Project 3 Help

Oct 31, 2019
DCSLab
SNU Operating Systems

Notice

Delay

1 day : -10%

2 days : -15%

3 ~ 5 days: -50%

Peer review

Today's presentation

Team 3,7



어서 와 Lock은 처음이지?

Project 3 Overview

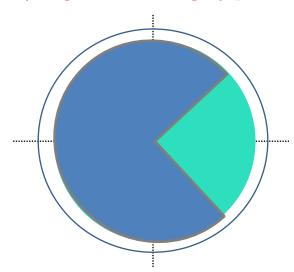
- Implement rotation-based read/write lock
- Each lock has a "rotation range"
 - Every lock can be acquired when the current rotation is in the rotation range
 - Or, it is blocked until the current rotation is located in the rotation range
- Read lock could be acquired when no acquired write lock range is overlapping with its range
- Write lock could be acquired when no acquired read/write lock range is overlapping with its range
 - Exclusive access

Rotation Range

- 1 axis: rotation(use daemon)
 - Actually, Tizen orientation has three axes! (Azimuth, Pitch, Roll)

Lock (degree, range) = [(degree - range), (degree + range)]

- Rotation ranges are inclusive
 - Ex) [30, 60], [60, 90] are overlapped
- Rotation ranges are circular
 - Ex) [330, 30] and [30, 330]
 - o [330 ... 0 ... 30]
 - o [30 ... 180 ... 330]



Range Example (1)

- Rotation 1
 - o degree = 30
 - o range = 30

• Rotation 2

- \circ degree = 45
- o range = 30

Are they overlapped?

Range Example (1)

- Rotation 1
 - \circ degree = 30
 - o range = 30
- Rotation 1
 - o [0, 60]

Are they overlapped?

Yes!

- Rotation 2
 - \circ degree = 45
 - o range = 30
- Rotation 2
 - o [15, 75]

Range Example (2)

- Rotation 1
 - degree = 30
 - o range = 60

• Rotation 2

- o degree = 315
- o range = 30

Are they overlapped?

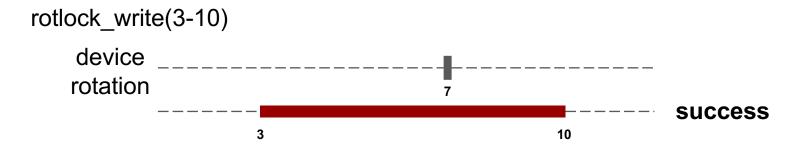
Range Example (2)

- Rotation 1
 - \circ degree = 30
 - o range = 60
- Rotation 1
 - o [0, 90] + [330, 360]

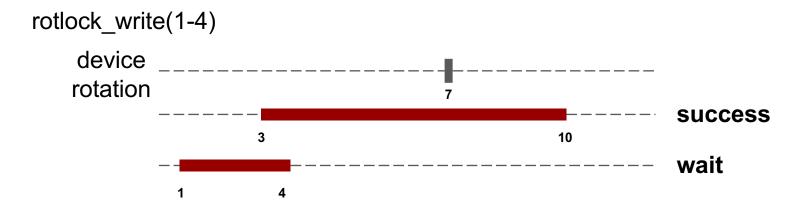
Are they overlapped?

Yes!

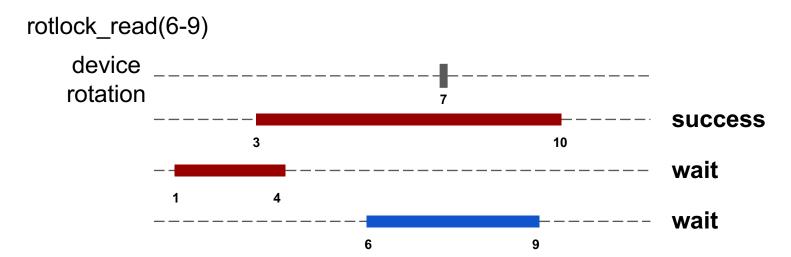
- Rotation 2
 - o degree = 315
 - o range = 30
- Rotation 2
 - **[285, 345]**



