

בחינה באלגברה לינארית 1 א

דוד גינזבורג

- משך הבחינה 3 שעות.
- יש לענות על כל השאלות.
- אין להשתמש בכל חומר עזר לרבות מחשבון.
- יש לנמק היטב את דרך הפיתרון.

שאלה 1 (25 נ') במרחב הוקטורי \mathbb{R}^4 נתונים שני תתי המרחב

$$W_1 = \text{Sp}\{(1,2,3,4); (3,4,5,6); (7,8,9,10)\},$$

$$W_2 = \{(a,b,c,d) : a+b=0; a,b,c,d \in \mathbb{R}\}.$$

מצאו תת מרחב W_3 של W_2 כך ש- $W_1 \oplus W_3 = W_2$.

שאלה 2 (25 נ') נתונה מערכת של n משוואות עם n נעלמים ופרמטר k ,

$$\begin{cases} kx_1 + x_2 + \dots + x_n = 1 \\ x_1 + kx_2 + \dots + x_n = 1 \\ \dots \quad \dots \quad \dots \quad \dots \\ x_1 + x_2 + \dots + kx_n = 1 \end{cases}.$$

לכל ערך של $k \in \mathbb{R}$ מצאו את כל הפתרונות של המערכת.

שאלה 3 (25 נ') יהי L תת המרחב של $Mat_{3 \times 3}(\mathbb{R})$ המוגדר על ידי

$$L = \left\{ A \in Mat_{3 \times 3}(\mathbb{R}) : A \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \right\}.$$

שאלה 4 א. (13 נ') יהי V מרחב וקטורי מעל השדה F . נתונה העתקה לינארית

$$T: V \rightarrow V \text{ המקיימת } T^2 = T. \text{ הוכיחו כי } \text{Ker} T \oplus \text{Im} T = V.$$

ב. (12 נ') נתונה $A \in Mat_{n \times n}(\mathbb{R})$. יהי W תת המרחב של $Mat_{n \times n}(\mathbb{R})$ המוגדר על

$$W = \{X \in V : AX = XA\}.$$

ידי $\dim W \geq 2$ הוכיחו כי

בהצלחה!

Solutions

Solution 1: We start by computing $\dim(W_1 + W_2)$. For that we use the dimension Theorem

$$\dim(W_1 + W_2) = \dim W_1 + \dim W_2 - \dim(W_1 \cap W_2)$$

To compute $\dim W_1$, we find a basis for W_1 . We write the three vectors as a matrix, and we perform the following row operations,

$$\begin{pmatrix} 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 6 \\ 7 & 8 & 9 & 10 \end{pmatrix} \xrightarrow[\substack{R_3 \rightarrow R_3 - 7R_1}]{\substack{R_2 \rightarrow R_2 - 3R_1}} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & -2 & -4 & -6 \\ 0 & -6 & -12 & -18 \end{pmatrix} \xrightarrow[\substack{R_2 \rightarrow -R_2}]{\substack{R_3 \rightarrow R_3 - 3R_2}} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Hence $\dim W_1 = 2$, and $\mathcal{B} = \{(1, 2, 3, 4); (0, 1, 2, 3)\}$ is a basis for W_1 .

As for $\dim W_2$, we can write a vector in W_2 as

$$(a, -a, c, d) = a(1, -1, 0, 0) + c(0, 0, 1, 0) + d(0, 0, 0, 1)$$

from which we deduce that $\dim W_2 = 3$. To compute $\dim(W_1 \cap W_2)$ we take a vector in $w \in W_1 \cap W_2$ and write it as

$$w = \alpha(1, 2, 3, 4) + \beta(0, 1, 2, 3) = (a, -a, c, d)$$

Here α, β, a, c and d are all scalars in \mathbf{R} . Comparing the coordinates on the right hand side of the equation, we get the system of equations $\alpha = a$; $2\alpha + \beta = -a$; $3\alpha + 2\beta = c$, and $4\alpha + 3\beta = d$. It is easy to see that the solution is $\alpha = a$; $\beta = c = -3a$, and $d = -5a$. Hence $W_1 \cap W_2 = \{(a, -a, -3a, -5a) : a \in \mathbf{R}\} = \text{Sp}\{(1, -1, -3, -5)\}$. In particular we obtain $\dim(W_1 \cap W_2) = 1$. Hence, from the dimension Theorem stated above we obtain that $\dim(W_1 + W_2) = 2 + 3 - 1 = 4 = \dim \mathbf{R}^4$. This implies that $W_1 + W_2 = \mathbf{R}^4$. Thus, the problem is reduced to finding $W_3 \subset W_2$ such that $W_1 \oplus W_3 = \mathbf{R}^4$. To do that it is enough to find two vectors $u_1, u_2 \in W_3$ such that the set $\mathcal{B} \cup \{u_1, u_2\}$ is a basis for \mathbf{R}^4 . It is easy to see that $u_1 = (0, 0, 1, 0)$ and $u_2 = (0, 0, 0, 1)$ is a such a choice.

