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1 Uboot

We have a configuration file needs to be copied to your uboot folder firstly, the uboot source code can build separately. Please follow up the below instructions.

Copy uboot source code and configs/cfg_gen/ModelConfig.mk

•

```
$ cp ~/na51000_linux_sdk/configs/cfg_gen/ModelConfig.mk
    ${UBOOT_DIR}/board/novatek/nvt-na51000/
$ export NVT_PRJCFG_MODEL_CFG=${UBOOT_DIR}/board/novatek/nvt-na51000/ModelConfig.mk
$ export ARCH=arm
$ export
CROSS_COMPILE=${YOUR_PATH}/arm-ca53-linux-gnueabihf-6.4/usr/bin/arm-ca53-linux-gnueabihf-
$ make distclean
$ make nvt-na51000_defconfig
$ make -j4
# Non-compression type uboot image
$(BUILD_DIR)/nvt-tools/encrypt_bin SUM $(UBOOT_DIR)/u-boot.bin 0x350 ub51000
# LZ compression type uboot image
$(BUILD_DIR)/nvt-tools/bfc c lz $(UBOOT_DIR)/u-boot.bin $(UBOOT_DIR)/u-boot.lz.bin 0 0
```



2 Linux kernel and modules

Linux kernel

```
$ export ARCH=arm
$ export

CROSS_COMPILE=${YOUR_PATH}/arm-ca53-linux-gnueabihf-6.4/usr/bin/arm-ca53-linux-gnueabihf-
AW$ cp ${KERNELDIR}/arch/$(ARCH)/configs/na51000_evb_smp_defconfig_debug ${KERNELDIR}/.config
$ cd ${KERNELDIR}
$ make uImage -j4
$ make distclean
```

Please build kernel firstly.

Linux kernel modules

```
$ cd ${KERNELDIR}
$ mkdir $(KERNELDIR)/_install_modules/
$ make modules -j4
# The modules will be installed on "$(KERNELDIR)/_install_modules/"
$ make INSTALL_MOD_PATH=$(KERNELDIR)/_install_modules/ modules_install -j4
```



3 Device Tree

Our device tree source is put in this path "configs", you can copy it into your folder, and running below procedures to generate dtb.

```
$ export NVT_PRJCFG_MODEL_CFG=${YOUR_PATH}/configs/cfg_${YOUR_MODEL}/ModelConfig.mk
$ export CONFIG_DIR=${YOUR_PATH}/configs/
$ export KERNELDIR=${YOUR_PATH}/linux-kernel
$ export BUILD_DIR=${YOUR_PATH}/build
$ cd ${YOUR_PATH}/configs/
$ make
```

You can get dtb image here: "cfg_gen/nvt-na51000-smp-evb.dtb"



4 Rootfs

Please follow the following build sequence:

\$ make busybox => Generate basic rootfs file system

\$ make app => Install app to rootfs

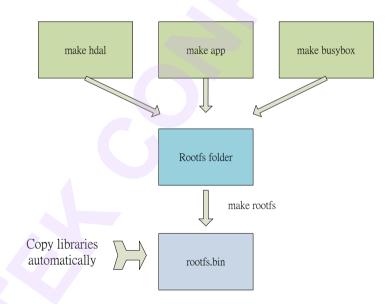
\$ make hdal => Install hdal *.ko, sample and application

\$ make library => Update library

\$ make rootfs => Generate rootfs image

4.1 Build flow

The rootfs build flow can be shown as below





4.2 Add application

TBD

4.3 Add customer driver code

The basic software stack is as below, the customer driver code is named linux-driver and Novatek will provide k driver and k flow.



Please refer to debug/nvt_data_breakpoint Makefile. na51000_linux_sdk/code/linux-driver\$ vi Makefile

```
obj-m += \
debug/nvt_data_breakpoint/
```

4.3.1 Build flow

You have two selections can be used to build linux driver module

 Only support build and install to temp folder nvt02854@oaalnx7:~/na51000_linux_sdk/code/linux-driver\$ make; make modules_install

Or

Including build and install to rootfs nvt02854@oaalnx7:~/na51000_linux_sdk/\$ make linux_driver



4.3.2 Install path

Install path: BSP/linux-kernel/_install_modules/lib/modules/
You can copy this folder to root-fs/rootfs/lib/modules/ and make rootfs to generate new rootfs.bin



5 Tools

We provide a method can install open source tools, the path is "na51000 linux sdk/tools"

5.1 Add Open source tools

- Get the *.tar.bz2 open source package and put into tools folder.
- Modify Makefile as below

Add file name

```
STRACE := strace-4.24
```

Add make target

```
strace: init
    @echo ">>>>>>>> $@ compiling >>>>>>>

    $(call check_exist, ${STRACE})
    @cd ${STRACE}; ./configure --host=${NVT_HOST} --target=${NVT_HOST}
--prefix=${TOOLS}/${INSTALL_DIR}
```

PS: You should control the open source build procedure by yourself. (e.g. Automake, CMAKE, SCons...etc)

The package will be installed into __install folder if your build is successful; then the install will be the below.

```
install:
    @echo ">>>>>>>>>> $@ >>>>>>>>
"
    @$(call check_exist_cp,bin)
    @$(call check_exist_cp,sbin)
    @$(call check_exist_cp,usr/bin)
    @$(call check_exist_cp,usr/sbin)
    @$(call check_exist_cp,usr/sbin)
    @$(call check_exist_cp,usr/lib)
    @$(call check_exist_cp,lib)
```



6 Library

Path: na51000_linux_sdk/code/lib

We have three type libraries are necessary, external and cutom.

necessary: Config the "must be" copied library to rootfs, it means that these libraries will be

copied to rootfs/lib.

External: Open source libraries Custom: Developed by ourselves

6.1 Add your custom library

Please refer to code/lib/nvtlibc Makefile. This library will be installed into code/lib/output/