EEE6512 Image Processing and Computer Vision Homework 4

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Part I Textbook Questions

4-2 Write the set representation of the binary image A, and the array representation of the binary image B.

$$A = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

 $B = \{(1,1), (2,1), (1,2), (2,2), (3,2), (1,3), (3,3)\}$

Solution:

 $A = \{(0,0), (1,0), (2,0), (1,1), (0,2), (1,2), (2,2)\}.$

$$B = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix}$$

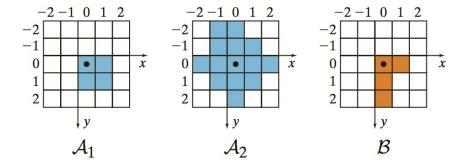
4-3 Apply the set operators of Figure 4.2 to the images A and B of the previous question, using b = (1,1). That is, compute $A \cup B$, $A \cap B$, $A \cap B$, $B \cap A$, $B \cap B$. Write the results as arrays.

Solution:

$$A \cup B = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix}, \ A \cap B = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \ A_b = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix}.$$

$$\check{B} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, \ \neg A = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}, \ A \backslash B = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

4-4 Compute Minkowski addition for sets A_1 and B, as well as Minkowski subtraction for sets A_2 and B, shown below. Ignore the out-of-bounds pixels. (a) Use the center-in approach. (b) Repeat, using the center-out approach.

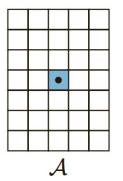


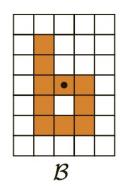
Solution:

- (a) With the center-in approach, the Minkowski addition of sets A_1 and B is the union of translation of A_1 with its origin places on every B, i.e. $A \oplus b = \bigcup_{b \in B} A_b$. Thus, $A_1 \oplus B = \{(0,0), (1,0), (2,0), (0,1), (1,1), (2,1), (0,2), (1,2)\}$. Similarly, the Minkowski addition with the center-in approach: $A \odot b = \bigcap_{b \in B} A_b$. Thus, $A_2 \odot B = \{(-1,0), (0,0), (0,1), (1,1)\}$
- (b) With the center-out approach, $A \oplus B = \{z : \check{B} \cap A \neq \emptyset\}, \ \check{B} = \{(0, -2), (0, -1), (0, 0), (-1, 0)\}, \ A \oplus b = \bigcup_{b \in B} A_b$. Thus, $A_1 \oplus B = \{(0, 0), (1, 0), (2, 0), (0, 1), (1, 1), (2, 1), (0, 2), (1, 2)\}$. Similarly, with the center-out approach, $A \ominus B = \{z : \check{B}_z \in A\}$. Thus, $A_2 \ominus B = \{(-1, 0), (0, 0), (0, 1), (1, 1)\}$
- **4-5** What is the difference between erosion and Minkowski subtraction?

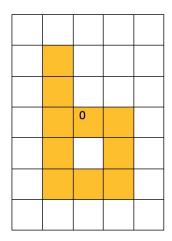
The erosion is defined to be Minkowski subtraction after reflecting the structure element.

4-6 Compute the dilation of the image A below using both center-in and center-out approaches. In both cases, do not reflect the structuring element B. In which approach is reflection necessary to ensure that the output exhibits the same orientation as the input?

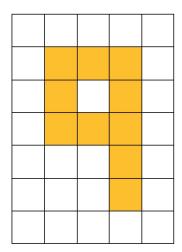




Center-in result:



Center-out result:

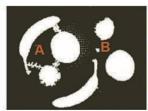


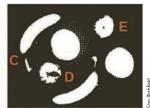
In center-out approach the reflection is necessary to ensure the output exhibits the same orientation as the input.

4-8 Recall the fruit image at the beginning of the chapter, which is reproduced below for convenience. On the two thresholded results shown, identify the name that best describes each of the labeled artifacts A-E: lake, bay, channel,

cape, isthmus, or island. Which morphological operator (opening or closing) should be applied to the image on the left to remove noise? To the image on the right?







A is near several isthmus, B is next to an island, C is next to a channel, D is next to a bay, E is next to a tiny lake.

To remove noise, image open should be applied to the left image, and image close should be applied to the right image.

4-12 Which of the labeled pixels below are 4-neighbors of the central pixel c? 8-neighbors? diagonal neighbors?

	a	b
	c	d
e		

4-neighbors: a, d.

8-neighbors: a, b, d, e.

diagonal neighbors: b, e

4-15 Compute the Euclidean, Manhattan, and chessboard distances from each pixel in a 5×5 image to the central pixel. What shape do the isocontours take in each case?

Table 1: Euclidean distance.

$2\sqrt{2}$	$\sqrt{5}$	2	$\sqrt{5}$	$2\sqrt{2}$
$\sqrt{5}$	$\sqrt{2}$	1	$\sqrt{2}$	$\sqrt{5}$
2	1	0	1	2
$\sqrt{5}$	$\sqrt{2}$	1	$\sqrt{2}$	$\sqrt{5}$
$2\sqrt{2}$	$\sqrt{5}$	2	$\sqrt{5}$	$2\sqrt{2}$

Table 2: Manhattan distance.

4	3	2	3	4
3	2	1	2	3
2	1	0	1	2
3	2	1	2	3
4	3	2	3	4

Table 3: chessboard.

2	2	2	2	2
2	1	1	1	2
2	1	0	1	2
2	1	1	1	2
2	2	2	2	2

For Euclidean distance, the isocontours are the circles concentric circles centered in the central pixel; for Manhattan

distance, the shape of isocontours are diamonds; for chessboard distance, the shape of isocontours are squares.

4-17 Given the following binary image:

$$I = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

- (a) Compute the zeroth-, first-, and second-order regular moments.
- (b) Compute the zeroth-, first-, and second-order central moments.

Solution: f(2,0) = 1, f(0,1) = 1, f(2,1) = 1, f(1,2) = 1, f(2,2) = 1

(a)
$$m_{00} = 2^00^0(1) + 0^01^0(1) + 2^01^0(1) + 1^02^0(1) + 2^02^0(1) = 5,$$

 $m_{01} = 2^00^1(1) + 0^01^1(1) + 2^01^1(1) + 1^02^1(1) + 2^02^1(1) = 6, m_{10} = 2^10^0(1) + 0^11^0(1) + 2^11^0(1) + 1^12^0(1) + 2^12^0(1) = 7$
 $m_{02} = 2^00^2(1) + 0^01^2(1) + 2^01^2(1) + 1^02^2(1) + 2^02^2(1) = 10, m_{20} = 2^20^0(1) + 0^21^0(1) + 2^21^0(1) + 1^22^0(1) + 2^22^0(1) = 13$
 $m_{11} = 2^10^1(1) + 0^11^1(1) + 2^11^1(1) + 1^12^1(1) + 2^12^1(1) = 8$

(b)
$$\bar{x} = (2+0+2+1+2)/5 = 1.4$$
, $\bar{y} = (0+1+1+2+2)/5 = 1.2$
 $\mu_{00} = m_{00} = 5$, $\mu_{10} = \mu_{01} = 0$, $\mu_{20} = 13 - 1.4 \times 7 = 3.2$, $\mu_{02} = 10 - 1.2 \times 6 = 2.8$, $\mu_{11} = 8 - 1.2 \times 7 = -0.4$.

Part II MATLAB Programming

The MATLAB code are attached.