Solution 2: Adding all the equations in the system we obtain

$$(k + n - 1)(x_1 + x_2 + \cdots + x_n) = n$$

If $k = 1 - n$, then the left hand side of the above equation is zero, and the right hand side is equal to n . So in this case there are no solutions.

Assume that $k \neq 1 - n$. Then, dividing by $k + n - 1$ we obtain the equation

$$x_1 + x_2 + \cdots + x_n = \frac{n}{k + n - 1} \quad (7)$$

Subtract this equation from the first equation of the system. We obtain the equation

$$(k - 1)x_1 = 1 - \frac{n}{k + n - 1}$$

Repeating this subtraction for each equation of the system, we obtain

$$(k - 1)x_i = 1 - \frac{n}{k + n - 1} \quad 1 \leq i \leq n$$

If $k \neq 1$, we can divide by $k - 1$, and obtain $x_i = \frac{1}{k+n-1}$. If $k = 1$, the system of equations reduces to one equation which is $x_1 + x_2 + \cdots + x_n = 1$.

Hence, the solutions of the system are as follows:

a) If $k = 1$, the system has infinite number of solutions given by

$$\{(1 - \alpha_2 - \alpha_3 - \cdots - \alpha_n, \alpha_2, \dots, \alpha_n) : \alpha_i \in \mathbf{R}; \quad 2 \leq i \leq n\}$$

b) If $k = 1 - n$, the system has no solutions.

c) If $k \neq 1, 1 - n$, the system has a unique solution given by

$$\left(\frac{1}{k + n - 1}, \frac{1}{k + n - 1}, \dots, \frac{1}{k + n - 1} \right).$$

Solution 3: Assume that $A = (a_{i,j})_{3 \times 3} \in L$. Then, by matrix multiplication, the equation

$$A \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = 0$$

is equivalent to the system of equations

$$a_{1,1} + 2a_{1,2} + 3a_{1,3} = 0$$

$$a_{2,1} + 2a_{2,2} + 3a_{2,3} = 0$$

$$a_{3,1} + 2a_{3,2} + 3a_{3,3} = 0$$

This system has 9 variables and 3 equations. From this we easily deduce that it has 6 free variables. Hence, $\dim L = 6$. An example for a basis for L is the set

$$\begin{pmatrix} -2 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \begin{pmatrix} -3 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \begin{pmatrix} 0 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \begin{pmatrix} 0 & 0 & 0 \\ -3 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}; \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ -2 & 1 & 0 \end{pmatrix}; \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ -3 & 0 & 1 \end{pmatrix}$$

Solution 4: a) First we prove that $\ker T \cap \operatorname{Im} T = \{0\}$. Let $v \in \ker T \cap \operatorname{Im} T$. Then, $Tv = 0$ (since $v \in \ker T$), and there is $u \in V$ such that $v = Tu$ (since $v \in \operatorname{Im} T$). Hence, $0 = Tv = T(Tu) = T^2u = Tu = v$. Here, we used the fact that $T^2 = T$. Using the two dimension Theorems we obtain

$$\begin{aligned} \dim(\ker T + \operatorname{Im} T) &= \dim(\ker T) + \dim(\operatorname{Im} T) - \dim(\ker T \cap \operatorname{Im} T) = \\ &= \dim(\ker T) + \dim(\operatorname{Im} T) = \dim V \end{aligned}$$

Here, we used the fact that $\ker T \cap \operatorname{Im} T = \{0\}$. Hence, $V = \ker T + \operatorname{Im} T$, and from the fact that $\ker T \cap \operatorname{Im} T = \{0\}$ we deduce that $V = \ker T \oplus \operatorname{Im} T$.

Since the set $\{v_1, \dots, v_r, w_1, \dots, w_{n-r}\}$ is a basis, then $\alpha_1 = \dots = \alpha_{n-r} = 0$.

Because $T^2 = 0$, for all $1 \leq i \leq n - r$ we have $T(Tw_i) = T^2w_i = 0$. Hence, $\{Tw_1, \dots, Tw_{n-r}\}$ is a linearly independent set inside $\ker T$. Since $\dim(\ker T) = r$, we obtain $n - r \leq r$, or $n \leq 2r$.

b) There are two cases to consider. First, assume that $A = aI$ for some $a \in \mathbf{R}$. Then it is easy to see that $W = V$. Hence, it is clear that $\dim W \geq 2$. In general it is clear that the matrices I and A are in W . Suppose that $A \neq aI$ for all $a \in \mathbf{R}$. Then the claim is that the set $\{I, A\}$ is a linearly independent set in V . Indeed, consider the equation $\alpha I + \beta A = 0$. If $\beta \neq 0$, then $A = -\frac{\alpha}{\beta}I$. This is a contradiction to the assumption that $A \neq aI$. Hence $\beta = 0$, which implies that $\alpha = 0$. Hence, again we have $\dim W \geq 2$.