

# Lecture 2: Continuous -Time and Discrete -Time Signals

Foundations of Digital Signal Processing

## Outline

- Signal Properties
- Periodicity
- Measures of signal “size”
- Signal Operations
- Special Signals: Impulses and Steps and Exponentials
- System Properties

# Notes

## ■ Homework

- To be submitted on Canvas
- Released on Thursday evenings
- Due at 11:59 PM on next Thursday

## ■ MATLAB

- Freely available to students via UF Apps
- <https://info.apps.ufl.edu/>
- If ineffective, student licenses are available (\$50 or \$100)
- Tutorial? Will try to post something today

## ■ Slack

- Up and operational

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- **Signal Properties**
- Periodicity
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- Signal Operations
- Special Signals: Impulses and Steps and Exponentials
- System Properties

# Signal Properties

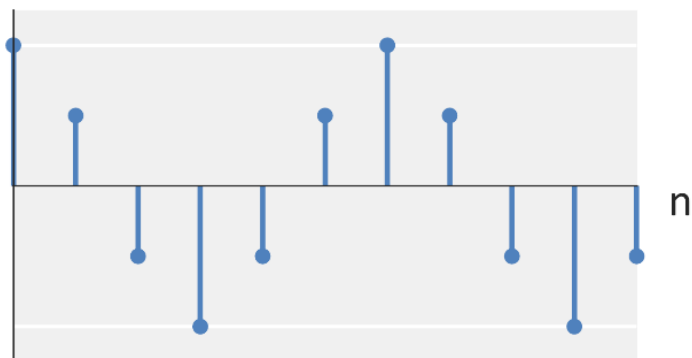
## ■ Signals: time signals (1D signals)

### ■ Continuous-time signals



$x(t)$

### ■ Discrete-time signals



$x[n]$

# Signal Properties

■ **Problem:** Sketch the signal

$$x[n] = 2^{-|n|}$$

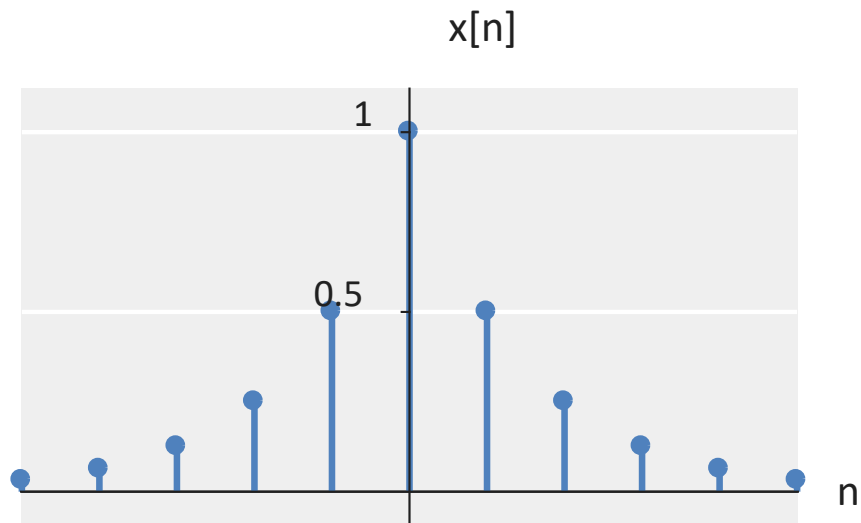
for  $-5 < n < 5$

# Signal Properties

## ■ Problem: Sketch the signal

$$x[n] = 2^{-|n|}$$

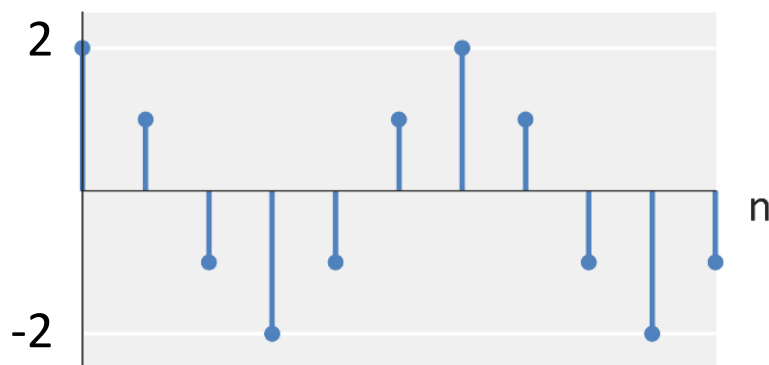
for  $-5 < n < 5$



# Signal Properties

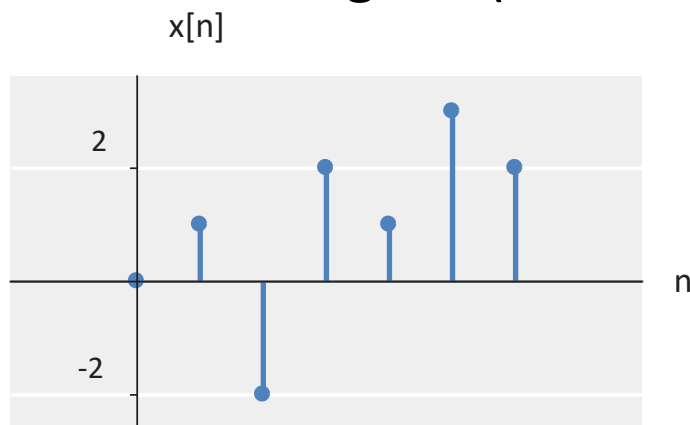
## ■ Signals: time signals (1D signals)

### ■ Discrete-time signals (infinite extent)



$x[n]$

### ■ Discrete-time signals (finite extent)



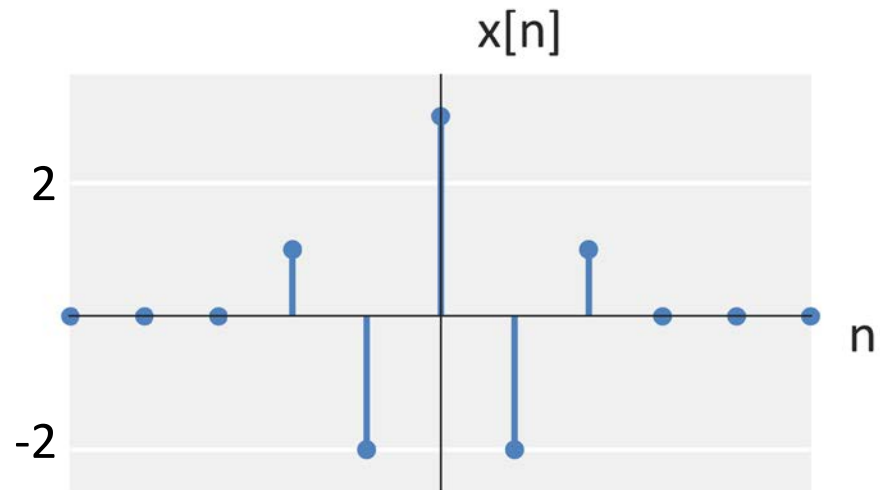
$$x[n] \text{ or } \mathbf{x} = \begin{bmatrix} 0 \\ 1 \\ -2 \\ 2 \\ 1 \\ 3 \\ 2 \end{bmatrix}$$

