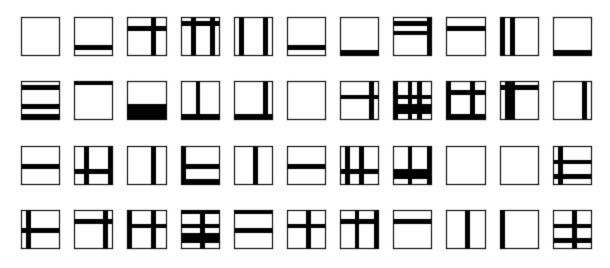
```
In [ ]: !pip install numpy
        !pip install matplotlib
        !pip install -U scikit-learn
        !pip install torch
        !pip install tqdm
In [1]: import time
        import pickle
        import warnings
        import numpy as np
        import matplotlib.pyplot as plt
        from sklearn.linear_model import LogisticRegression
        import torch
        import torch.nn as nn
        import torch.nn.functional as F
        import torch.optim as optim
        from tqdm import tqdm
In [2]: warnings.filterwarnings('ignore')
        rng = np.random.default_rng()
In [3]: def gen_sample(L1=8, L2=8, p1=[1/8.0]*8, p2=[1/8.0]*8):
            im = np.zeros((L1,L2))
            for i in range(L1):
                11 = rng.choice([1,0], p=[p1[i], 1-p1[i]])
                im[i,:] += 11
            for i in range(L2):
                12 = rng.choice([1,0], p=[p2[i], 1-p2[i]])
                im[:,i] += 12
            im = (im > 0).astype(int).astype(float)
            return im.flatten()
In [4]: def display_samples(L1=8, L2=8, p1=[1/8.0]*8, p2=[1/8.0]*8):
            samples = []
            for i in range(44):
                samples.append(gen_sample(L1, L2, p1, p2))
            fig = plt.figure(figsize=(6,3))
            plt.title('Foldiak Figure 2')
            plt.axis('off')
            for i in range(4):
                for j in range(11):
                    fig.add_subplot(4,11,i*11+j+1)
                    plt.imshow(samples[i*11+j].reshape((L1,L2)), cmap='Greys')
                    plt.xticks([], [])
                    plt.yticks([], [])
                    plt.tick_params(left=False, right=False, top=False, bottom=False,
                                     labelleft=False, labelright=False,
                                     labeltop=False, labelbottom=False)
            plt.tight_layout()
In [5]: L1 = 8
        L2 = 8
        p1 = [1.0/L1]*L1
        p2 = [1.0/L2]*L2
        display_samples(L1, L2, p1, p2)
```

