
- Take a snapshot of the assignments when the point gets assigned to a cluster
- Confirm that the snapshot works by saving it to a file
- Don't forget to close the matplotlib plot after saving the figure
- Gather the snapshots in a list of images that you can then save as a gif using the code below
- Use ax.set_aspect('equal') so that the circles don't appear to be oval shaped
- To create the above dataset you need two blobs for the eyes. For the mouth you can use the following process to generate (x, y) pairs:
 - Pick an x at random in an interval that makes sense given where the eyes are positioned
 - For that x generate y that is 0.2 * x^2 plus a small amount of randomness
 - zip the x's and y's together and append them to the dataset containing the blobs

```
[4]: import numpy as np
  from PIL import Image as im
  import matplotlib.pyplot as plt
  import sklearn.datasets as datasets

TEMPFILE = 'temp.png'

class DBC():

  def __init__(self, dataset, min_pts, epsilon):
      self.dataset = dataset
      self.min_pts = min_pts
      self.epsilon = epsilon
      self.snaps = []
      self.assignments = [-1 for x in range(len(self.dataset))]

'''A get function to return the x axis of the point i in the dataset'''
  def getX(self,i):
```

```
return self.dataset[i,0]
   '''A get function to return the y axis of the point i in the dataset'''
  def getY(self,i):
      return self.dataset[i,1]
  def snapshot(self,i):
       fig, ax = plt.subplots()
       '''This colors variables follows the same one as the gif '''
       colors = np.array([x for x in 'gcrmykbgrcmykbgrcmykbgrcmyk'])
       colors = np.hstack([colors] * 200)
       I I I
       I need the x and y axis of the dataset to plot the point i for the \sqcup
⇔circle. This way the circle will be centered around the point i
      x = self.dataset[:,0]
      y = self.dataset[:,1]
      coloring = []
       ^{\prime\prime\prime}Because the example qif has the unassigned points as blue I will do_\sqcup
⇔the same.'''
       for j in range(len(self.dataset)):
           if self.assignments[j] == -1:
               coloring.append('b')
           else:
               coloring.append(colors[self.assignments[j]])
       '''Here we create the sanpshot of the current state of the dataset and
⇒the clusters. and use the coloring we assigned in the above for loop'''
       ax.scatter(x, y, s=10, linewidth=0.25, color=coloring)
       '''Here we create the circle and center it around the point i. I tried _{\sqcup}
\rightarrowto make the circle just as big as in the example qif. I did fill = false to<sub>11</sub>
⇒make it transparent and edgecolor to make the circle black.'''
       cir = plt.Circle(xy=[self.getX(i), self.getY(i)], radius=.25 , fill =
→False, edgecolor= 'black' ) # create circle around the point assigned
      ax.add patch(cir)
      ax.set_xlim(min(x)-1,max(x)+1)
       ax.set_ylim(min(y)-1, max(y)+1)
```

```
ax.set_aspect('equal') # necessary or else the circles appear to be_
⇔oval shaped
      fig.savefig(TEMPFILE)
      plt.close()
      return im.fromarray(np.asarray(im.open(TEMPFILE)))
  def dbscan(self):
      cluster_id = 0 #changed cluster num to cluster id cause it makes more_
⇔sense to me
      for i in range(len(self.dataset)):
          if not self.is_unassigned(i) :
              continue
          if self.is_core_point(i):
               #start building new cluster
               self.make_cluster(i, cluster_id=cluster_id)
               cluster_id += 1
      return self.assignments
  def is_core_point(self, i):
      return len(self.get_neigborhood(i)) >= self.min_pts
  def is_unassigned(self, i):
      return self.assignments[i] == -1
  def get_neigborhood(self, i):
      neighborhood = []
      for j in range(len(self.dataset)):
          if i != j and self.distance(i, j) <= self.epsilon:</pre>
              neighborhood.append(j)
      return neighborhood
  def get_unassigned_neigborhood(self, i):
      neighborhood = self.get_neigborhood(i)
      return [point for point in neighborhood if self.is_unassigned(point)]
  def distance(self, i, j):
      return np.linalg.norm(self.dataset[i] - self.dataset[j])
```

```
def make_cluster(self, i, cluster_id):
        self.assignments[i] = cluster id
        neighbors queue = self.get_unassigned_neigborhood(i) #maybe qet a stack_
 →or a double ended queue
        while len(neighbors queue) > 0:
            next_pt = neighbors_queue.pop()
            if not self.is_unassigned(next_pt): #Todo: Make this a function and_
 ⇒improve data structure
                continue
            self.assignments[next_pt] = cluster_id #Note: border points will be_
 ⇔assigmend to the cluster in a last come last serve basis
            if self.is_core_point(next_pt):
                neighbors_queue += self.get_unassigned_neigborhood(next_pt)
                 '''I snap after each point is assigned to a cluster, This makes_{\sqcup}
 _{
ightharpoonup} it so that you can see the points get assigned to the cluster in the gif as_{\sqcup}
 ⇔well as seeing
                the circle move around in the gif'''
                self.snaps.append(self.snapshot(next_pt))
        return
Centers of the eyes are about one interval apart, this is great for the face
since the eyes are the same distance from the center of the face.
and are spaced apart enough'''
centers = [[1, 2], [-1, 2]]
eyes, _= datasets.make_blobs(n_samples=350,centers=centers, cluster_std=0.2,__
→random state=0)
'''the x axis of the mouth is between the interval of -2 and 2 This is great_\sqcup
⇔for the face and a wide smile
The way im using the given function multiplying it by 4 and subtracting two so \sqcup
\hookrightarrow its in the range [-2,2]'''
mouth_x = 4 * np.random.random(500)-2
```