# Signal Properties

## ■ Even / Odd

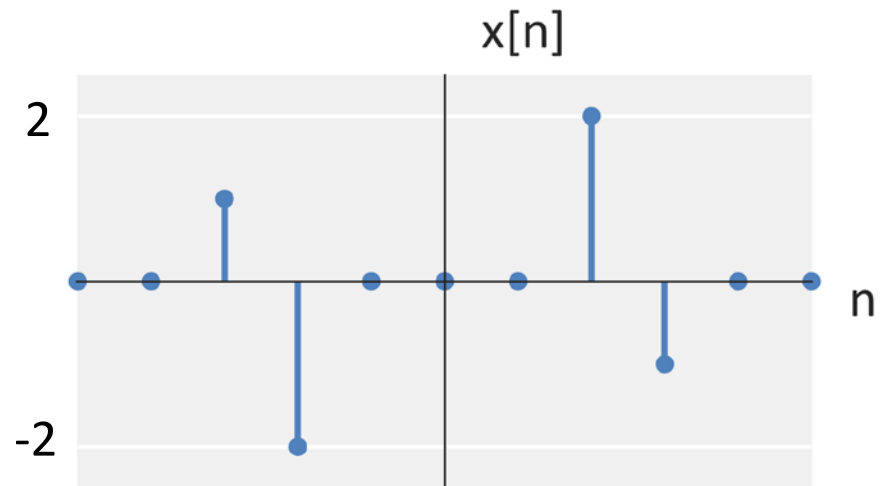
- Even signal

◇  $x[n] = x[-n]$



- Odd signal

◇  $x[n] = -x[-n]$



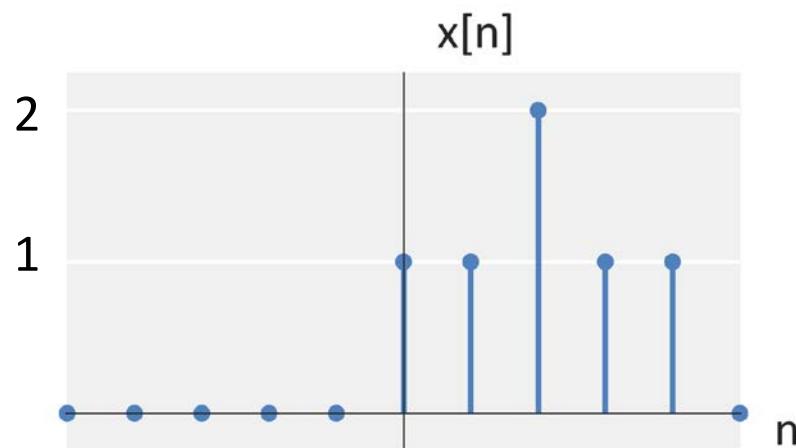


# Signal Properties

## ■ Causal / Acausal

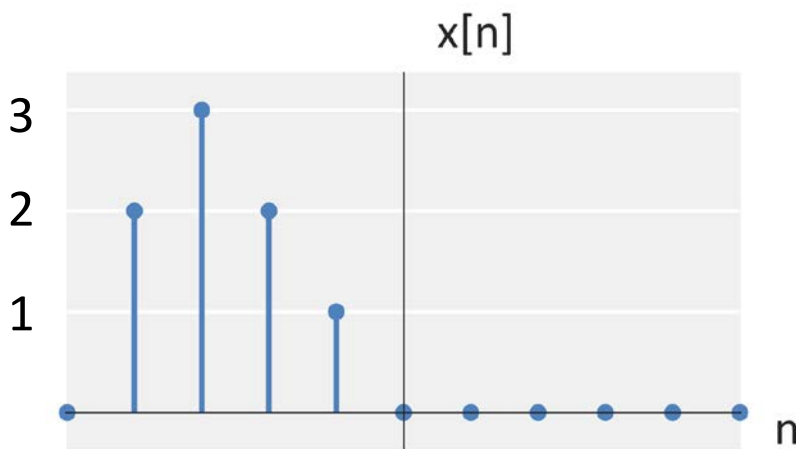
### ■ Causal signal

◇  $x[n] = 0, n < 0$



### ■ Anti-causal signal

◇  $x[n] = 0, n \geq 0$



### ■ Acausal signal

◇ Has non-zero components before and after  $n = 0$

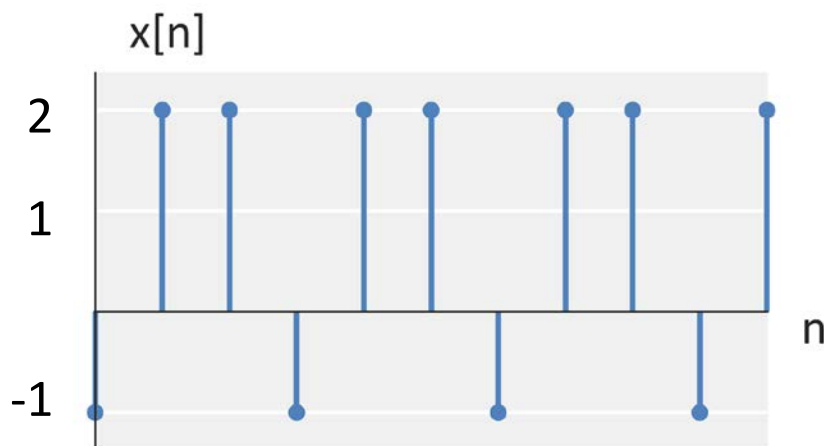
# Signal Properties

## ■ Periodic / Aperiodic

### ■ Periodic signal

◇  $x[n] = x[n + aN]$  where  $N$  and  $a$  are integers

◇  $N$  is the period of the signal



# Signal Properties

## ■ **Problem:** Consider the signal

$$x[n] = 2^{-|n|}$$

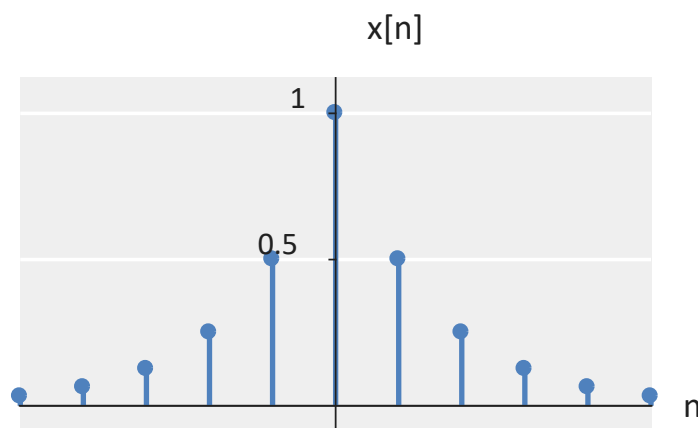
- Sketch the signal.
- Is the signal even, odd, or neither?
- Is the signal causal, anti-causal, or acausal?
- Is the signal periodic or aperiodic?

# Signal Properties

## ■ **Problem:** Consider the signal

$$x[n] = 2^{-|n|}$$

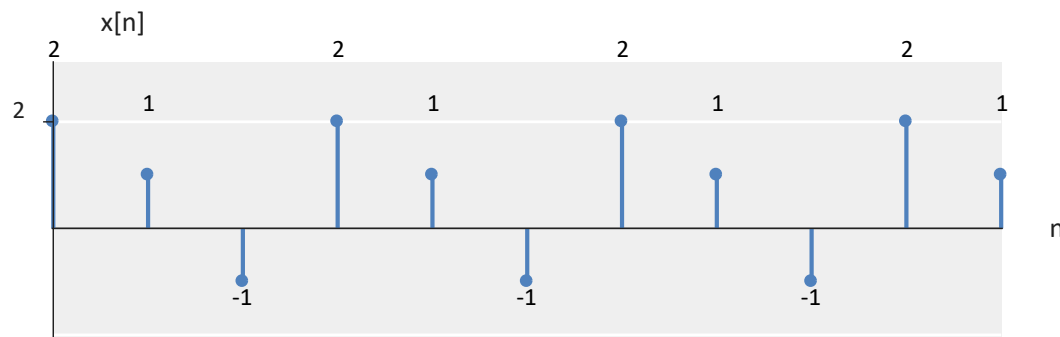
- Sketch the signal.



- Is the signal even, odd, or neither? **Even.**
- Is the signal causal, anti-causal, or acausal? **Acausal.**
- Is the signal periodic or aperiodic? **Aperiodic.**

# Signal Properties

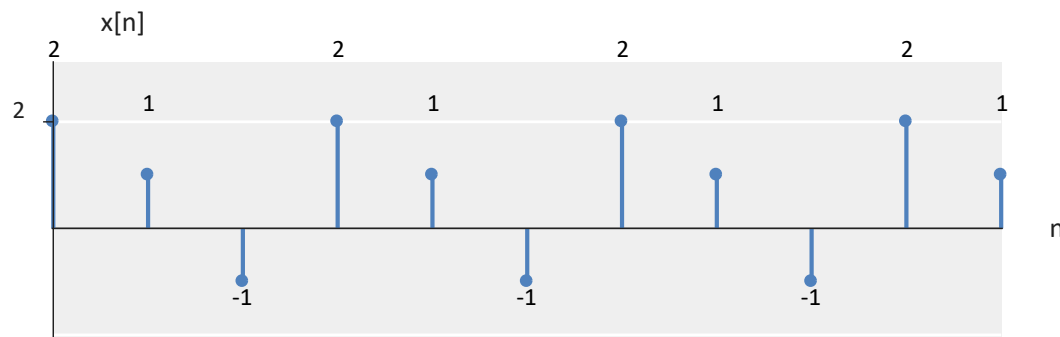
■ **Problem:** Consider the signal (assume pattern continues for  $-\infty < n < \infty$ )



- Is the signal even, odd, or neither?
- Is the signal causal, anti-causal, or acausal?
- Is the signal periodic or aperiodic?

# Signal Properties

■ **Problem:** Consider the signal (assume pattern continues for  $-\infty < n < \infty$ )



- Is the signal even, odd, or neither? **Neither.**
- Is the signal causal, anti-causal, or acausal? **Acausal.**
- Is the signal periodic or aperiodic? **Periodic.**

# Lecture 2: Continuous -Time and Discrete -Time Signals

Foundations of Digital Signal Processing

## Outline

- Signal Properties
- **Periodicity**
- Measures of signal “size”
- Signal Operations
- Special Signals: Impulses and Steps and Exponentials
- System Properties

# Periodicity

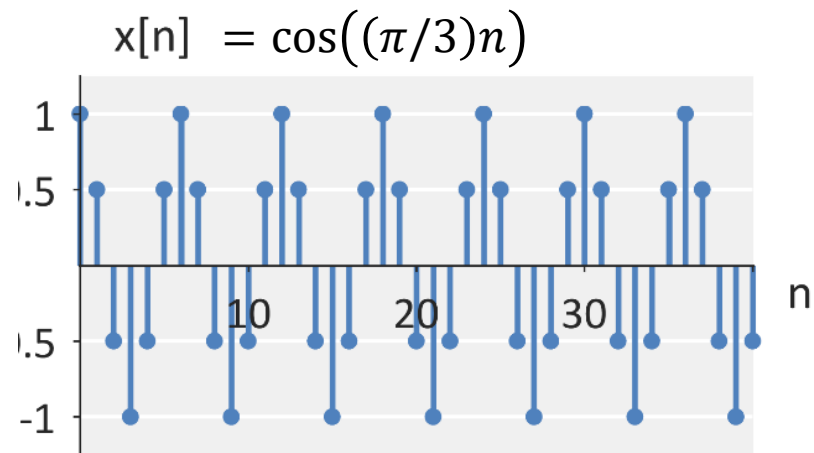
## ■ Discrete-time Periodicity

- A discrete-time signal is periodic if
  - ◇ Its period is an integer  $N$
- A discrete-time signal is periodic if and only if
  - ◇ Its frequency  $f_0 = k/N$  is a rational number
- Two discrete-time sinusoids are identical if
  - ◇ The angular frequencies are separated by integer multiples of  $2\pi$
- The highest frequency discrete-time sinusoid has
  - ◇ An angular frequency  $\omega_0 = \pi$



# Periodicity

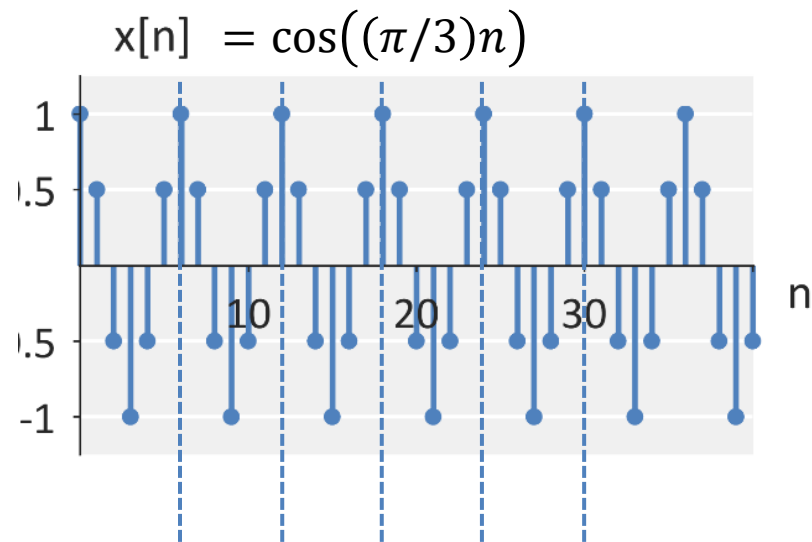
## ■ Computing Periodicity



- **Question:** Is this signal periodic?

