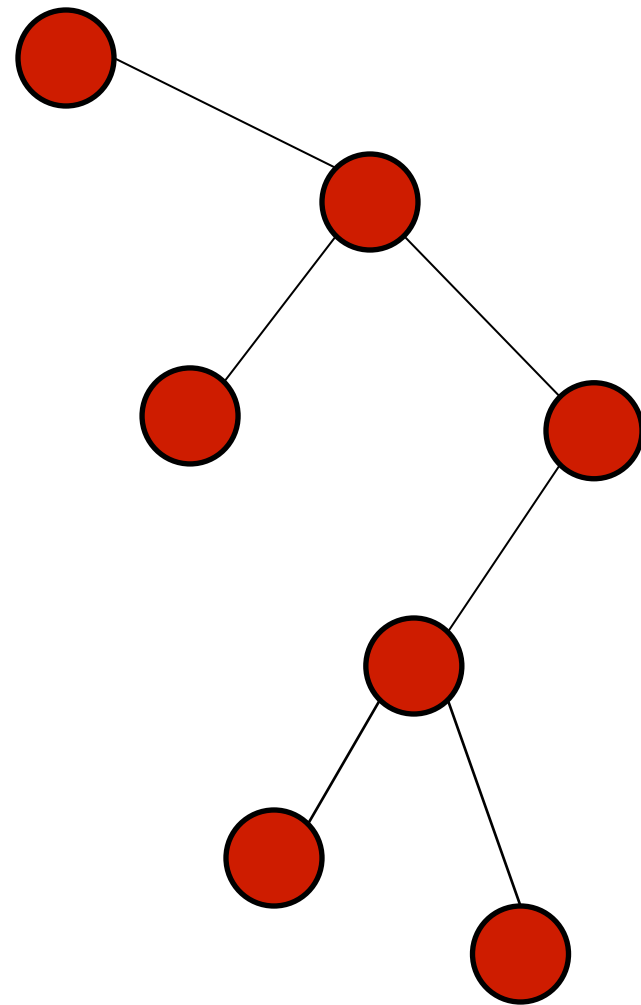


Lecture 5
Tree walks
and tree representations
EECS-214

Remember trees?

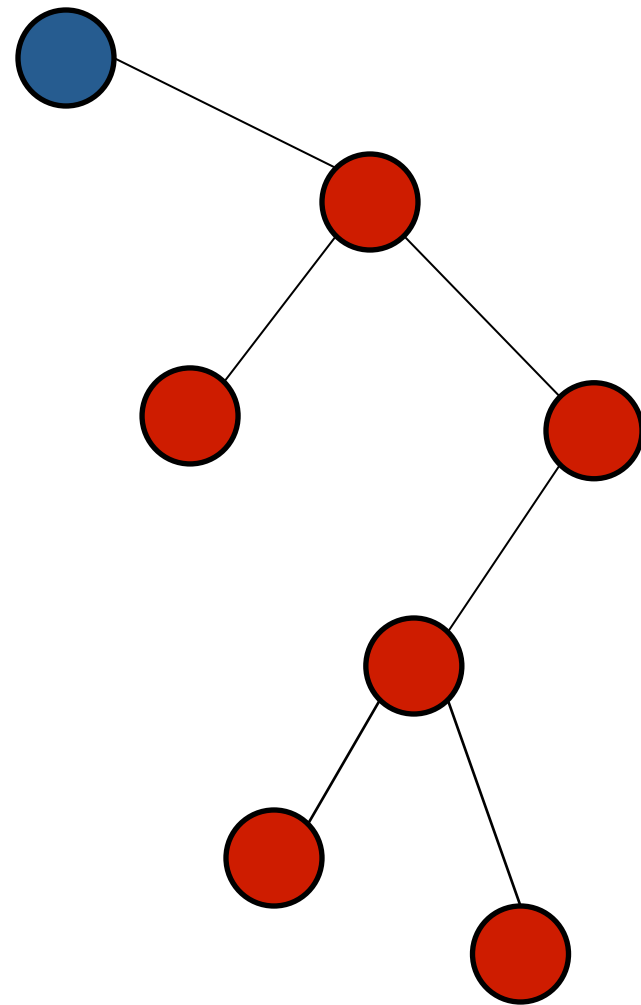
Trees

- A tree is a graph in which any pair of nodes has exactly one path between them



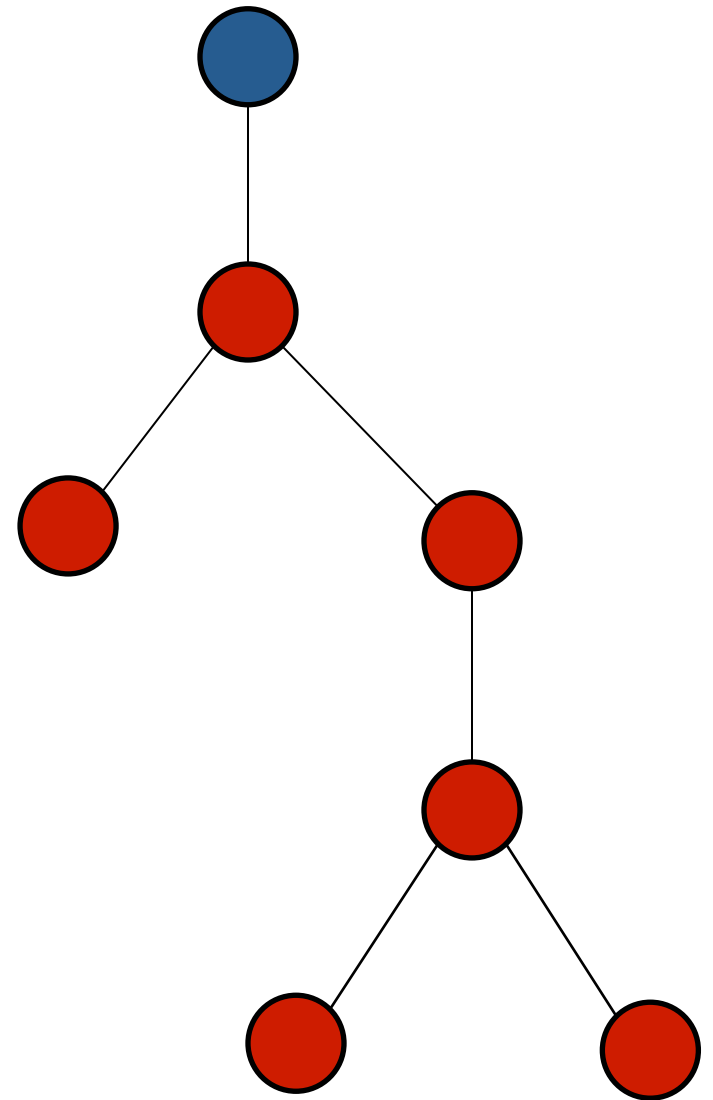
Trees

- In computer science, we usually think of trees as having a distinguished node call the **root**



Rooted trees

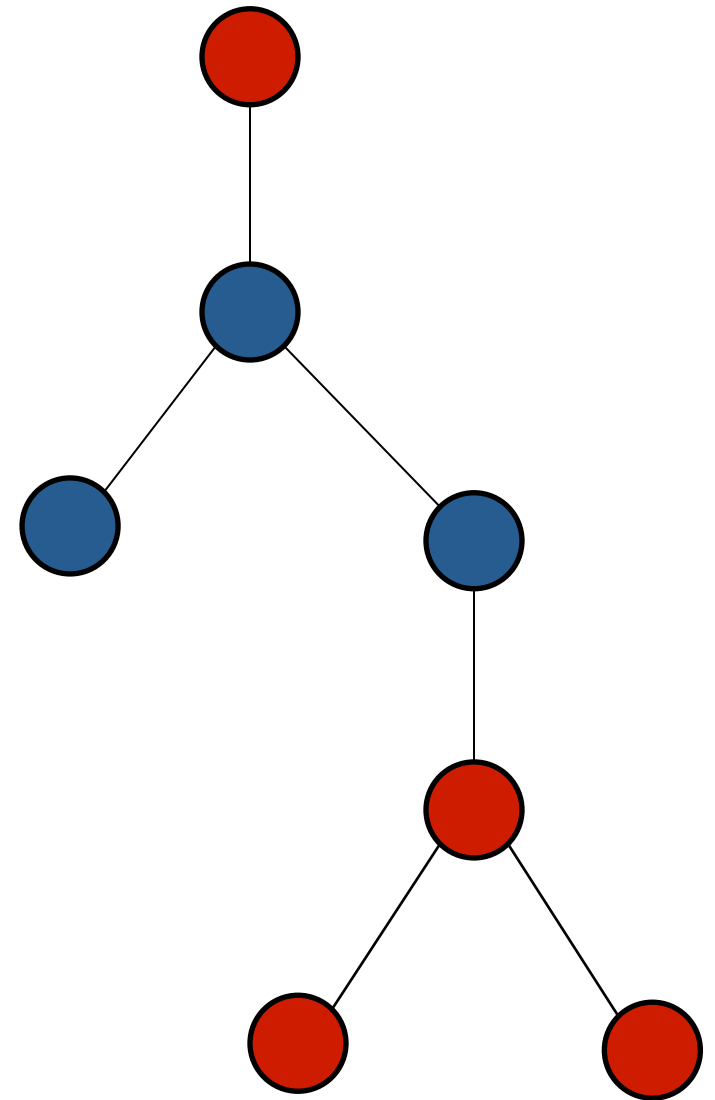
- In computer science, we usually think of trees as having a distinguished vertex called the **root**
- And we draw it
 - With the root at the top
 - And other vertices arranged by their distance from the root



Children

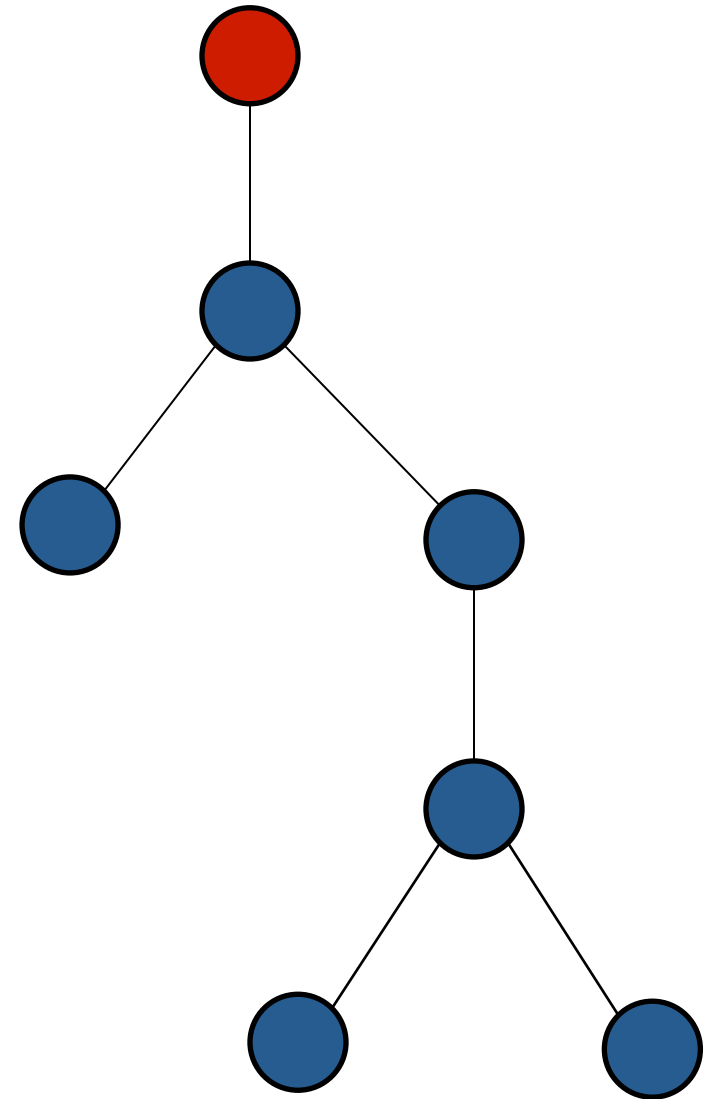
- The nodes adjacent to a node, but at the next lower depth are called its **children**

Note: node and vertex are synonyms



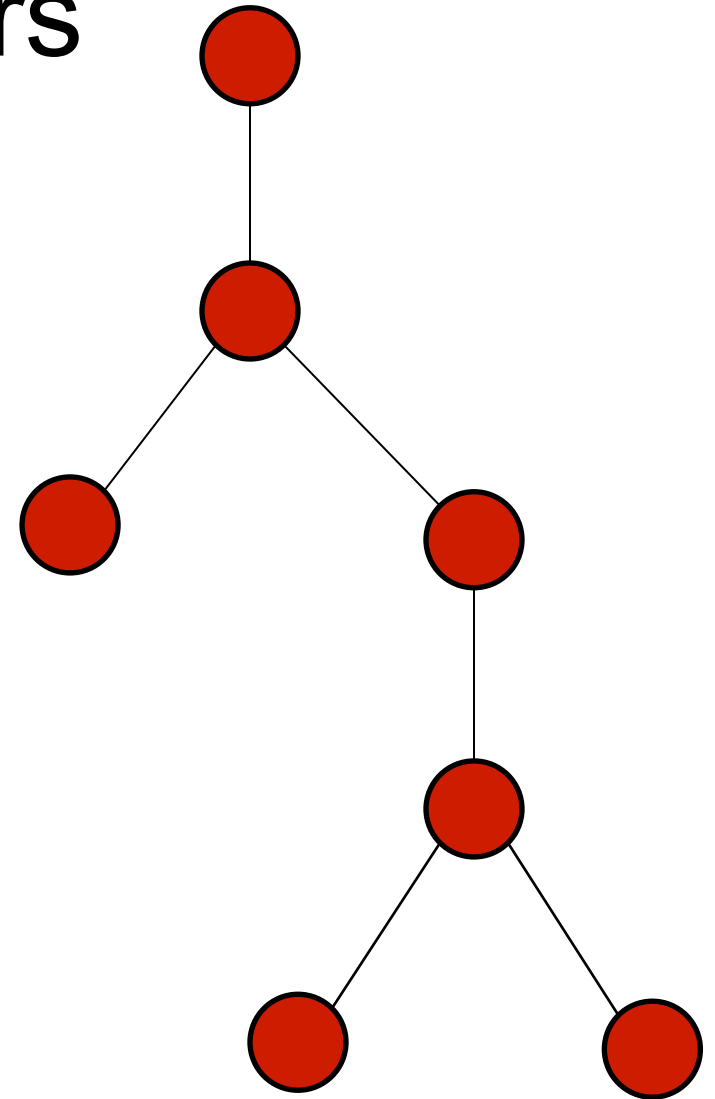
Children

- The nodes adjacent to a node, but at the next lower depth are called its **children**
- And the nodes that are its children, children's children, etc., are called its **descendants**



Parents and ancestors

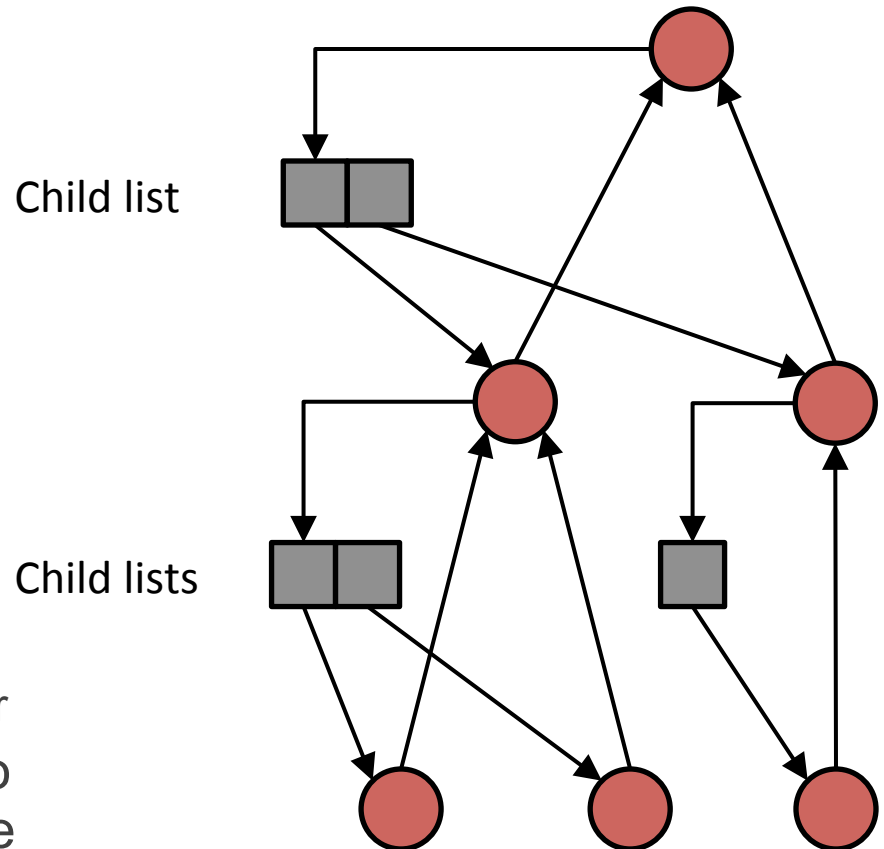
- The nodes above a node in the tree are its **ancestors**
- The node immediately above a node in the tree is its **parent**
 - All nodes have parents except the root
- Nodes with the same parent are called **siblings**



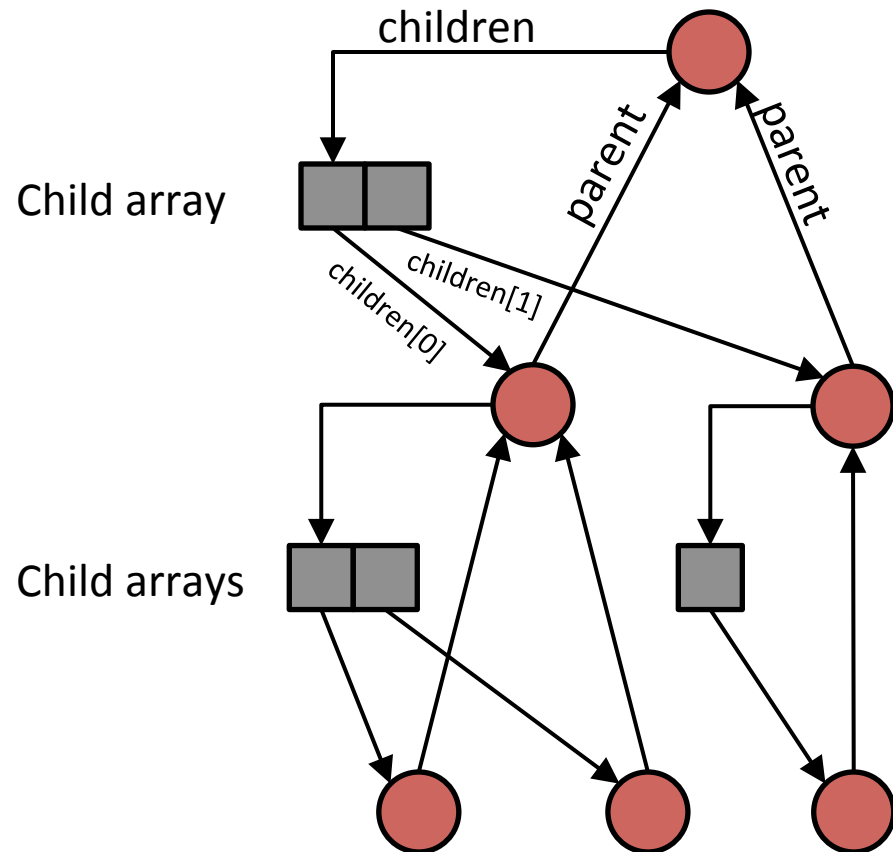
Data structures for trees

General representation of trees

- Each tree node is an object
 - (Red circles)
- Each node object contains
 - Parent
 - (Upward arrows)
 - List of children
 - (Grey boxes)
 - linked list, array, whatever
 - Anything else you want to remember about the node

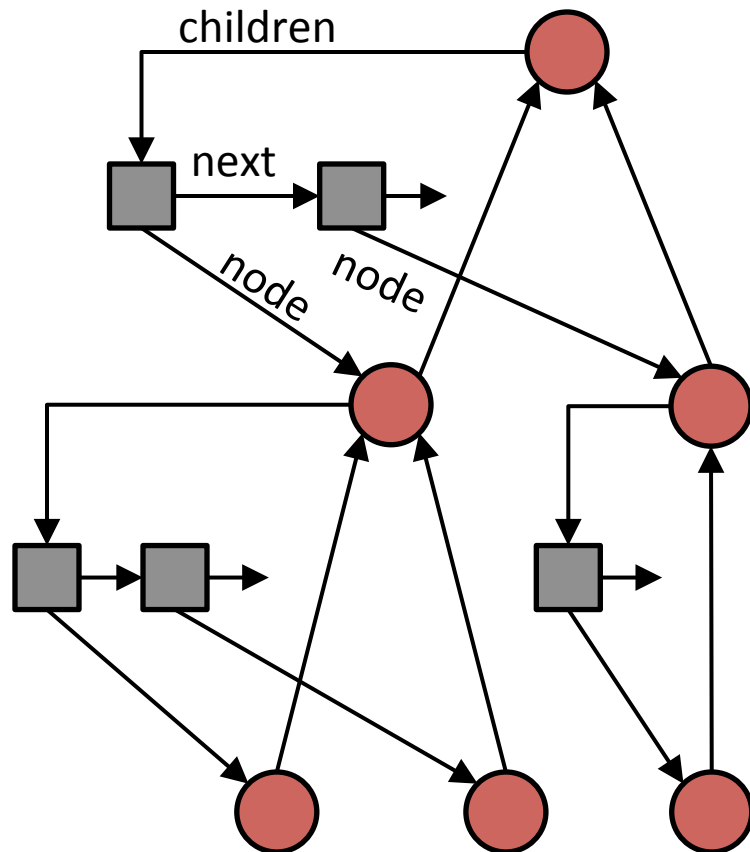


Using an array



```
class TreeNode {  
    TreeNode parent;  
    TreeNode[] children;  
    ... other data ...  
}
```

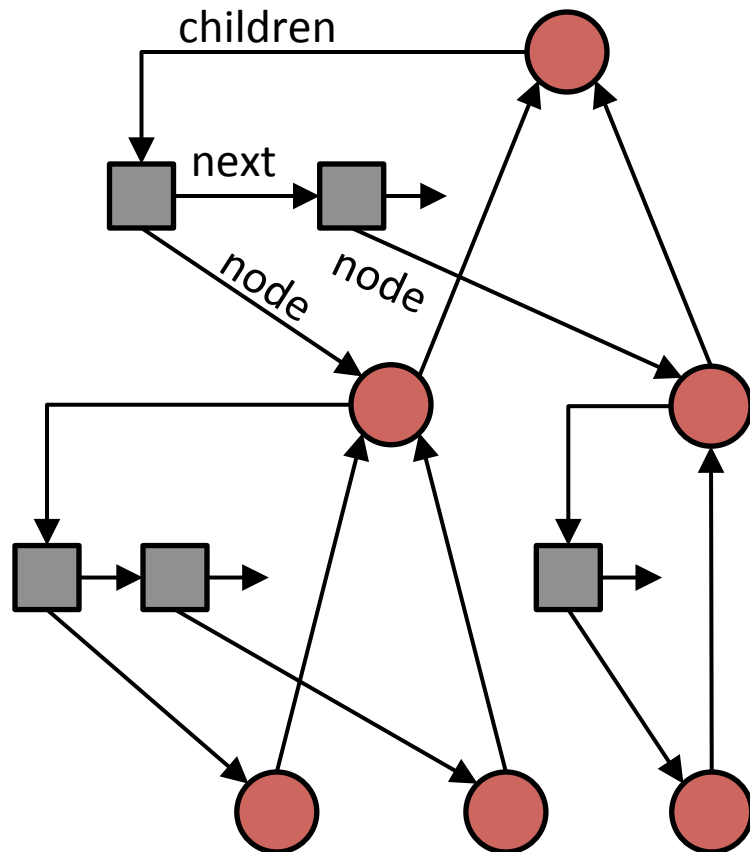
Using a linked list



```
class TreeNode {  
    TreeNode parent;  
    TreeNodeList children;  
    ... other data ...  
}
```

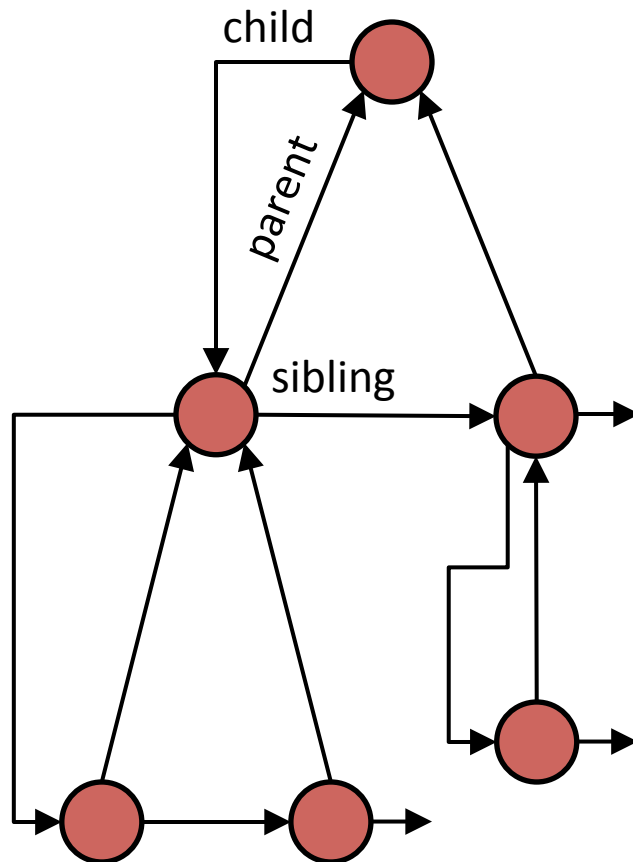
```
Class TreeNodeList {  
    TreeNode node;  
    TreeNodeList next;  
}
```

Using a linked list



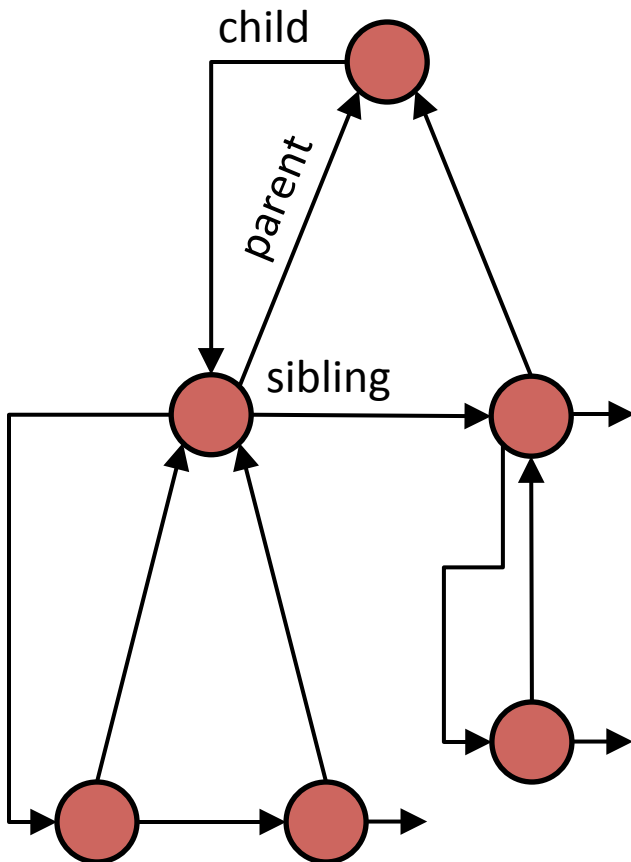
- Notice that we have exactly one linked list cell per node
– (except the root)
- So we can just move the next pointer into the node itself

Moving the link into the node



- Notice that we have exactly one linked list cell per node
 - (except the root)
- So we can just move the next pointer into the node itself
- And remove the linked list cells