Foldiak Figure 2

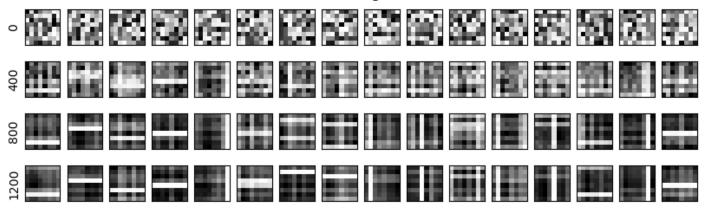


```
In [90]: class FoldiakNetwork():
                             def __init__(self, L1=8, L2=8, p1=[1/8.0]*8, p2=[1/8.0]*8):
                                     # i runs from 1 to n = len(y) = L1 + L2
                                     # j runs from 1 to m = len(x) = L1 * L2
                                     self.L1 = L1 # length of vertical side of input
                                     self.L2 = L2 # length of horizontal side of input
                                     self.y = np.zeros(self.L1 + self.L2) + 0.5 # output values
                                     self.q = rng.uniform(size=(self.L1 + self.L2,
                                                                                              self.L1 * self.L2)) # q_ij connects xj to yi, shape len(y),len
                                     # and normalize so sum_j((q_{ij})**2)=1
                                     self.q = self.q / np.sqrt(np.sum(self.q**2, axis=1)).reshape((self.q.shape[0],1))
                                     self.w = np.zeros((self.L1 + self.L2, self.L1 + self.L2)) # w_ij connects yi to yj, shape
                                     self.t = np.zeros(self.L1 + self.L2) # t_i is the threshold for y_i, shape len(y)
                                     self.p1 = np.array(p1) # L1-length vector of probabilities of line being drawn from vert
                                     self.p2 = np.array(p2) # L2-length vector of probabilities of line being drawn from horiz
                                     self.p = np.matmul(self.p1.reshape((self.p1.shape[0],1)), self.p2.reshape((1,self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shape(),self.p2.shap
                             def f(self, u, lam=20):
                                     return 1.0 / (1 + np.exp(-lam * u))
                            def uTrans(self, im):
                                     return np.sum(self.q * im.reshape((1, im.shape[0])), axis=1) + \
                                                    np.sum(self.w * self.y) - self.t
                            def dy(self, im, lam=20, T=10):
                                     return (self.f(self.uTrans(im), lam) - self.y) / T
                             def simTrans(self, im, lam=20, T=10):
                                     # T is the number of time steps to simulate
                                     for dt in range(int(T)):
                                             dy = self.dy(im, lam, T)
                                             self.y += dy
                                             ynorm = np.linalg.norm(self.y)
                                              if np.linalg.norm(dy) / (ynorm+1e-9) < 1/100000.0:</pre>
                                                      break
                                     self.y = np.around(self.y)
                            def hebbian(self, imj, i, j, beta=0.05):
                                     # imj is the value of the image at index j
                                     self.q[i,j] += beta * self.y[i] * (imj - self.q[i,j])
                                     self.q = self.q / np.sqrt(np.sum(self.q**2, axis=1)).reshape((self.q.shape[0],1))
                             def antihebb(self, i, j, alpha=0.05):
```

```
if i == j or self.w[i,j] > 0:
        self.w[i,j] = 0
    else:
        if i >= self.L1:
            pi = self.p2[i - self.L1]
        else:
            pi = self.p1[i]
        if j >= self.L1:
            pj = self.p2[j - self.L1]
        else:
            pj = self.p1[j]
        self.w[i,j] -= alpha * (self.y[i] * self.y[j] - pi*pj)
def dthresh(self, i, gamma=0.2):
    if i >= self.L1:
        pi = self.p2[i - self.L1]
    else:
        pi = self.p1[i]
    self.t[i] += gamma * (self.y[i] - pi)