# Periodicity

## ■ Computing Periodicity

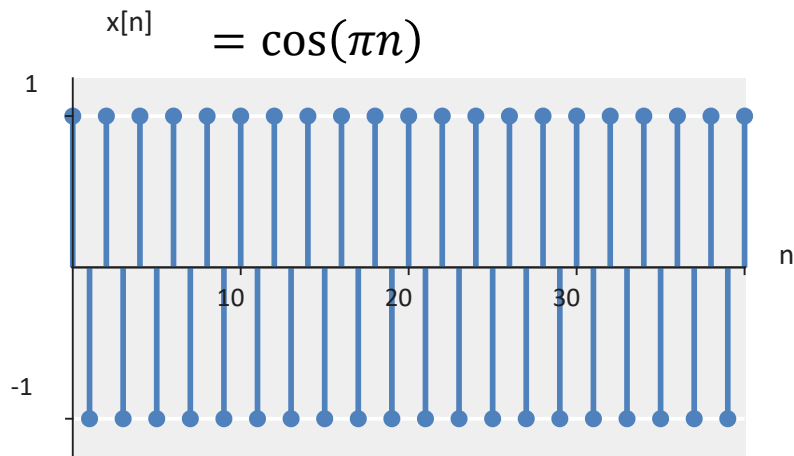


■ **Question:** Is this signal periodic? **Yes.**

- ◇ Integer Period :  $N = 6$
- ◇ Rational Frequency :  $f = 1/6$

# Periodicity

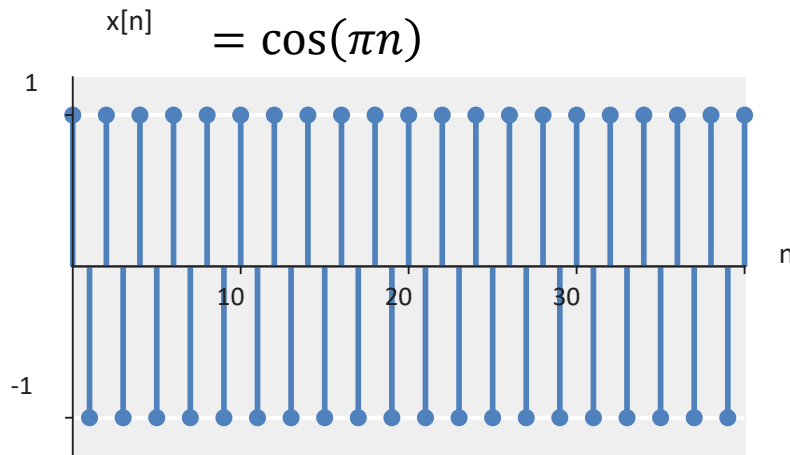
## ■ Computing Periodicity



■ **Question:** Is this signal periodic?

# Periodicity

## ■ Computing Periodicity

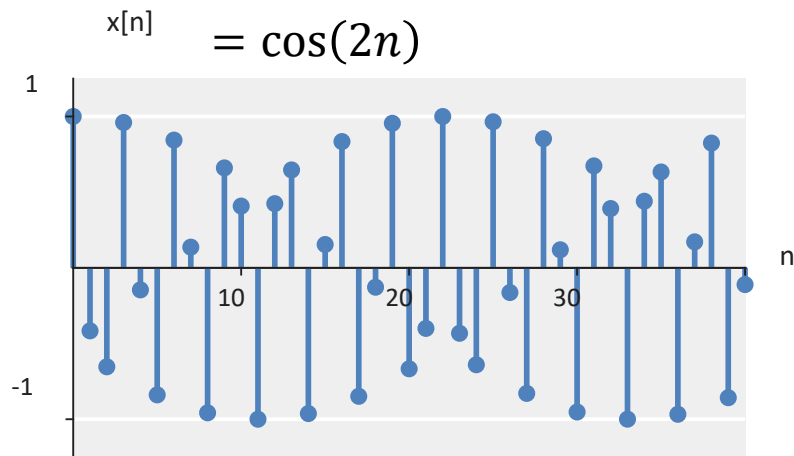


■ **Question:** Is this signal periodic? **Yes.**

- ◇ Integer Period :  $N = 1$
- ◇ Rational Frequency :  $f = 1$

# Periodicity

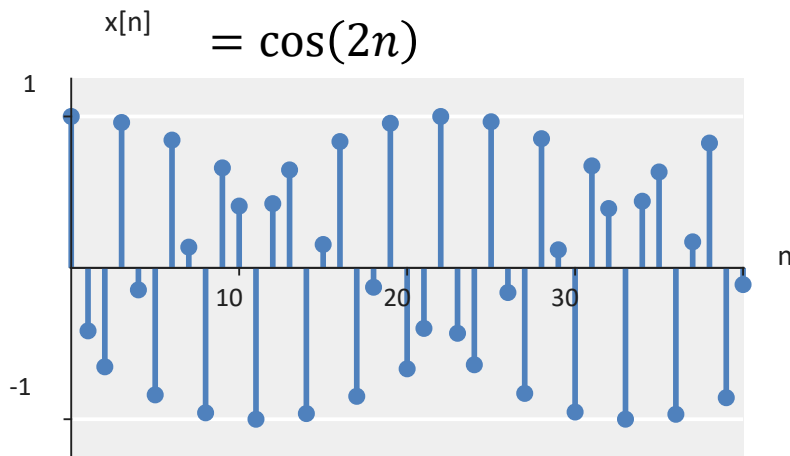
## ■ Computing Periodicity



■ **Question:** Is this signal periodic?

# Periodicity

## ■ Computing Periodicity



■ **Question:** Is this signal periodic? **No.**

- ◇ Integer Period :  $N =$  does not exist
- ◇ Rational Frequency :  $f =$  does not exist

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# Signal Size

## ■ Signal Energy

- Signal energy (infinite length signal)

$$E_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$$

- Signal energy (finite length signal)

$$E_x = \sum_{n=0}^{N-1} |x[n]|^2$$



# Signal Size

## ■ Signal Energy

- Signal energy (infinite length signal)

$$E_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$$

- Signal energy (finite length signal) ( $\ell_2$  vector norm)

$$E_x = \sum_{n=0}^{N-1} |x[n]|^2 = \|\mathbf{x}\|_2$$

# Signal Size

## ■ Signal Power

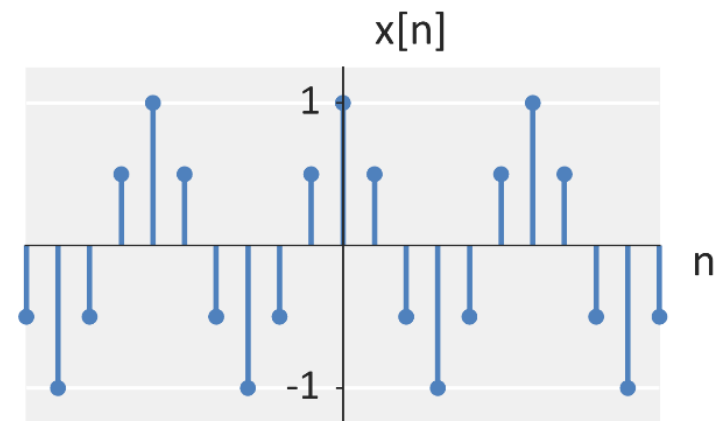
- Signal power (infinite length signal)

$$P_x = \lim_{N \rightarrow \infty} \frac{1}{2N + 1} \sum_{n=-N}^N |x[n]|^2$$

- For periodic signals, this simplifies to:

$$P_x = \frac{1}{N} \sum_{n=0}^{N-1} |x[n]|^2$$

where  $N$  is a period of the signal.



# Signal Size

## ■ Types of signals

	Energy	Power
Energy Signal	Finite $0 < E_x < \infty$	0
Power Signal	$\infty$	Finite $0 < P_x < \infty$

# Signal Size

- **Question:** Are there other measures of signal “size”?

# Signal Size

- **Question:** Are there other measures of signal “size”?
  - Yes!

# Signal Size

## ■ Applications

- When is energy (or signal size, in general) important?

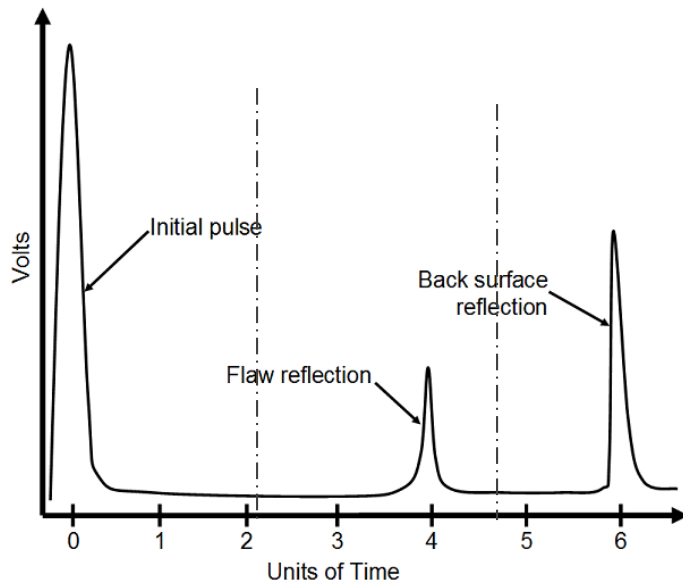
# Signal Size

## ■ Applications

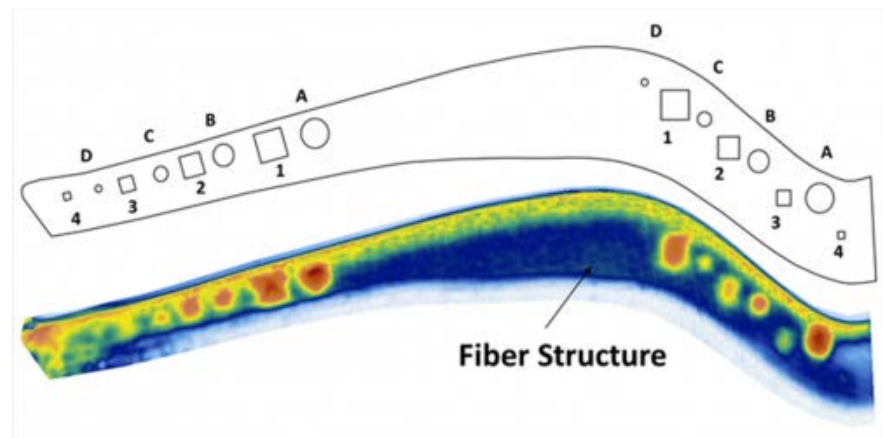
- When is energy (or signal size, in general) important?