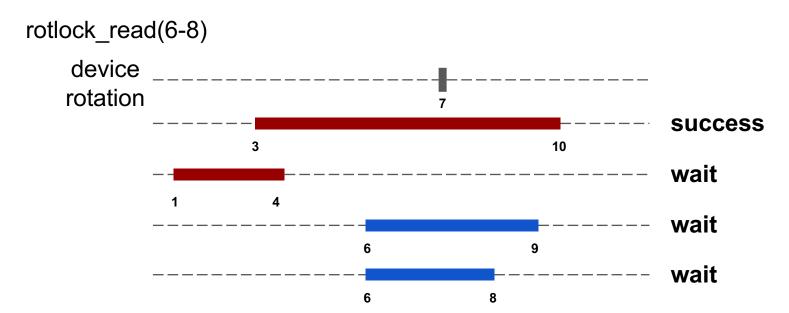




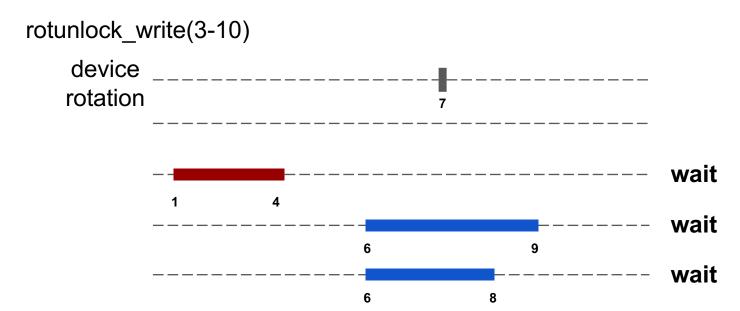




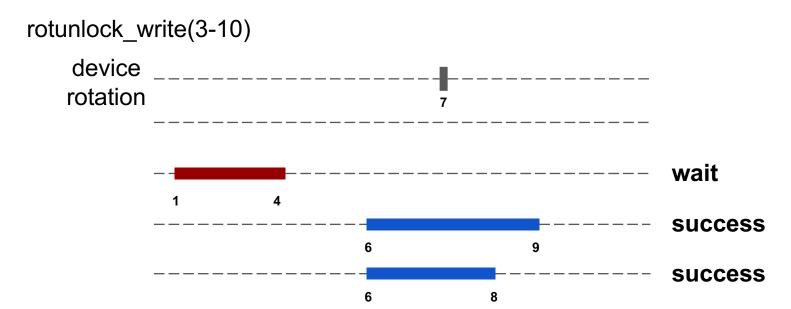






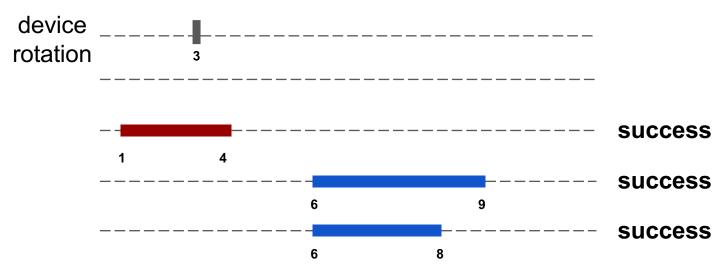








Device rotation changed to 3

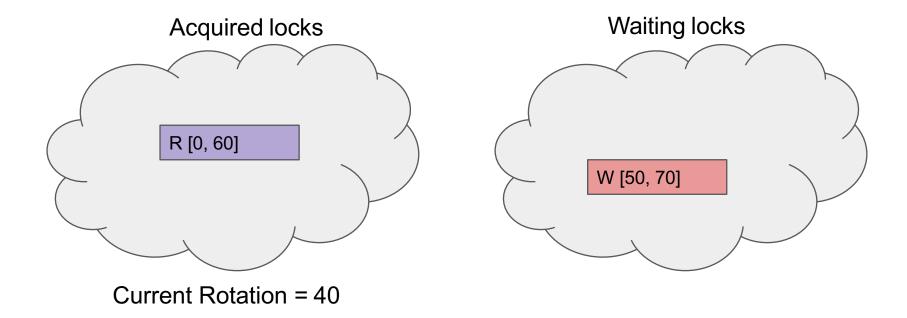




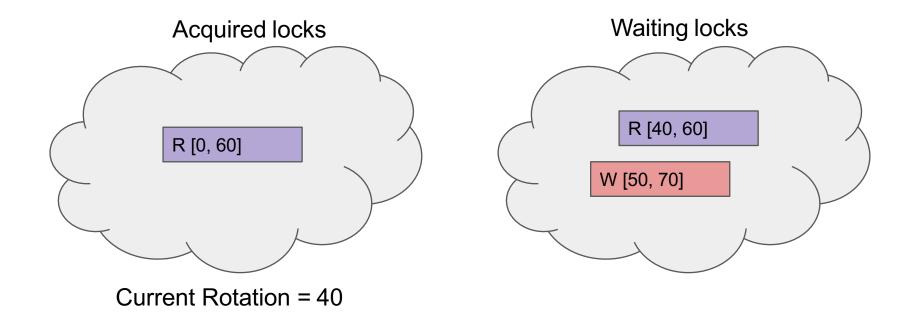
Preventing writer starvation

- You should implement a policy for preventing starvation of writers
 - Why? If reader comes in infinitely, a writer could wait forever!
- If a reader holds a lock and a writer wants to take the lock, no more readers can take the lock
- If you design your own additional policy, explain that in your README.md file, report, and slides!

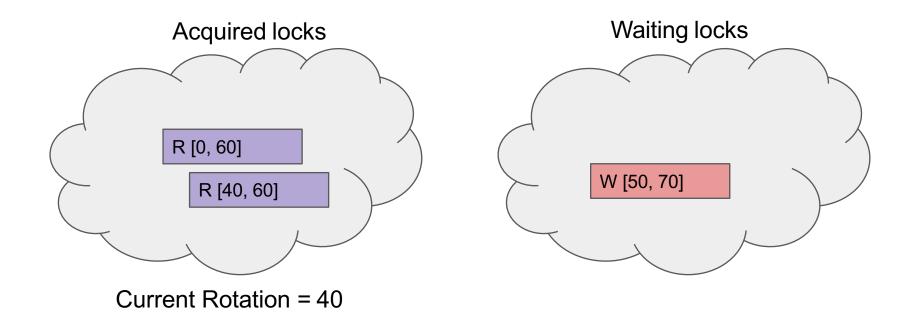
 A write lock is waiting for the rotation changes & the reader to release its lock