Moving the link into the node

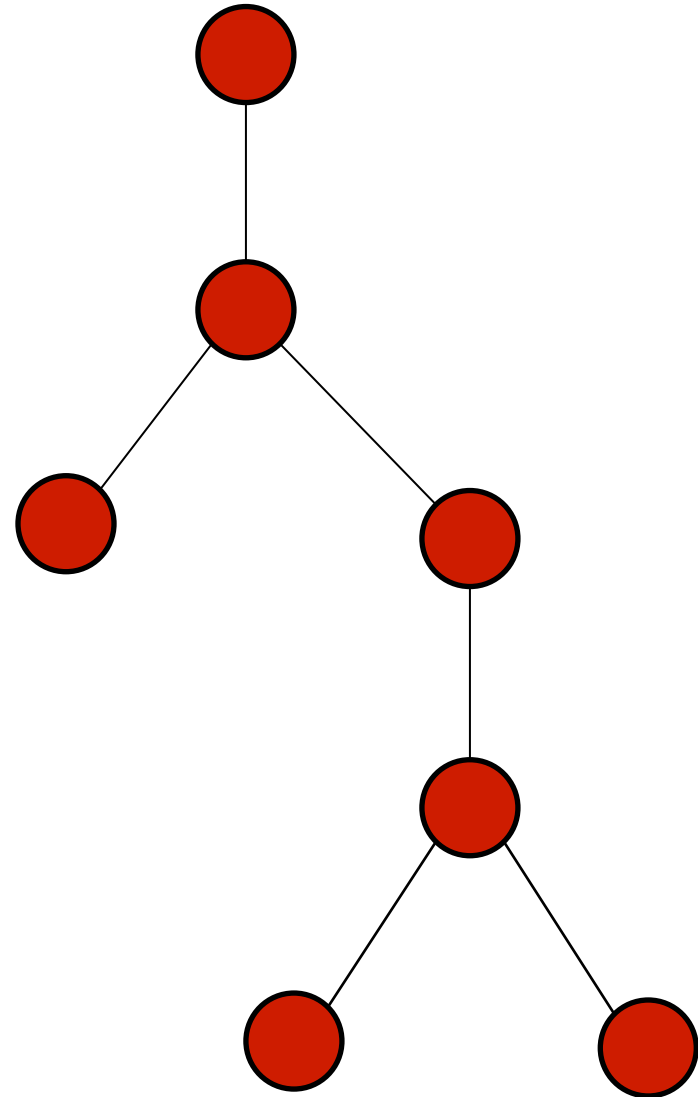


```
class TreeNode {  
    TreeNode parent;  
    TreeNode firstChild;  
    TreeNode nextSibling;  
    ... other data ...  
}
```

The CLR book calls this the left child/right sibling representation

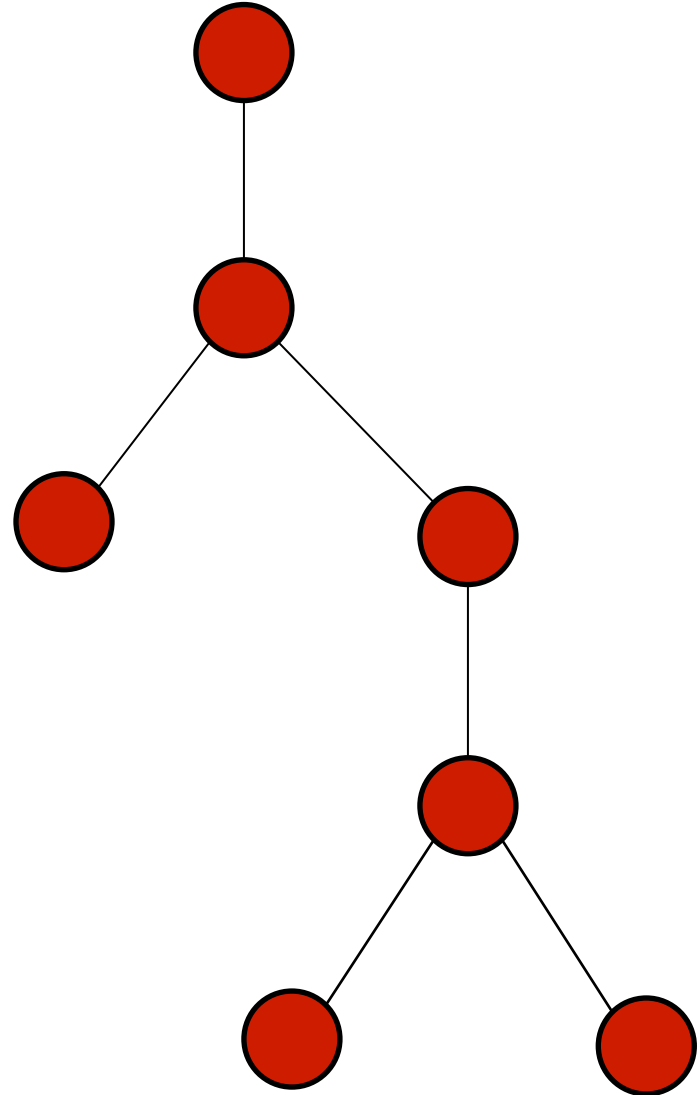
Tree walks

- We generally don't talk about **iterating** through the nodes in a tree
- We talk about **walking** through them or **traversing** them
 - That's partly because tree walks are often written as recursions
 - And we think of iterations as being while and for loop, and recursions being something different



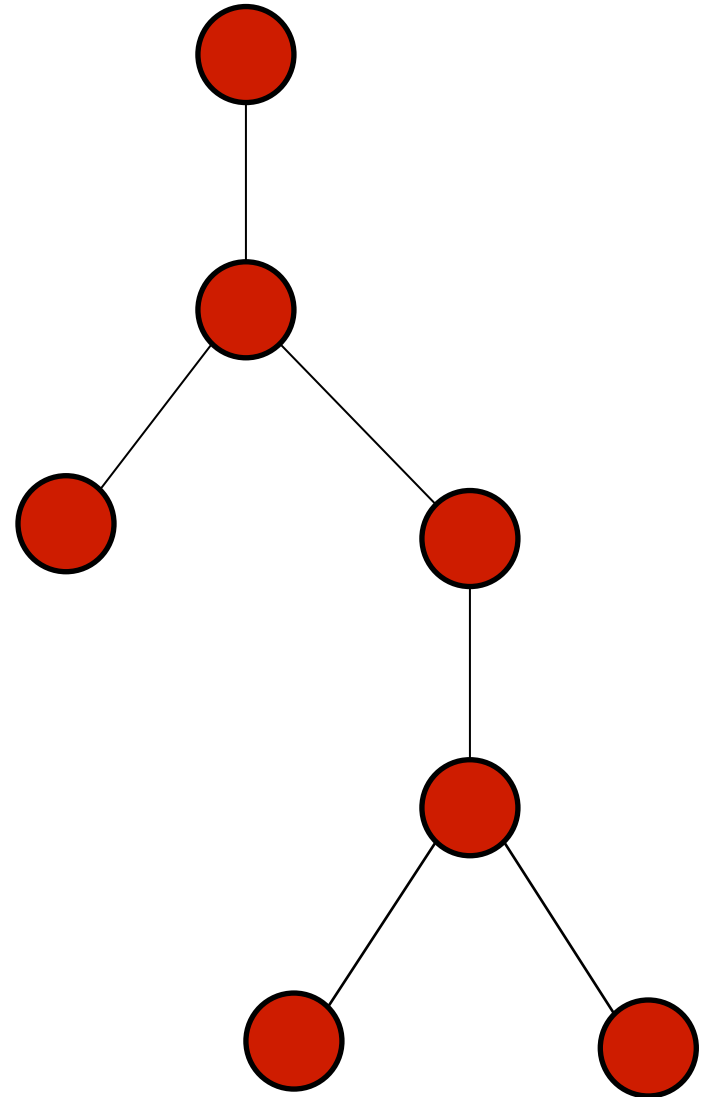
Tree walks

- You can walk trees in different orders



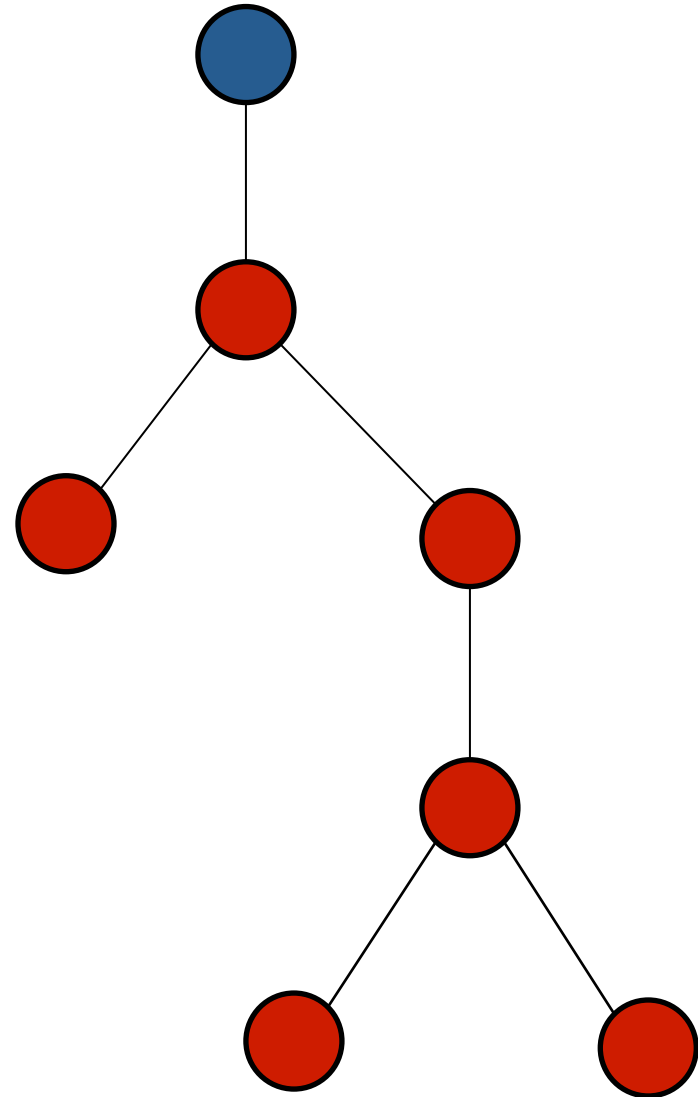
Tree walks

- You can walk trees in different orders
- **Breadth-first** walks



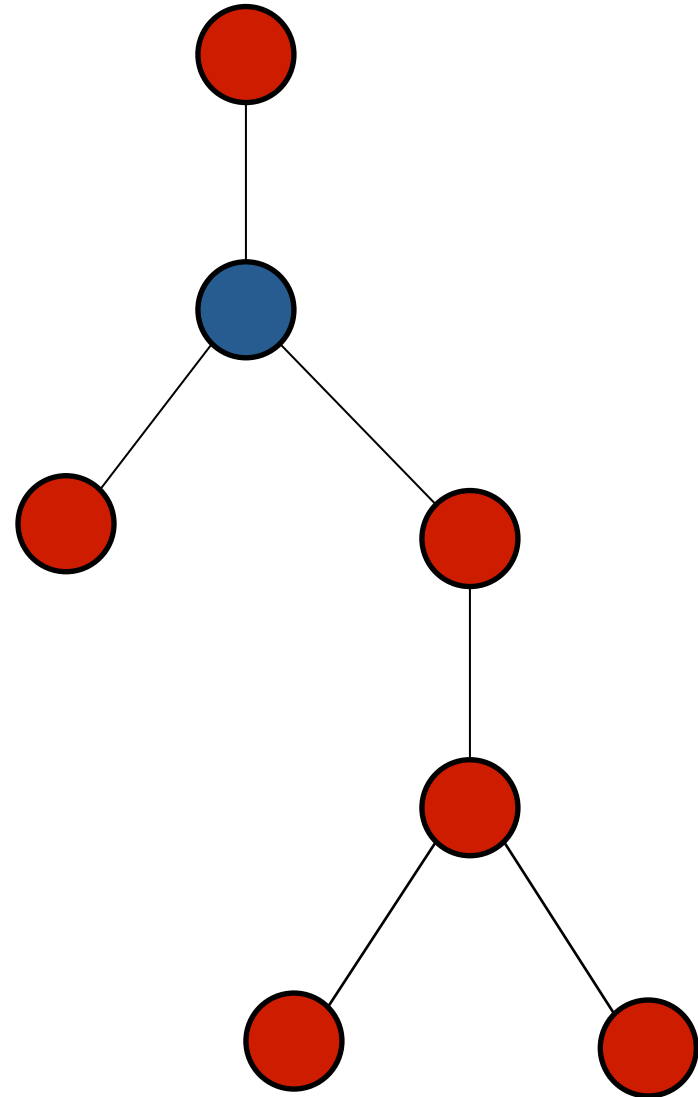
Tree walks

- You can walk trees in different orders
- **Breadth-first** walks
 - Start with the root



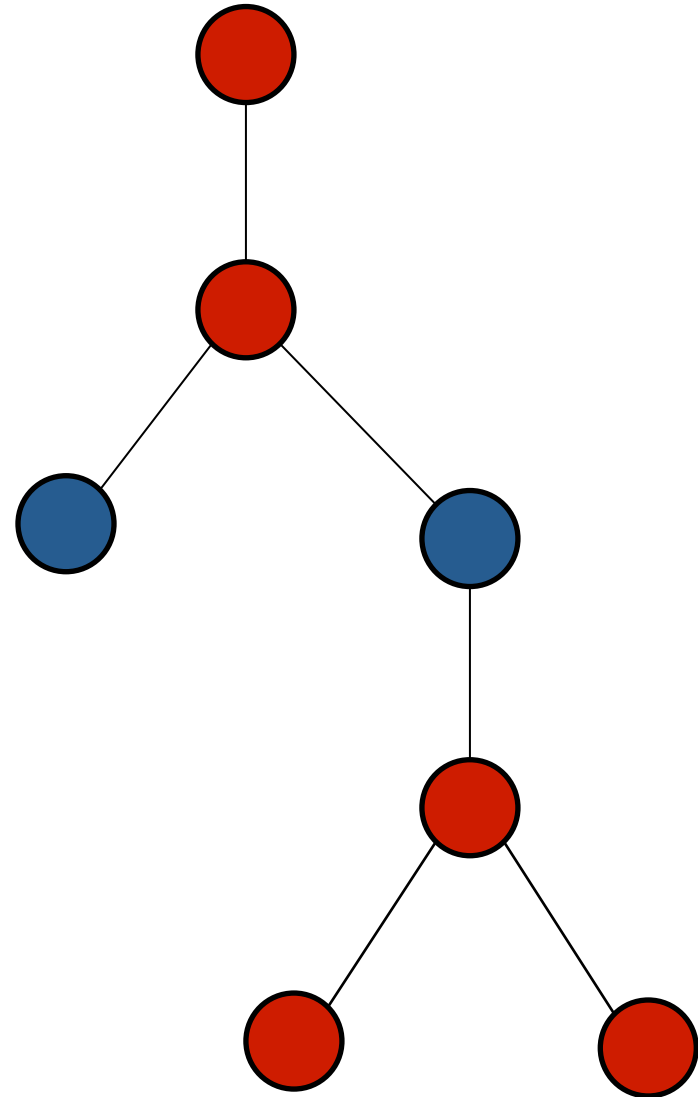
Tree walks

- You can walk trees in different orders
- **Breadth-first** walks
 - Start with the root
 - Then do all the nodes at depth 1 (just one in this case)



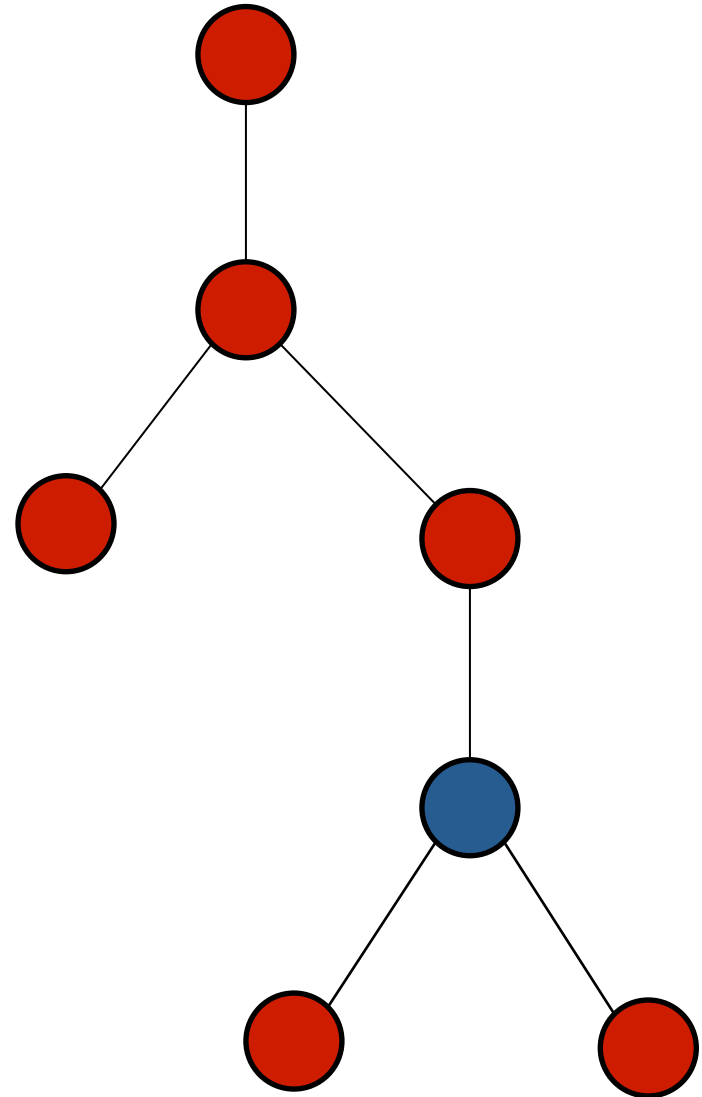
Tree walks

- You can walk trees in different orders
- **Breadth-first** walks
 - Start with the root
 - Then do all the nodes at depth 1
 - Then depth 2



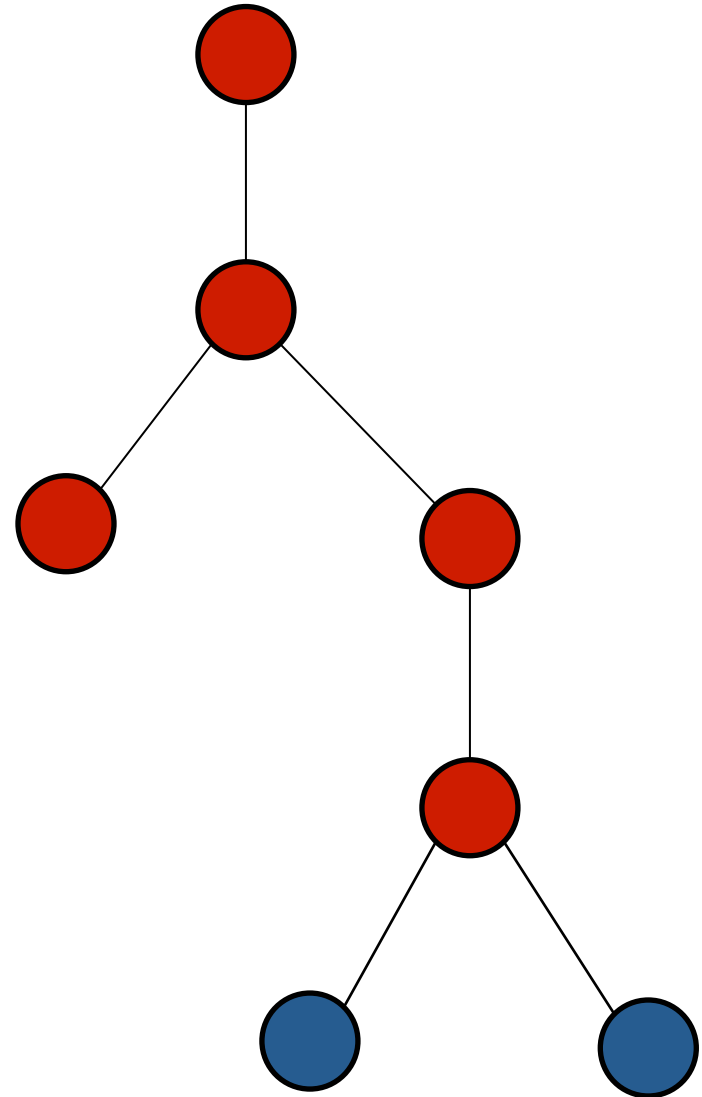
Tree walks

- You can walk trees in different orders
- **Breadth-first** walks
 - Start with the root
 - Then do all the nodes at depth 1
 - Then depth 2
 - Then depth 3



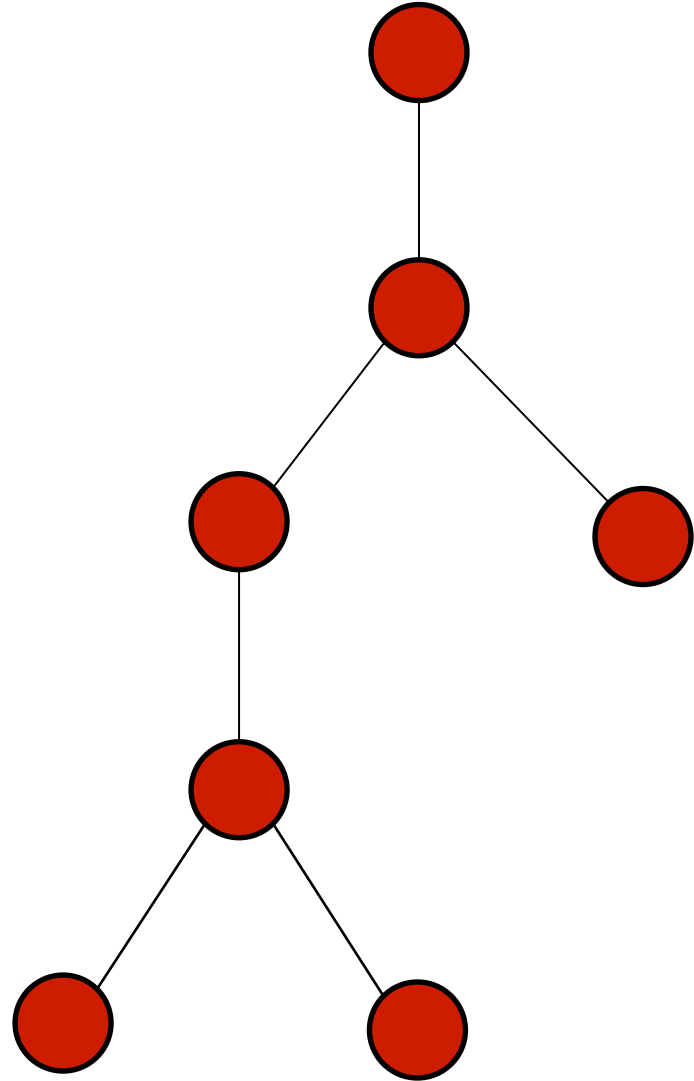
Tree walks

- You can walk trees in different orders
- **Breadth-first** walks
 - Start with the root
 - Then do all the nodes at depth 1
 - Then depth 2
 - Then depth 3
 - And so on ...



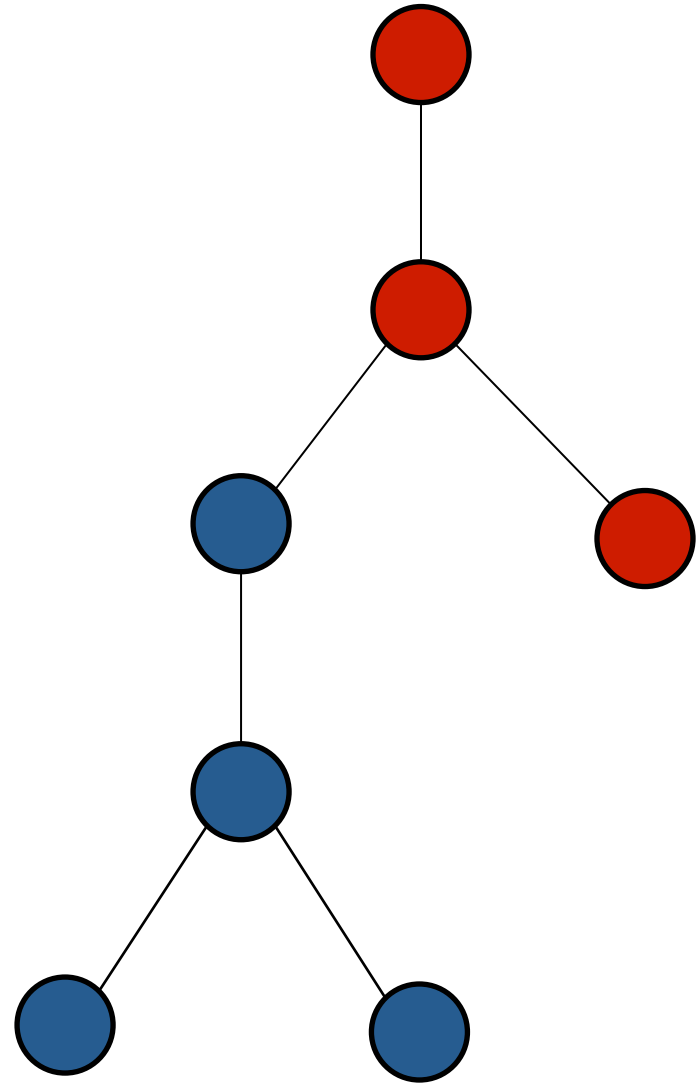
Tree walks

- A **depth-first** walk



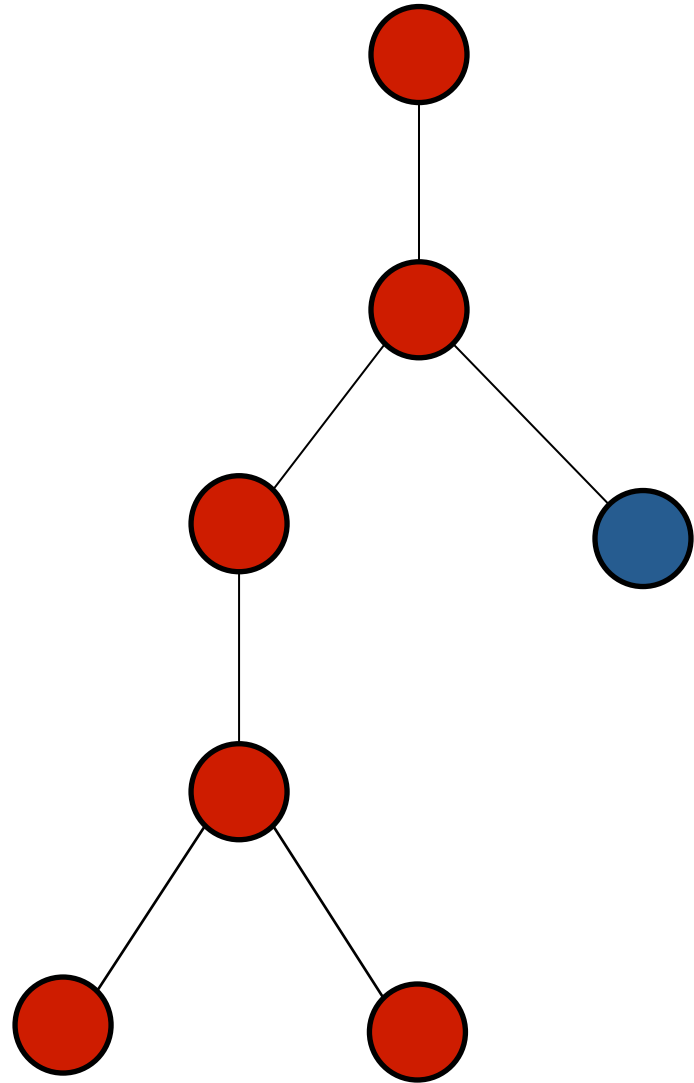
Tree walks

- A **depth-first** walk
 - Goes through all the decedents of a node



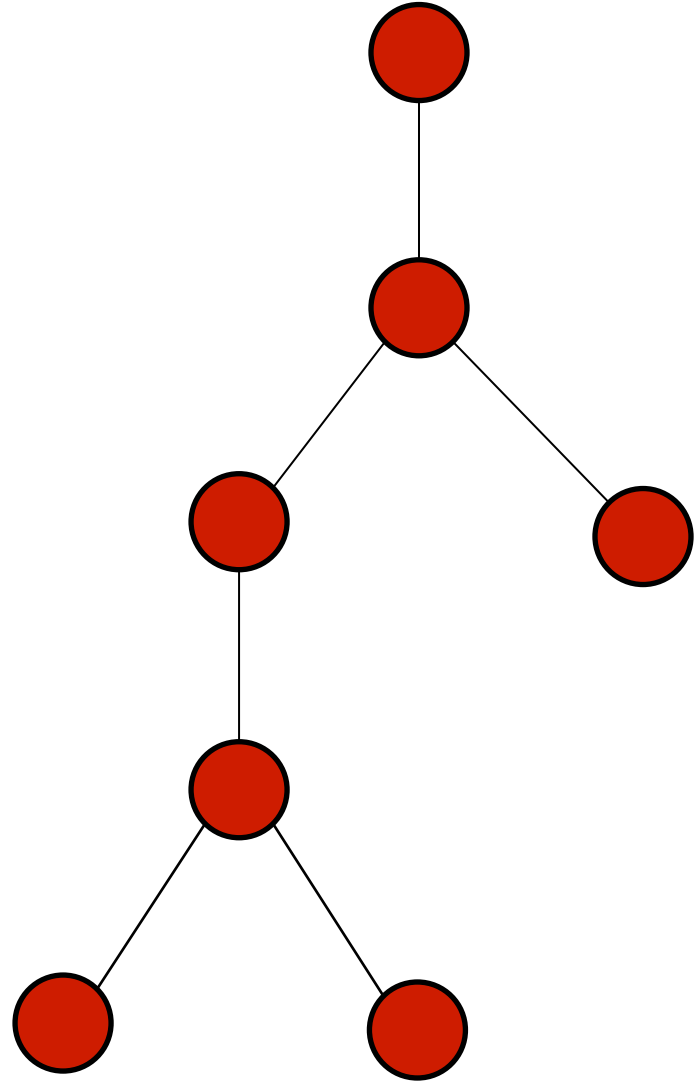
Tree walks

- A **depth-first** walk
 - Goes through all the decedents of a node
 - Before moving to the node's sibling