## ■ Example: Ultrasonic C-Scan Inspection

### Ultrasonic signal from one location



<http://www.ni.com/white-paper/3368/en/>



Source: <https://www.tecscan.ca/products/ultrasonic-immersion-scanners/scan3d-high-precision-immersion-scanners/>

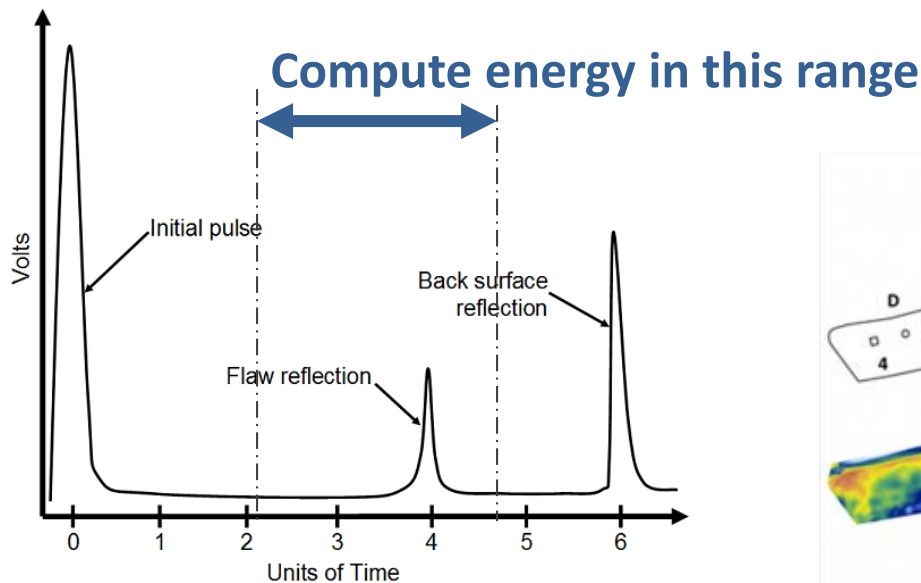
# Signal Size

## ■ Applications

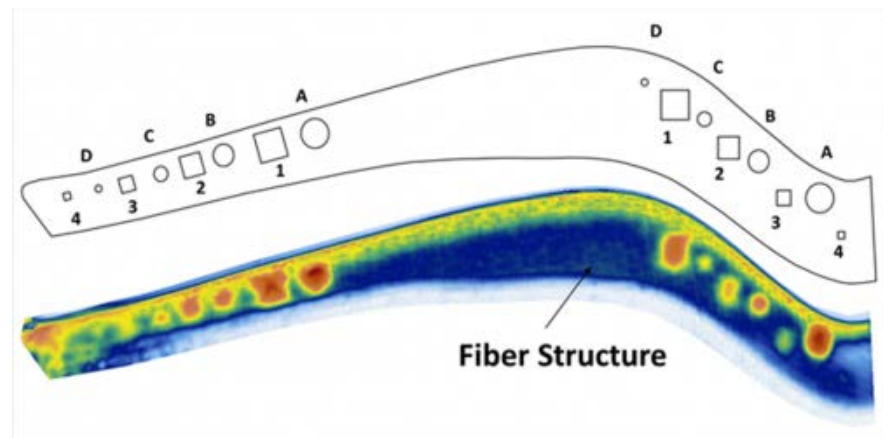
- When is energy (or signal size, in general) important?

## ■ Example: Ultrasonic C-Scan Inspection

### Ultrasonic signal from one location



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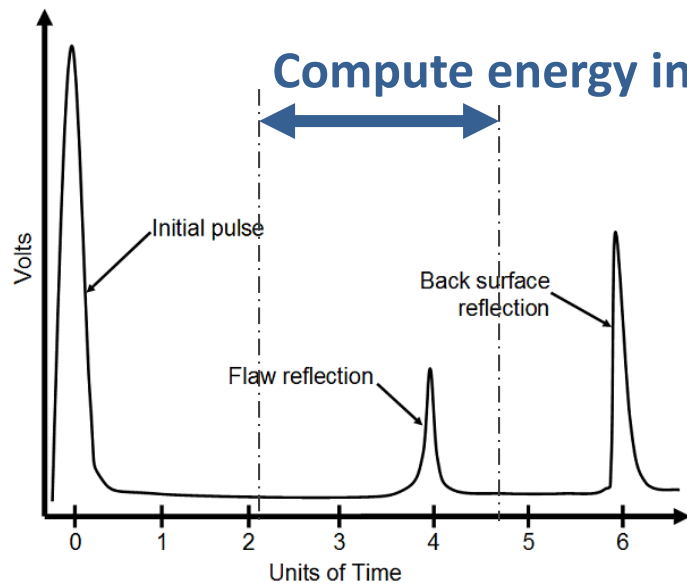
# Signal Size

## ■ Applications

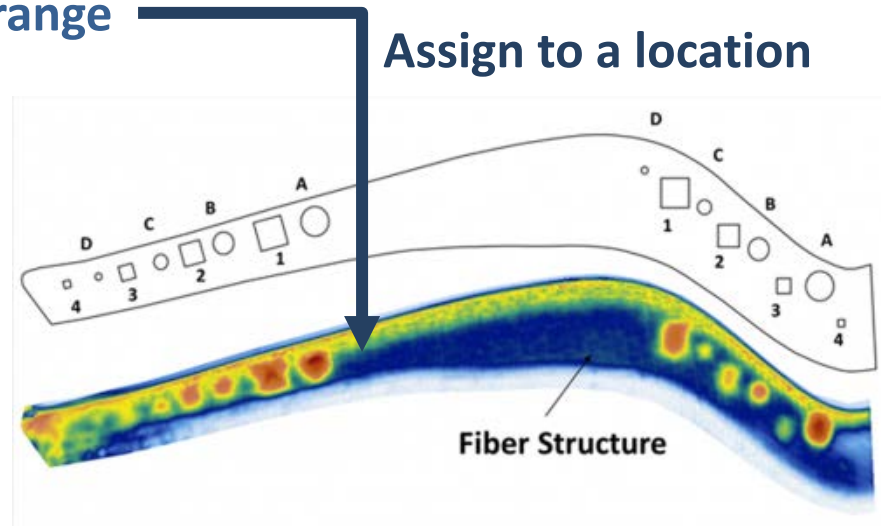
- When is energy (or signal size, in general) important?

## ■ Example: Ultrasonic C-Scan Inspection

### Ultrasonic signal from one location



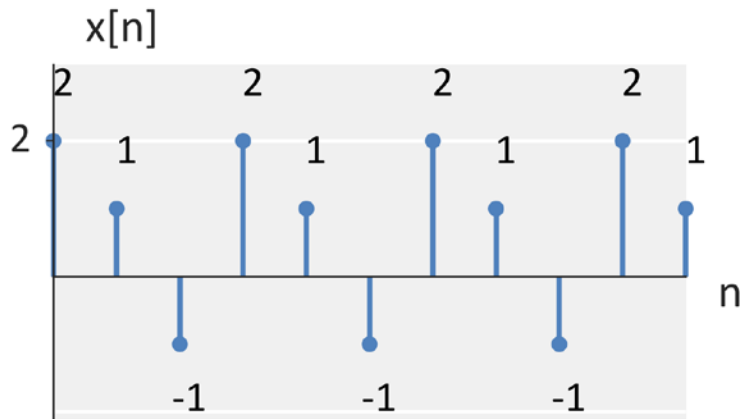
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# Signal Size

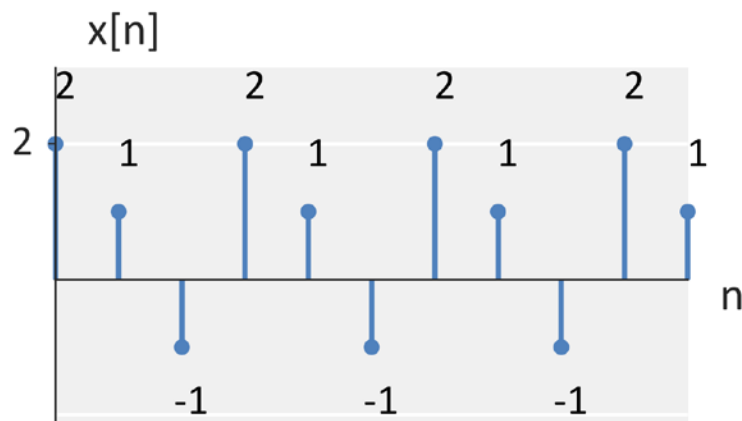
## ■ Consider the signal



- Compute the energy of the signal.
- Compute the power of the signal.

# Signal Size

## ■ Consider the signal



- Compute the energy of the signal.  $E_x = \infty$
- Compute the power of the signal.

$$P_x = \frac{1}{3} [2^2 + 1^2 + (-1)^2] = 2$$

# Signal Size

## ■ Consider the signal

$$x[n] = 2^{-|n|}$$

- Compute the energy of the signal.
- Compute the power of the signal.

# Signal Size

## ■ Consider the signal

$$x[n] = 2^{-|n|}$$

- Compute the energy of the signal.
- Compute the power of the signal.

## ■ Solution:

$$\begin{aligned} E_x &= \sum_{n=-\infty}^{\infty} 2^{-|n|} = 2 \sum_{n=1}^{\infty} 2^{-n} + \sum_{n=0}^0 2^{-n} \\ &= 2 \sum_{n=1}^{\infty} 2^{-n} + 1 = 2 \sum_{n=1}^{\infty} (1/2)^n + 1 = \\ &= 2 \sum_{n=1}^{\infty} (1/2)^n + 1 = 2 \left[ \frac{1}{1-1/2} - 1 \right] + 1 = 3 \end{aligned}$$

**Geometric series**

# Signal Size

## ■ Consider the signal

$$x[n] = 2^{-|n|}$$

- Compute the energy of the signal.
- Compute the power of the signal.

## ■ Solution:

$$P_x = 0$$

# Signal Size

## ■ Consider the signal

- Assume
  - ◇  $E_x$  is the energy of  $x[n]$
  - ◇  $E_y$  is the energy of  $y[n]$
- Show that the energy of  $x[n] + y[n]$  is not  $E_x + E_y$ .

# Signal Size

## ■ Consider the signal

- Assume
  - ◇  $E_x$  is the energy of  $x[n]$
  - ◇  $E_y$  is the energy of  $y[n]$
- Show that the energy of  $x[n] + y[n]$  is not  $E_x + E_y$ .

