

EEE-6512: Image Processing and Computer Vision

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Lecture #8: Edges and Features

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Chapter Outline

- Course Recap
- Going Forward
- Computer Vision Overview
- Multiresolution Processing
- Edge Detection
- Approximating Intensity Edges with Polylines
- Feature Detectors
- Feature Descriptors

What have we covered so far?

(Image Processing)

- Introduction
- Fundamentals of Imaging
- Point and Geometric Transformations
- Binary Image Processing
- Spatial Domain Filtering
- Frequency Domain Filtering

Going Forward

- Edges and Features
- Segmentation
- Model Fitting
- Classification
- Color*

Computer Vision

What is computer vision?

- Enabling computers to “see” – extract information from the world by processing images obtained from visual sensors
- A sensor modality for robotics
- Computer emulation of human vision
- Inverse of Computer Graphics (Image Model -> World Model)

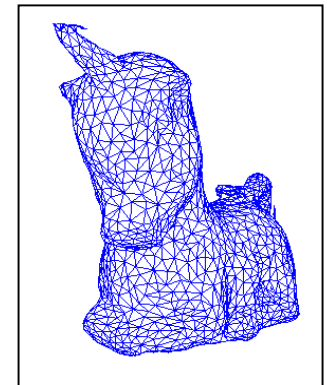
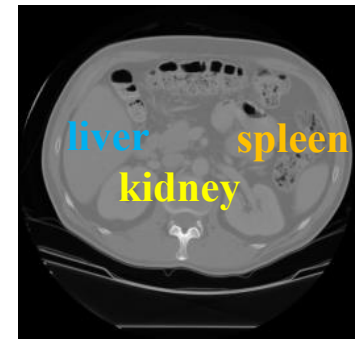
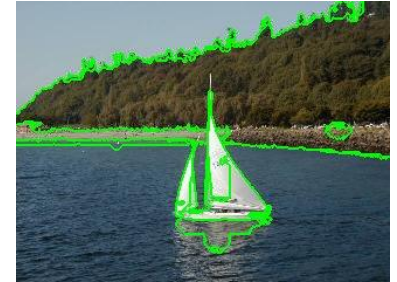


→ “Two cars are parked in front of a large gothic building during the day, after a heavy rain”

- **Used to solve:**
 - classification
 - tracking
 - structure from X

Goals of Computer Vision

- Segment an image into useful regions
- Perform measurements on certain areas
- Determine what object(s) are in the scene
- Calculate the precise location(s) of objects
- Visually inspect a manufactured object
- Construct a 3D model of the imaged object
- Find “interesting” events in a video



The Three Stages of Computer Vision

- low-level

image  **image**

- mid-level

image  **features**

- high-level

features  **analysis**

Low-Level

Sharpening



Blurring



Low-Level

Canny



Original Image



Edge Image

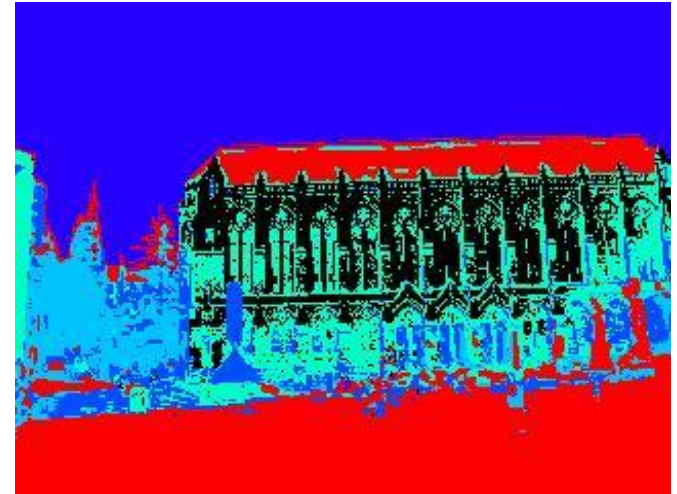
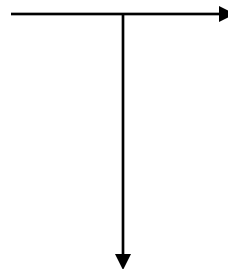
Mid-Level



original color image

K-means
clustering

(followed by
connected
component
analysis)



