

EEE-6512: Image Processing and Computer Vision

November 17, 2017

Lecture #11: Model-Fitting

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Outline

- Overview
- Fitting Lines
- Fitting Curves
- Addressing Noise
- Fitting Multiple Models

Fitting

- We've learned how to detect edges, corners, blobs. Now what?
- We would like to form a higher-level, more compact representation of the features in the image by grouping multiple features according to a simple model

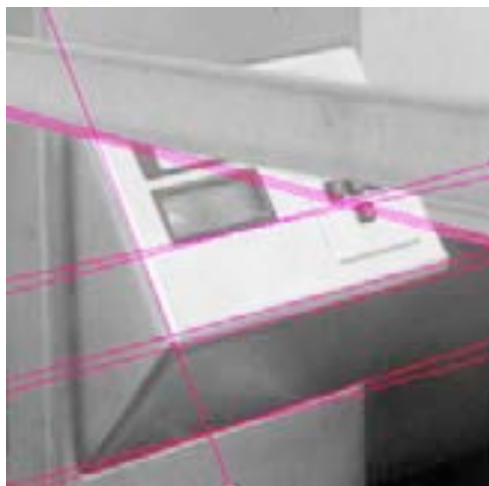


Fitting: Main idea

- **Choose a parametric model to represent a set of features**
- **Membership criterion is not local**
 - Can't tell whether a point belongs to a given model just by looking at that point
- **Three main questions:**
 - What model represents this set of features best?
 - Which of several model instances gets which feature?
 - How many model instances are there?
- **Computational complexity is important**
 - It is infeasible to examine every possible set of parameters and every possible combination of features

Fitting

Choose a *parametric model* to represent a set of features



simple model: lines



simple model: circles



complicated model: car



complicated model: face shape

Fitting -Design challenges

- Design a suitable **goodness of fit** measure
 - Similarity should reflect application goals
 - Encode robustness to outliers and noise
- Design an **optimization** method
 - Avoid local optima
 - Find best parameters quickly

Fitting: Issues

Case study: Line detection



- **Noise** in the measured feature locations
- **Extraneous data:** clutter (outliers), multiple lines
- **Missing data:** occlusions

Fitting: Overview (cont.)

- **If we know which points belong to the line, how do we find the “optimal” line parameters?**

Least squares

- **What if there are outliers?**

Robust fitting, RANSAC

- **What if there are many lines?**

Voting methods: RANSAC, Hough transform

Questions?

Slide Credits

Some slides from Dr. Stanley Birchfield, Dr. Kristen Grauman, Dr. Svetlana Lazebnik, Dr. Jia-Bin Huang