## ■ Solution

The energy of  $x[n] + y[n]$  is

$$\begin{aligned}\sum_{n=-\infty}^{\infty} |x[n] + y[n]|^2 &= \sum_{n=-\infty}^{\infty} |x[n]|^2 + |y[n]|^2 + 2x[n]y[n] \\ &\neq E_x + E_y = \sum_{n=-\infty}^{\infty} |x[n]|^2 + |y[n]|^2\end{aligned}$$



# Lecture 2: Continuous -Time and Discrete -Time Signals

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## Outline

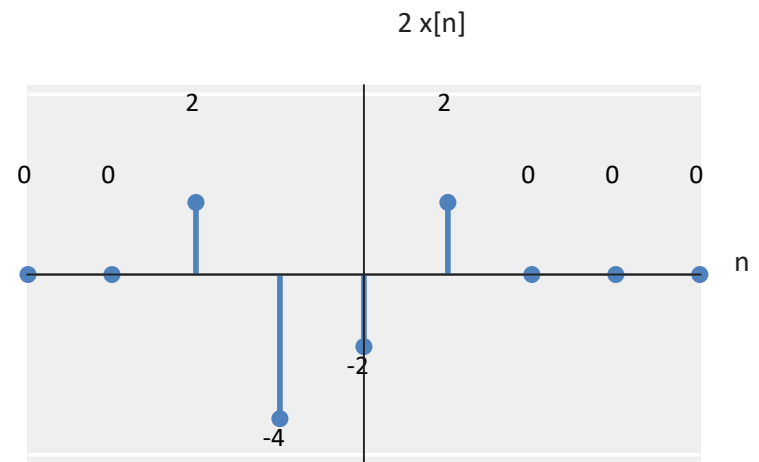
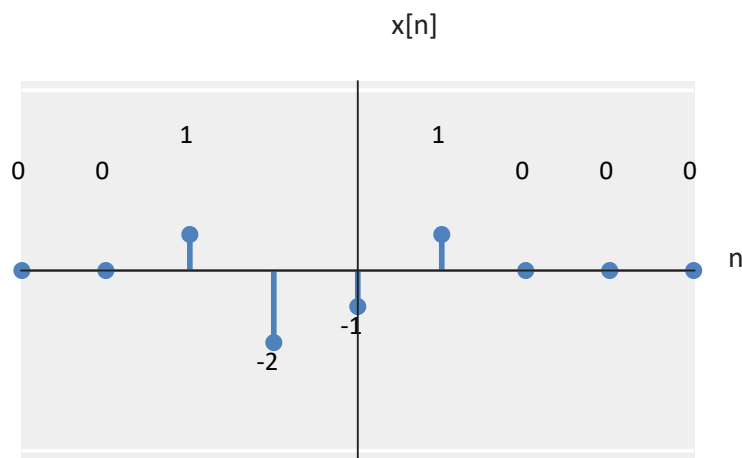
- Signal Properties
- Periodicity
- Measures of signal “size”
- **Signal Operations**
- Special Signals: Impulses and Steps and Exponentials
- System Properties

# Signal Operations

## ■ Amplitude Change

- Amplify signal by  $A$

◇  $A x[n]$

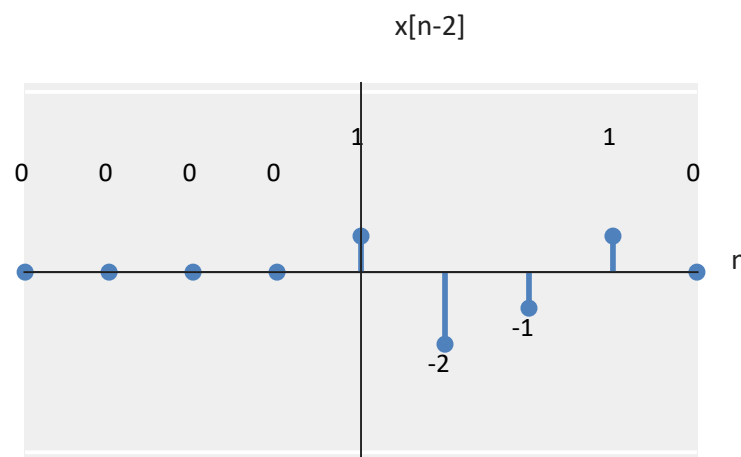
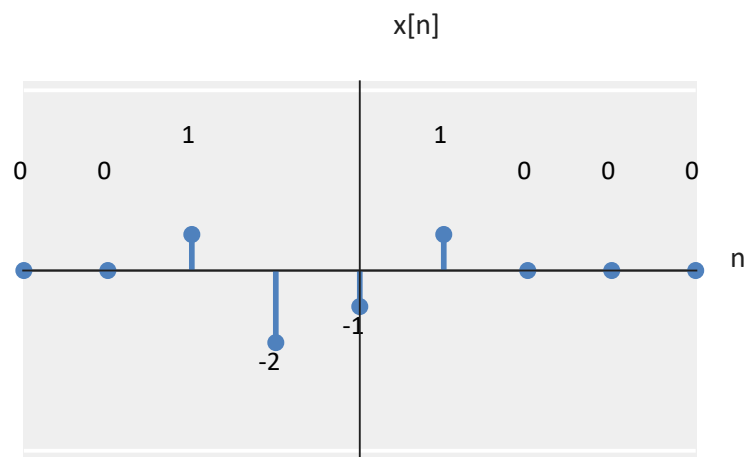


# Signal Operations

## ■ Time Shifting

- Shift to the right by  $N_0$

◇  $x[n - N_0]$

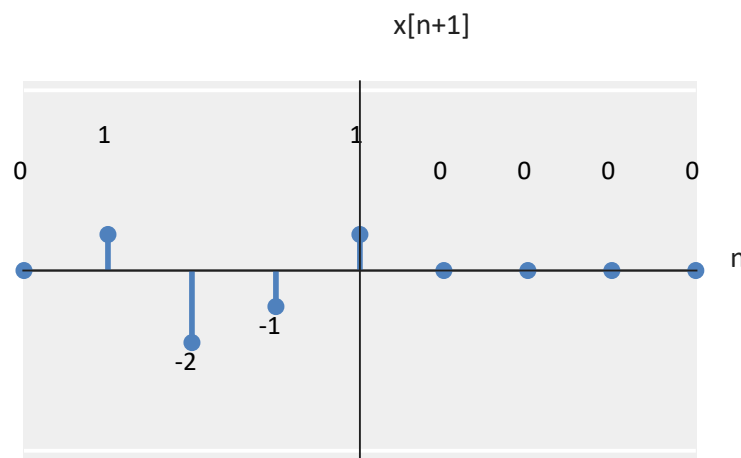
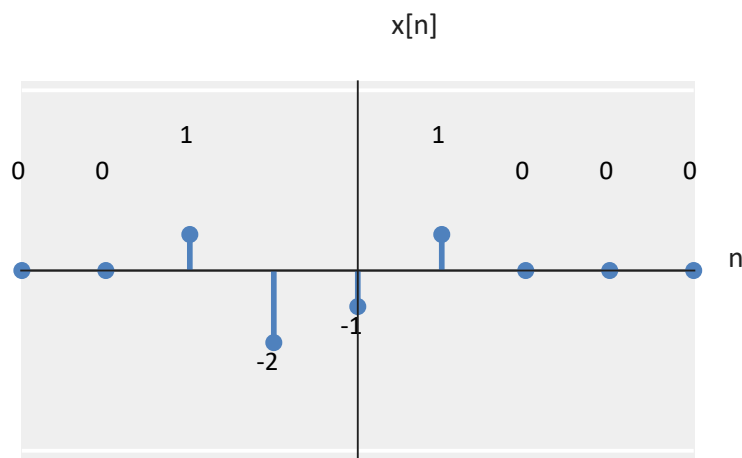


# Signal Operations

## ■ Time Shifting

- Shift to the right by  $N_0$

◇  $x[n - N_0]$

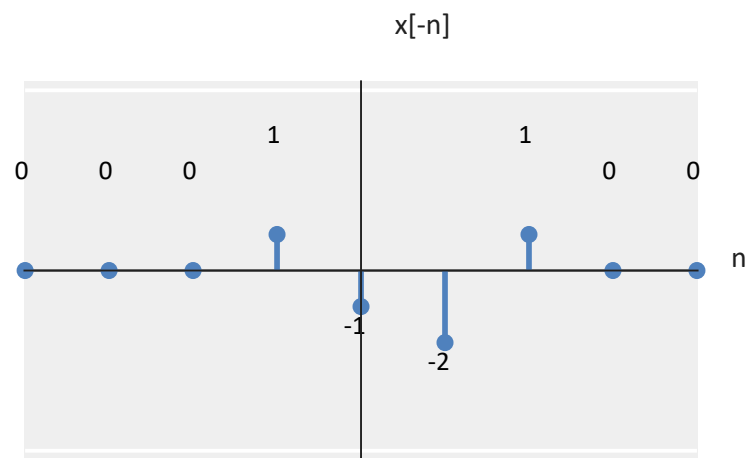
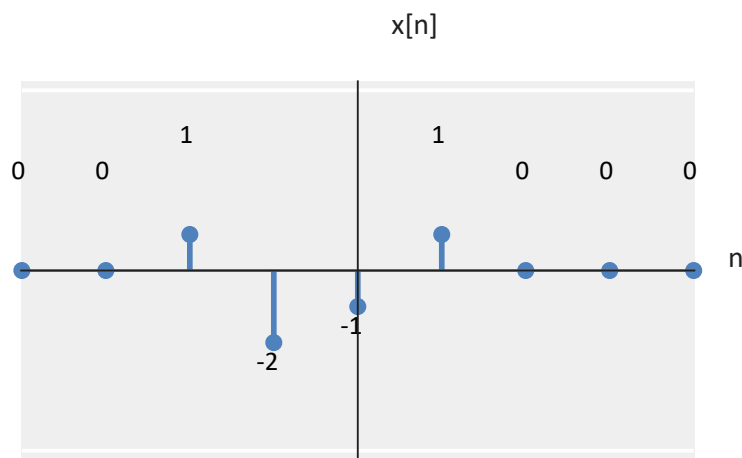


# Signal Operations

## ■ Time Reversal

- Flip the signal around  $n = 0$

◇  $x[-n]$

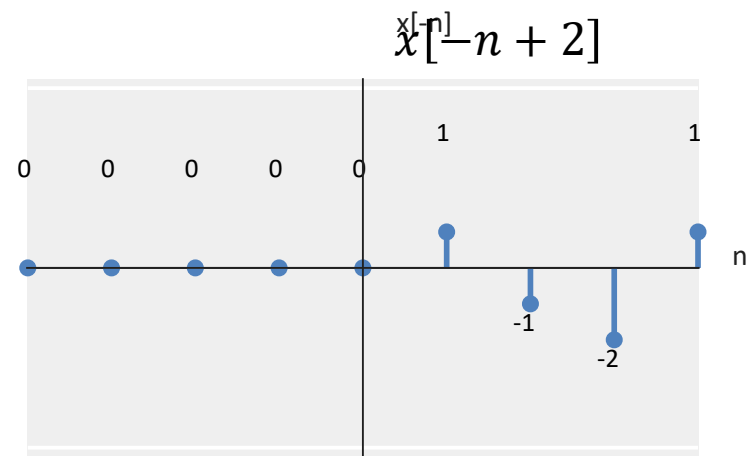
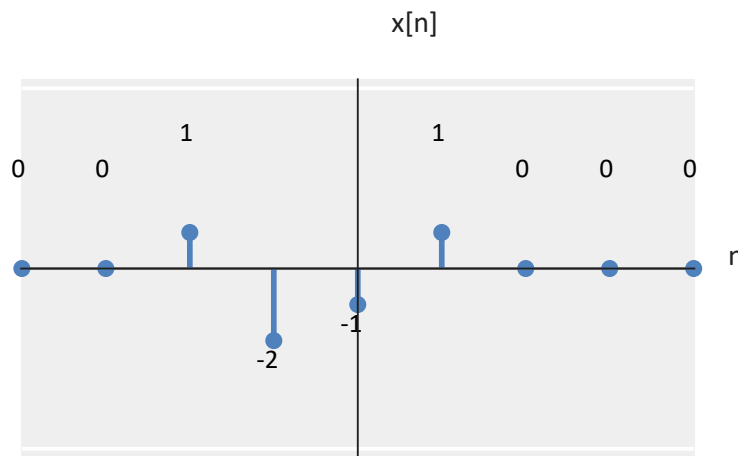


