view_frames Result Recorded at time: 1762.563 world Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1762.563 sec old) Most recent transform: 0.000 (1762.563 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_rgb_frame dummy_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1762.563 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec camera_link base_link camera_depth_frame camera_rgb_optical_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 51.515 Hz Most recent transform: 0.000 (1762.563 sec old) Most recent transform: 1762.544 (0.019 sec old) Buffer length: 0.660 sec Buffer length: 0.000 sec Link1 camera_depth_optical_frame Broadcaster: /robot_state_publisher Average rate: 51.515 Hz Most recent transform: 1762.544 (0.019 sec old) Buffer length: 0.660 sec Link2 Broadcaster: /robot_state_publisher Average rate: 51.515 Hz Most recent transform: 1762.544 (0.019 sec old) Buffer length: 0.660 sec Link3 Broadcaster: /robot_state_publisher Average rate: 51.515 Hz Most recent transform: 1762.544 (0.019 sec old) Buffer length: 0.660 sec Link4 Broadcaster: /robot_state_publisher Average rate: 51.515 Hz Most recent transform: 1762.544 (0.019 sec old) Buffer length: 0.660 sec Link5 Broadcaster: /robot_state_publisher Average rate: 51.515 Hz Most recent transform: 1762.544 (0.019 sec old) Buffer length: 0.660 sec Link6 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1762.563 sec old) Buffer length: 0.000 sec robotiq_85_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 51.515 Hz Average rate: 51.515 Hz Average rate: 51.515 Hz Average rate: 51.515 Hz Most recent transform: 1762.544 (0.019 sec old) Buffer length: 0.660 sec Buffer length: 0.660 sec Buffer length: 0.660 sec Buffer length: 0.660 sec right_outer_knuckle right_inner_knuckle left_outer_knuckle left_inner_knuckle Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 51.515 Hz Average rate: 51.515 Hz Most recent transform: 0.000 (1762.563 sec old) Most recent transform: 0.000 (1762.563 sec old) Most recent transform: 1762.544 (0.019 sec old) Most recent transform: 1762.544 (0.019 sec old) Buffer length: 0.000 sec Buffer length: 0.660 sec Buffer length: 0.000 sec Buffer length: 0.660 sec left_outer_finger left_inner_finger right_outer_finger right_inner_finger