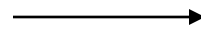
regions of homogeneous color

data
structure

Low- to High-Level



low-level



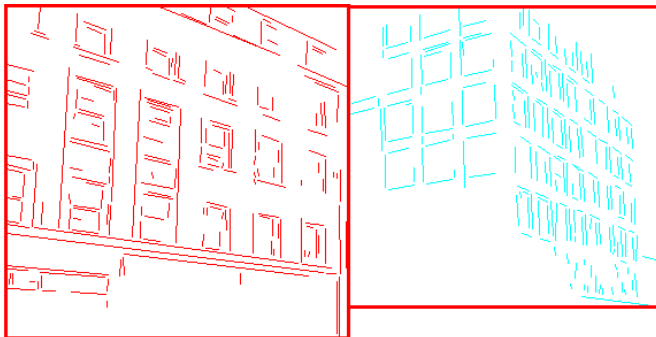
edge image

mid-level



consistent
line clusters

high-level



Building Recognition

Why is computer vision hard?



- What do the pictures show? Easy. What algorithm did you use? Difficult.
- Lots of invariants: pose, scale, lighting, color, shape, occlusion
- Context plays a big role.

What does **Computer Vision** Involve?

- Image Processing (Pre-processing)
- **Feature Extraction***
- Pattern Recognition / Machine Learning

Edges and Features

Image Pyramids: What are they good for?

- **Improve Search**

- Search over translations
Classic coarse-to-fine strategy
- Search over scale
 - Template matching
 - E.g. find a face at different scales

- **Precomputation**

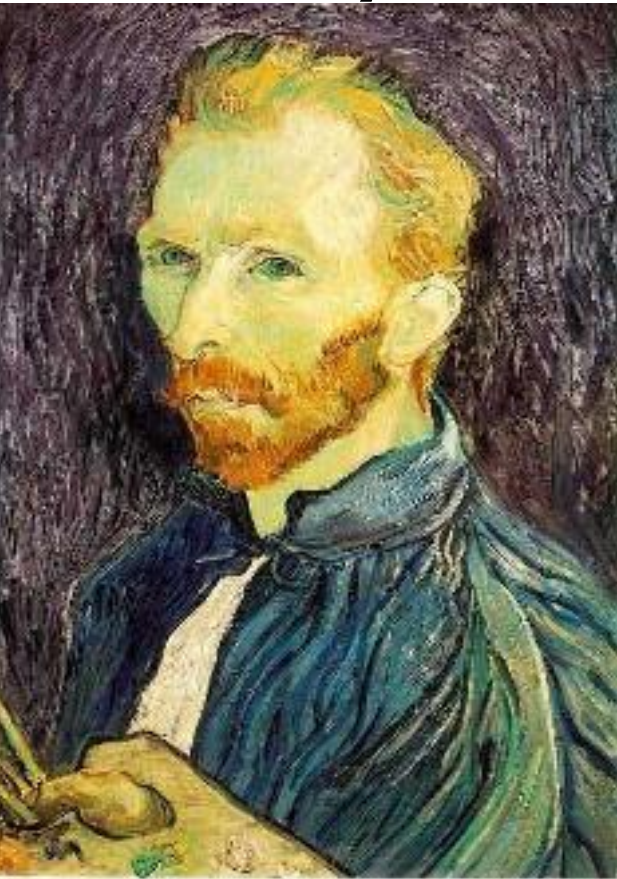
Need to access image at different blur levels

- **Image Processing**

- Editing frequency bands separately
- E.g. image blending...

Dropping Pixels v.s.
Smoothing and then dropping Pixels

Why does this look so bad?