# Signal Operations

## ■ Shift & Time Reversal

- Shift first, then flip around the axis

◇  $x[-n + 2]$



# Signal Operations

## ■ Operations on two signals

### ■ Sum

$$z[n] = x[n] + y[n]$$

$$z[n] = \sum_{k=0}^{K-1} x_k[n]$$

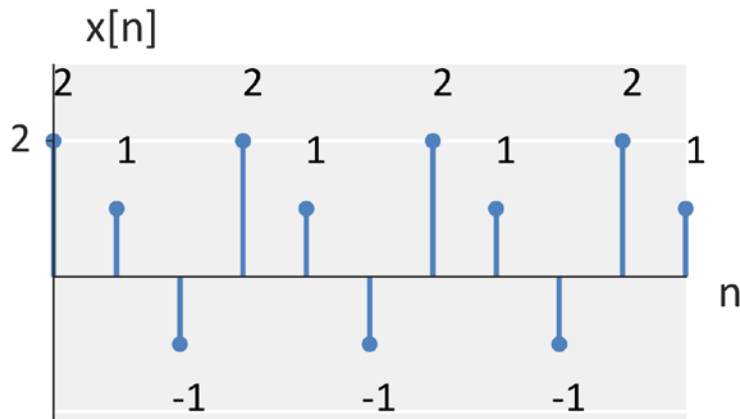
### ■ Multiplication

$$z[n] = x[n]y[n]$$

$$z[n] = \prod_{k=0}^K x_k[n]$$

# Signal Operations

- **Problem: Consider the signal** (assume the pattern continues for  $-\infty < n < \infty$ )

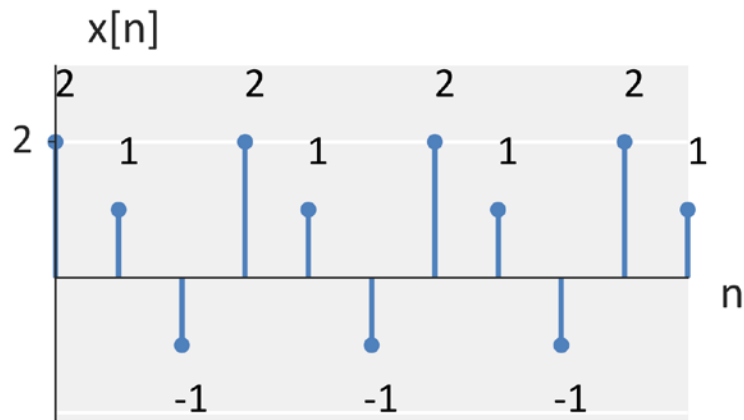


- Sketch  $x[n + 4]$

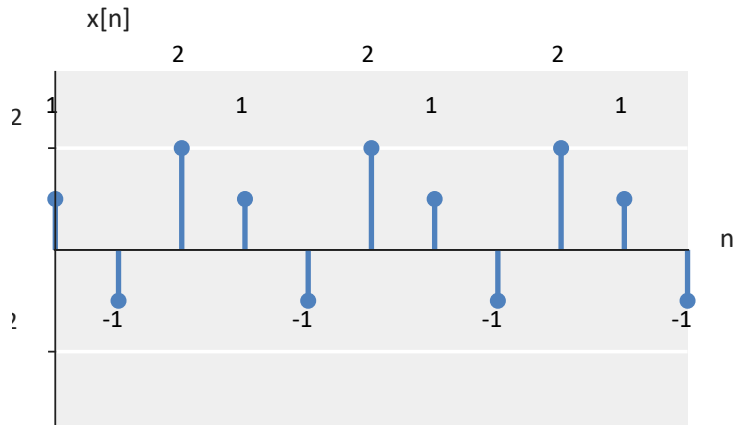


# Signal Operations

- **Problem: Consider the signal** (assume the pattern continues for  $-\infty < n < \infty$ )

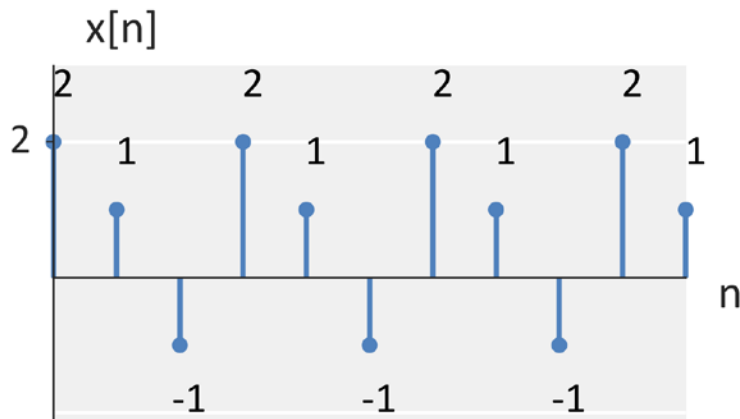


- Sketch  $x[n + 4]$



# Signal Operations

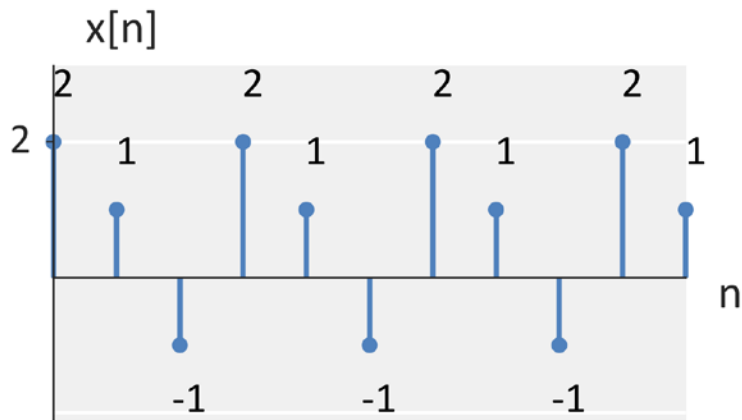
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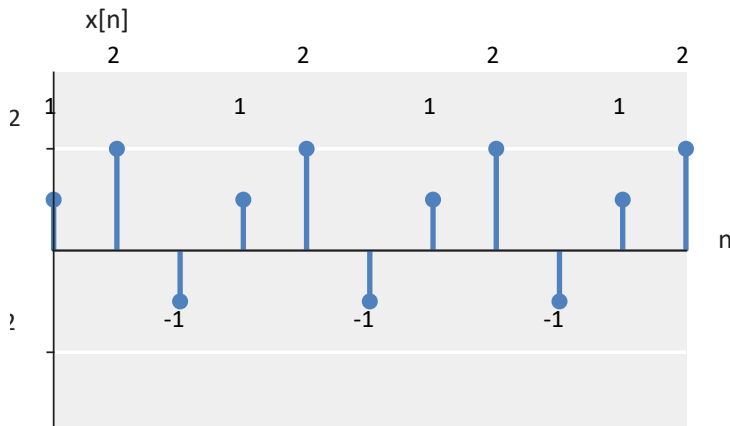
- Sketch  $x[4 - n]$

# Signal Operations

- **Problem: Consider the signal** (assume the pattern continues for  $-\infty < n < \infty$ )



- Sketch  $x[4 - n]$



# Signal Operations

## ■ Example Problems

- Assume  $x[n]$  has an energy of  $E_x = 10$ .
- Compute the energy of  $Ax[n - N_1]$

# Signal Operations

## ■ Example Problems

- Assume  $x[n]$  has an energy of  $E_x = 10$ .
- Compute the energy of  $Ax[n - N_1]$

## ■ Solution:

$$\begin{aligned} E'_x &= \sum_{n=-\infty}^{\infty} |Ax[n - N_1]|^2 \\ &= \sum_{n=-\infty}^{\infty} |A|^2 |x[n - N_1]|^2 \\ &= |A|^2 \sum_{n=-\infty}^{\infty} |x[n - N_1]|^2 \\ &= |A|^2 \sum_{n=-\infty}^{\infty} |x[n]|^2 \\ &= 10|A|^2 \end{aligned}$$

# Lecture 2: Continuous -Time and Discrete -Time Signals

Foundations of Digital Signal Processing

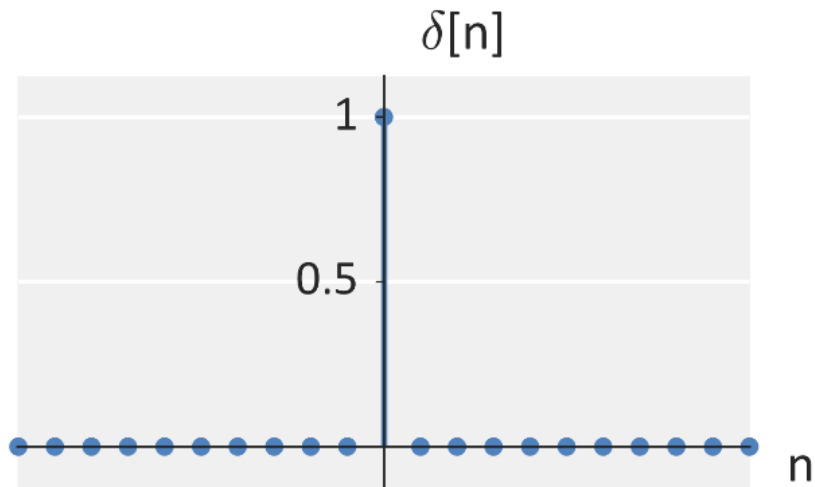
## Outline

- Signal Properties
- Periodicity
- Measures of signal “size”
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- **Special Signals: Impulses and Steps and Exponentials**
- System Properties

# Special Signals

## ■ Impulse Signals

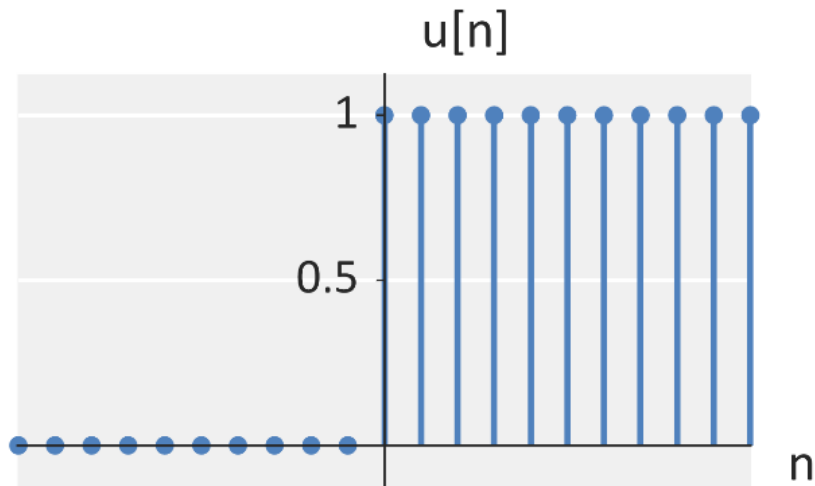
$$\delta[n] = \begin{cases} 1 & \text{when } n = 0 \\ 0 & \text{when } n \neq 0 \end{cases}$$