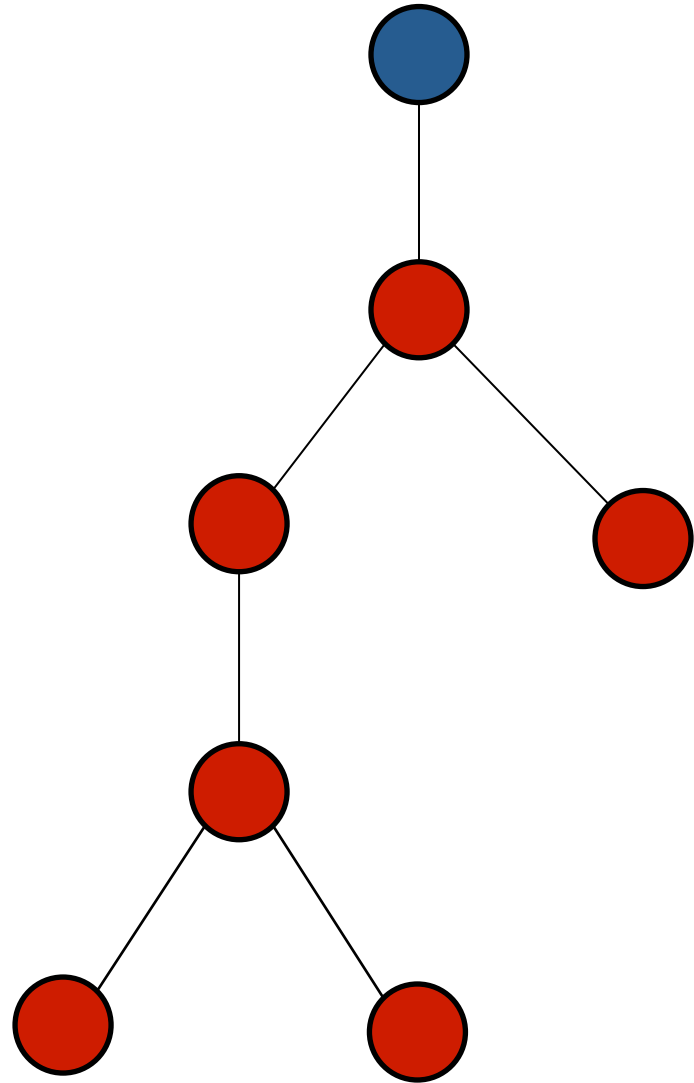
Tree walks

- A **depth-first** walk



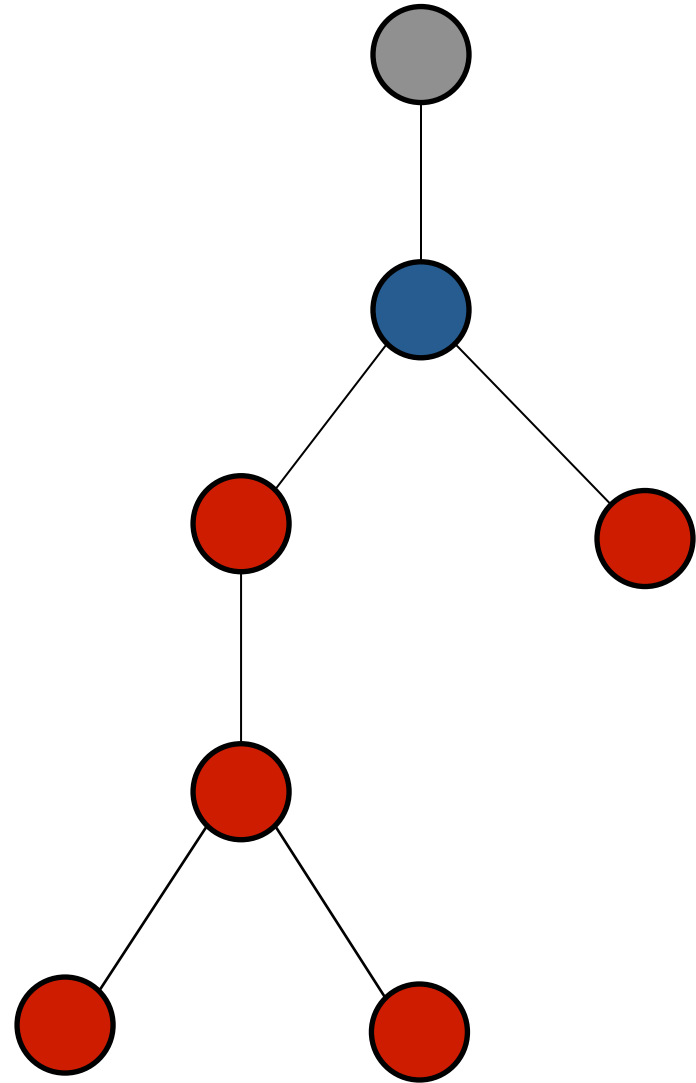
Tree walks

- A **depth-first** walk
 - Starts with the root



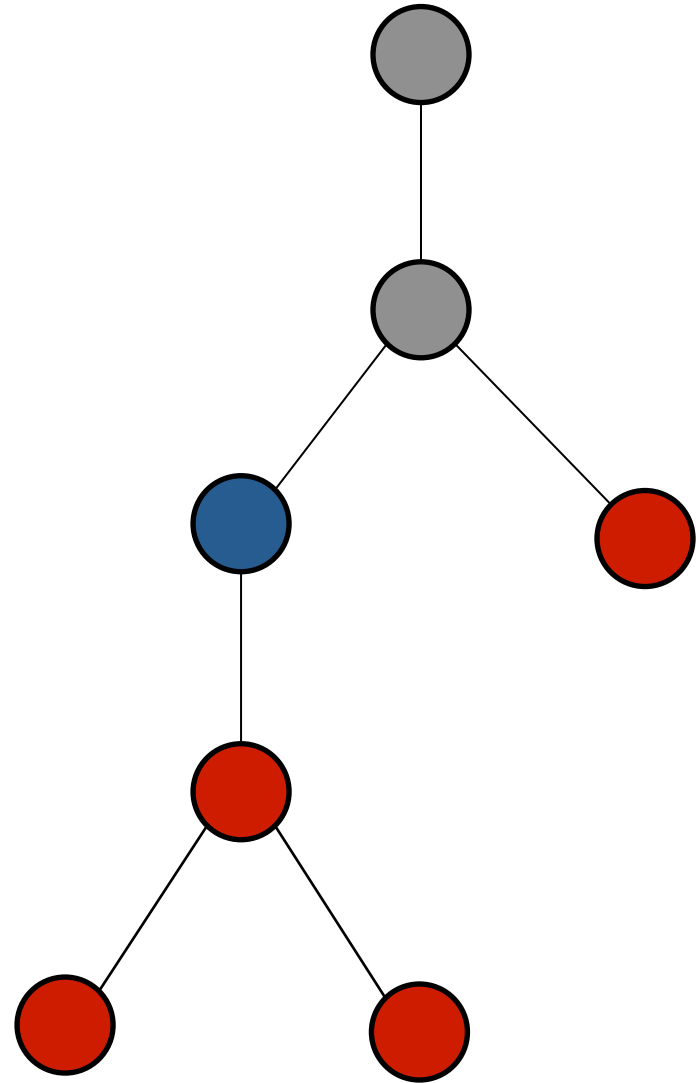
Tree walks

- A **depth-first** walk
 - Starts with the root
 - Moves to its first child (in this case, the only child)



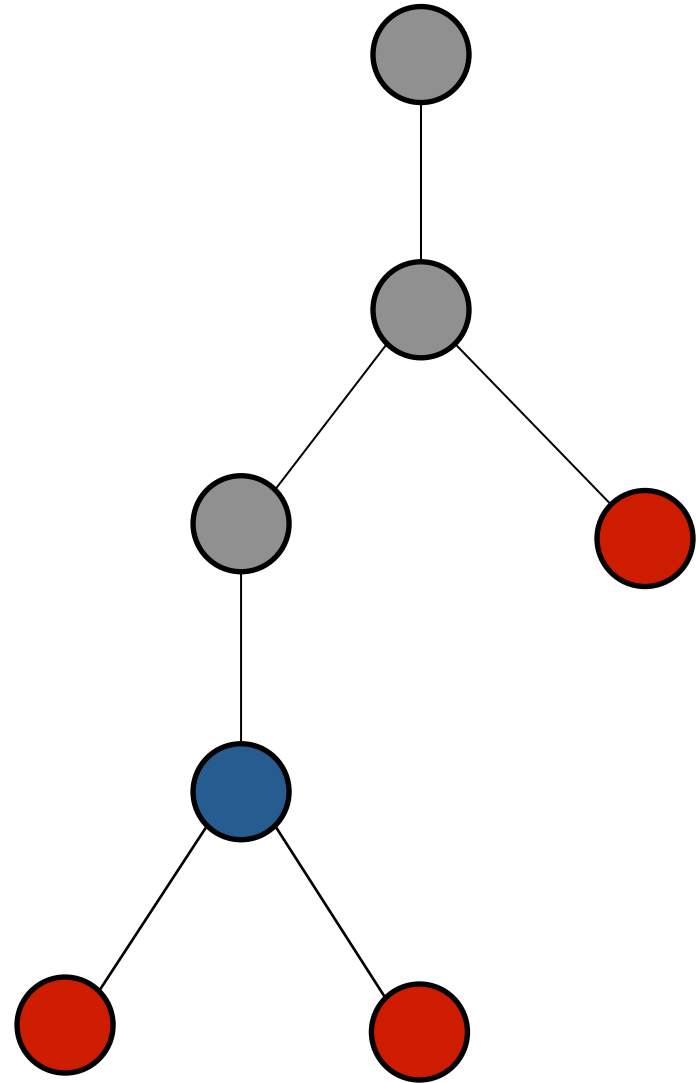
Tree walks

- A **depth-first** walk
 - Starts with the root
 - Moves to its first child
 - Then its first child



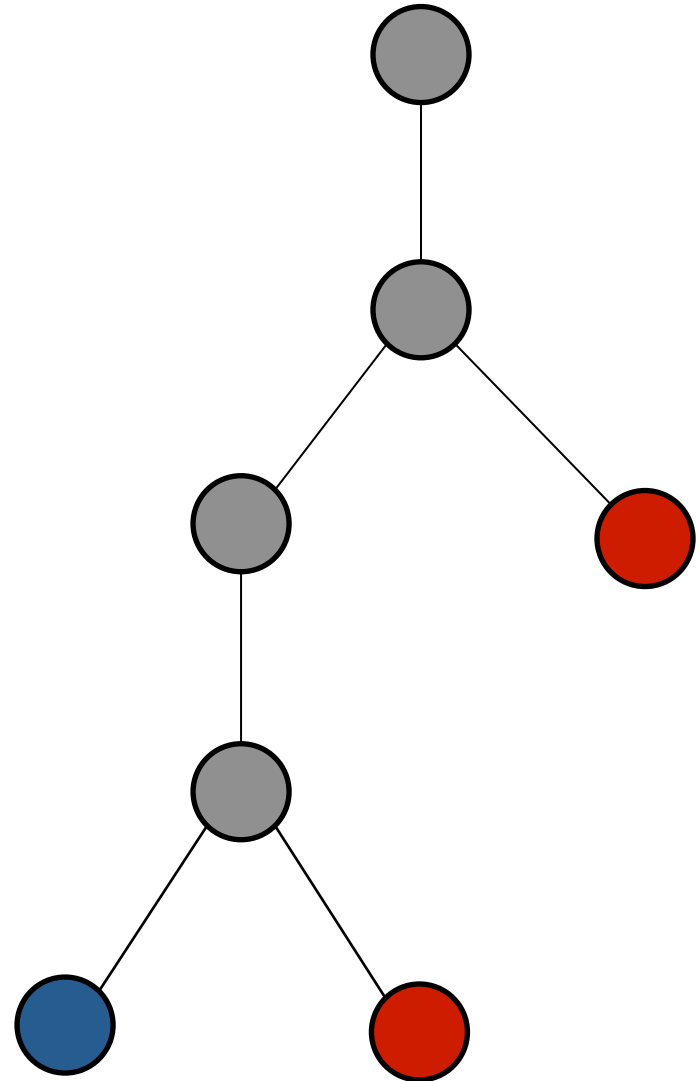
Tree walks

- A **depth-first** walk
 - Starts with the root
 - Moves to its first child
 - Then its first child
 - And so on



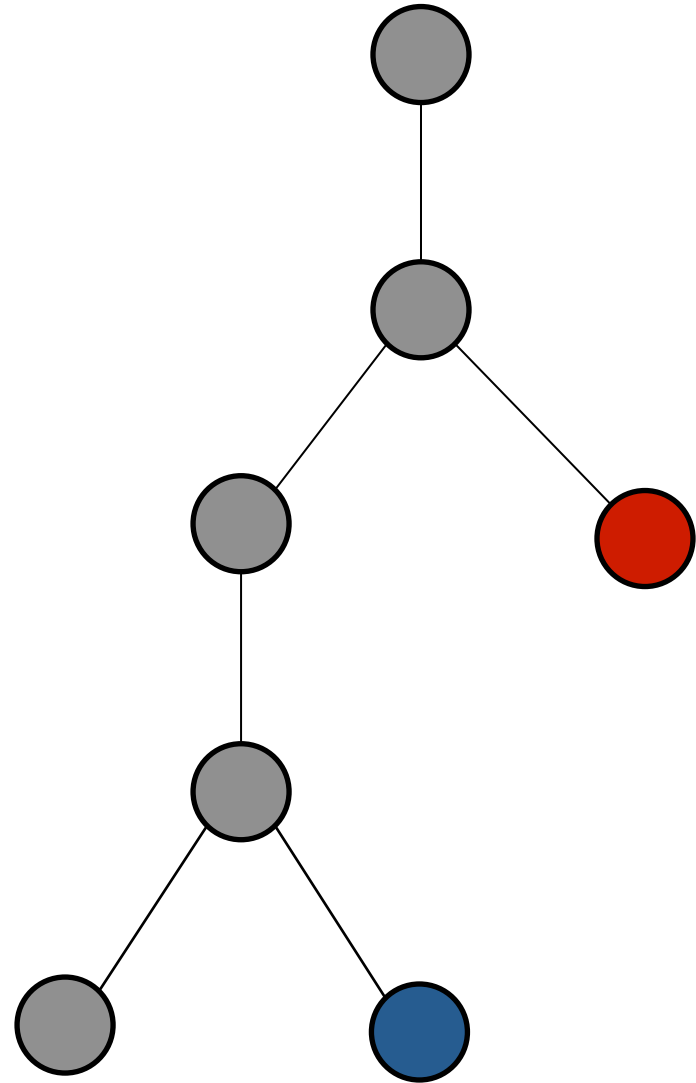
Tree walks

- A **depth-first** walk
 - Starts with the root
 - Moves to its first child
 - Then its first child
 - And so on
 - Until we hit a leaf (a node with no children)



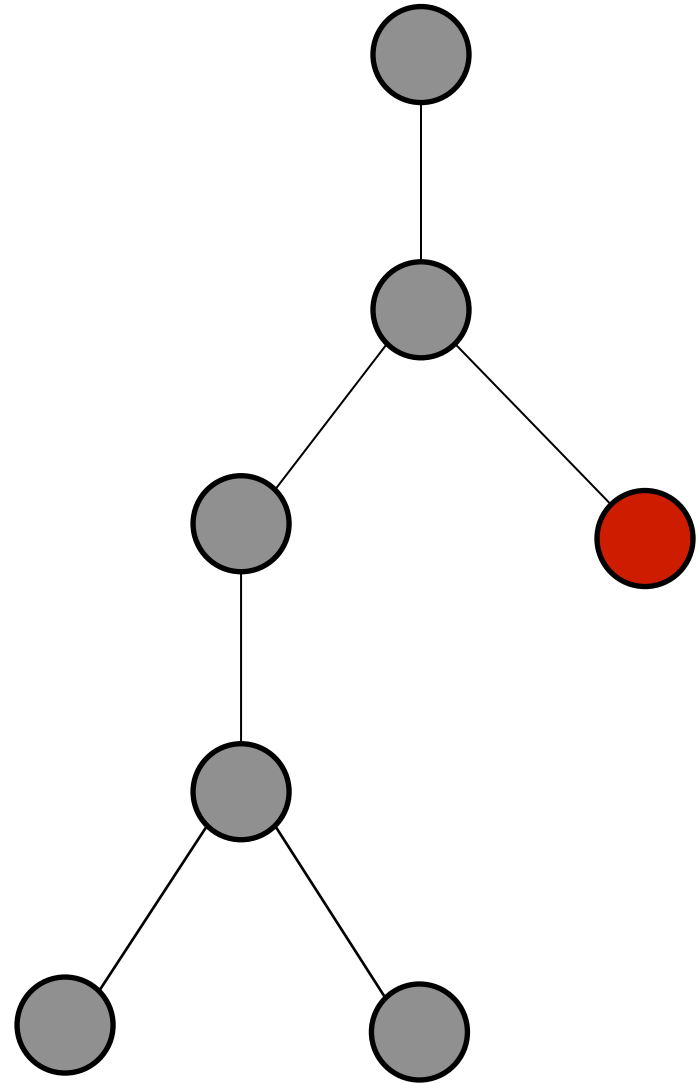
Tree walks

- A **depth-first** walk
 - Starts with the root
 - Moves to its first child
 - Then its first child
 - And so on
 - Until we hit a leaf
 - Then moves to the leaf's sibling



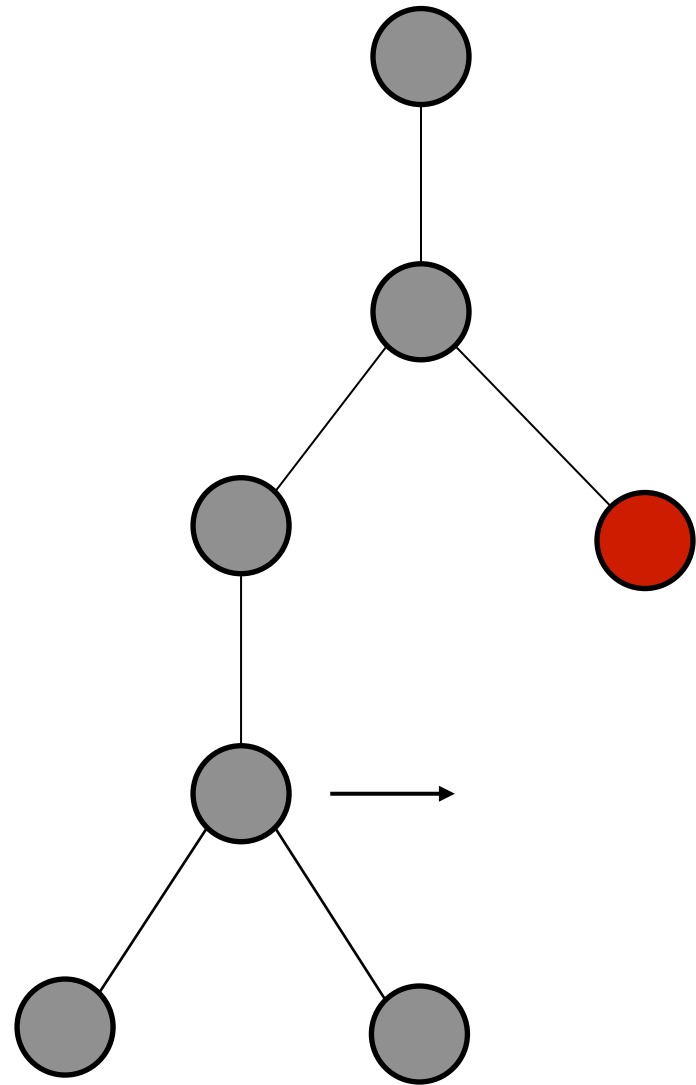
Tree walks

- A **depth-first** walk
 - Starts with the root
 - Moves to its first child
 - Then its first child
 - And so on
 - Until we hit a leaf
 - Then moves to the leaf's sibling
 - Until we run out of siblings



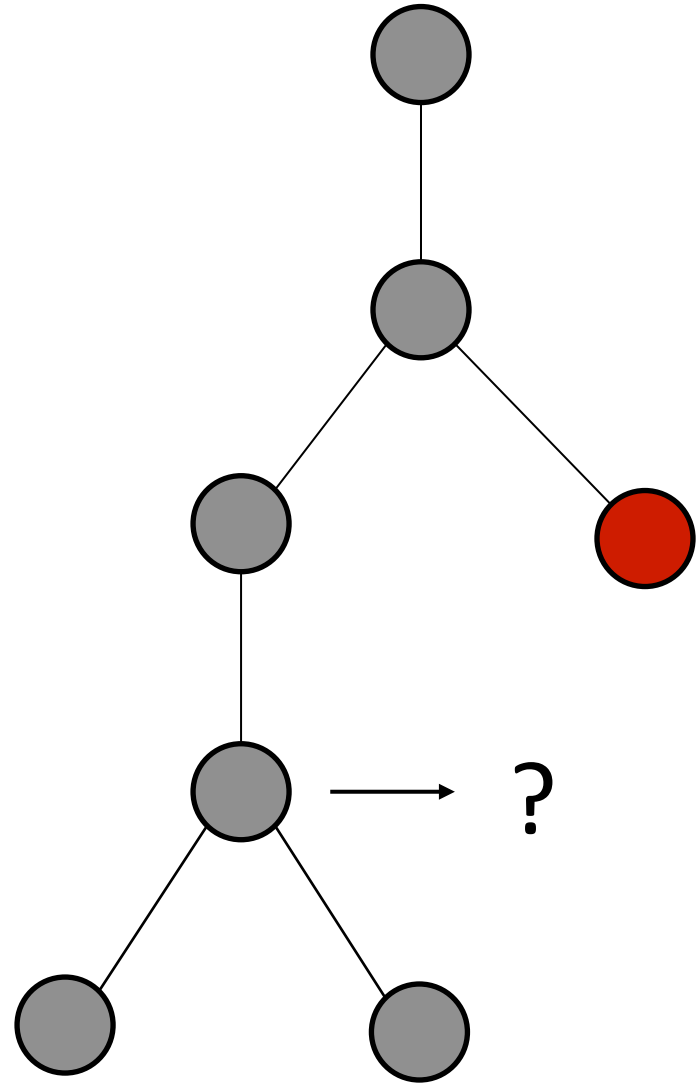
Tree walks

- A **depth-first** walk
 - Then we try the parent's next sibling



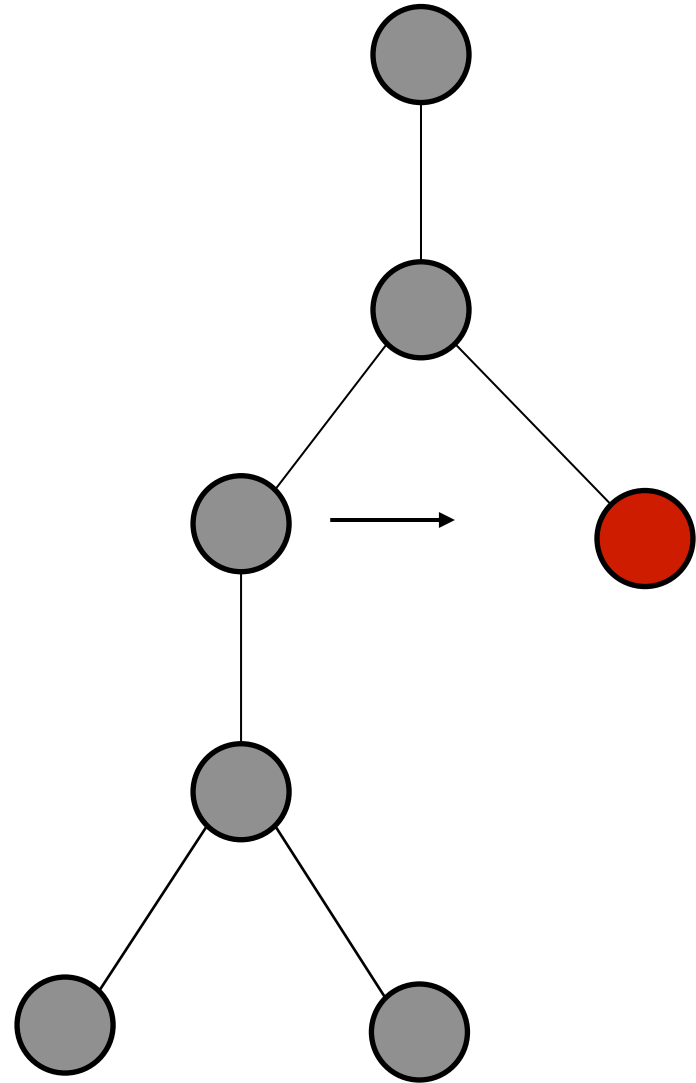
Tree walks

- A **depth-first** walk
 - Then we try the parent's next sibling
 - But, tragically, it's an only child



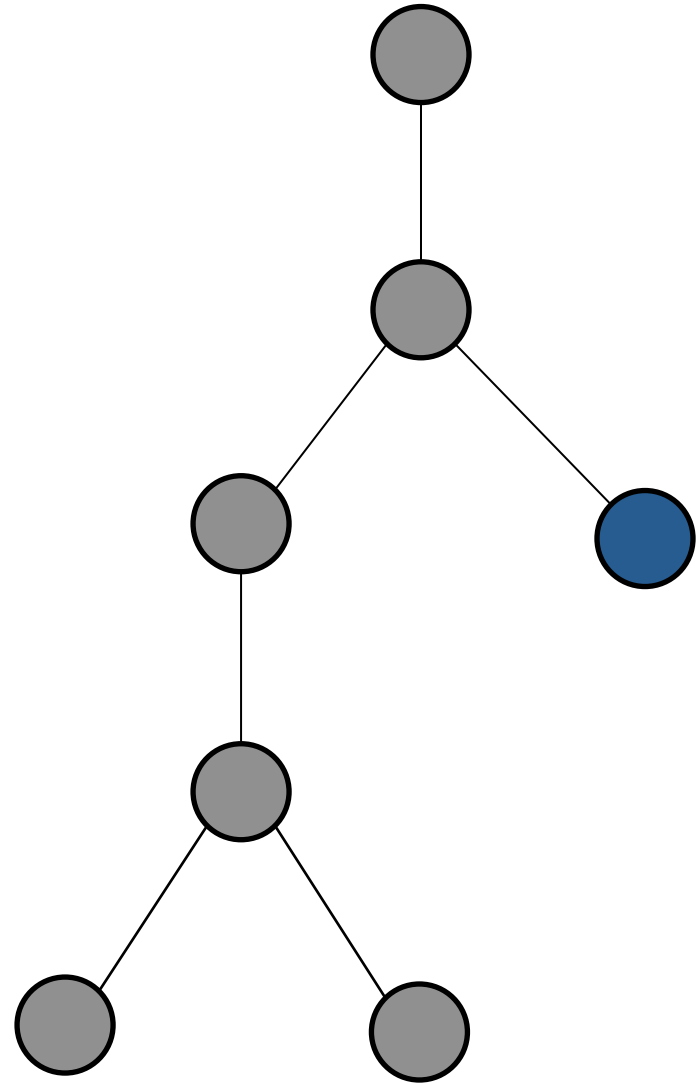
Tree walks

- A **depth-first** walk
 - Then we try the parent's next sibling
 - But, tragically, it's an only child
 - So we move to its parent