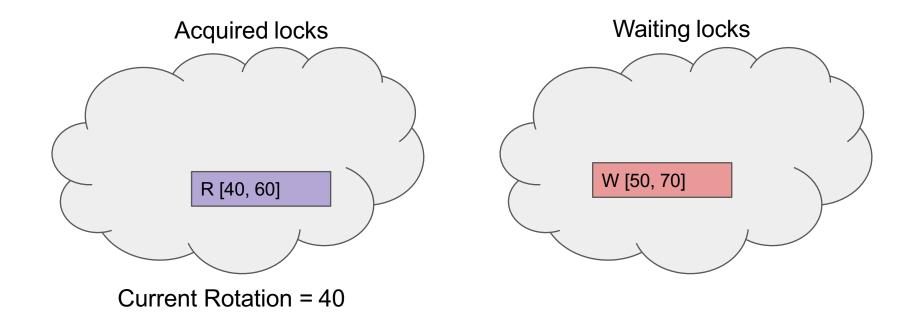
• A read lock [40, 60] came



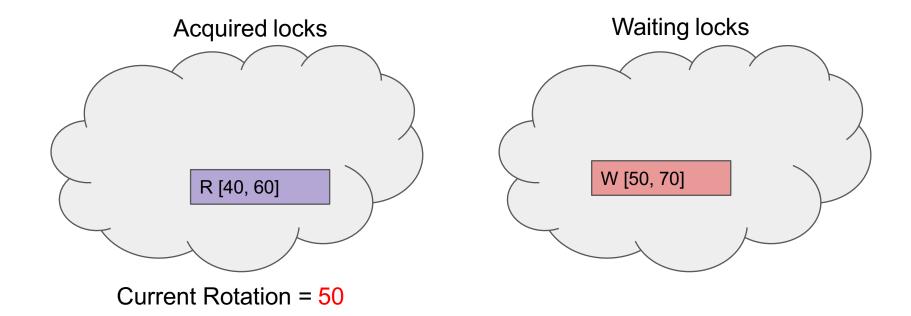
• 40 ∈ [40, 60] → Acquires its lock immediately