# Special Signals

## ■ Heaviside step functions

$$u[n] = \begin{cases} 1 & \text{when } n \geq 0 \\ 0 & \text{when } n < 0 \end{cases}$$

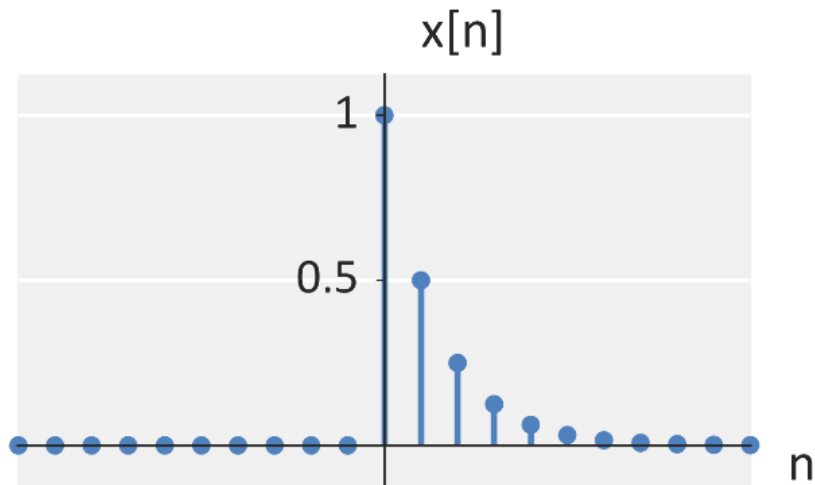




# Special Signals

## ■ Stepped Exponentials

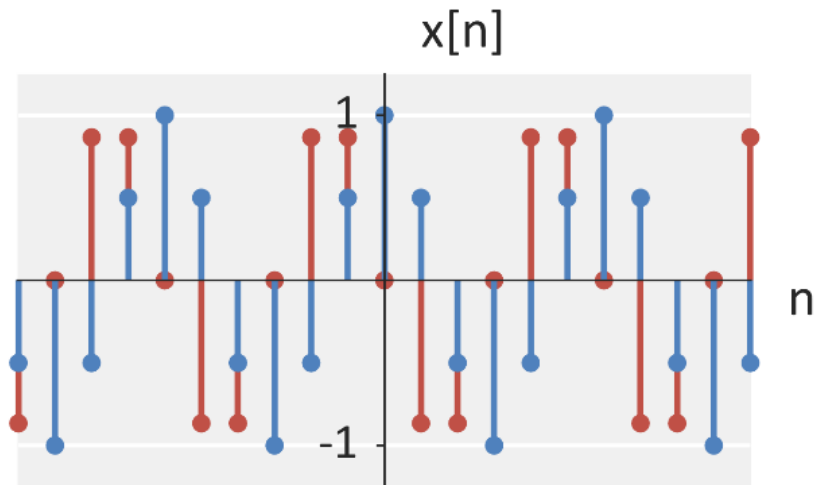
- $x[n] = e^{-an}u[n]$
- $x[n] = r^{-n}u[n], \quad r > 1$



# Special Signals

## ■ Complex Exponentials

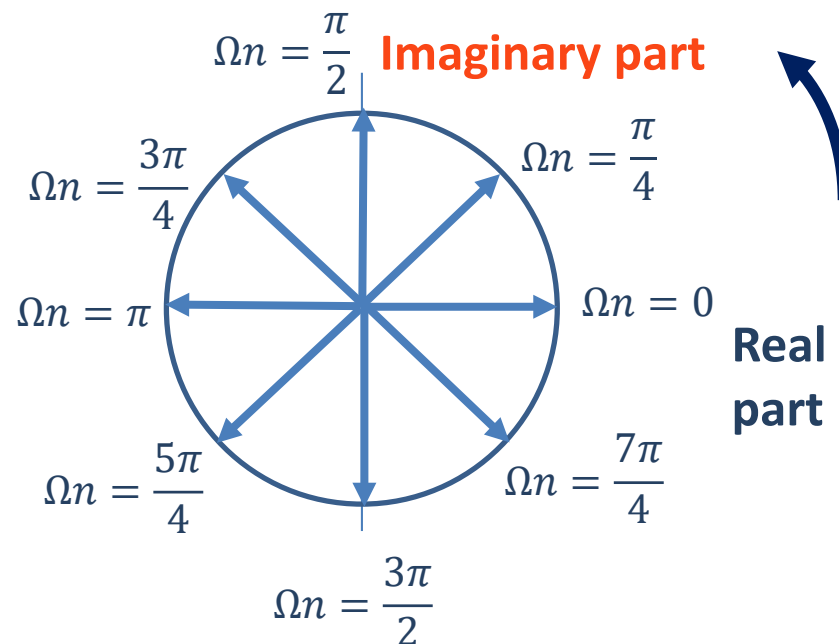
- $x[n] = e^{-(j\Omega + \sigma)n}$
- $x[n] = (r + j\gamma)^{-n}$



# Special Signals

## ■ Complex Exponentials

- $x[n] = e^{-j\Omega n}$
- $= \cos(\Omega n) + j\sin(\Omega n)$
- $= \text{real} + j \text{imag}$



# Special Signals

## ■ Example Problem

Assume  $x[n] = \cos((\pi/3)n)$

Let  $y[n] = x[n]\delta[n]$

- Simplify  $y[n]$

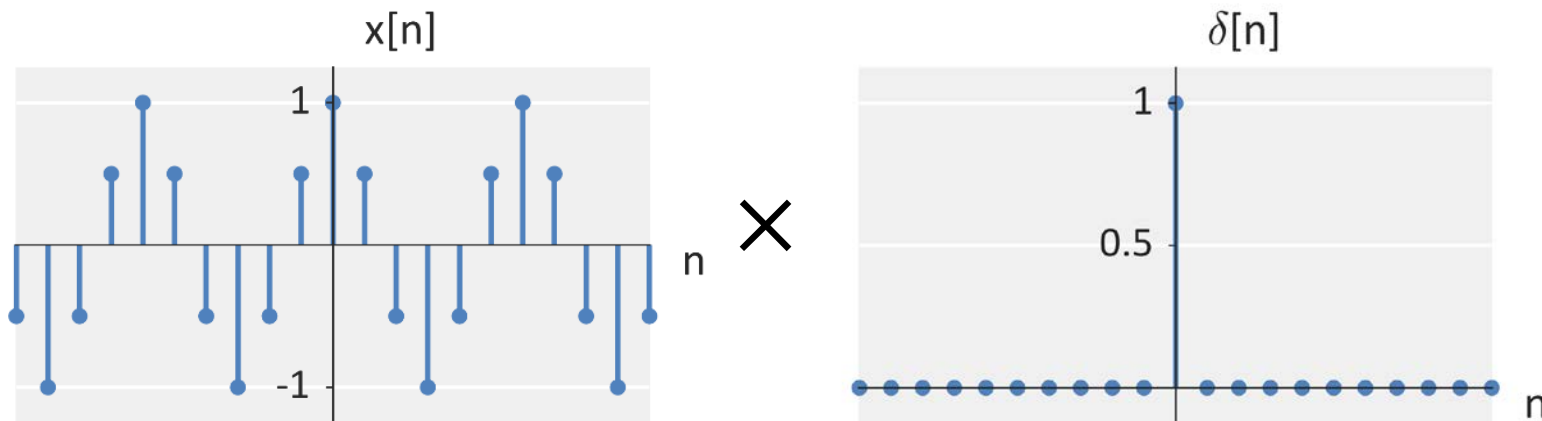
# Special Signals

## ■ Example Problem

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# Special Signals

## ■ Example Problem

Assume  $x[n] = \cos((\pi/3)n)$

Let  $y[n] = x[n]\delta[n]$

- Simplify  $y[n]$
- $y[n] = x[n]\delta[n]$
- $y[n] = x[0]\delta[n] = \cos((\pi/3)0) = \delta[n]$

# Special Signals

## ■ Example Problem

Assume  $x[n] = \cos((\pi/3)n)$

Let  $y[n] = x[n]\delta[n - 3]$

- Simplify  $y[n]$

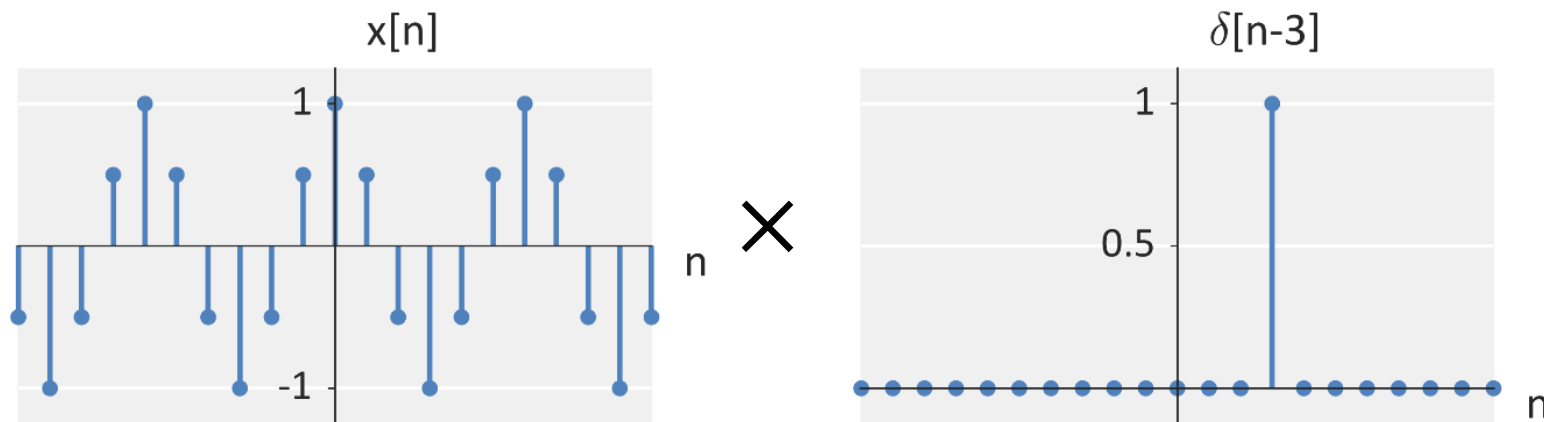
# Special Signals

## ■ Example Problem

$$\text{Assume } x[n] = \cos((\pi/3)n)$$

$$\text{Let } y[n] = x[n]\delta[n - 3]$$

### ■ Simplify $y[n]$





# Special Signals

## ■ Example Problem

Assume  $x[n] = \cos((\pi/3)n)$

Let  $y[n] = x[n]\delta[n - 3]$

- Simplify  $y[n]$  (i.e., remove  $\delta[n]$ ).
- $y[n] = x[n]\delta[n]$
- $y[n] = x[5] = \cos((\pi/3)3) = -\delta[n - 3]$

