

# YUANHONG ZENG

1631 Barry Ave, Los Angeles, CA 90025

📞 310-963-5641 📩 [yuanhongzeng@ucla.edu](mailto:yuanhongzeng@ucla.edu) 💬 [linkedin.com/in/yuanhong-zeng](https://linkedin.com/in/yuanhong-zeng) 🐾 [github.com/Danny-zyh](https://github.com/Danny-zyh)

## Education

<b>University of California, Los Angeles</b> <i>MS in Electrical and Computer Engineering</i>	Sep 2024 – Jun 2026 (Expected) Los Angeles, CA
<b>University of California, Los Angeles</b> <i>BS in Computer Engineering with minors in Mathematics and Bioinformatics</i> Capstone: PickyBot - Mobile manipulator for warehouse pick-and-place tasks	Sep. 2020 – Jul 2024 Los Angeles, CA GPA: 3.9/4.0

## Relevant Coursework

- Feedback Control (A+)
- Numerical Computing (A+)
- Convex Optimization (A+)
- Deep Learning (A+)
- Computational Robotics
- Signal Processing
- Statistical Machine Learning
- Operating Systems

## Research Experiences

<b>UCLA Practice Lab</b>   Advisor: Anushri Dixit	Oct 2024 - Now
• Built risk aware policies with CVaR constraint RL and adapting risk-level online with multi-arm bandit	
• Benchmarked Sim2Real performance in Isaac Lab and a Unitree Go2 robot; built software infrastructure for SLAM, policy inference, and sensor communication with ROS2	
<b>UCLA Robot Intelligence Lab</b>   Advisor: Yuchen Cui	Feb 2025 - Now
• Built a framework for steering diffusion policy with user generated sketch based on guided diffusion	
• Improved imitation learning policy with 3D perceptions by augmenting RGB observation with Depth Anything	
<b>VCLA at UCLA</b>   Advisor: Ying Nian Wu	Oct 2022 - Jun 2024
• Built a human robot interaction pipeline for pick-and-place with Segment Anything and GPT; tested on Kinova Gen 3.	
• Investigated domain adaptation for Sim2Real in vision and control; Improved pick-and-pour success rate by 30%.	
• Investigated embodied AI for indoor scene arrangement. Conducted human assessment study on Amazon MTurk.	
<b>The Graeber Lab</b>   Advisor: Thomas G. Graeber	Dec 2021 - Jun 2023
• Investigated the trans-differentiation in prostate cancer through temporal multi-omics analysis. Work published in <i>Cell</i> .	
• Built research website using Docker and HTML/PHP for visualizing PCA and UMAP of bulk/single-cell RNA-seq data.	

## Work Experience

<b>Digital Bot Lab, Inc</b>	Aug 2023 – Oct 2023
<i>Research Engineering Intern</i>	San Jose, California
• Developed robot.digitalbotlab.com, a virtual robot asset marketplace, using Next.js.	
• Joined the UCLA Startup to develop MVP for on-cloud robot training platform using NVIDIA Omniverse Cloud.	
<b>Galixir</b>	Dec 2020 – Jun 2021
<i>Data Analyst Intern</i>	Beijing, China
• Annotated 10M chemicals in the company's drug database chemical, biological, and clinical attributes.	
• Built web scraper based on Scrapy to collect patent and drug information from European Patent Office and SciFinder.	

## Publications

1. Y Zeng, Y Zhao, YN Wu. **Triple Regression for Sim2Real Adaptation in Human-Centered Robot Grasping and Manipulation**, *Workshop in Human-Centered Collaborative Robot, Conference of Robot Learning (CoRL) 2024*
2. CC Chen, [...], Y Zeng, et al. **Temporal evolution reveals bifurcated lineages in aggressive neuroendocrine small cell prostate cancer trans-differentiation**, *Cancer Cell 2023*

## Activities

<b>ASA DataFest at UCLA</b>	Apr 2024
<i>Best Statistical Model (Honorable Mention)</i>	
• Improved CourseKata's learning platform by developing a graphical model to analyze student performance dependencies.	

<b>Biomedical Engineering Society (BMES) at UCLA</b>	Sep 2020 – Jun 2022
<i>Design Team</i>	

- Worked on year-long projects, including an embedded immersive sleeping device that tracks sleep quality through EEG and a therapeutic glove for stroke and arthritis patient recovery

## Skills

**Languages:** Python, C/C++, Typescript, R, Latex, SQL   **Frameworks:** Nvidia Isaac Sim, ROS2, Pytorch  
**Soft skills:** project management and planning, website construction, scientific drawing