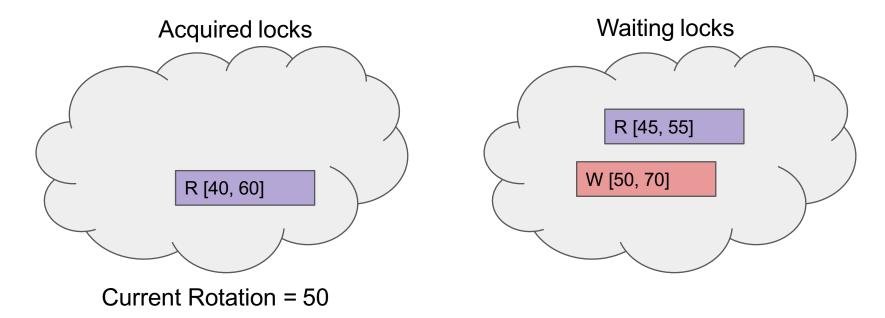
• R [0, 60] releases its lock



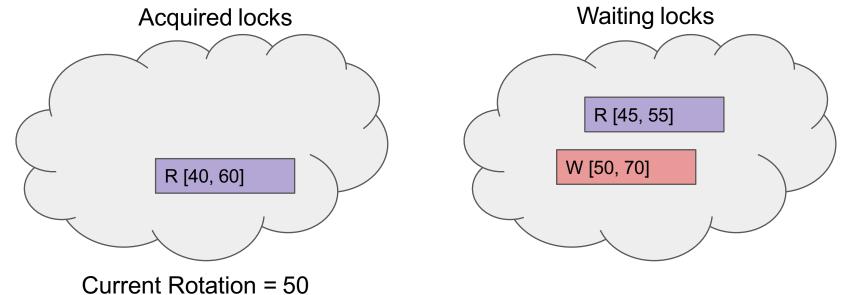
Rotation changes 40 → 50

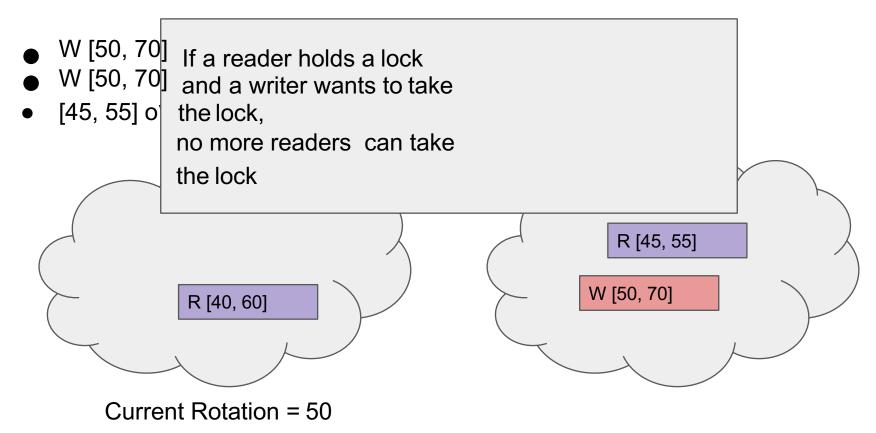


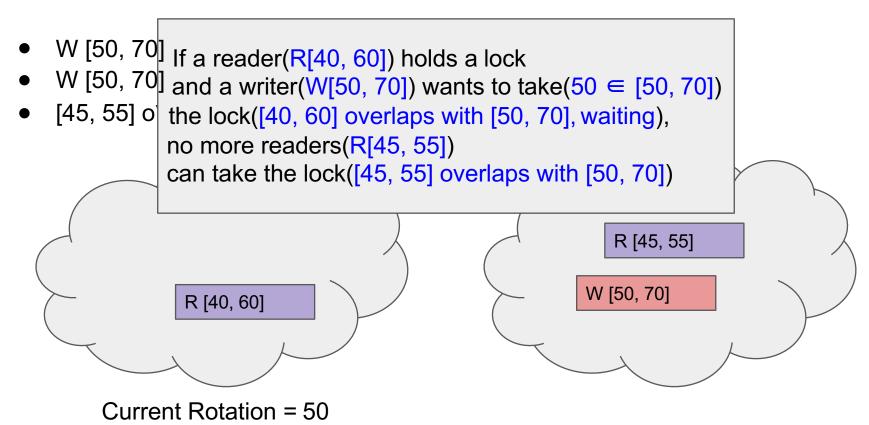
- A read lock [45, 55] came
- 50 ∈ [45, 55] but cannot acquire its lock, because ...



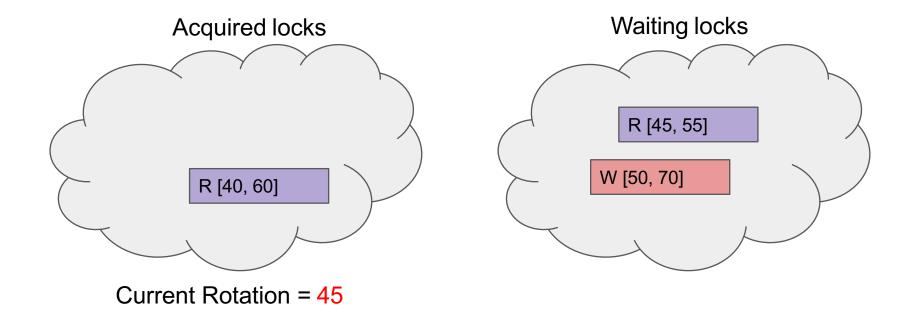