# Special Signals

## ■ Example Problem

- Show that

$$x[n] = \sum_{m=-\infty}^{\infty} x[n]\delta[n-m]$$

# Special Signals

## ■ Example Problem

- Show that

$$x[n] = \sum_{m=-\infty}^{\infty} x[n] \delta[n - m]$$

## ■ Solutions

$$\begin{aligned} x[n] &= \sum_{m=-\infty}^{\infty} x[n] \delta[n - m] \\ &= \sum_{m=-\infty}^{\infty} x[m] \delta[n - m] = x[m] \sum_{m=-\infty}^{\infty} \delta[n - m] \\ &= x[n] \end{aligned}$$

# Lecture 2: Continuous -Time and Discrete -Time Signals

Foundations of Digital Signal Processing

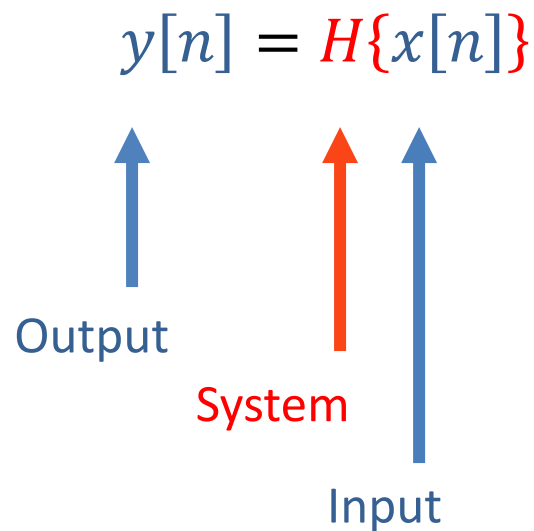
## Outline

- Signal Properties
- Periodicity
- Measures of signal “size”
- Signal Operations
- Special Signals: Impulses and Steps and Exponentials
- **System Properties**

# System Properties

## ■ Input-output system model

- A generic system is define by



# System Properties

## ■ Linear / Nonlinear

- A system is linear if

$$y_1[n] = H\{x_1[n]\} \quad , \quad y_2[n] = H\{x_2[n]\}$$

then

$$ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$$

# System Properties

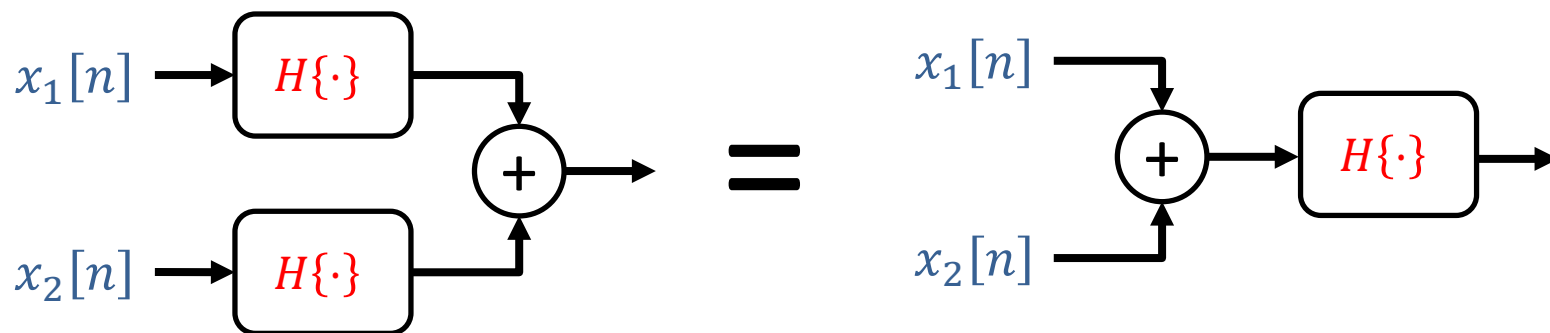
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# System Properties

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- **Question:** Why do I care about linearity?



# System Properties

## ■ Linear / Nonlinear

- A system is linear if

$$y_1[n] = H\{x_1[n]\} \quad , \quad y_2[n] = H\{x_2[n]\}$$

then

$$ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$$

- **Question:** What is an example of a non-linear system?

# System Properties

## ■ Time invariant / time varying

- A system is time-invariant if

$$y[n] = H\{x[n]\}$$

then

$$y[n + N] = H\{x[n + N]\}$$

# System Properties

## ■ Time invariant / time varying

- A system is time-invariant if

$$y[n] = H\{x[n]\}$$

then

$$y[n + N] = H\{x[n + N]\}$$

- **Question:** Why do I care about time-invariance?

# System Properties

## ■ Time invariant / time varying

- A system is time-invariant if

$$y[n] = H\{x[n]\}$$

then

$$y[n + N] = H\{x[n + N]\}$$

- **Question:** What is an example of a time varying system?

# System Properties

## ■ Memoryless / with memory

- A system  $H\{\cdot\}$  is memoryless if

$y[n]$  is a function of  $x[n]$  at **only** time  $n$

$y[n]$  is **not** a function of  $x[n - N]$  for any  $N > 0$  (past values of  $x[n - N]$ )

$y[n]$  is **not** a function of  $x[n + N]$  for any  $N > 0$  (future values of  $x[n - N]$ )

# System Properties

## ■ Memoryless / with memory

- A system  $H\{\cdot\}$  is memoryless if

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- **Question:** What is an example of a system without memory?

# System Properties

## ■ Memoryless / with memory

- A system  $H\{\cdot\}$  has memory if

$y[n]$  is a function of  $x[n]$  at **only** time  $n$

$y[n]$  is **not** a function of  $x[n - N]$  for any  $N > 0$  (past values of  $x[n - N]$ )

$y[n]$  is **not** a function of  $x[n + N]$  for any  $N > 0$  (future values of  $x[n - N]$ )

- **Question:** What is an example of a system with memory?

# System Properties

## ■ Causal / non-causal

- A system  $H\{\cdot\}$  is causal if

$y[n]$  **is only** a function of  $x[n - N]$  for any  $N \geq 0$   
(past and present values of  $x[n - N]$ )



# System Properties

## ■ Causal / non-causal

- A system  $H\{\cdot\}$  is causal if

$y[n]$  **is only** a function of  $x[n - N]$  for any  $N \geq 0$   
(past and present values of  $x[n - N]$ )

- **Question:** What is an example of a non-causal system?

# System Properties

## ■ Bounded-input, bounded-output (BIBO) stable / unstable

- A system  $H\{\cdot\}$  is BIBO stable if

$$x[n] < \infty \rightarrow H\{x[n]\} < \infty$$

# System Properties

## ■ Consider

- $y[n] = H\{x[n]\} = 5x[n] + 1$
- Is this system linear?
- Is this system time-invariant?
- Is this system memoryless?
- Is this system causal?

# System Properties

## ■ Consider

- $y[n] = H\{x[n]\} = 5x[n] + 1$

- Is this system linear?

- ◇  $H\{ax_1[n] + bx_2[n]\} = 5(ax_1[n] + bx_2[n]) + 1$

- ◇  $H\{ax_1[n]\} + H\{bx_2[n]\} = [5(ax_1[n]) + 1] + [5(bx_2[n]) + 1]$

  - ◇ **Non-linear (non-equal)**

- Is this system time-invariant?

- Is this system memoryless?

- Is this system causal?

# System Properties

## ■ Consider

- $y[n] = H\{x[n]\} = 5x[n] + 1$
  
- Is this system linear?
  
- Is this system time-invariant?
  - ◇  $H\{x[n + N]\} = 5(x[n + N]) + 1$
  - ◇  $y[n] = 5(ax[n + N]) + 1$
  - ◇ **Time-invariant (Equal!)**
  
- Is this system memoryless?
  
- Is this system causal?

# System Properties

## ■ Consider

- $y[n] = H\{x[n]\} = 5x[n] + 1$
- Is this system linear?
- Is this system time-invariant?
- Is this system memoryless?
  - ◇  $y[n]$  only depends on  $x[n]$  at the current time
  - ◇ **Memoryless**
- Is this system causal?

# System Properties

## ■ Consider

- $y[n] = H\{x[n]\} = 5x[n] + 1$

- Is this system linear?
- Is this system time-invariant?
- Is this system memoryless?
- Is this system causal?

◇ **Causal because we are memoryless**

# Lecture 2: Continuous -Time and Discrete -Time Signals

Foundations of Digital Signal Processing

## Outline

- Signal Properties
- Periodicity
- Measures of signal “size”
- Signal Operations
- Special Signals: Impulses and Steps and Exponentials
- System Properties
- **Convolution**



# Convolution

## ■ Linear and Time-Invariant (LTI)

- If a system is both linear and time-invariant, then...

**Linear:**  $ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$

**Time-invariant:**  $y[n + N] = H\{x[n + N]\}$

# Convolution

## ■ Linear and Time-Invariant (LTI)

- If a system is both linear and time-invariant, then...

**Linear:**  $ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$

**Time-invariant:**  $y[n + N] = H\{x[n + N]\}$

- Recall

$$x[n] = \sum_{m=-\infty}^{\infty} x[m]\delta[n - m]$$

$$H\{x[n]\} = H\left\{\sum_{m=-\infty}^{\infty} x[m]\delta[n - m]\right\}$$

# Convolution

## ■ Linear and Time-Invariant (LTI)

- If a system is both linear and time-invariant, then...

**Linear:**  $ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$

**Time-invariant:**  $y[n + N] = H\{x[n + N]\}$

- Recall

$$x[n] = \sum_{m=-\infty}^{\infty} x[m]\delta[n - m]$$

$$H\{x[n]\} = \sum_{m=-\infty}^{\infty} x[m] H\{\delta[n - m]\} \quad \text{Apply linearity}$$

# Convolution

## ■ Linear and Time-Invariant (LTI)

- If a system is both linear and time-invariant, then...

**Linear:**  $ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$

**Time-invariant:**  $y[n + N] = H\{x[n + N]\}$

- Recall

$$x[n] = \sum_{m=-\infty}^{\infty} x[m] \delta[n - m]$$

$$H\{x[n]\} = \sum_{m=-\infty}^{\infty} x[m] h[n - m]$$

**Apply time-invariance**

# Convolution

## ■ Linear and Time-Invariant (LTI)

- If a system is both linear and time-invariant, then...

**Linear:**  $ay_1[n] + by_2[n] = H\{ax_1[n] + bx_2[n]\}$

**Time-invariant:**  $y[n + N] = H\{x[n + N]\}$

- Recall

$$x[n] = \sum_{m=-\infty}^{\infty} x[m] \delta[n - m]$$

$$y[n] = \sum_{m=-\infty}^{\infty} x[m] h[n - m]$$

**Convolution!**