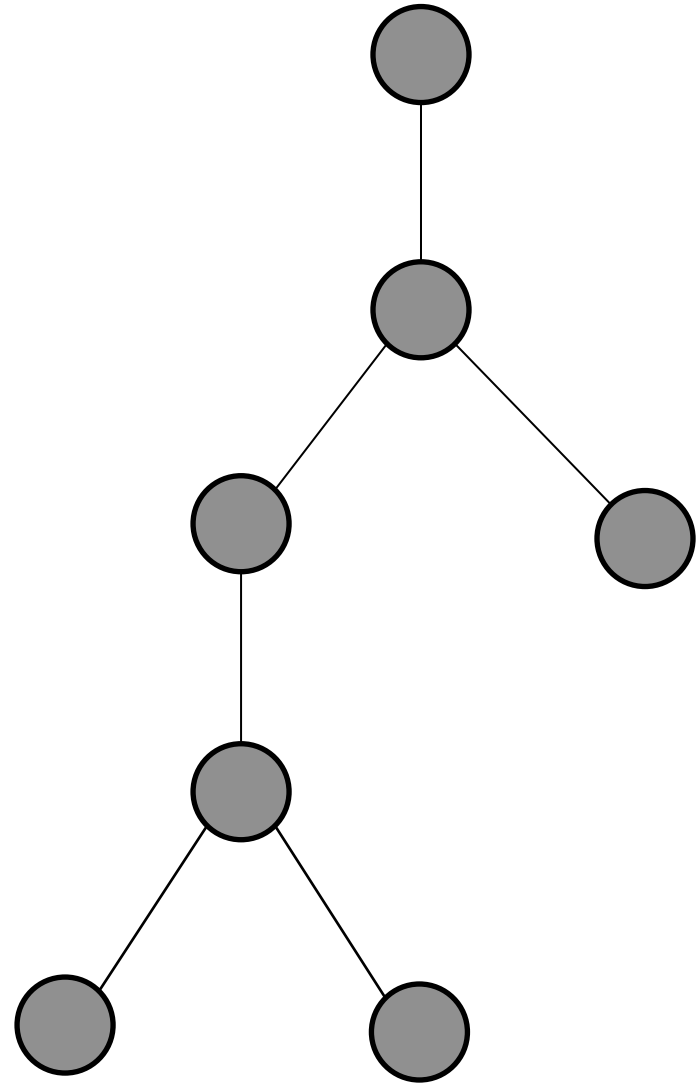
Tree walks

- A **depth-first** walk
 - Then we try the parent's next sibling
 - But, tragically, it's an only child
 - So we move to its parent
 - And select its next sibling



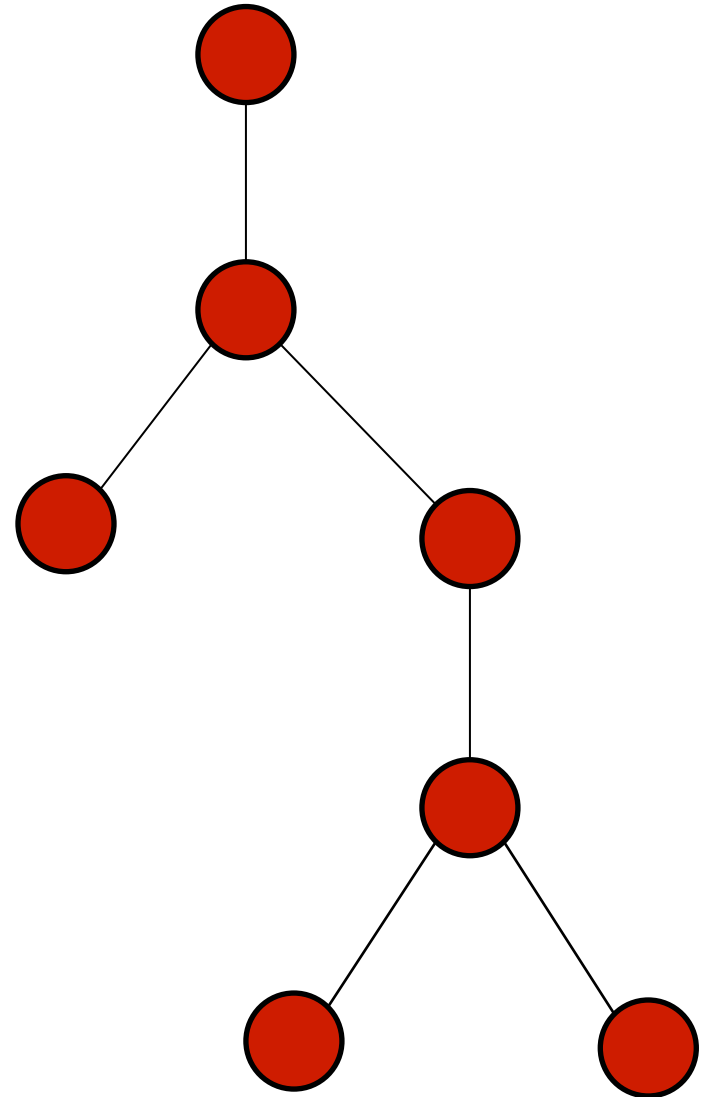
Tree walks

- A **depth-first** walk
 - Then we try the parent's next sibling
 - But, tragically, it's an only child
 - So we move to its parent
 - And select its next sibling
 - After which, we've walked the whole tree



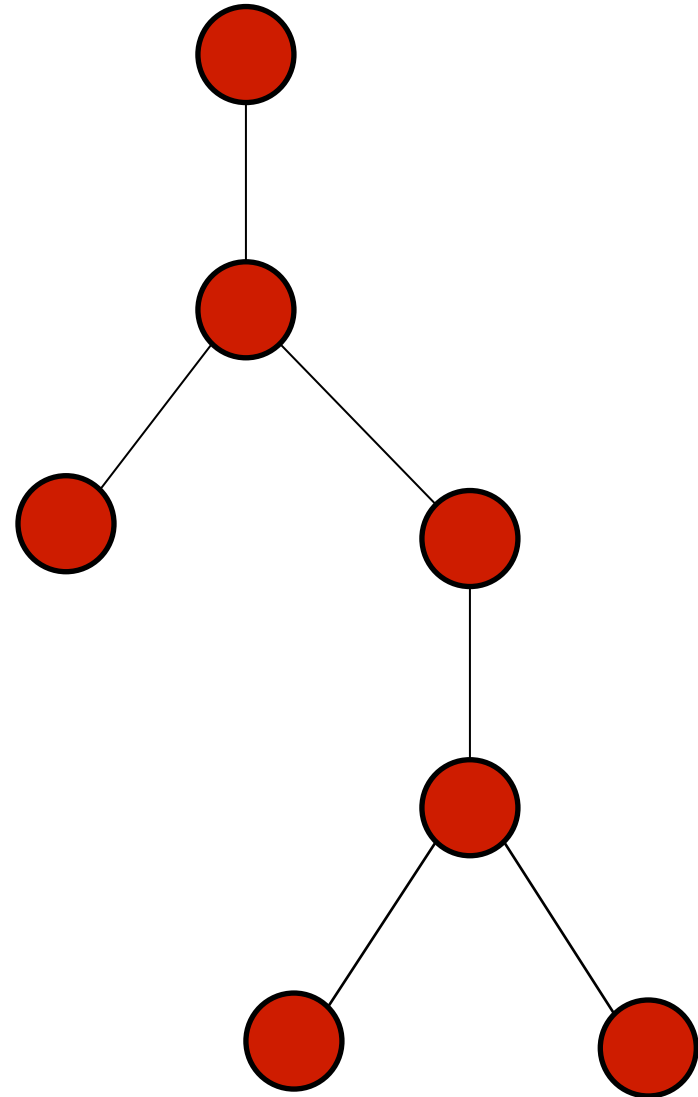
Tree walks

- Depth-first walks go **subtree to subtree**
- Breadth-first walks go **level to level**

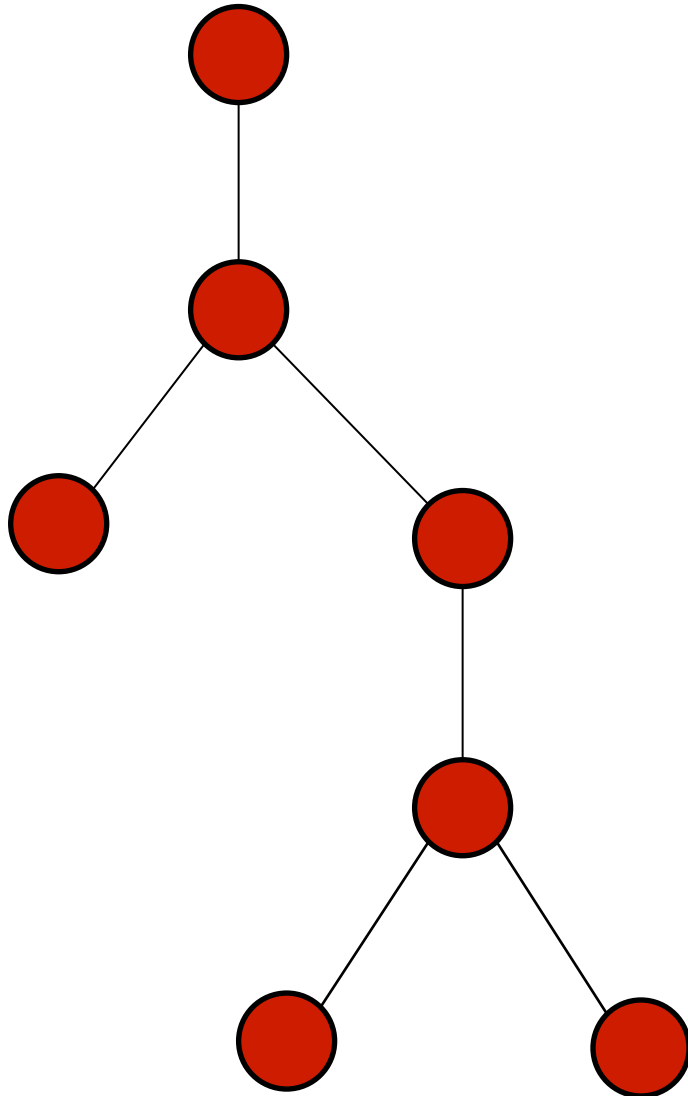


Tree walks

- When **depth-first** comes to a node
 - It walks its children **immediately**
- When **breadth-first** comes to a node
 - It **remembers** its children to be walked in the future

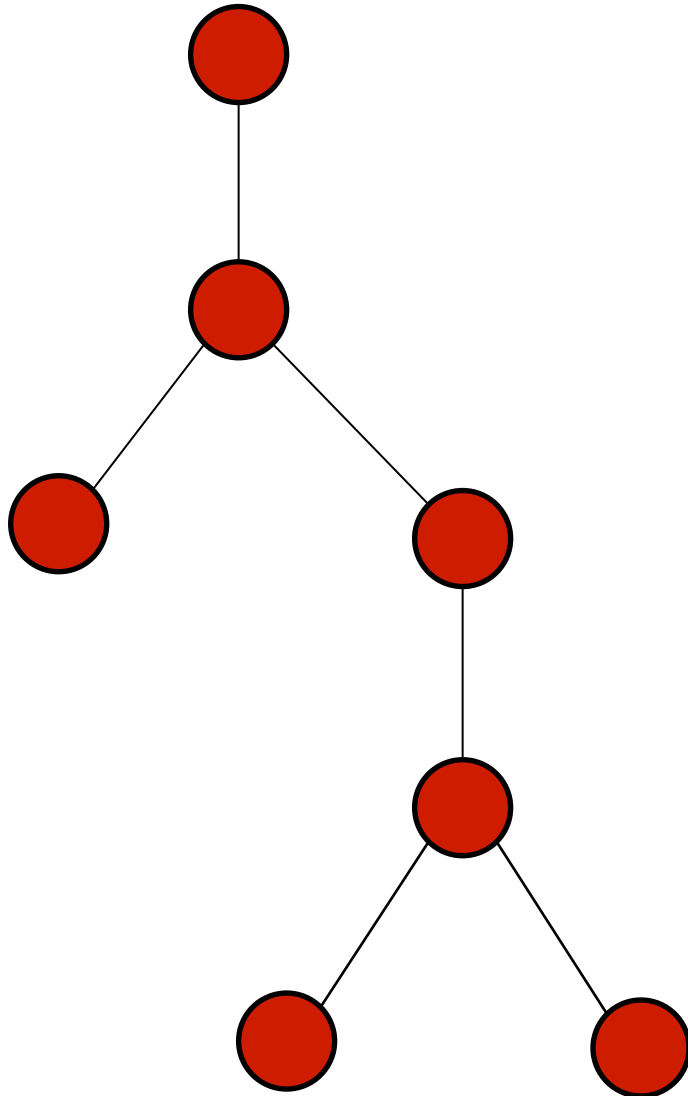


Breadth-first walk



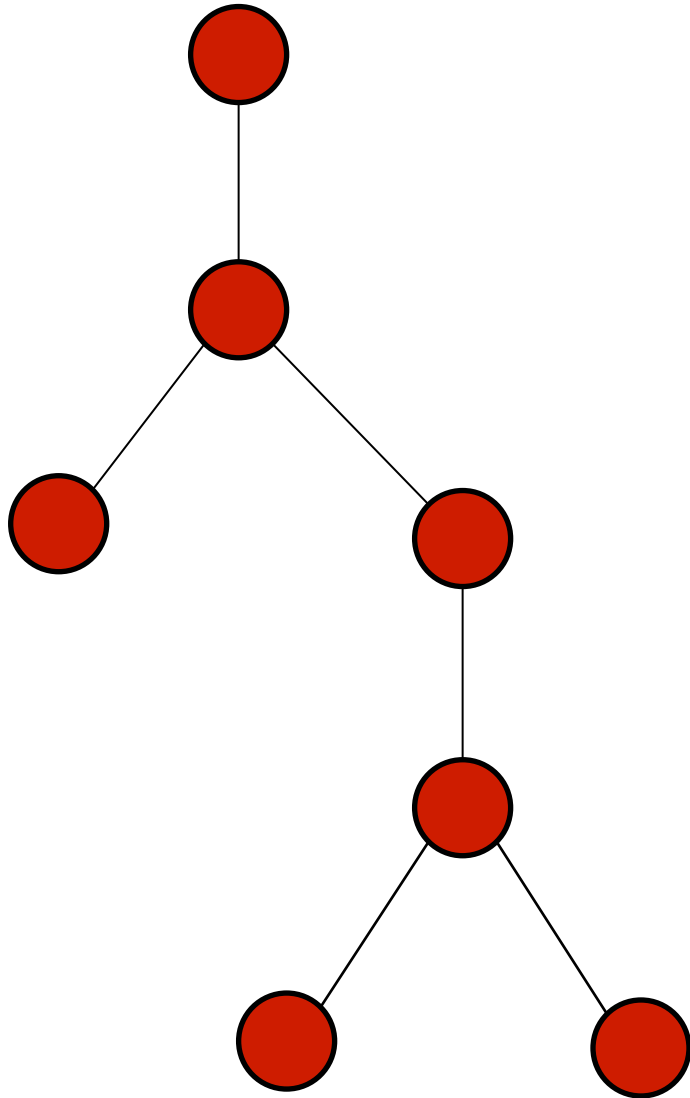
- Needs to remember
 - The children of nodes it's walked
 - But that haven't yet been walked themselves
- So it needs to store a collection of nodes
- What kind of collection?

Breadth-first walk



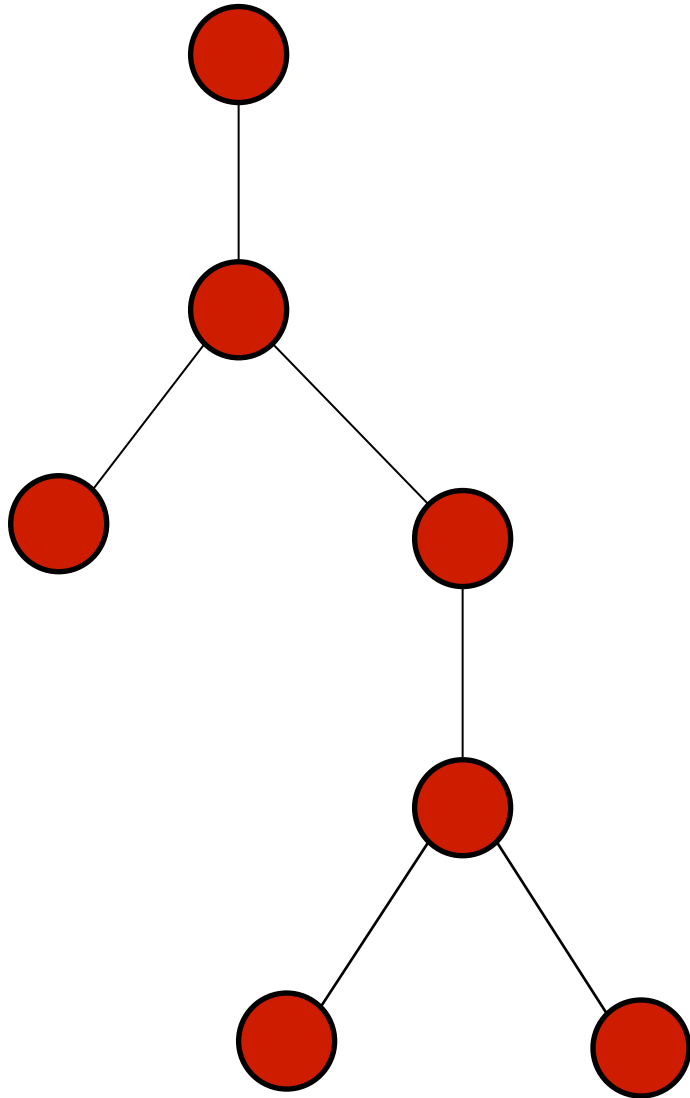
- Needs to finish current level of tree
 - Before moving to nodes in the next level
- So the nodes that get walked first
 - Are the nodes that are added first to the collection

Breadth-first walk



- So we walk the nodes in the order that they're added to the collection
- That sounds like a queue!

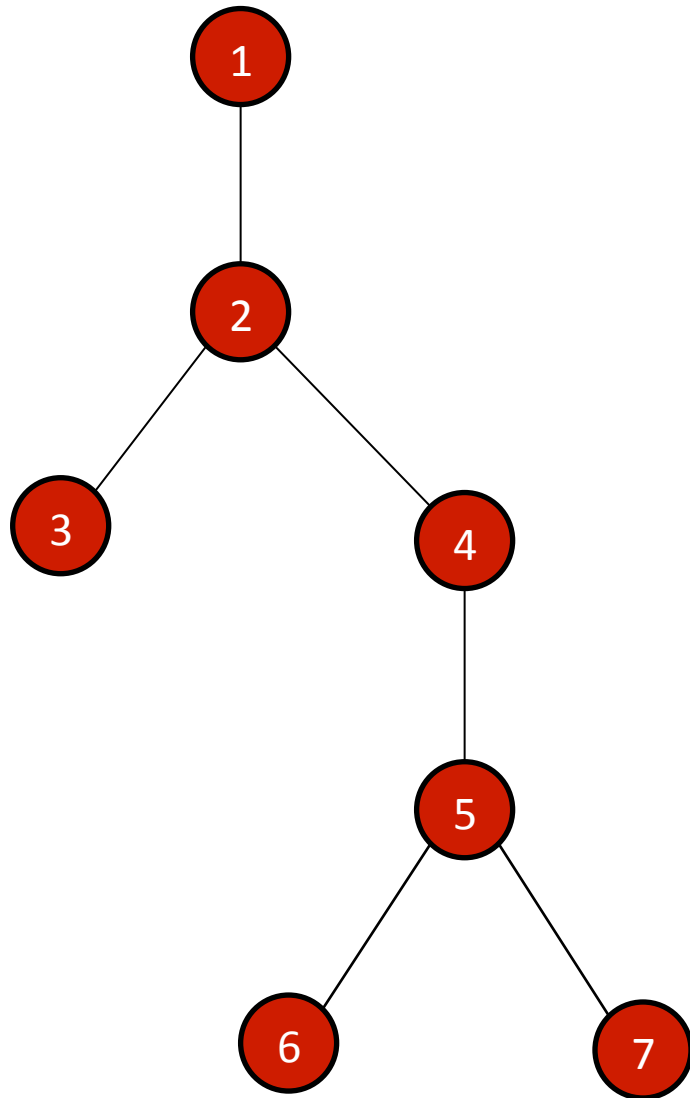
Breadth-first walk



Pseudocode:

```
BreadthFirst(root) {  
  q = empty queue  
  q.Enqueue(root)  
  while q not empty {  
    node = q.Dequeue()  
    for each child c of node  
      q.Enqueue(c)  
  }  
}
```

Breadth-first walk

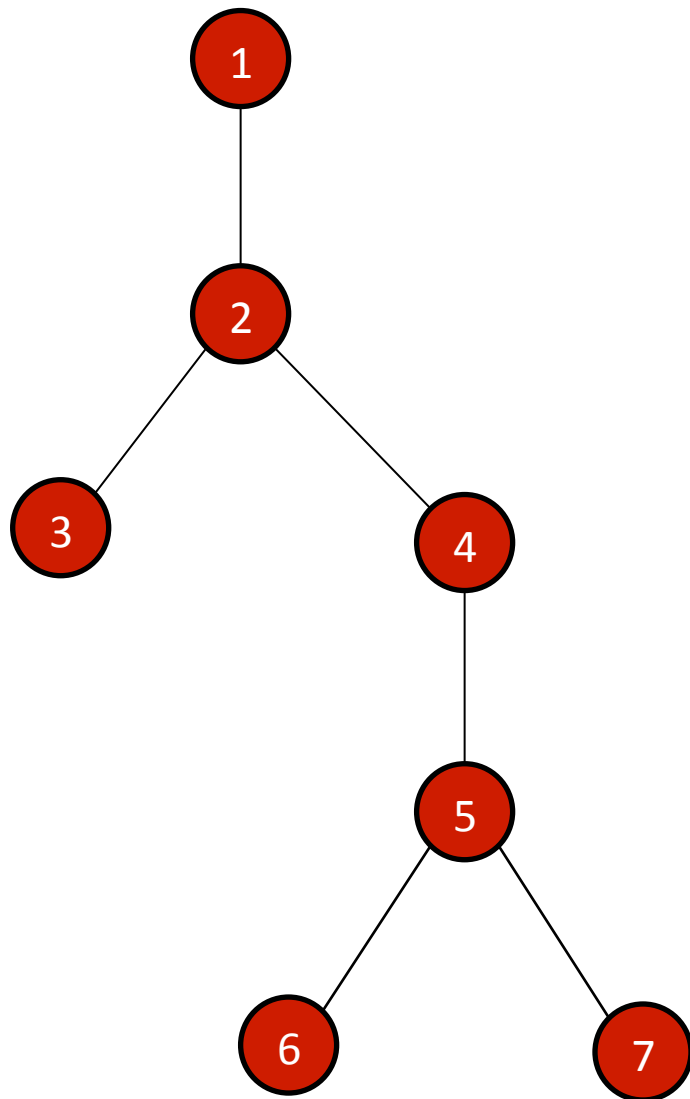


Queue

empty

Start with empty queue

Breadth-first walk

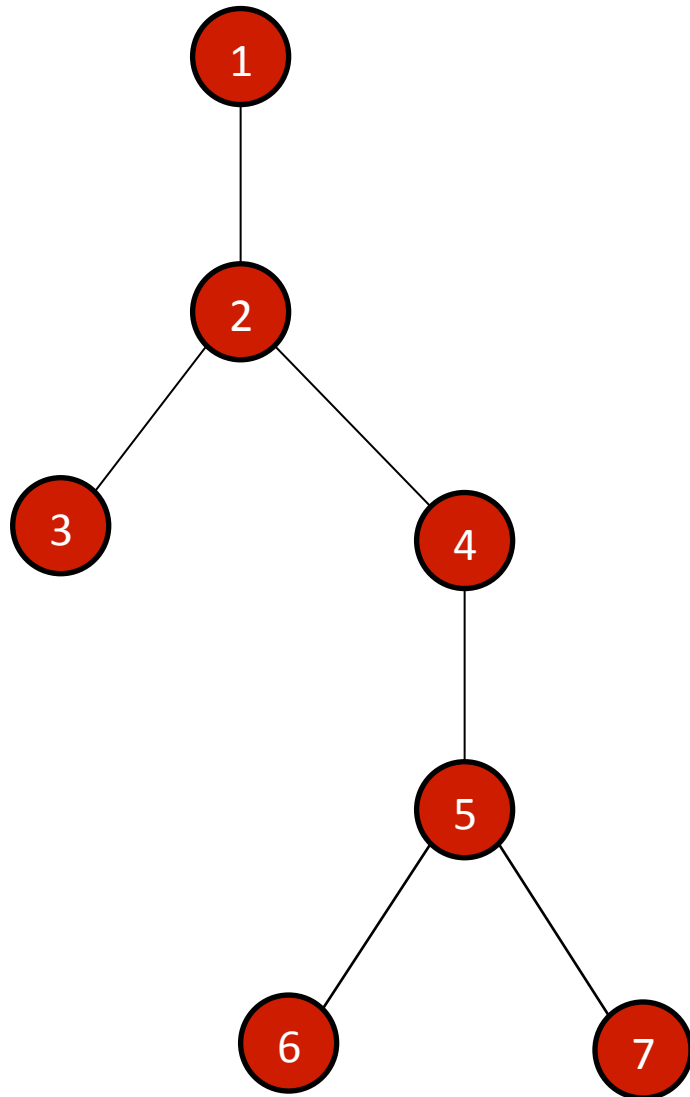


Queue

1

Add the root

Breadth-first walk

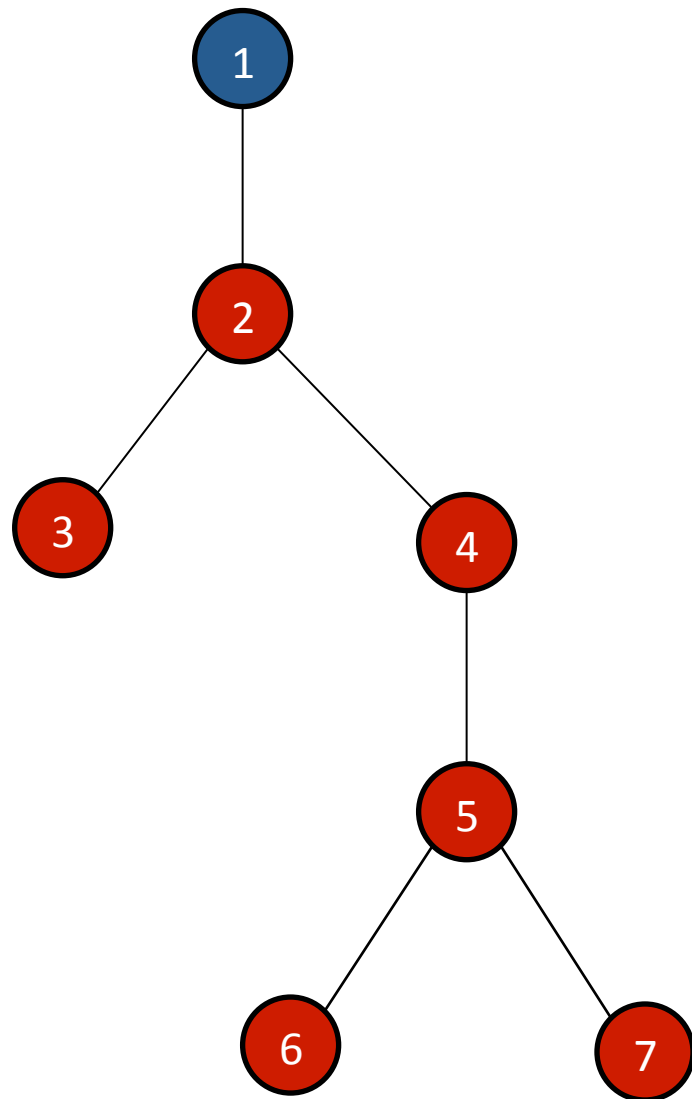


Queue

1

Now repeat until the queue is empty:

Breadth-first walk

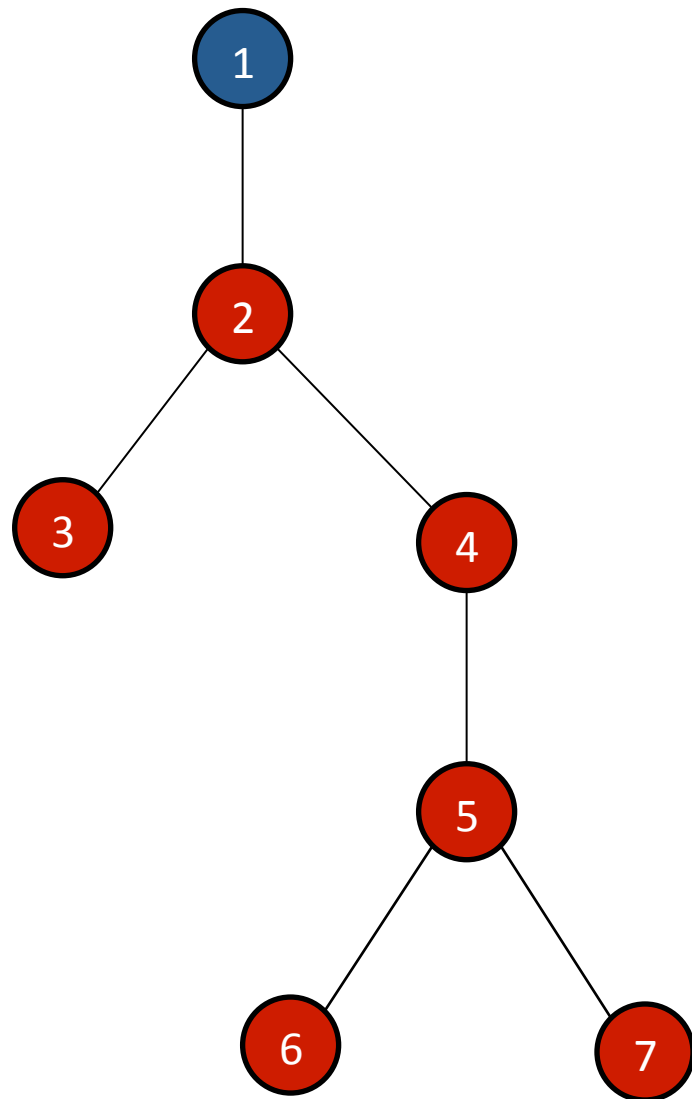


Queue

empty

Dequeue the next node

Breadth-first walk

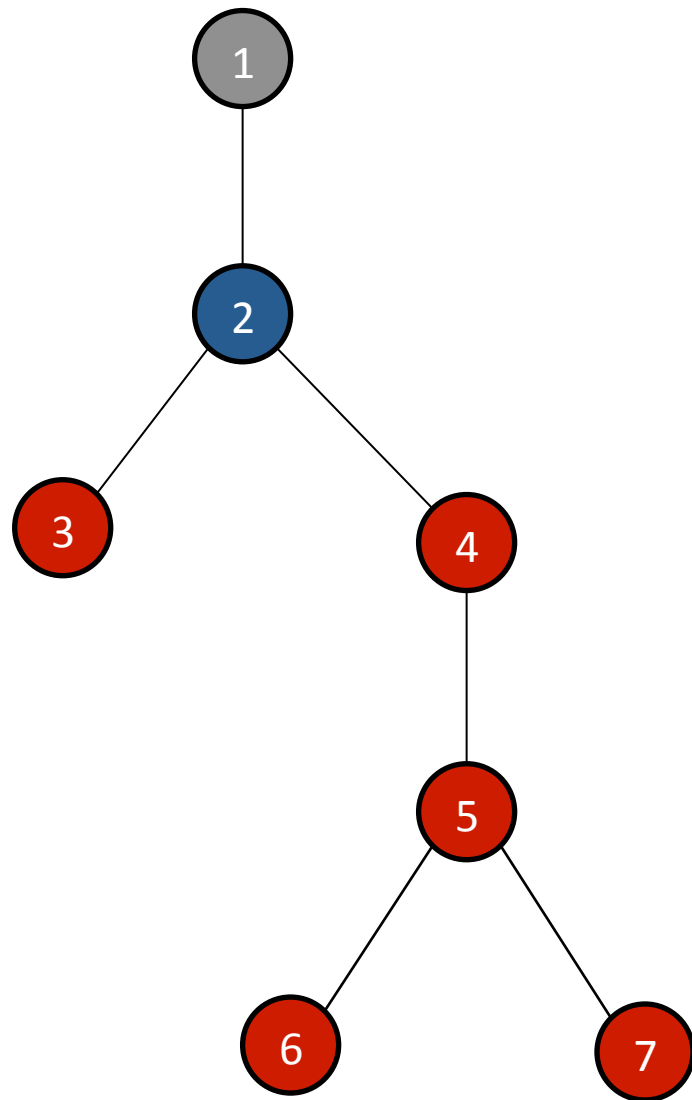


Queue

2

Add its children to
queue

Breadth-first walk

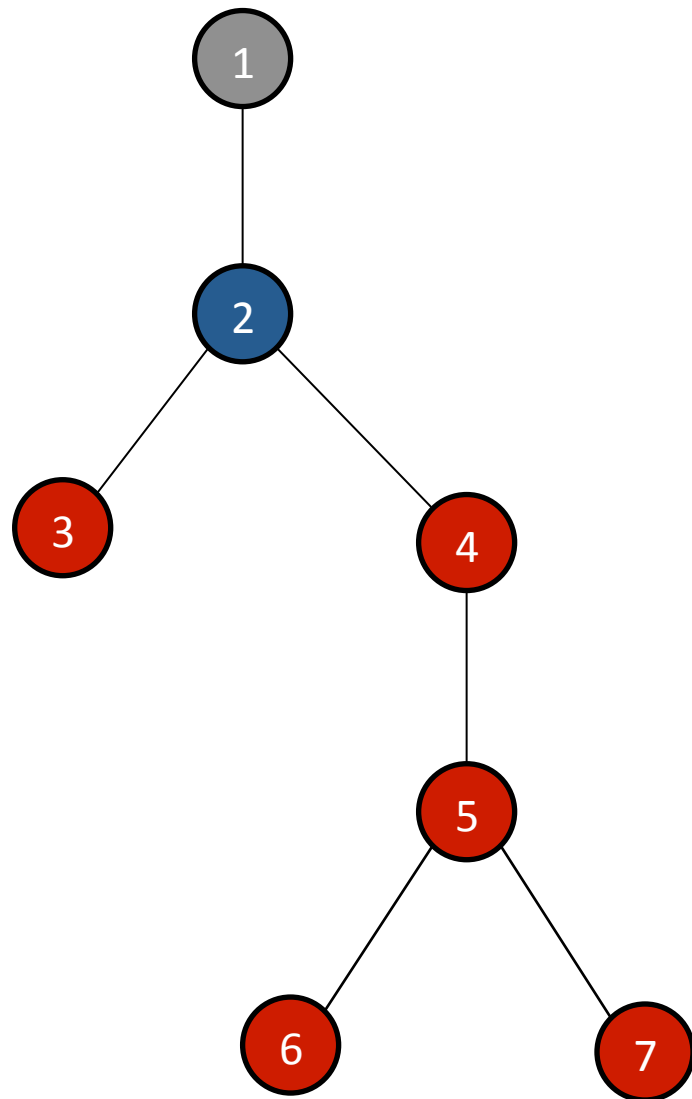


Queue

empty

Dequeue

Breadth-first walk

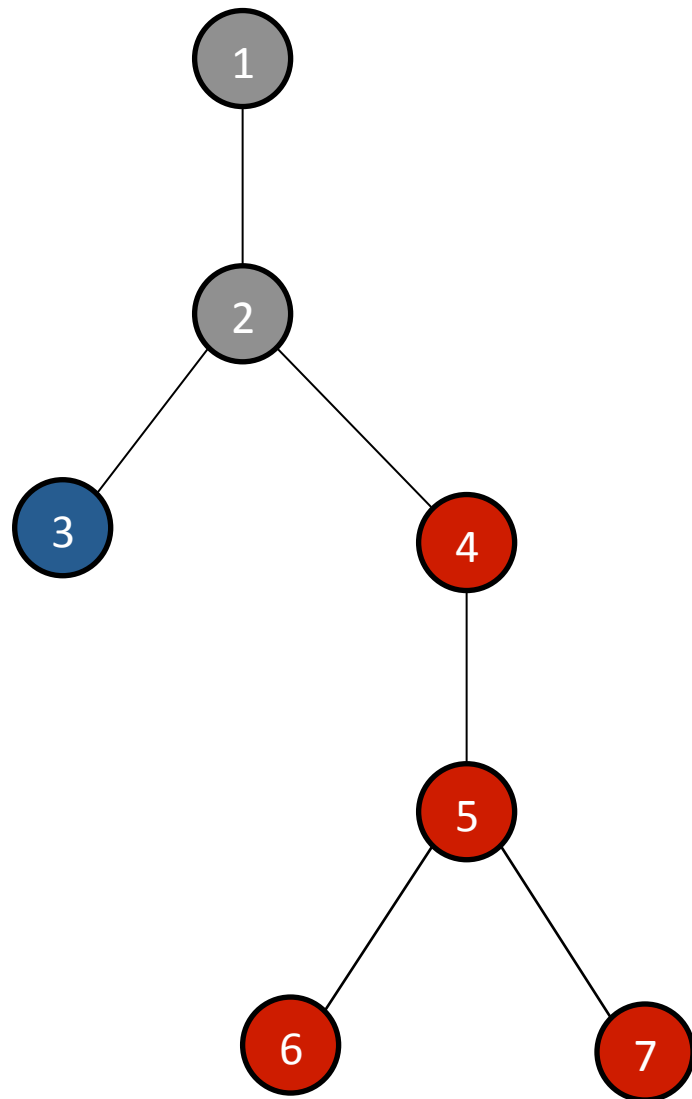


Queue

3 4

Enqueue children

Breadth-first walk

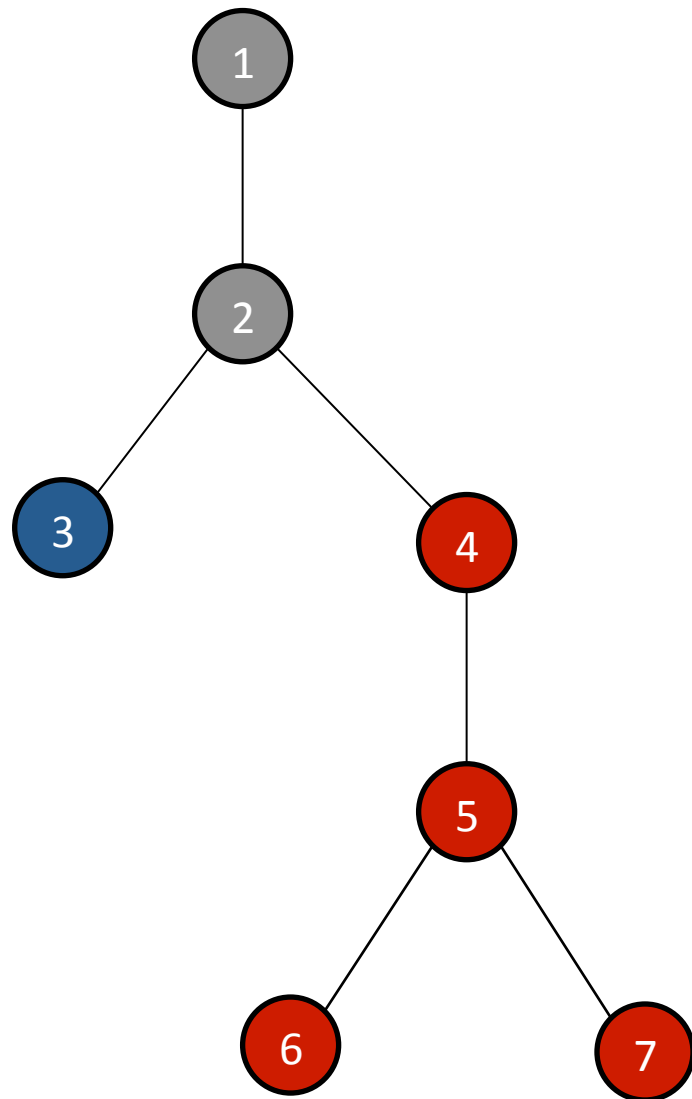


Queue

4

Dequeue

Breadth-first walk

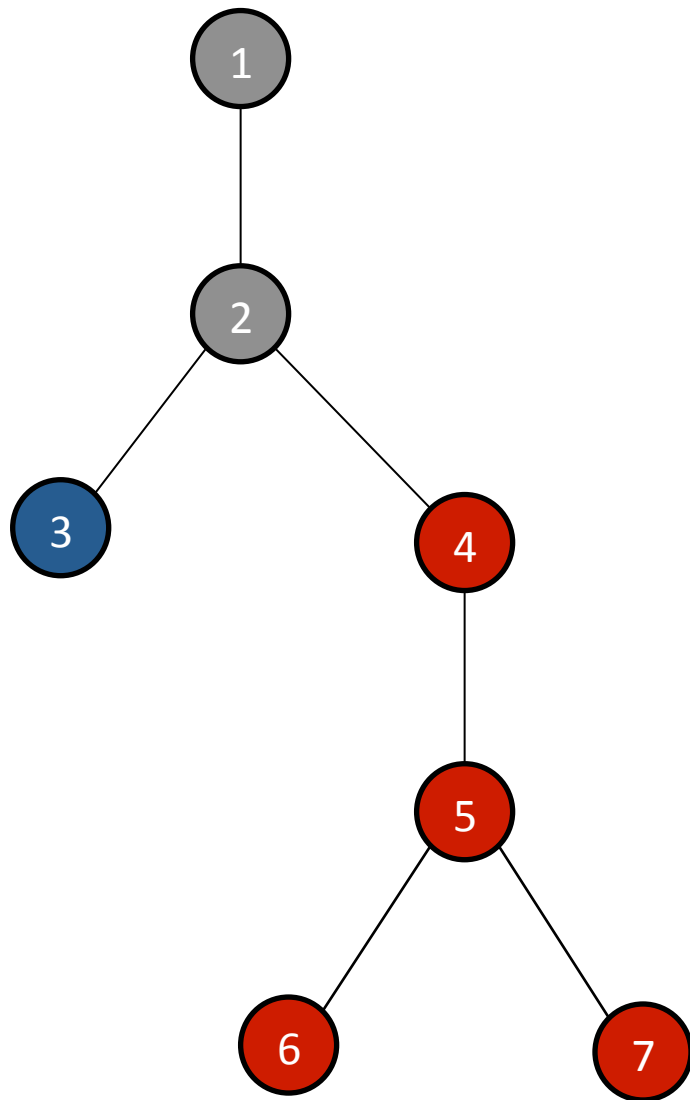


Queue

4

Enqueue children

Breadth-first walk

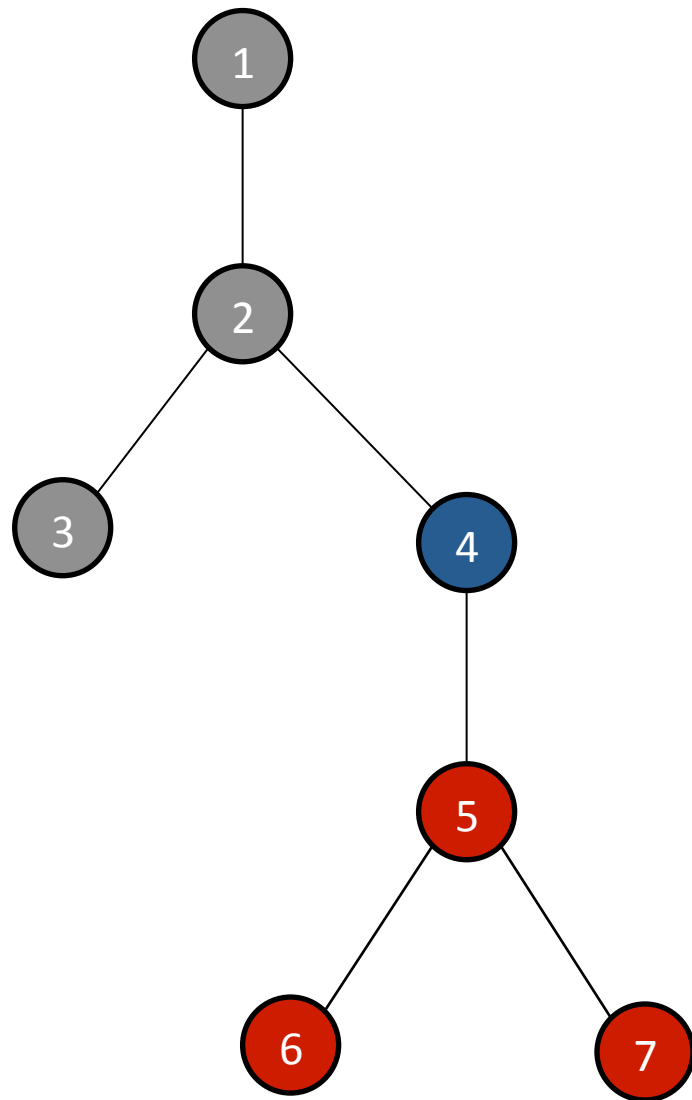


Queue

4

Enqueue children
(of course, there aren't any)

Breadth-first walk

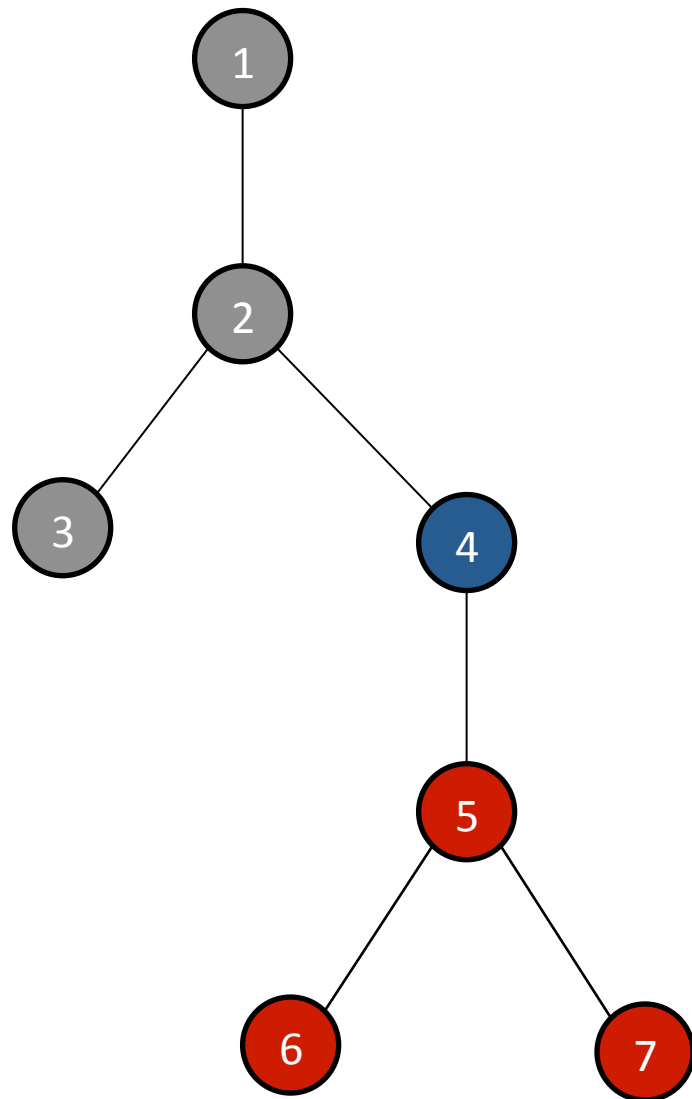


Queue

empty

Dequeue

Breadth-first walk

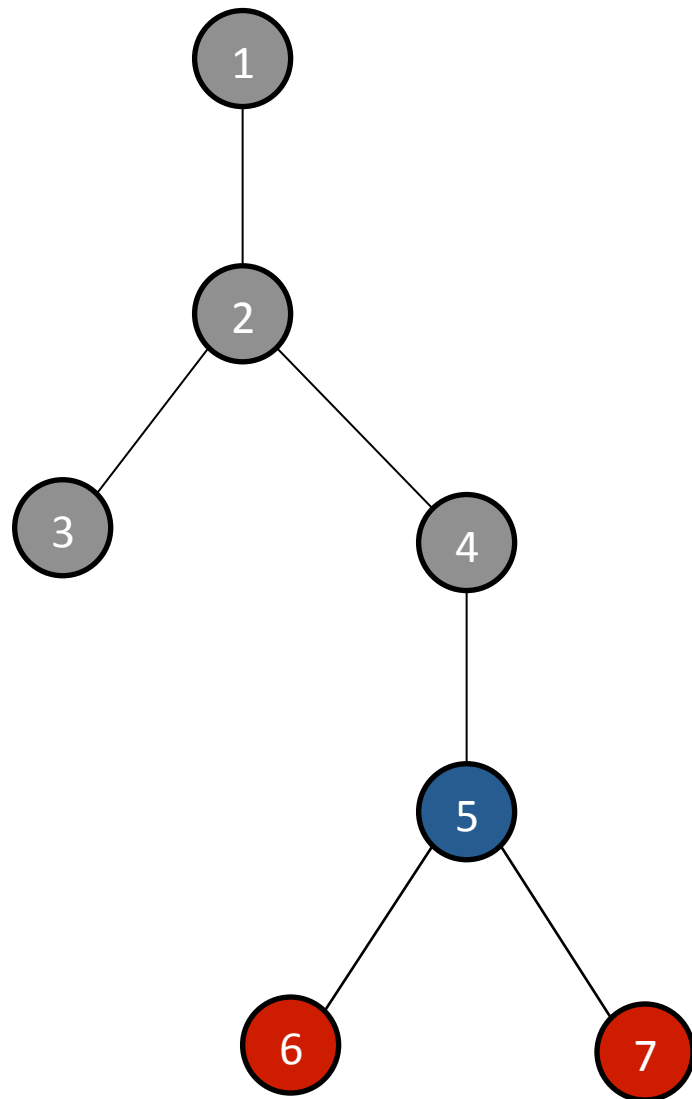


Queue

5

Add children

Breadth-first walk

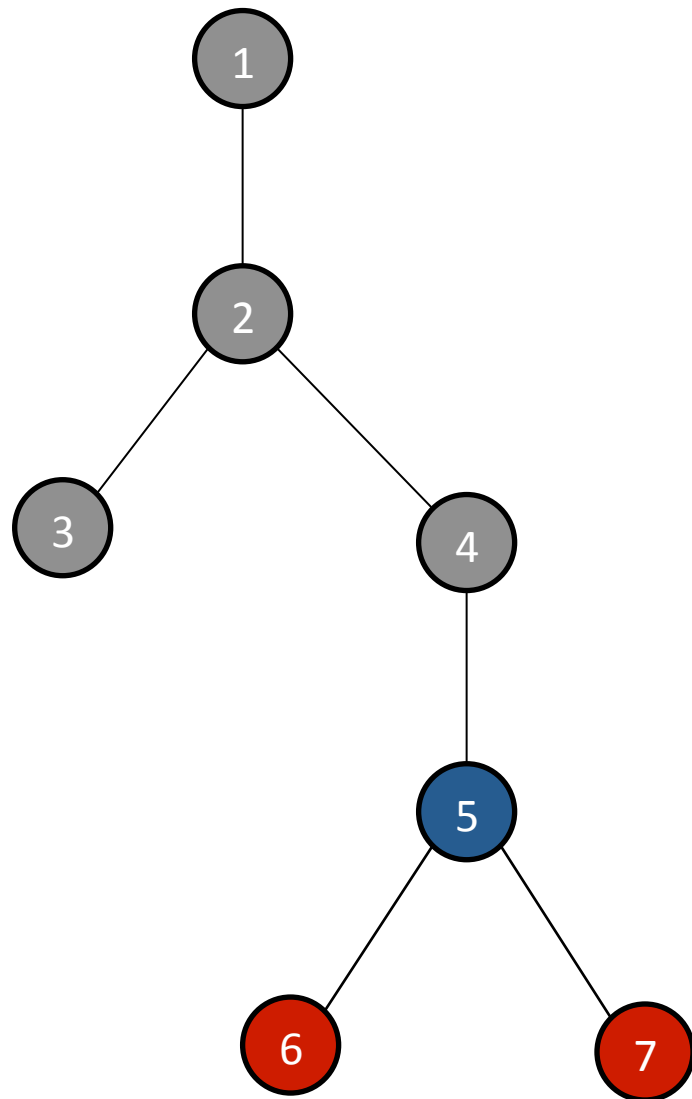


Queue

empty

Dequeue

Breadth-first walk

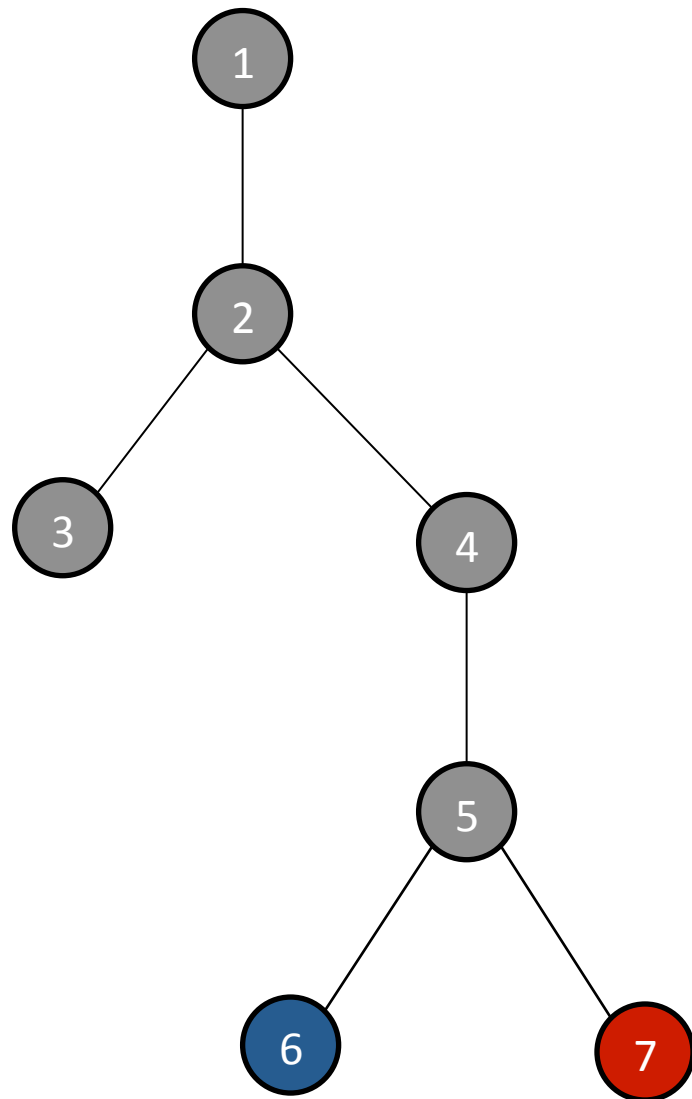


Queue

6 7

Add children

Breadth-first walk

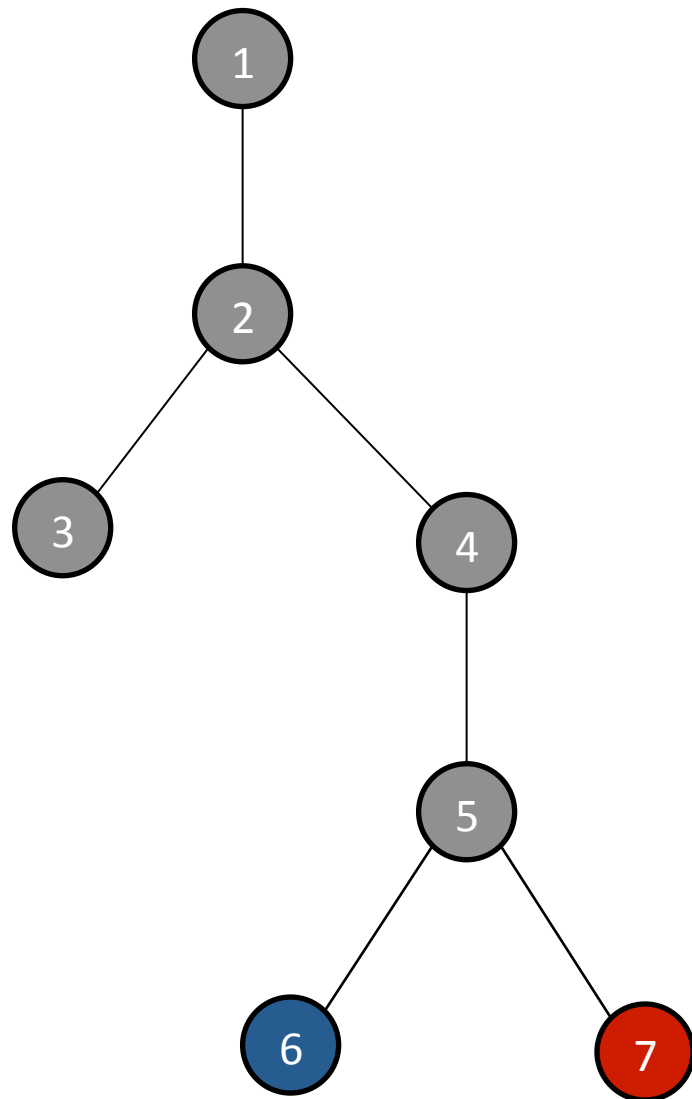


Queue

7

Dequeue

Breadth-first walk

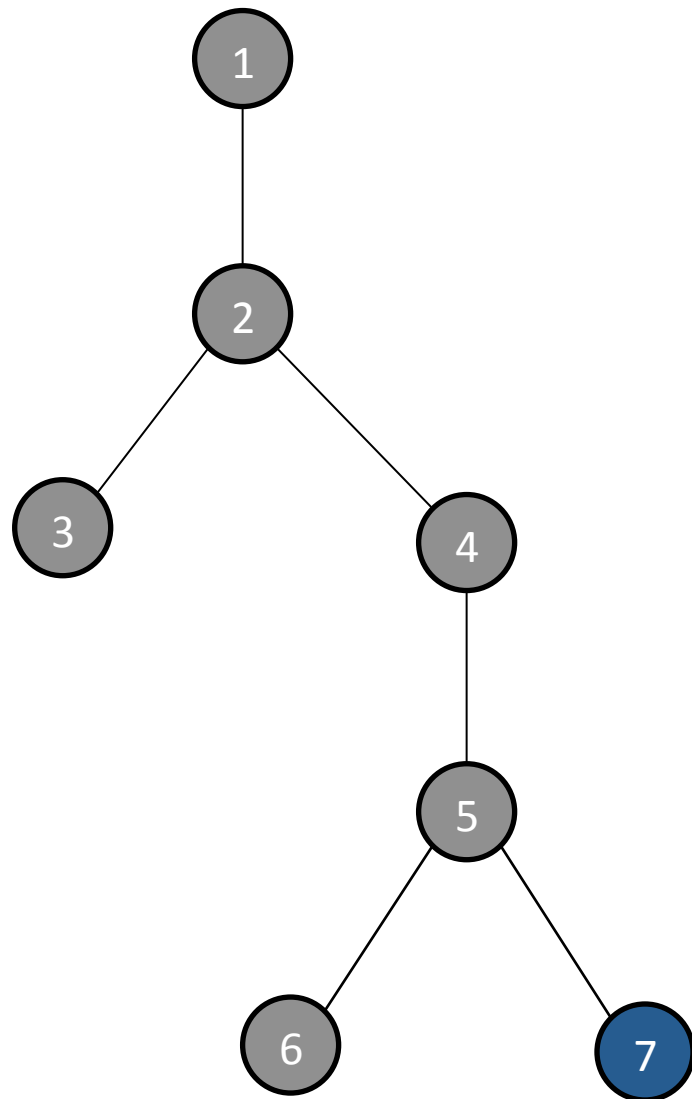


Queue

7

Add children (none)