- W [50, 70] is waiting and 50 ∈ [50, 70]
- W [50, 70] is waiting for R [40, 60] to release its lock
- [45, 55] overlaps with [50, 70]



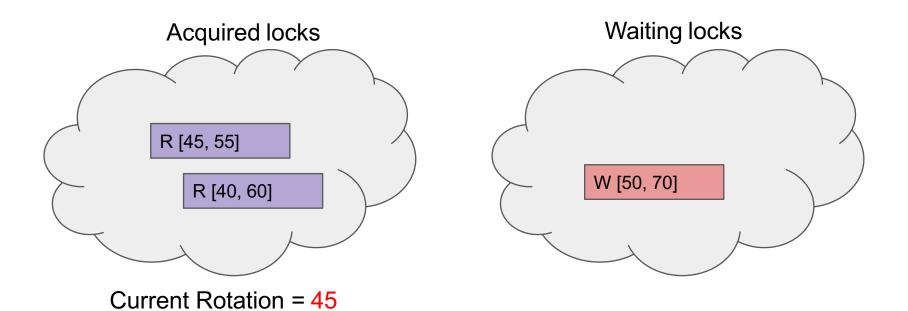




Rotation changes 50 → 45



- W [50, 70] cannot grab its lock anymore (∴ 45 ∉ [50, 70])
- Starvation prevention policy is no more applied → R [45, 55] acquires its lock