$1/2$



$1/4$ (2x zoom)



$1/8$ (4x zoom)

[From Alexei Efros' lecture on Sampling and Pyramids]

Subsampling with Gaussian pre-filtering



Gaussian $1/2$



G $1/4$

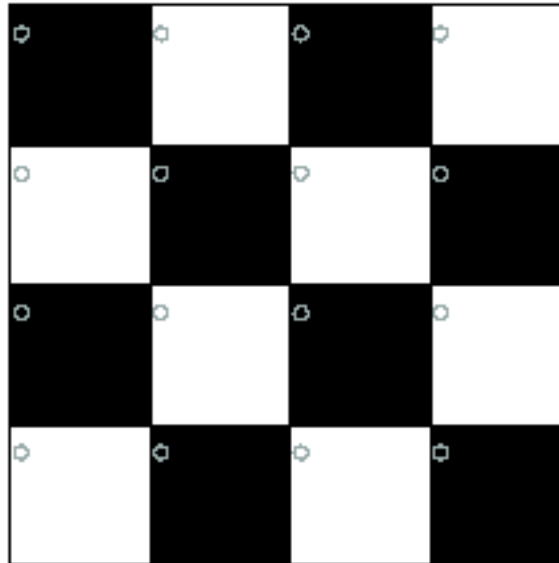
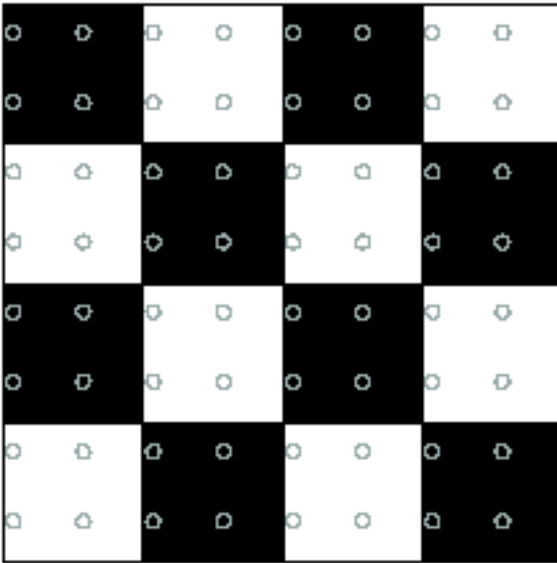


G $1/8$

- Solution: filter the image, *then* subsample
 - Filter size should double for each $1/2$ size reduction.

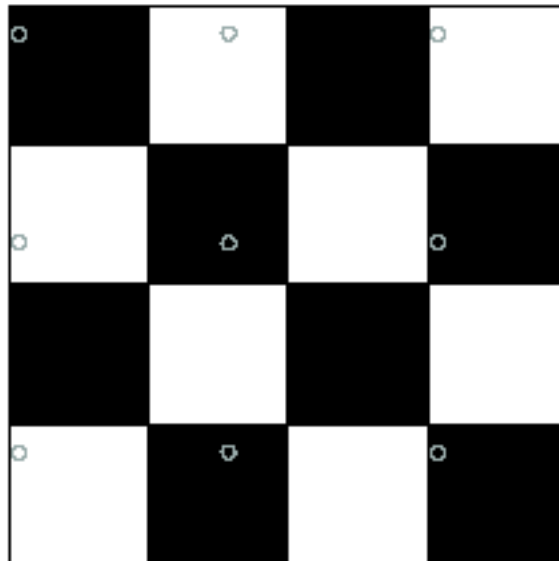
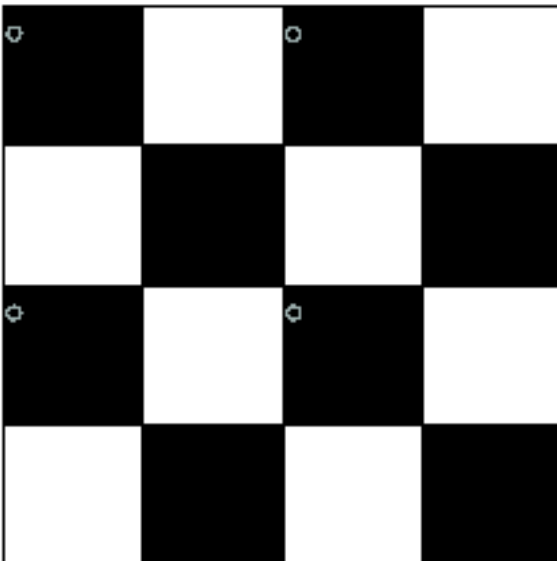
[From Alexei Efros' lecture on Sampling and Pyramids]

Sampling



Good sampling:

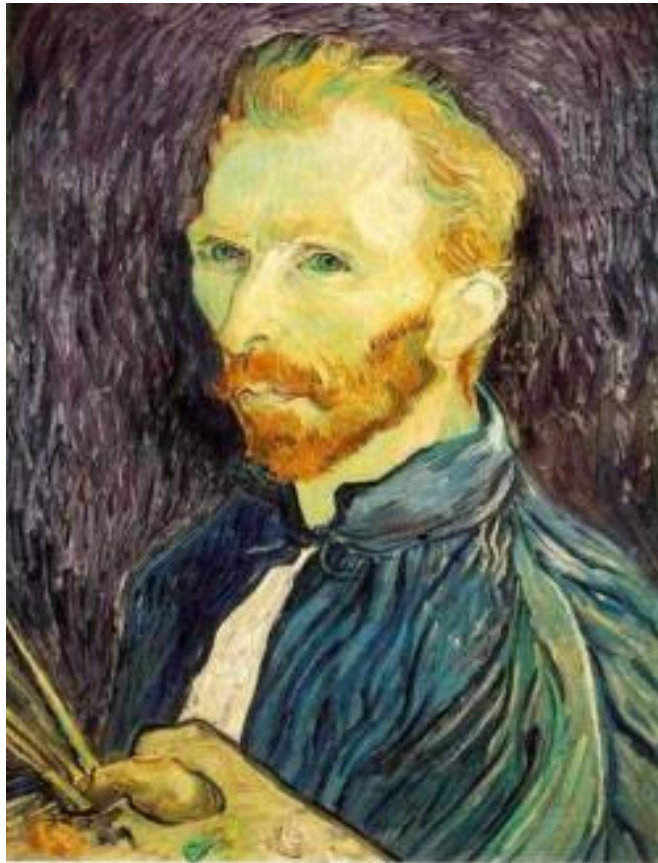
- Sample often or,
- Sample wisely



Bad sampling:

- see aliasing in action!

Gaussian pre-filtering



Gaussian $1/2$



G $1/4$



G $1/8$

- Solution: filter the image, *then* subsample
 - Filter size should double for each $1/2$ size reduction.

The Gaussian Pyramid

Low resolution

G_4

G_3

G_2

G_1

$G_0 = \text{Image}$

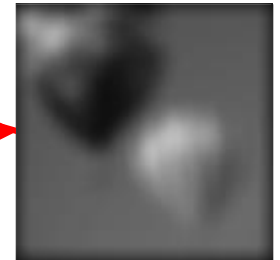
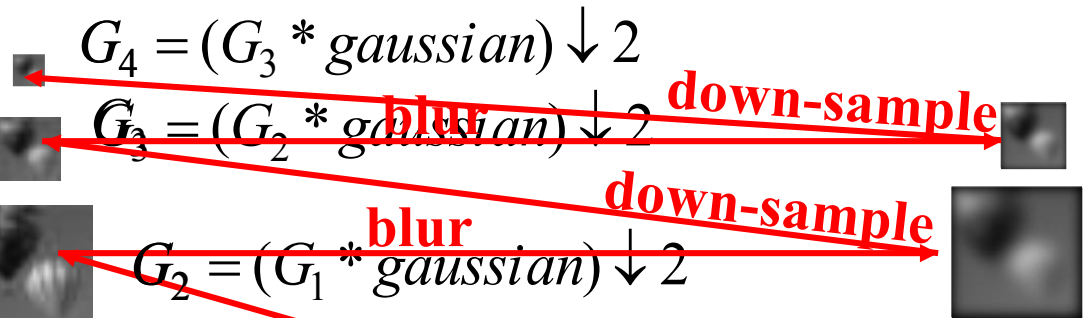
High resolution

Gaussian Pyramid

- A face that appears to occupy a 40×40 region in the original image will occupy only a 20×20 region in the downsampled image, a 10×10 region in the twice downsampled image, and so forth.
 - Because each successive image is smaller than its predecessor, stacking the images on top of one another yields the shape of a pyramid.
 - The sequence of images is known as an **image pyramid**.
- The most popular way to smooth an image is to convolve with a Gaussian kernel, leading to a **Gaussian pyramid**.

The Gaussian Pyramid

Low resolution



$G_0 = \text{Image}$
 blur down-sample

High resolution

Questions?