Breadth-first walk

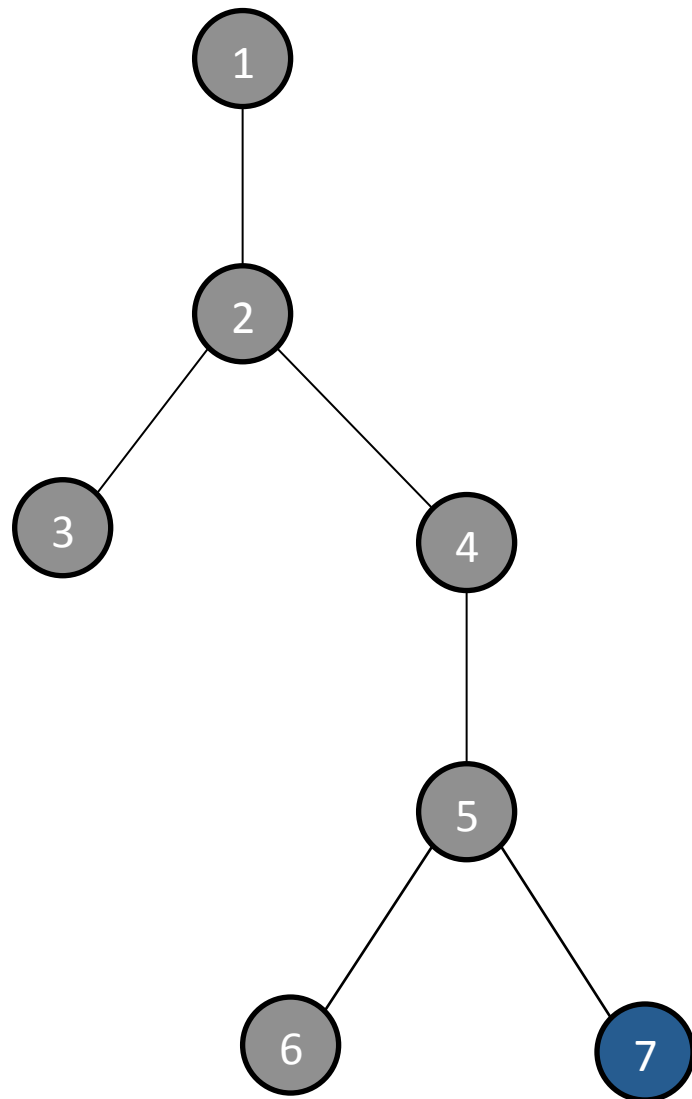


Queue

empty

Dequeue

Breadth-first walk

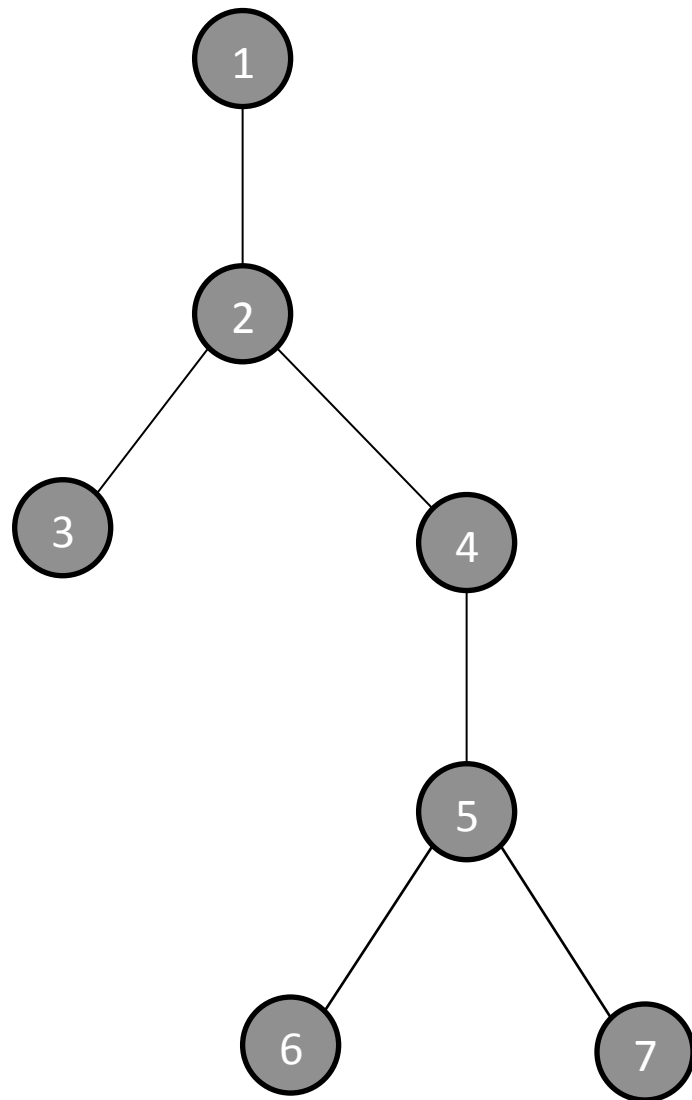


Queue

empty

Add children (none)

Breadth-first walk

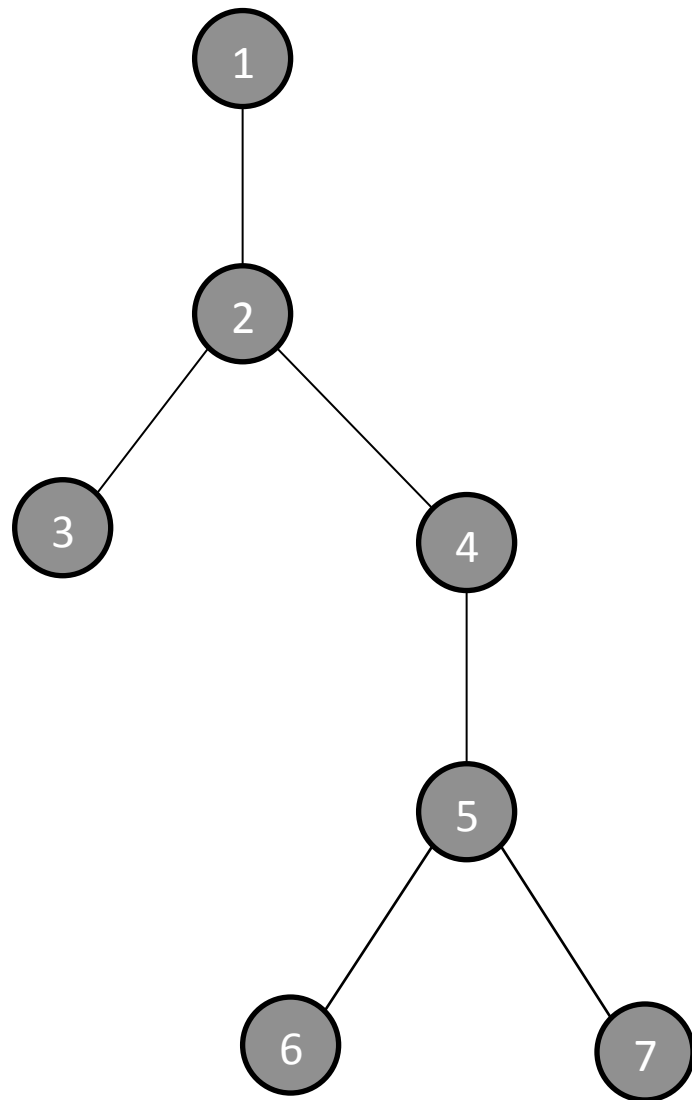


Queue

empty

Dequeue

Breadth-first walk

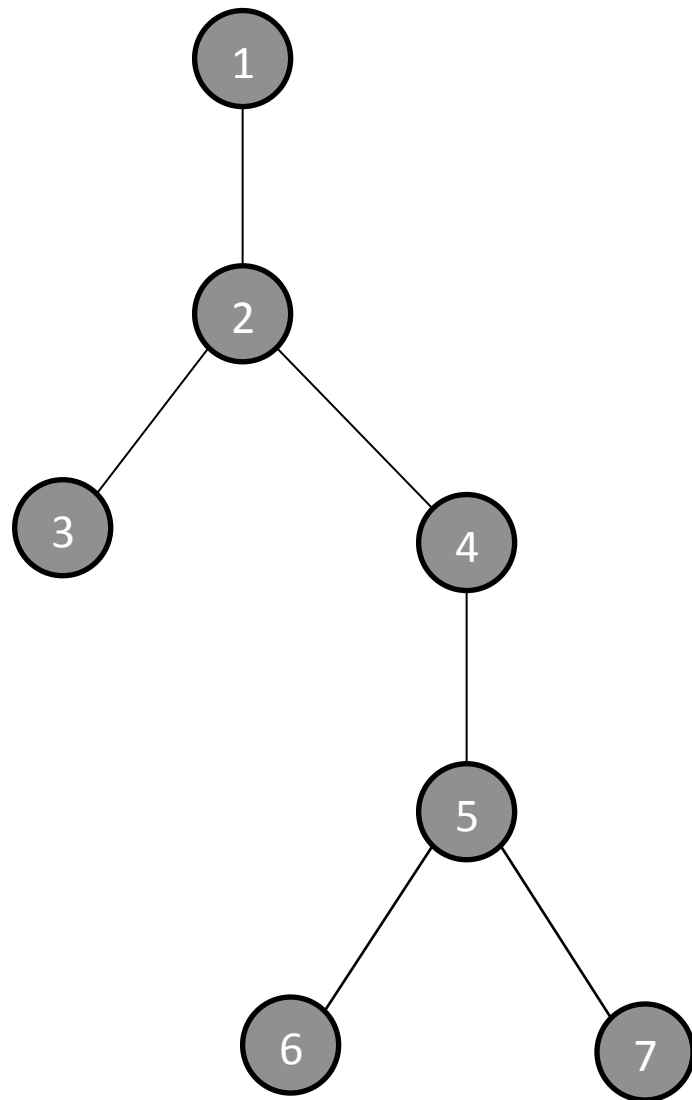


Queue

empty

Dequeue – queue empty

Breadth-first walk



Queue

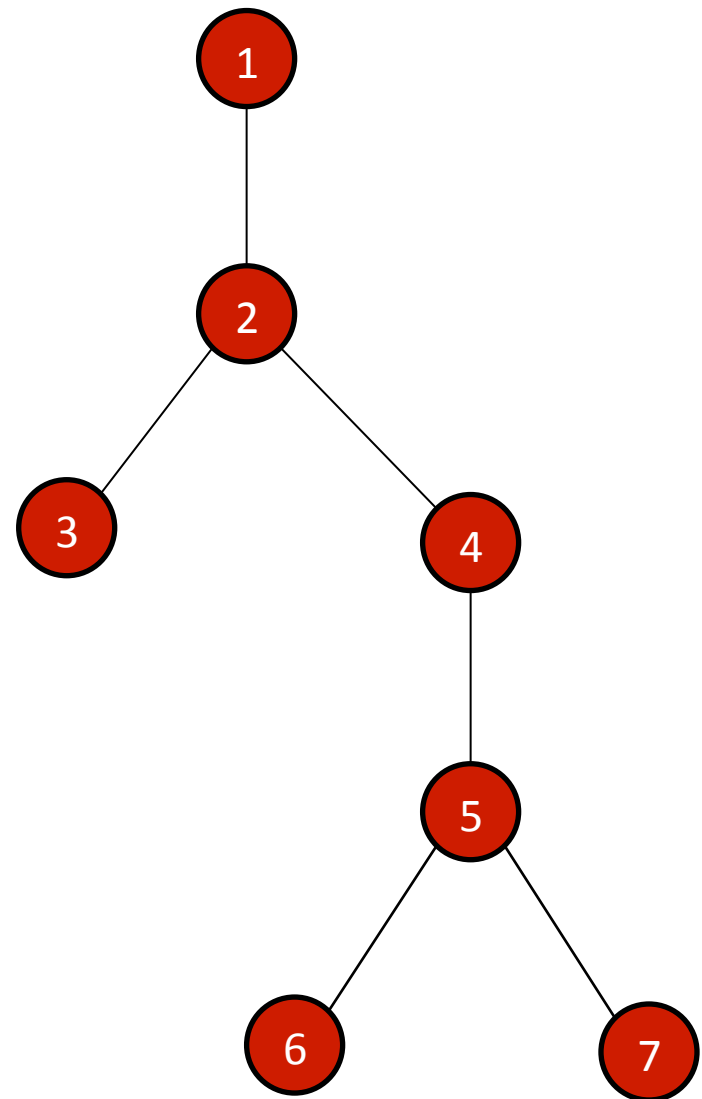
empty

Finished

Using a stack

What happens if we change the queue to a stack?

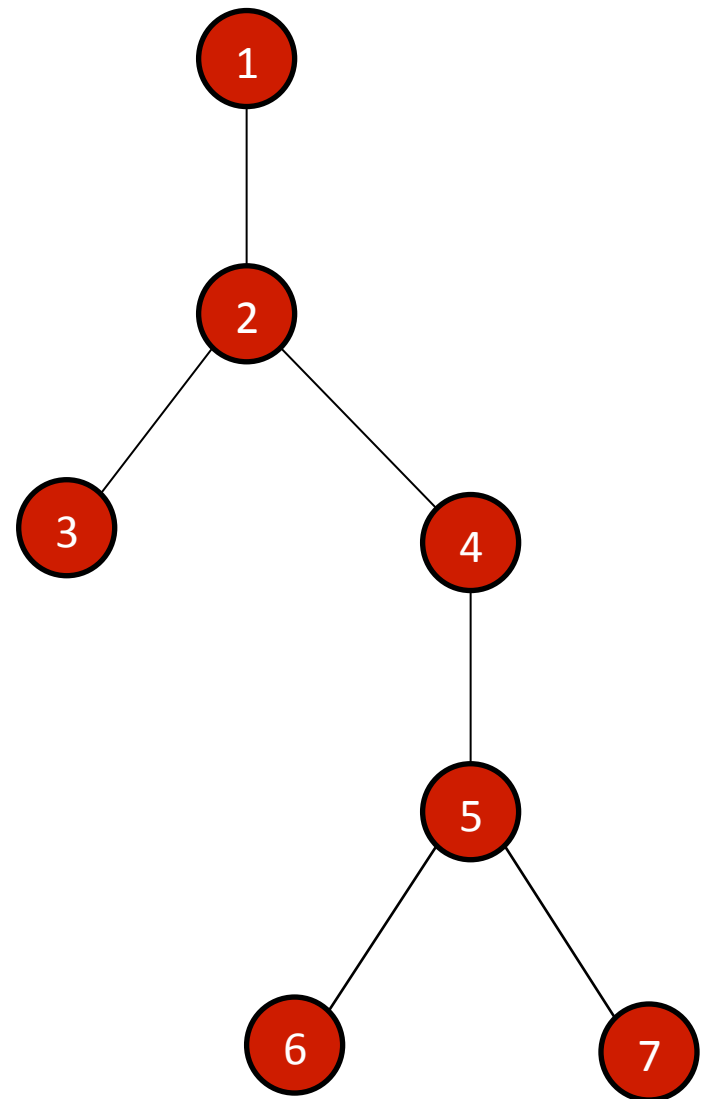
```
StackWalk(root) {  
  s = empty stack  
  s.Push(root)  
  while s not empty {  
    node = s.Pop()  
    for each child c of node  
      s.Push(c)  
  }  
}
```



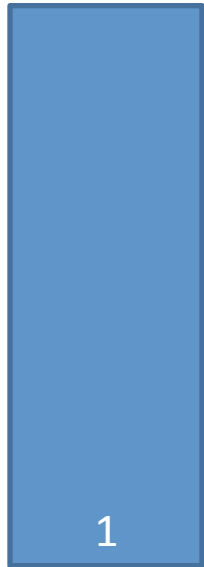
Using a stack



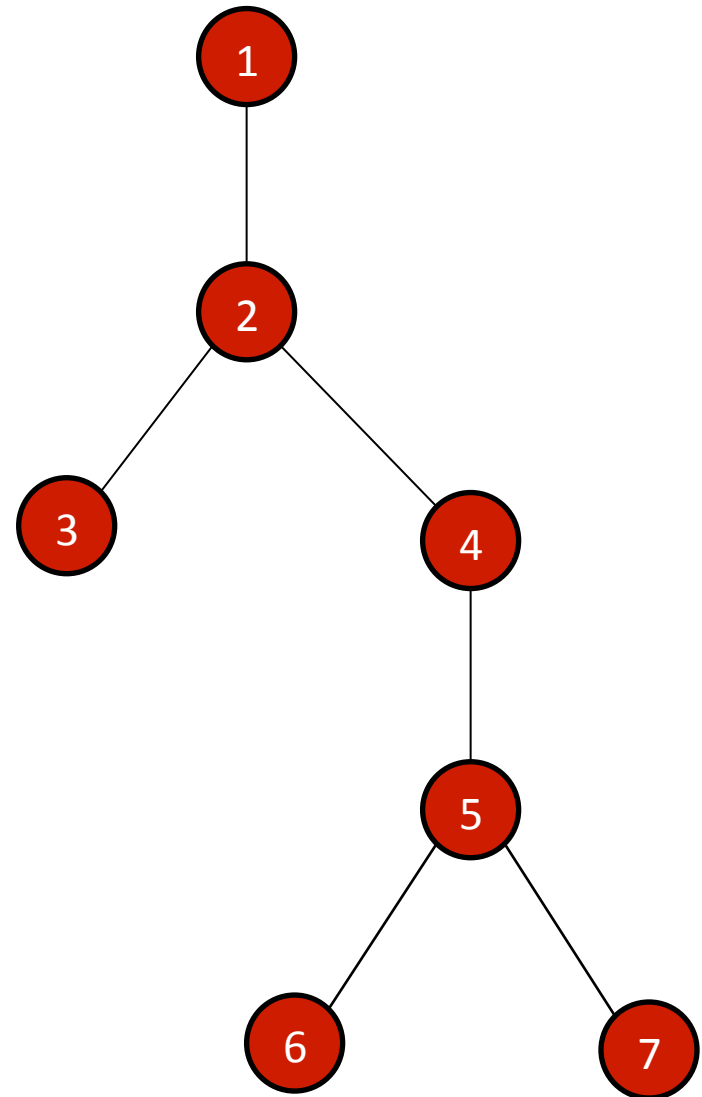
Start with empty stack



Using a stack



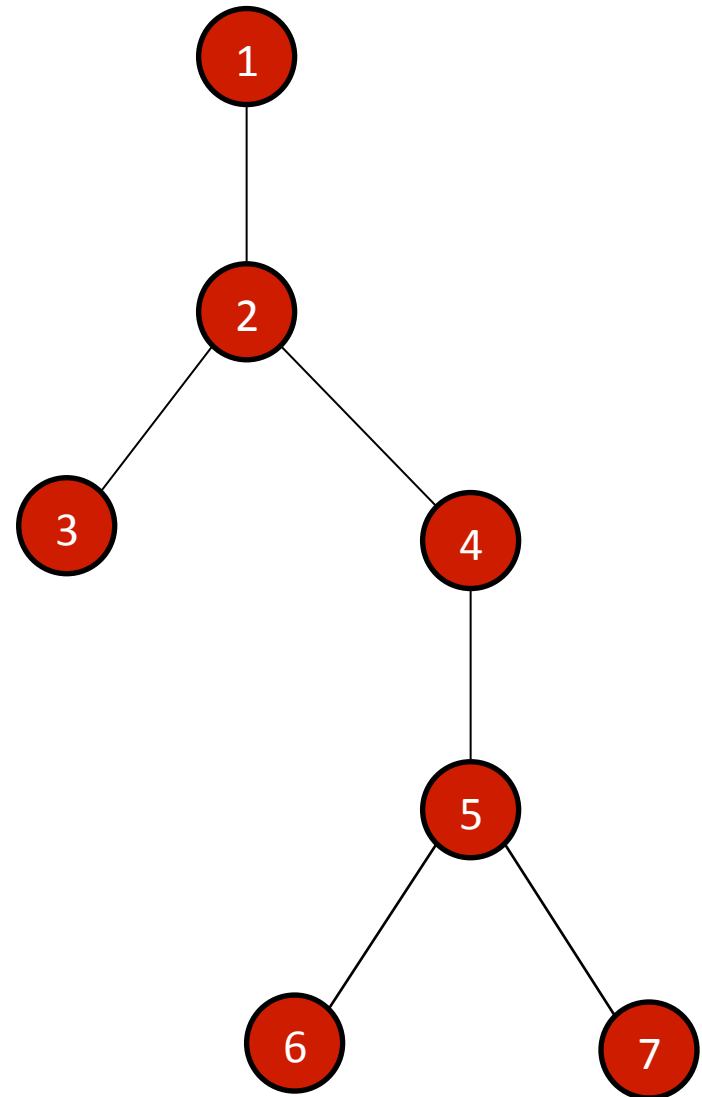
Push the root



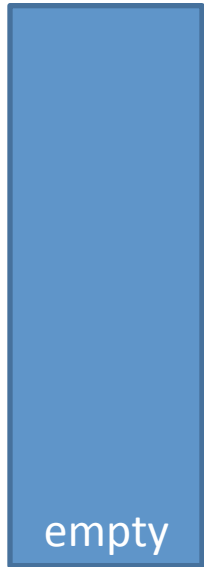
Using a stack



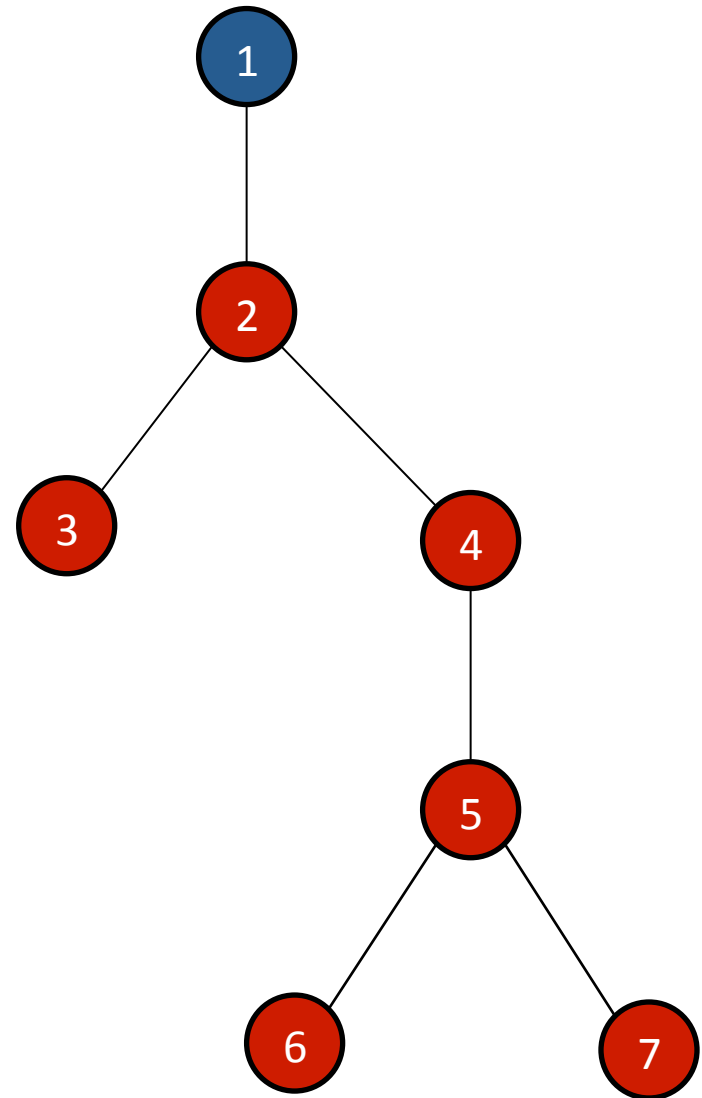
Repeat until stack empty:



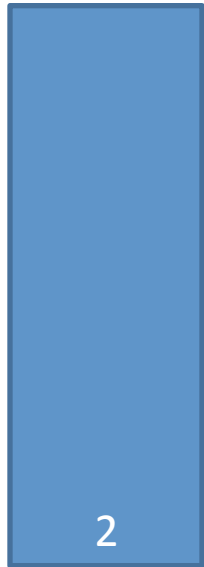
Using a stack



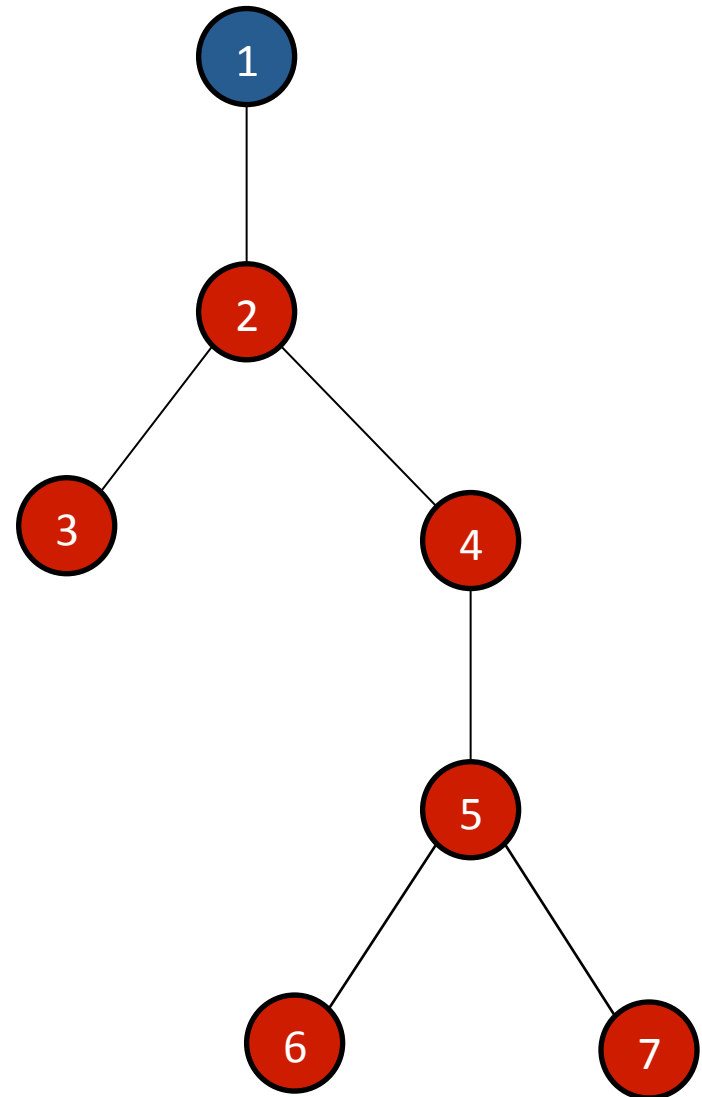
Pop node



Using a stack



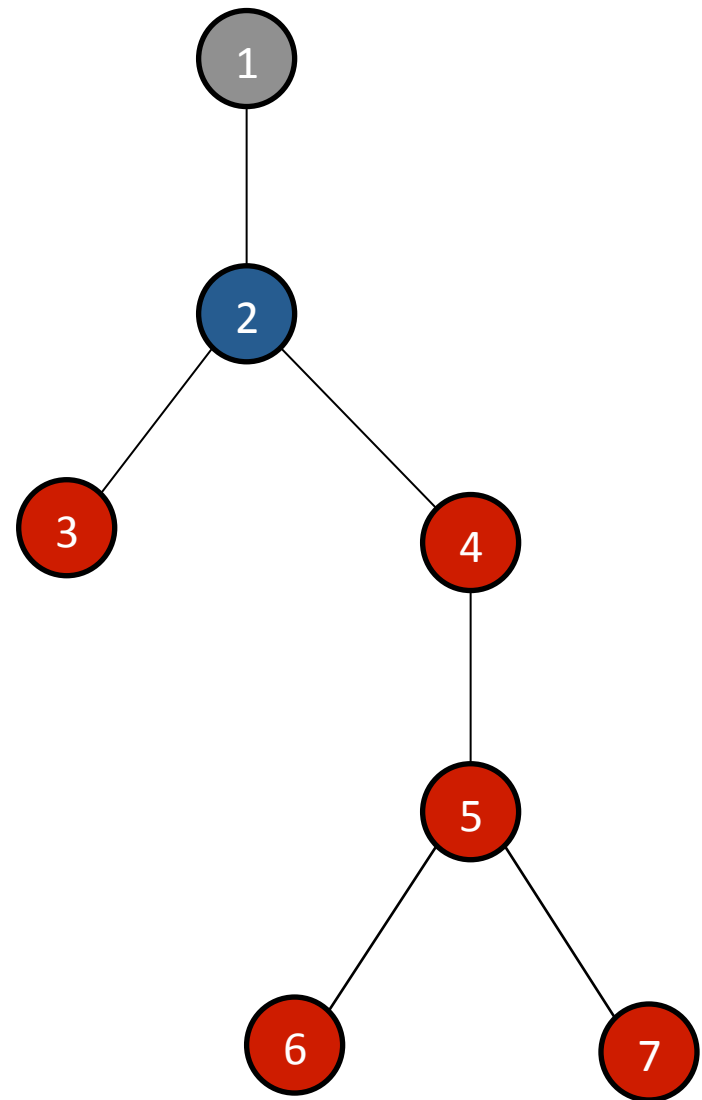
Push children



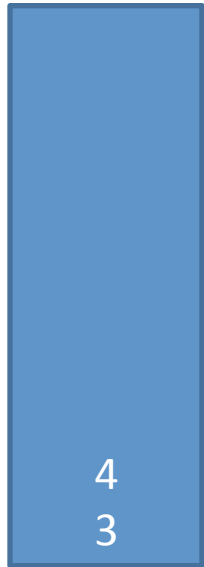
Using a stack



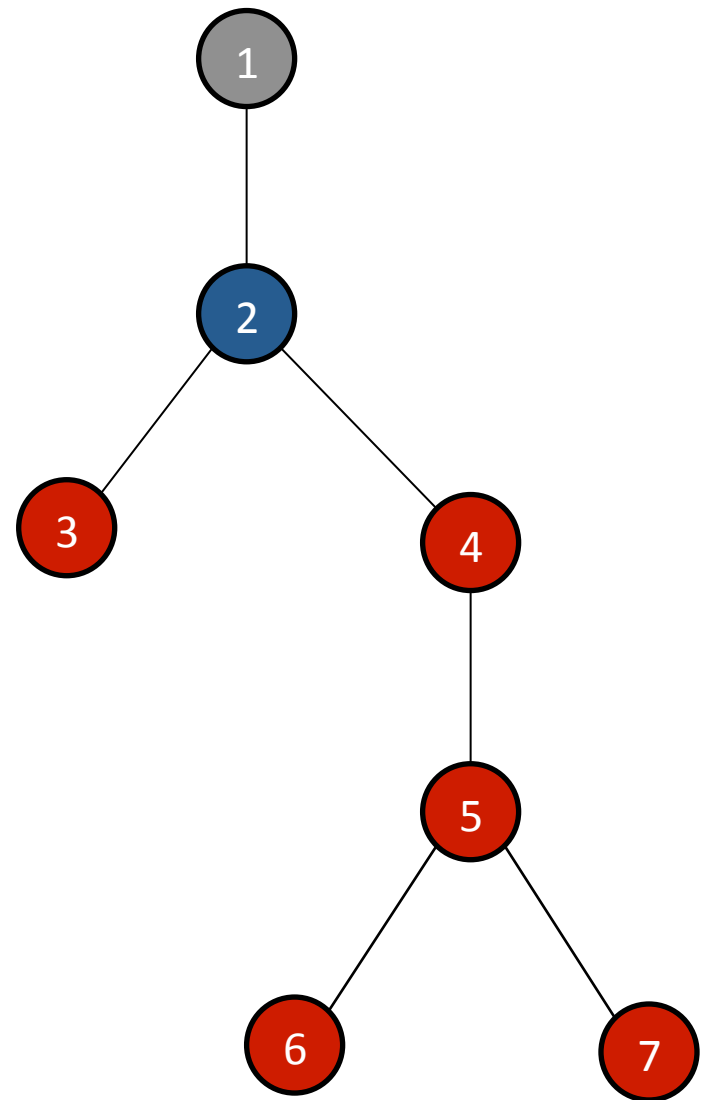
Pop node



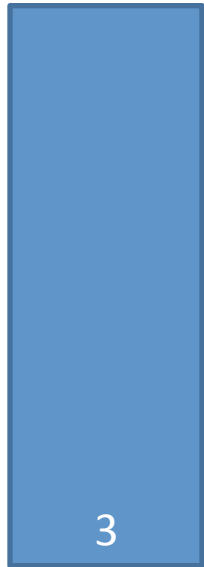
Using a stack



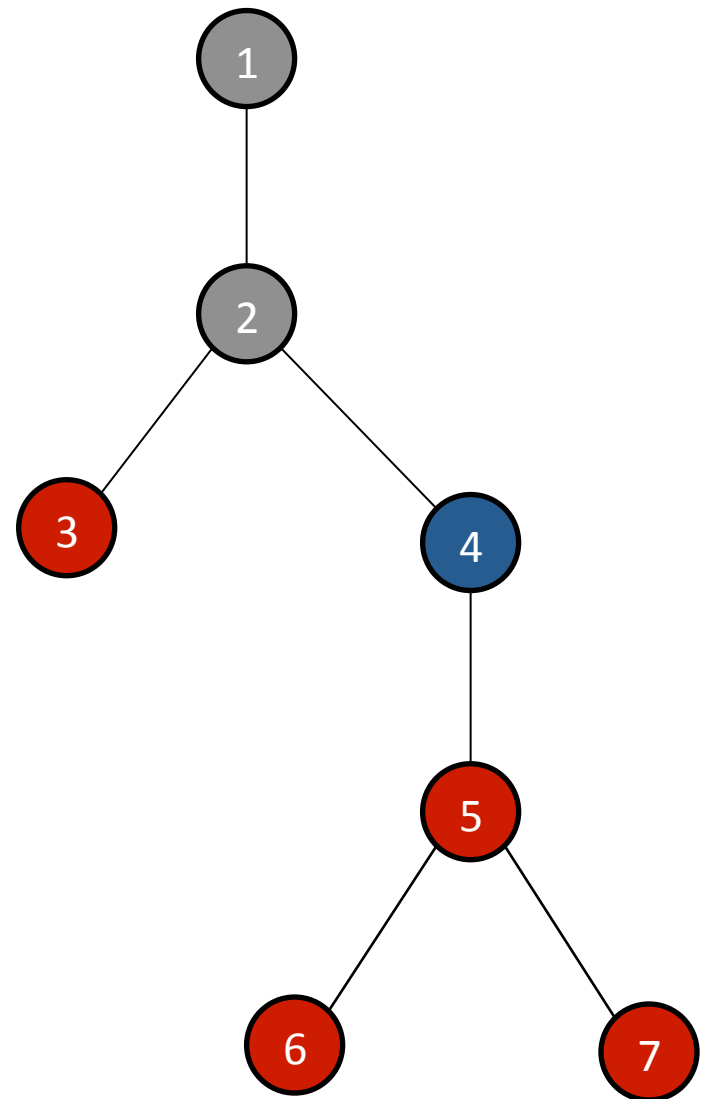
Push children



Using a stack



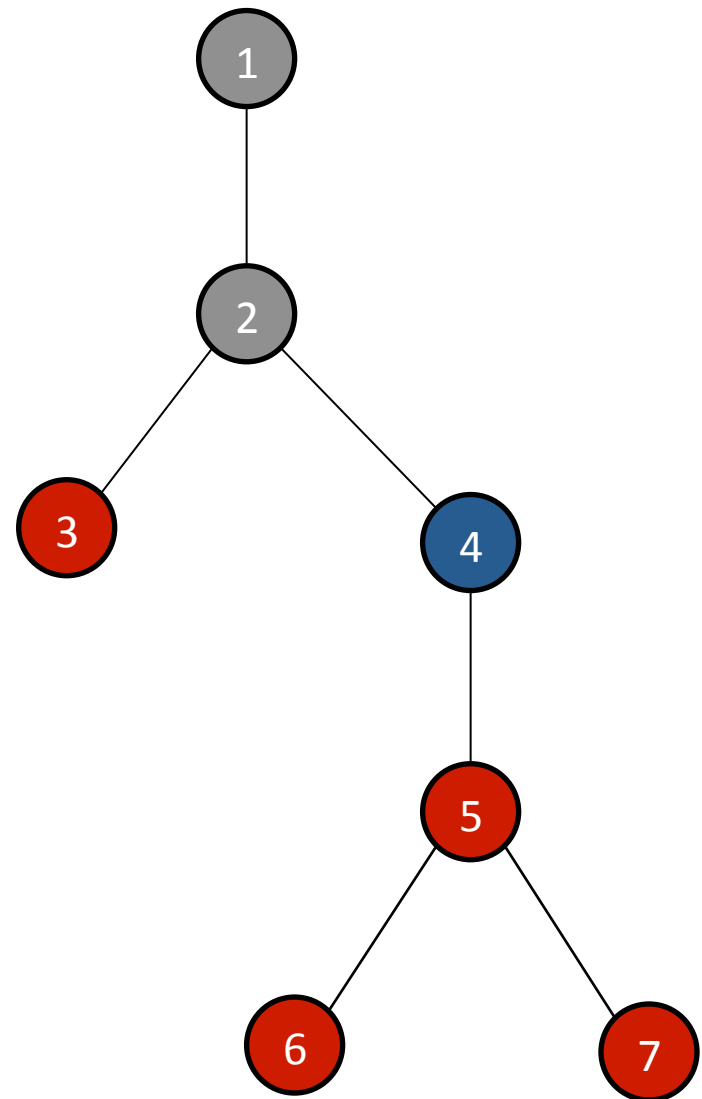
Pop node



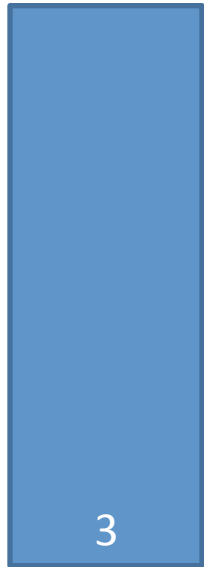
Using a stack



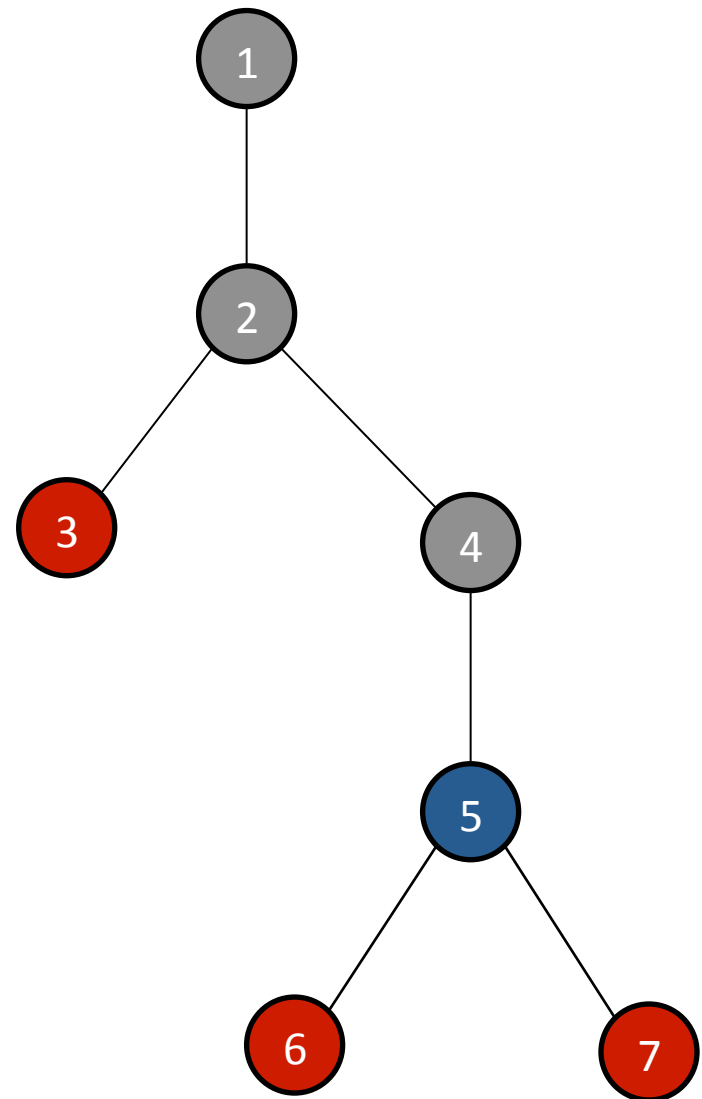
Push children



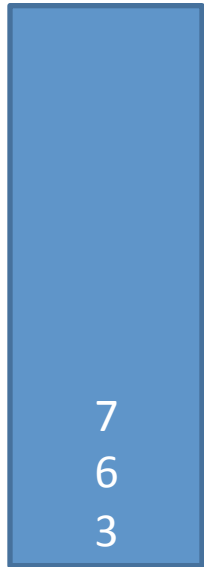
Using a stack



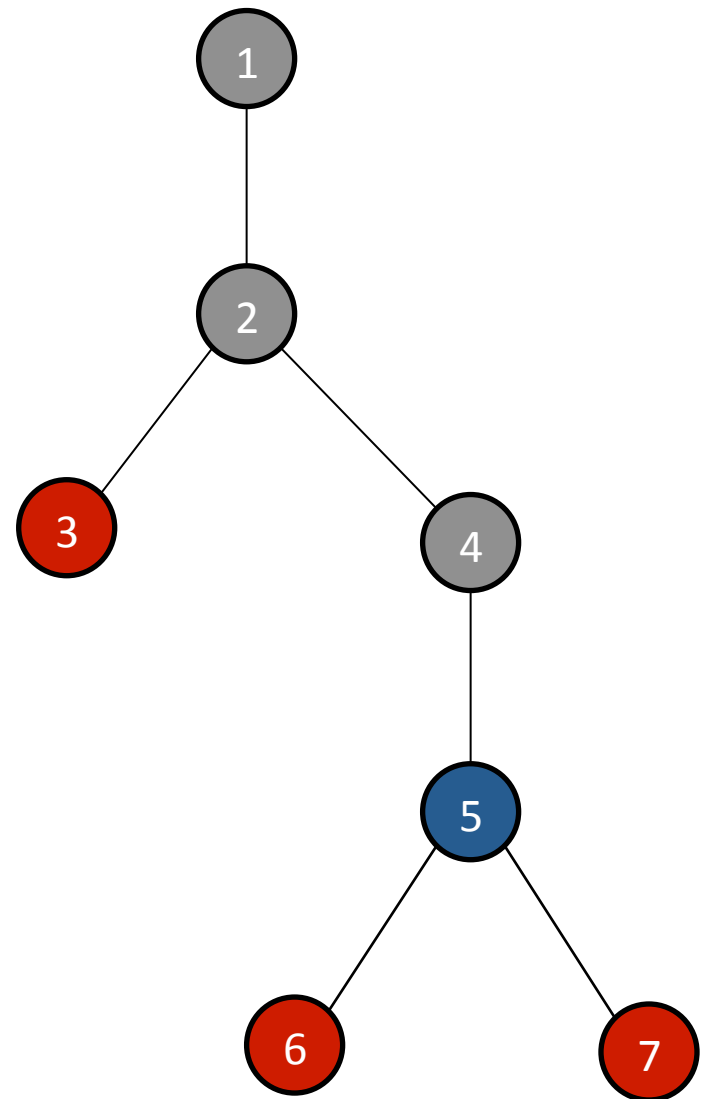
Pop node



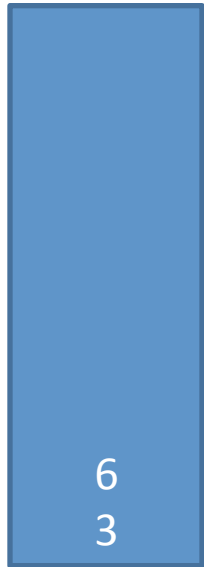
Using a stack



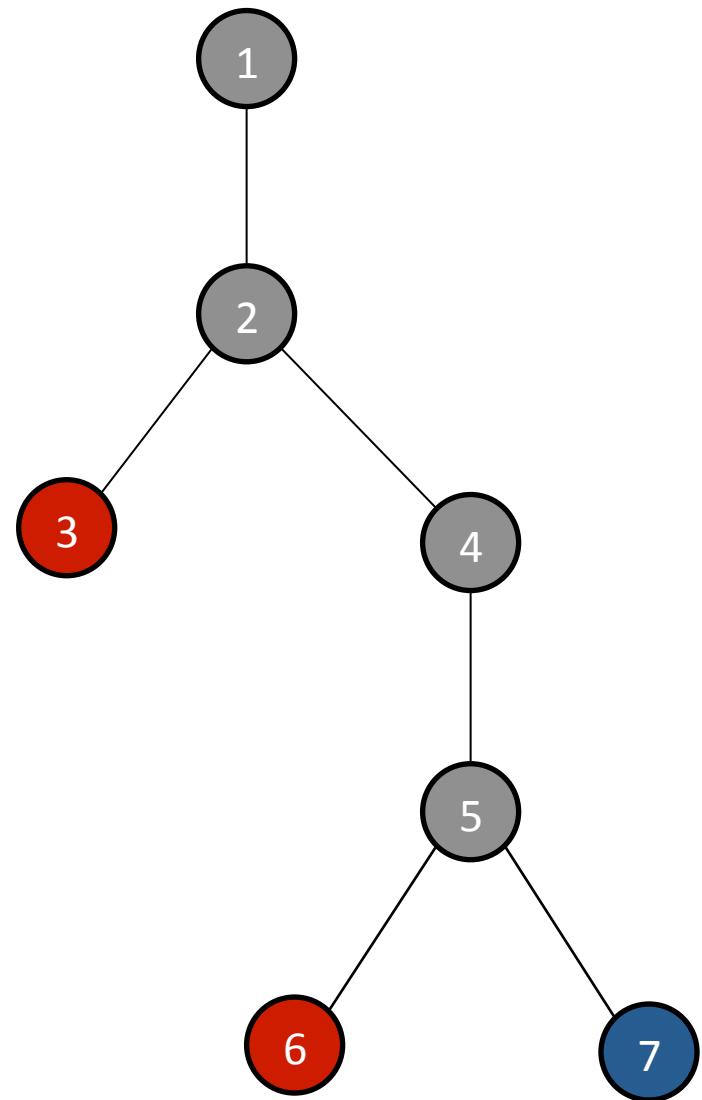
Push children



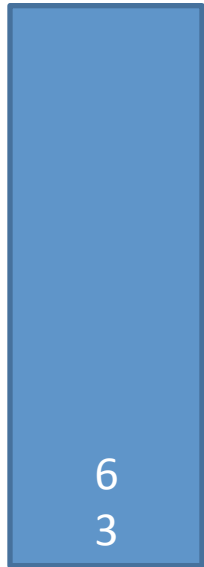
Using a stack



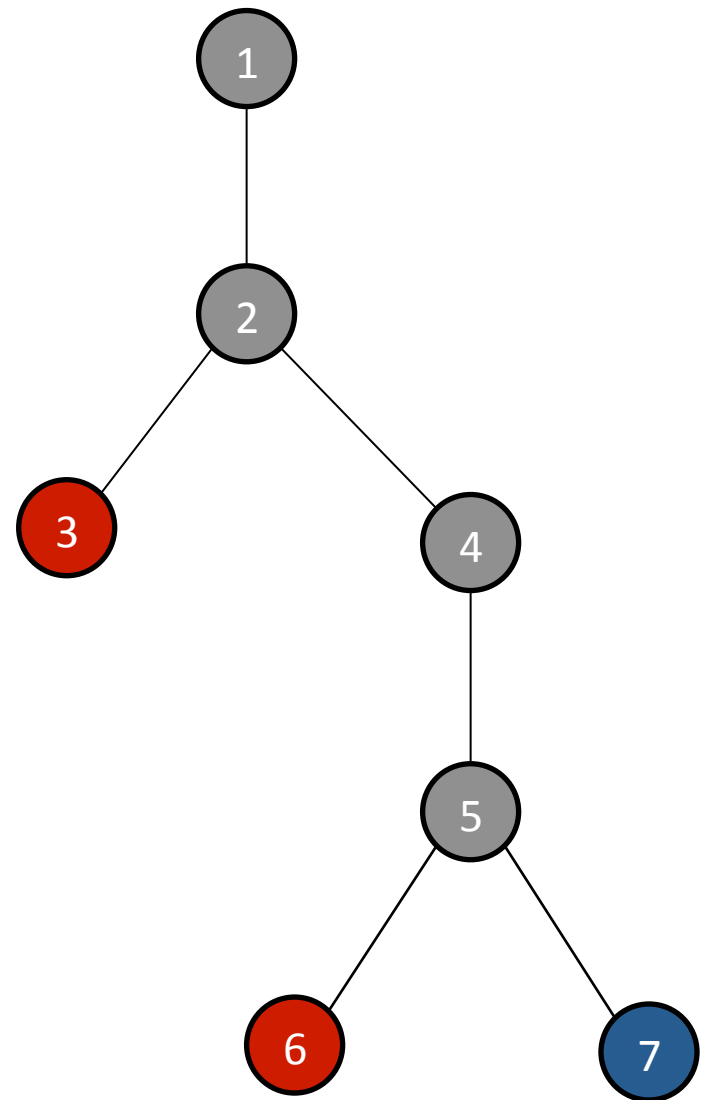
Pop node



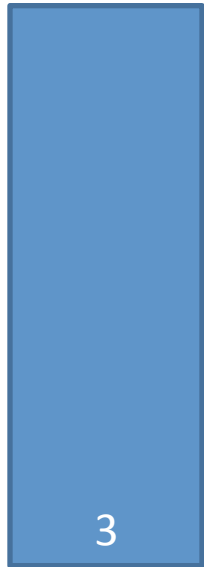
Using a stack



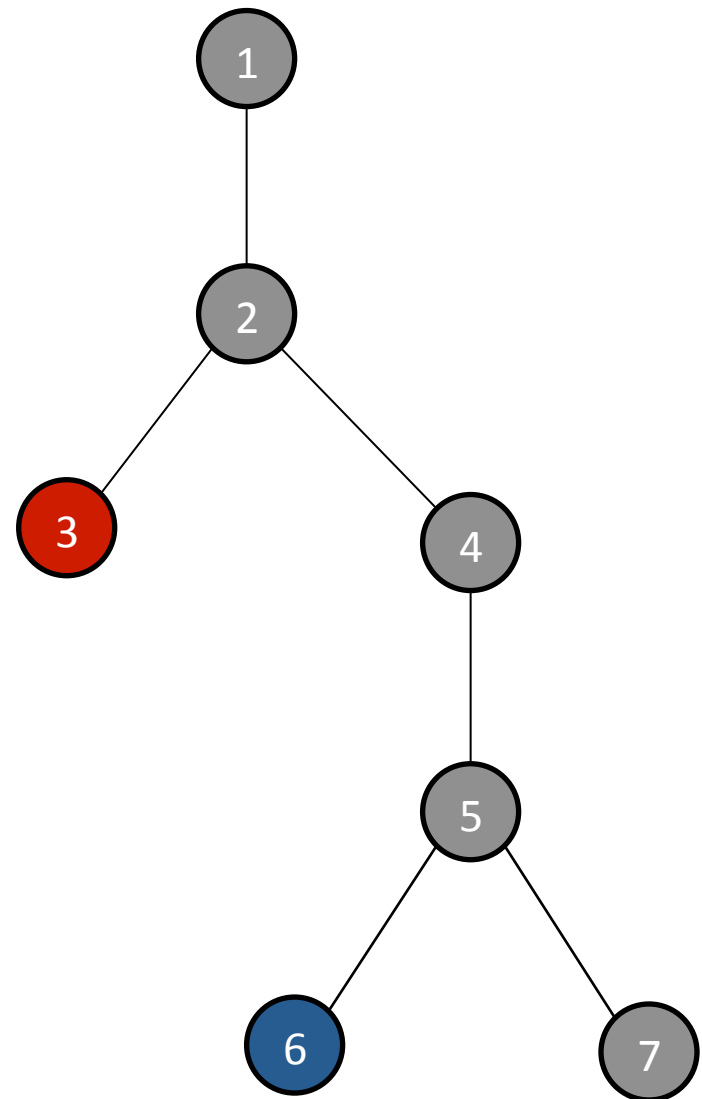
Push children (none)