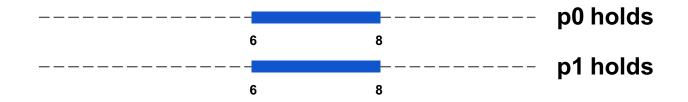


Terminating routine

- When a thread that has some holding or waiting locks is termin ating, the remaining locks should be released (holding) or removed (waiting).
- Hints
 - exit rotlock() in kernel/rotation.c
 - Release holding locks
 - Remove waiting locks
 - Inject exit_rotlock() to do_exit() in kernel/exit.c

Isolation

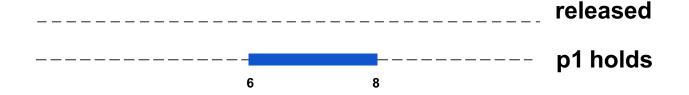
- Multiple processes shares same rotation lock system.
 - You have to identify which process (thread) the lock belongs to.
- A process can't release locks that other processes hold.



Isolation

• A process can't release locks that other processes hold.

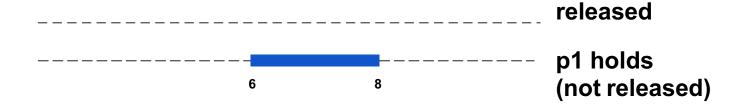
p0 calls unlock(6-8)



Isolation

A process can't release locks that other processes hold.

p0 calls unlock(6-8) again



- You will create things like acquired lock list and waiting lock list
 - Different approaches are also possible :)
 - Ex) Bitmap, linked list, ...
- Accessing those lists could result in race conditions
 - Remind: RPI3 has 4 cores
 - You should carefully design your code to prevent possible race conditions
 - Ex) One thread is removing a lock from waiting list, but another thread can access to the waiting list at the same time

- Possible approaches
 - Global
 - Ex) Manage acquired lock list and waiting lock list using a same lock
 - Fine-grained
 - Ex) Manage acquired lock list and waiting lock list using separated locks
 - Better concurrency, more complicated :)
- Synchronization mechanism
 - Spin Lock
 - Eligible for short sleep (e.g. short list iteration)
 - RCU (Read-Copy-Update)
 - 0 ...

- How to block processes || How to wake up blocked processes
 - You may use Study by yourself :)
 - Wait Queue (Starts with DECLARE_WAIT_QUEUE_HEAD)
 - Condition Variable (Define your own CV)
 - Mutex
 - **■** ...

- Lists could be changed during iteration
 - list_for_each_entry_safe could be useful to you
- Please remember that ...
 - The rotation range is circular!
 - You should implement a logic for determining two circular ranges are overlapping or not
 - Be aware of deadlocks!

Selector & Trial

- Selector & Trial require a same lock (0 <= range <= 180)
 - If current rotation is 240, both selector & trial wait.
- When the device rotation is out of that range, both Selector & Trial stop working
- When the device rotation gets inside that range, Selector & Trial start to work

Selector & Trial

Selector	Trial
write_lock ———	read lock & wait
10 write_unlock ———	acquire lock
write_lock & wait ——	10 = 2 * 5
acquire lock ———	—— read unlock

About submission (IMPORTANT!)

- Make sure your branch name: proj3
- Don't be late!
 - TA will not grade the commits after the deadline.
- Slides and Demo
 - Send it to the TA's email (os-tas@dcslab.snu.ac.kr) before the deadline.
 - Title: [OS-ProjX] TeamX slides&demo submission
 - File name: TeamX-slides.ppt(.pdf), TeamX-demo.mp4(.avi....)
- Save your C program as: test/selector.c, test/trial.c
- Check for format : slides title / demo name / test file names / branch name and directory name
- Please aggregate your demo videos (=submit only one video!)

Announcement

- Deadline
 - Due: 2019-11-21 Thursday 13:00.
- Check your source code before submission
 - There were some codes which were not compiled....

Q&A