def update(self, im, alpha=0.05, beta=0.05, gamma=0.2):
    for i in range(self.L1 + self.L2):
        for j in range(self.L1 * self.L2):
            self.hebbian(im[j], i, j, beta)
        for j in range(self.L1 + self.L2):
            self.antihebb(i, j, alpha)
        self.dthresh(i, gamma)
def trial(self, im, T=10, alpha=0.05, beta=0.05, gamma=0.2, lam=20):
    self.simTrans(im, lam, T)
    self.update(im, alpha, beta, gamma)
def plot_q(self, fig, n_trial, row, n_rows):
    for i in range(self.L1 + self.L2):
        fig.add_subplot(n_rows, self.L1 + self.L2, row*(self.L1 + self.L2) + i+1)
        if i == 0:
            plt.ylabel(n_trial)
        plt.imshow(-1*self.q[i,:].reshape((self.L1, self.L2)),
                   cmap='Greys')
        plt.tick_params(left=False, right=False, top=False, bottom=False,
                        labelleft=False, labelright=False,
                        labeltop=False, labelbottom=False)
    return row + 1
def train_lines(self, fig, n_rows=4, n_trials=1200, T=10, alpha=0.05, beta=0.05, gamma=0.2,
    for n in range(n_trials):
        im = gen_sample(self.L1, self.L2, self.p1, self.p2)
        self.trial(im, T, alpha, beta, gamma, lam)
        if n % 400 == 399:
            row = self.plot_q(fig, n+1, row, n_rows)
def warmup_lines(self, n_warmup, T=10, alpha=0, beta=0, gamma=0.1, lam=10):
    for t in range(n_warmup):
        im = gen_sample(self.L1, self.L2, self.p1, self.p2)
        self.trial(im, T, alpha=0, beta=0, gamma=0.1, lam=10)
def learn_lines(self, title, n_trials=1200, n_warmup=0, T=10, alpha=0.05, beta=0.05, gamma=0
    self.warmup_lines(n_warmup, alpha=0, beta=0, gamma=0.1, lam=10)
    n_rows = int(n_trials / 400) + 1
    row = 0
    fig = plt.figure(figsize=(10,3))
```

```
plt.title(title)
   plt.axis('off')
   row = self.plot_q(fig, n_trial=0, row=row, n_rows=n_rows)
   self.train_lines(fig, n_rows, n_trials, T, alpha, beta, gamma, lam)
   plt.show(fig)
def learn_mnist(self, n_trials=1, n_warmup=0, T=10, alpha=0.05, beta=0.05, gamma=0.2, lam=20
   # Returns tuple of learned representations as (60000,56) and (10000,56) ndarrays
   train, test = pickle.load(open('mnist.pkl', 'rb'), encoding='bytes')
   trainx, trainy = train
   testx, testy = test
   trainx = trainx[:1000] / trainx.max()
   testx = testx[:200] / testx.max()
   for n in range(n_warmup):
        print(f'Warming Up {n+1}')
        order = rng.permutation(np.arange(len(trainx)))
       xn = trainx[order,:,:]
       for im in tqdm(xn):
            self.trial(im.flatten(), T, alpha=0, beta=0, gamma=0.1, lam=10)
   for n in range(n_trials):
       print(f'Doing Trial {n+1}')
        order = rng.permutation(np.arange(len(trainx)))
       xn = trainx[order,:,:]
       for im in tqdm(xn):
            self.trial(im.flatten(), T, alpha, beta, gamma, lam)
   train_reps = []
   print('Getting Training Representations')
   for im in tqdm(trainx):
        self.trial(im.flatten(), T, alpha, beta, gamma, lam)
        train_reps.append(self.y)
   test_reps = []
   print('Getting Testing Representations')
   for im in tqdm(testx):
        self.trial(im.flatten(), T, alpha, beta, gamma, lam)
       test_reps.append(self.y)
   print('Done!')
   return np.stack(train_reps), np.stack(test_reps)
def pred mnist(self, n trials=1, n warmup=0, T=10, alpha=0.05, beta=0.05, gamma=0.2, lam=20)
   # Prints test accuracy on MNIST
   train, test = pickle.load(open('mnist.pkl', 'rb'), encoding='bytes')
   trainx, trainy = train
   testx, testy = test
   trainx = trainx[:1000] / trainx.max()
   testx = testx[:200] / testx.max()
   trainy = trainy[:1000]
   testy = testy[:200]
   train_reps, test_reps = self.learn_mnist(n_trials, n_warmup, T, alpha, beta, gamma, lam)
   logreg = LogisticRegression(penalty=None)
   logreg.fit(train_reps, trainy)
   print('Foldiak-trained MNIST Score:', logreg.score(test_reps, testy))
```

Foldiak Figure 3



Parameters for Near-Optimal Convergence

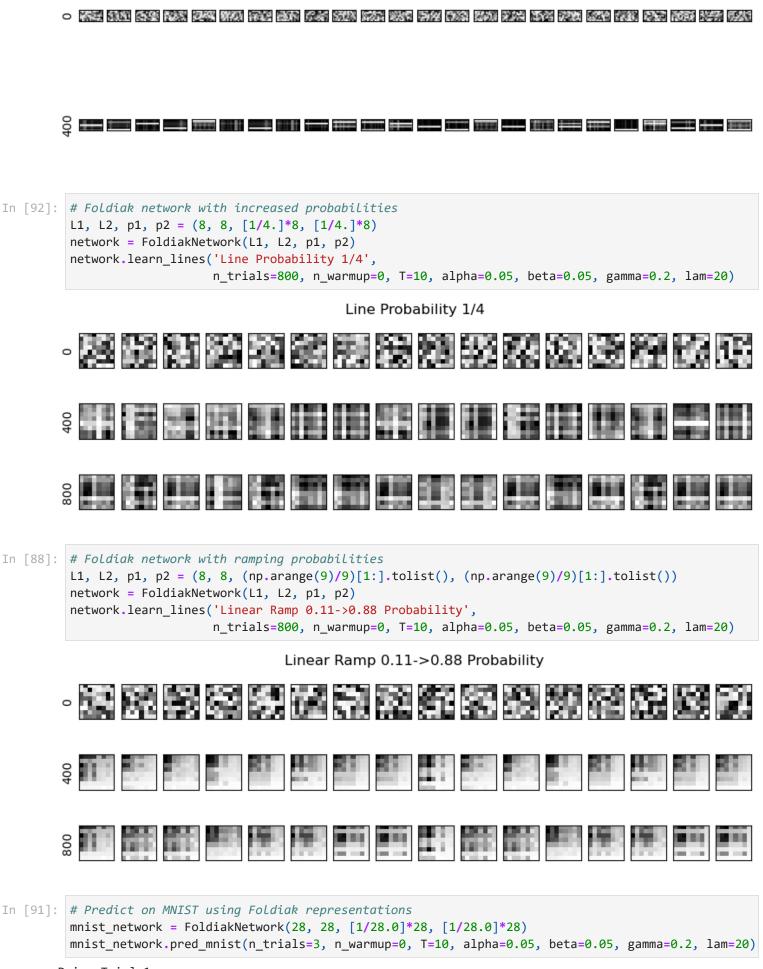




16x16 Foldiak Network







Doing Trial 1

```
| 1000/1000 [55:53<00:00, 3.35s/it]
        100%
       Doing Trial 2
       100%
                                                      1000/1000 [56:00<00:00, 3.36s/it]
        Doing Trial 3
        100%
                                                      1000/1000 [56:05<00:00, 3.37s/it]
       Getting Training Representations
                                                      1000/1000 [55:46<00:00, 3.35s/it]
        Getting Testing Representations
       100%
                                                        200/200 [11:11<00:00, 3.36s/it]
       Done!
        Foldiak-trained MNIST Score: 0.09
In [12]: | train, test = pickle.load(open('mnist.pkl', 'rb'), encoding='bytes')
         trainx, trainy = train
         testx, testy = test
         trainx = trainx[:10000] / trainx.max()
         testx = testx[:2000] / testx.max()
         trainy = trainy[:10000]
         testy = testy[:2000]
In [13]: # Predict on MNIST using standard Logistic regression
         logreg = LogisticRegression(penalty=None)
         logreg.fit(trainx.reshape((10000,28**2)), trainy)
         print('Regular Logistic Regression Score:', logreg.score(testx.reshape((2000,28**2)), testy))
        Regular Logistic Regression Score: 0.8495
In [57]: # Create a basic CNN for image classification
         class BasicCNN(nn.Module):
             def __init__(self):
                 super(BasicCNN, self).__init__()
                 self.Conv = nn.Conv2d(1, 1, 3, padding='same')
                 self.Pool = nn.MaxPool2d(2, 2)
                 self.Lin = nn.Linear(1*14*14, 10)
             def forward(self, x):
                 x = self.Pool(F.relu((self.Conv(x))))
                 x = self.Lin(x.flatten(start_dim=1))
                 return F.softmax(x)
         # Train the CNN
In [58]:
         model = BasicCNN()
         loss_fn = nn.CrossEntropyLoss(reduction='sum')
         optimizer = optim.Adam(model.parameters(), lr=0.001)
         scheduler = optim.lr_scheduler.StepLR(optimizer, 3)
         n_{epochs} = 12
         model.train()
         for epoch in range(n_epochs):
             train_loss = 0
             order = rng.permutation(np.arange(len(trainx)))
             xn = trainx[order,:,:]
             yn = trainy[order]
             n_batches = int(10000 / 50)
             for i in tqdm(range(n_batches)):
                 ims = xn[i*50:(i+1)*50, :, :]
                 output = model(torch.tensor(ims, dtype=torch.float)[:,None,:,:])
                 loss = loss_fn(output, torch.tensor(yn[i*50:(i+1)*50]))
                 train_loss += loss / xn.shape[0]
                 optimizer.zero_grad()
```

```
loss.backward()
                 optimizer.step()
             print(f'Epoch {epoch+1} Train Loss:', train_loss.detach().item())
                                                     | 200/200 [00:00<00:00, 465.16it/s]
        Epoch 1 Train Loss: 2.018294095993042
                                                       200/200 [00:00<00:00, 496.80it/s]
        Epoch 2 Train Loss: 1.6736501455307007
                                                       200/200 [00:00<00:00, 483.97it/s]
        Epoch 3 Train Loss: 1.6170748472213745
                                                       200/200 [00:00<00:00, 505.26it/s]
        Epoch 4 Train Loss: 1.5922285318374634
                                                       200/200 [00:00<00:00, 491.07it/s]
        Epoch 5 Train Loss: 1.5779067277908325
                                                       200/200 [00:00<00:00, 498.62it/s]
        Epoch 6 Train Loss: 1.5684329271316528
                                                       200/200 [00:00<00:00, 498.48it/s]
        Epoch 7 Train Loss: 1.5618879795074463
                                                       200/200 [00:00<00:00, 495.56it/s]
        Epoch 8 Train Loss: 1.557023048400879
                                                       200/200 [00:00<00:00, 495.70it/s]
        Epoch 9 Train Loss: 1.5532472133636475
                                                       200/200 [00:00<00:00, 494.04it/s]
        Epoch 10 Train Loss: 1.5492901802062988
                                                       200/200 [00:00<00:00, 491.45it/s]
        Epoch 11 Train Loss: 1.5466704368591309
                                                      200/200 [00:00<00:00, 482.16it/s]
        Epoch 12 Train Loss: 1.5440311431884766
In [59]: # Evaluate the CNN performance
         accuracy = 0
         model.eval()
         for idx, im in tqdm(enumerate(testx)):
             output = model(torch.tensor(im, dtype=torch.float)[None,None,:,:])
             pred = torch.argmax(output)
             accuracy += int(pred == testy[idx]) / testy.shape[0]
         print('Basic CNN Score:', accuracy)
        2000it [00:00, 5245.06it/s]
        Basic CNN Score: 0.883999999999988
```