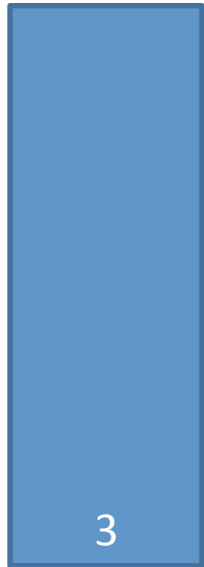
Using a stack



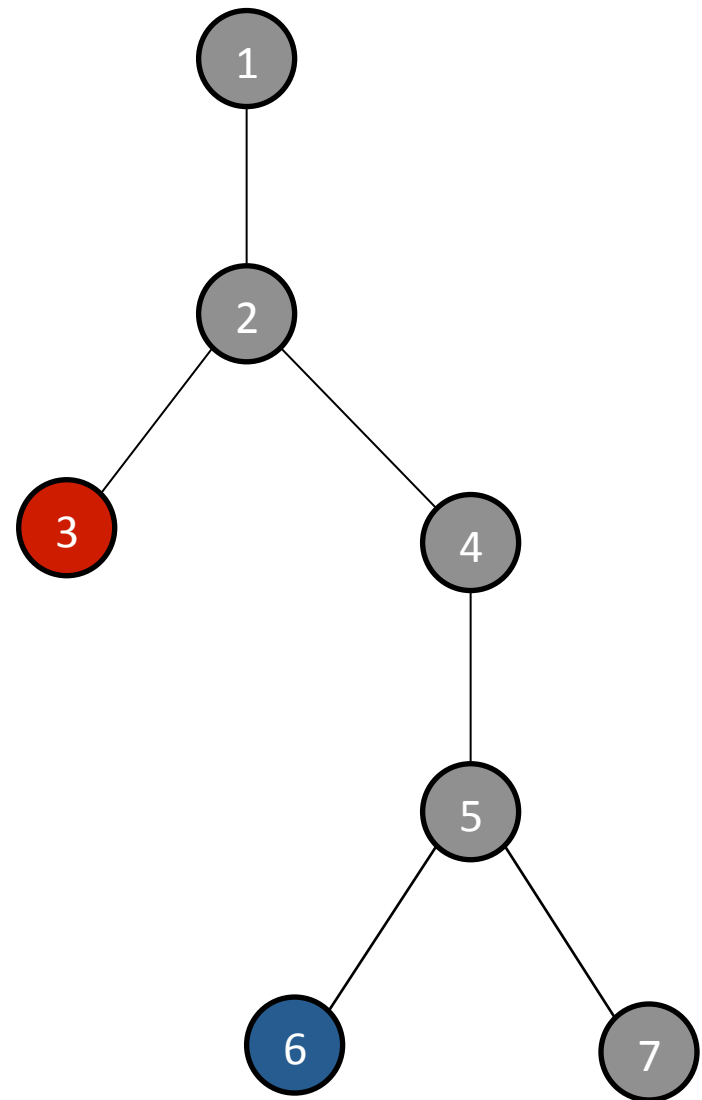
Pop node



Using a stack



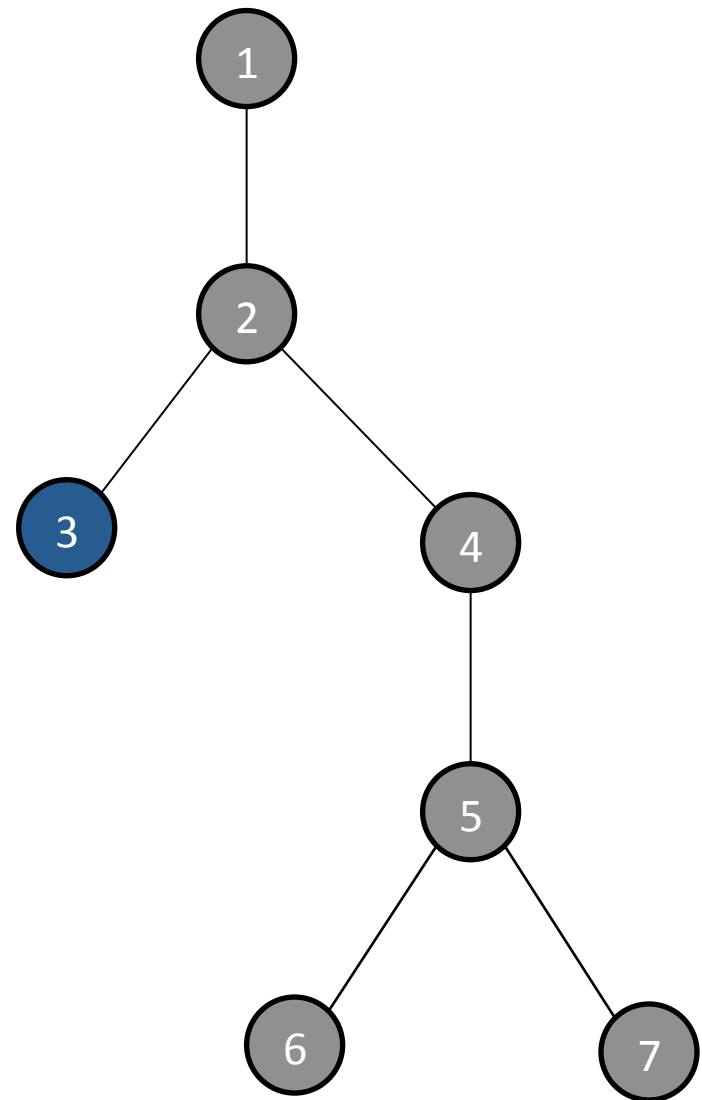
Push children (none)



Using a stack



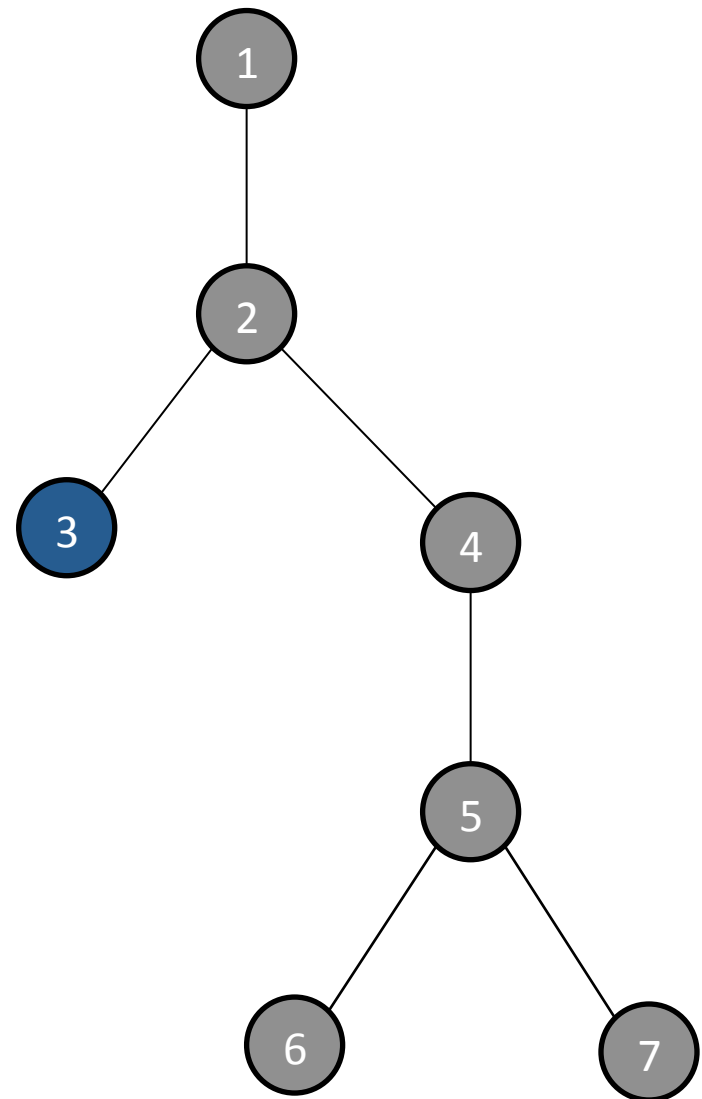
Pop node



Using a stack



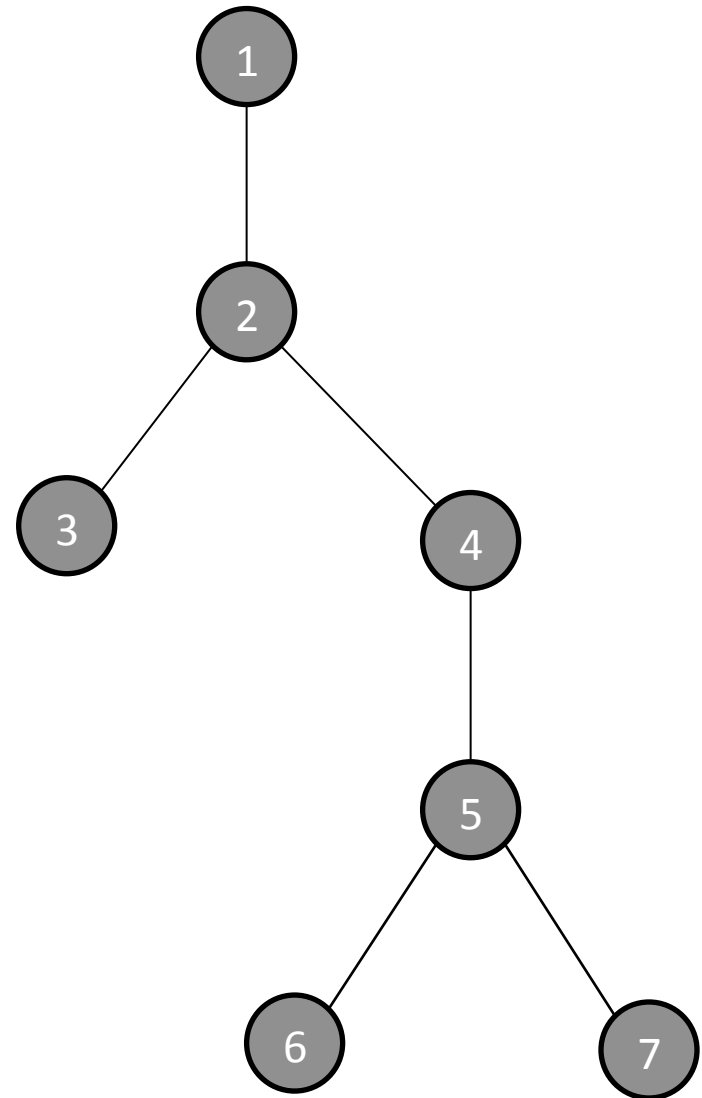
Push children (none)



Using a stack



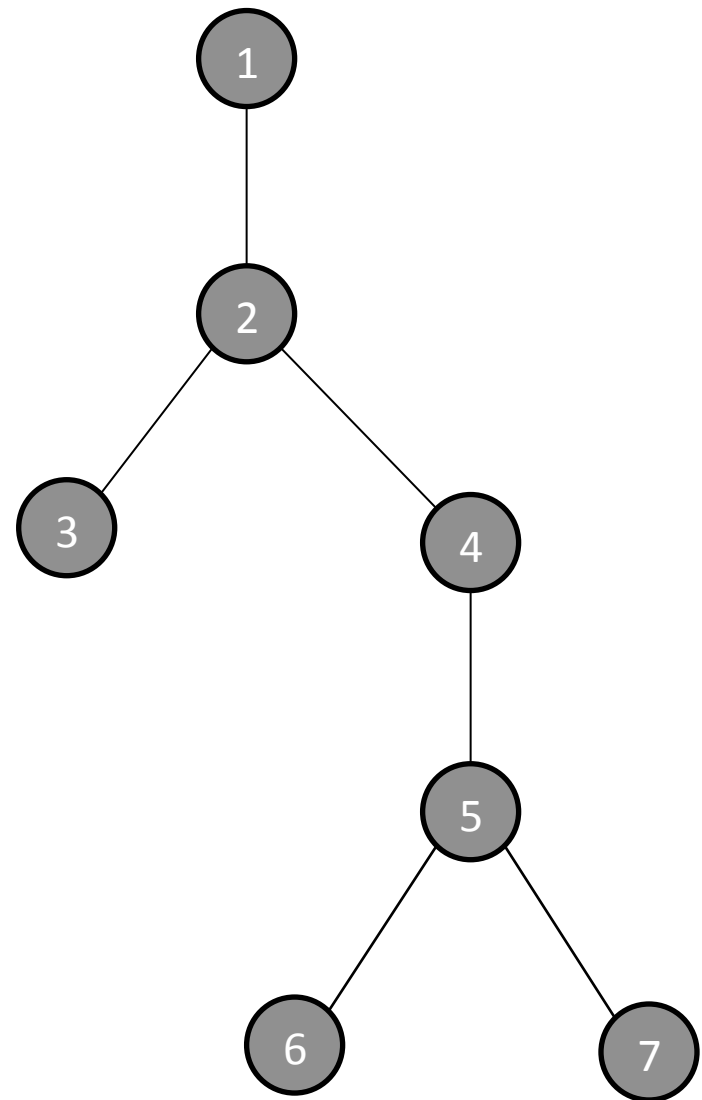
Pop node



Using a stack



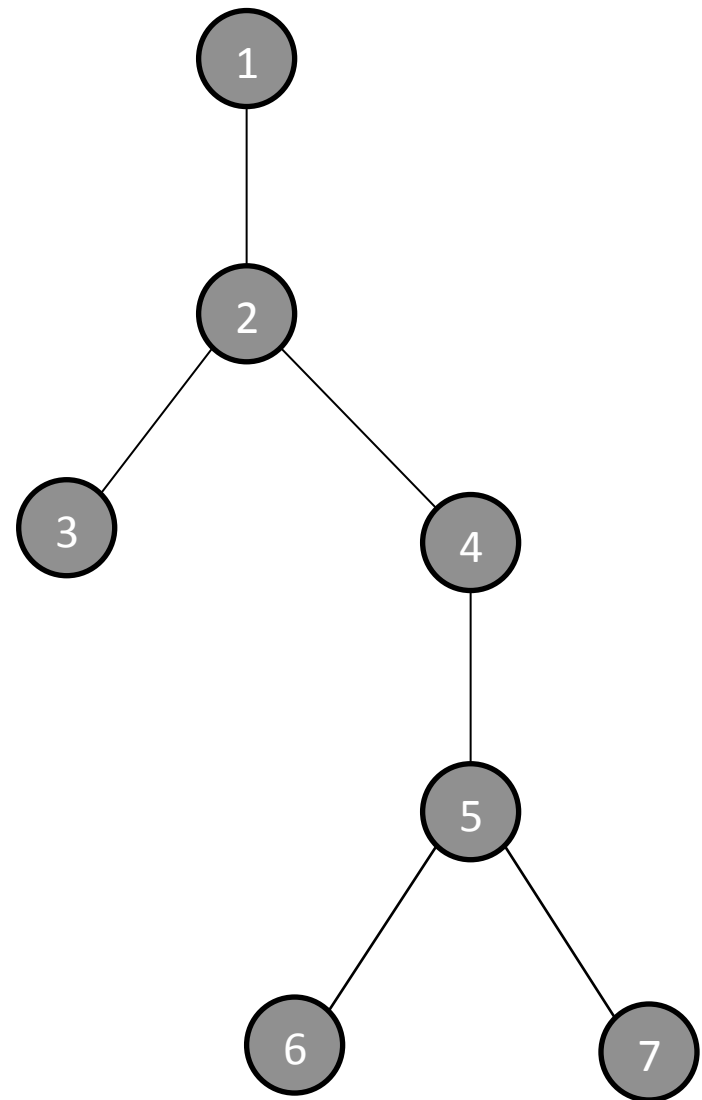
Pop node – stack empty



Using a stack

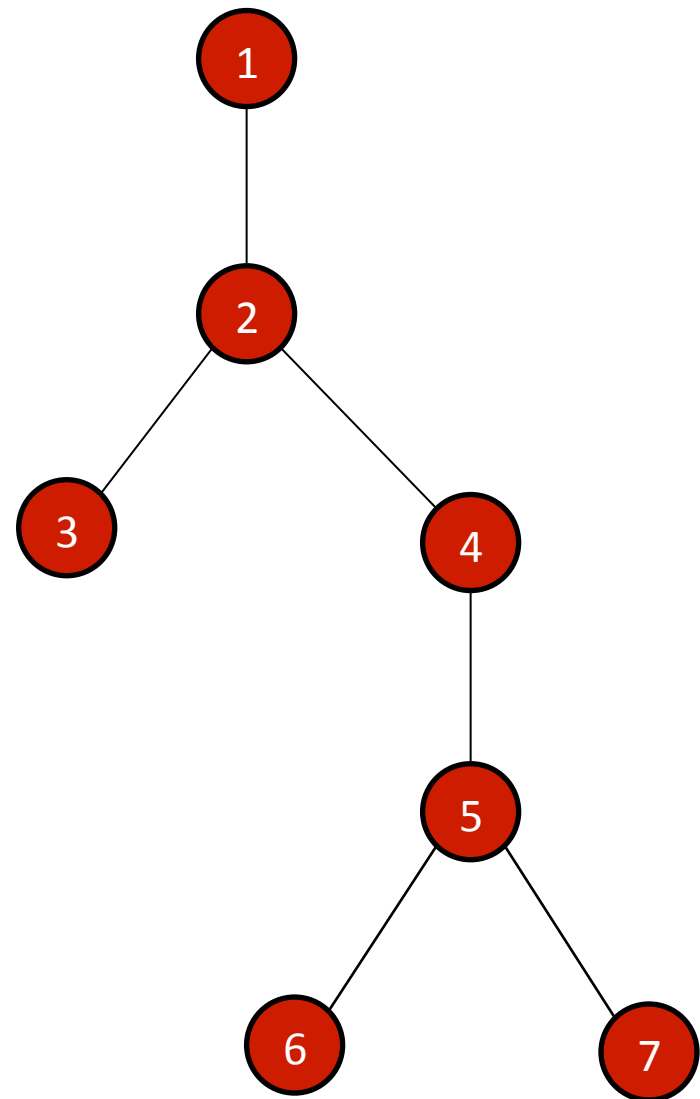


Finished



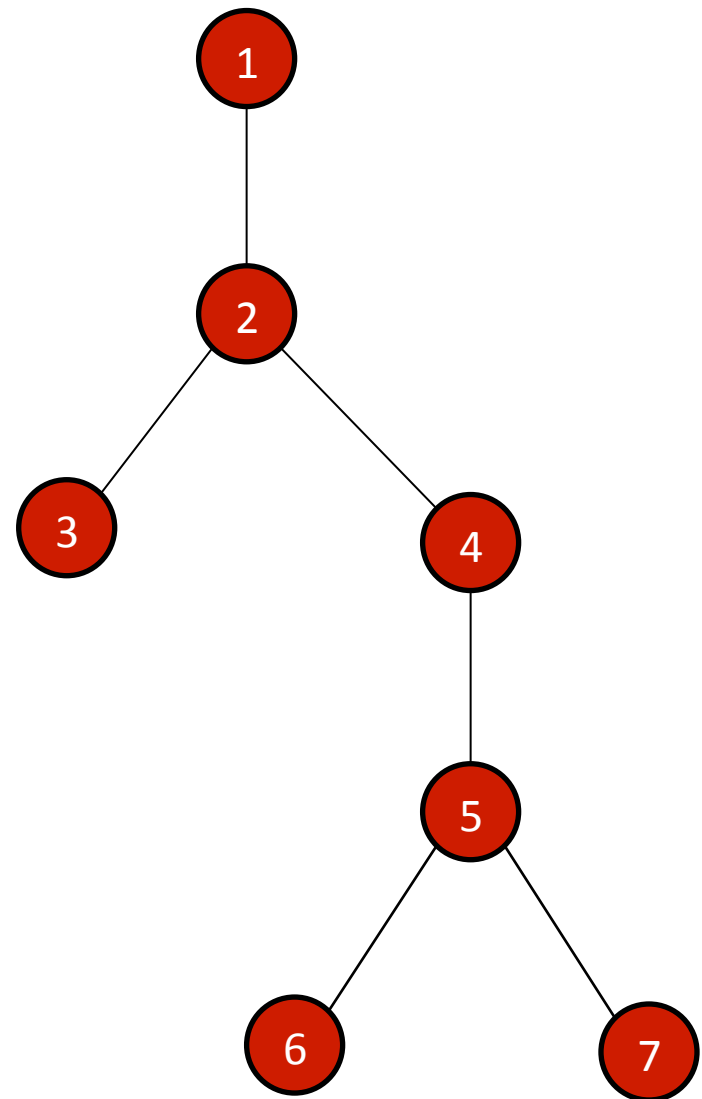
Depth-first walk

- **Substituting a stack** for a queue gives us depth-first traversal instead of breadth-first
- Although in this case, it visited the children right to left instead of left to right
 - If we cared, we could just push the children on the stack in reverse order



Depth-first walk

- Of course, we already have a perfectly good stack
- The **execution stack**
 - Every procedure call pushes the execution stack
 - Every return pops it
- Why not just use that stack?

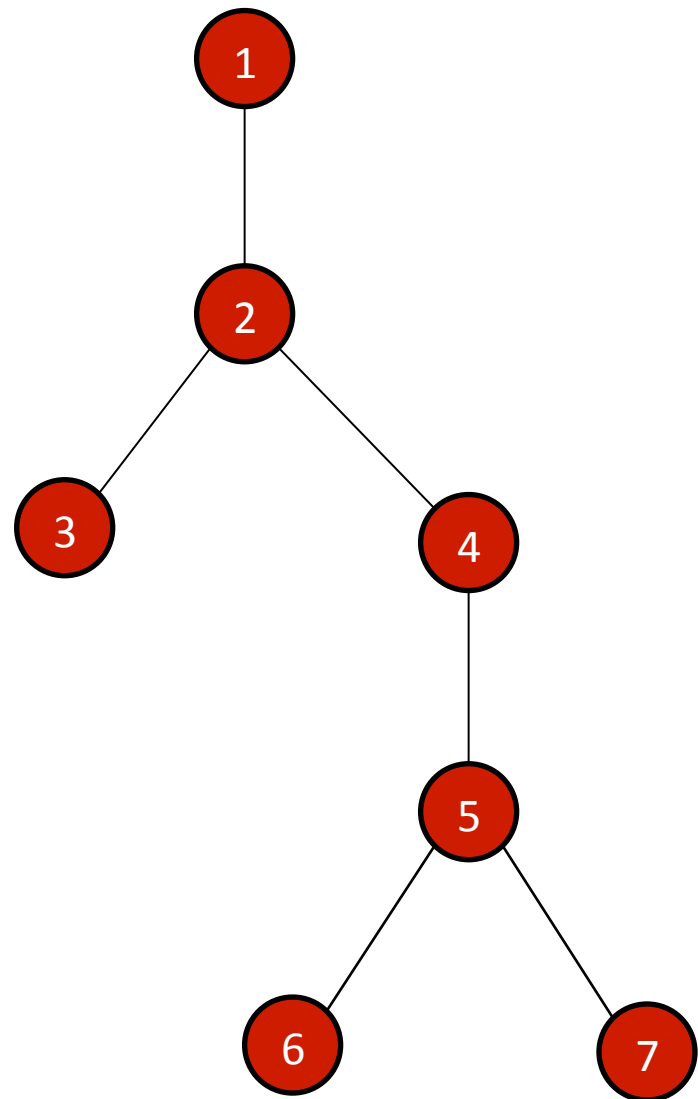


Recursive depth-first walk

Pseudocode:

```
DepthFirst(node)
  for each child c of node
    DepthFirst(c)
```

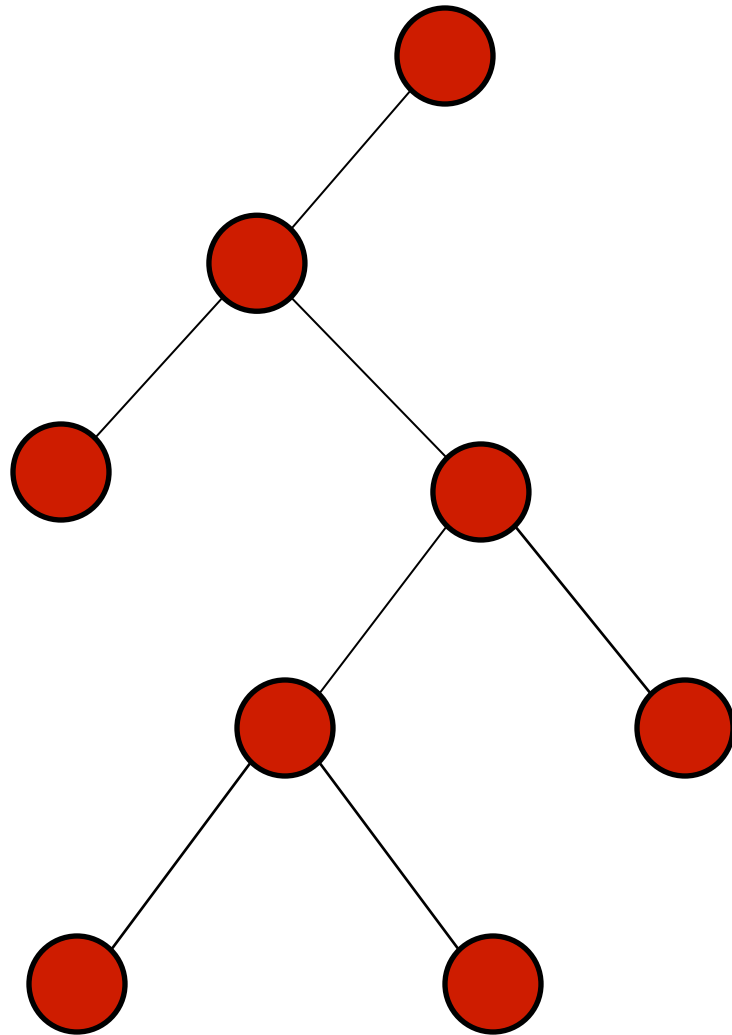
- Most of the time it's easier and clearer to write depth-first traversals as recursions
- And you thought recursion always made things more complicated!



Specialized tree representations

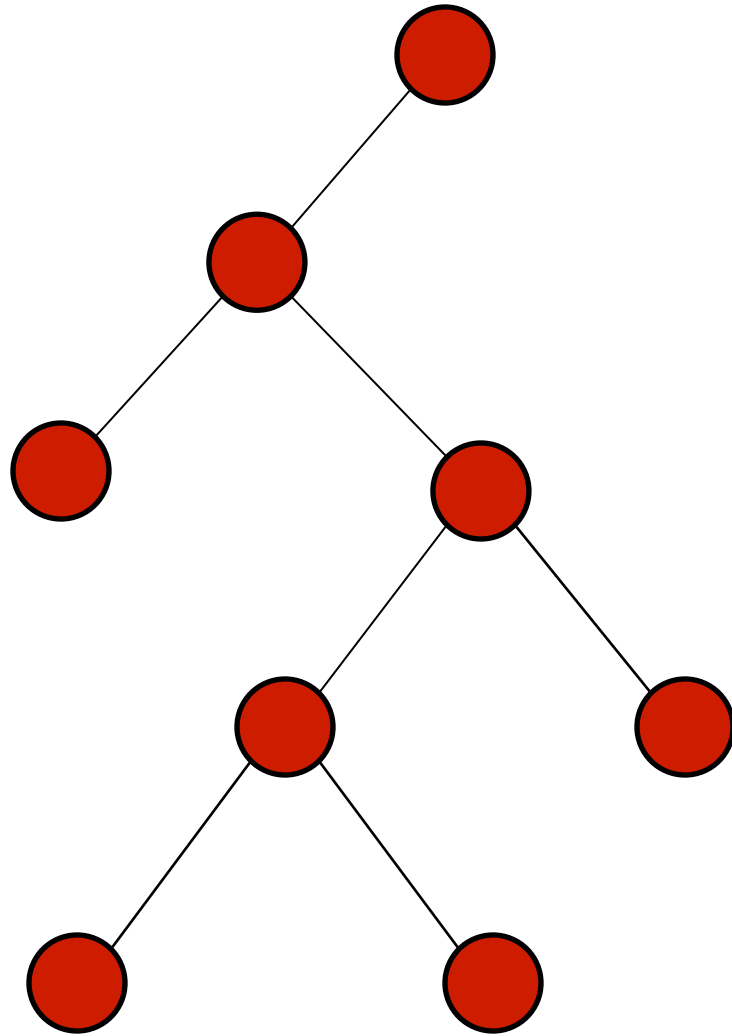
- Small, fixed branching factor
 - Put child pointers directly in nodes
 - Usually uses only for trees with a branching factor of 2 or 3
- Restricted information in nodes
 - No parent pointer
 - Used if you never need to find the parent of a node
 - Example: lists in lisp and scheme
 - No child pointers
 - Used in disjoint set representation
- Heaps
 - We'll talk about these later

Binary trees



- Common case
- Fixed branching factor of 2
 - Every node has at most 2 children
 - Referred to as the left child and right child

Optimized binary tree representation

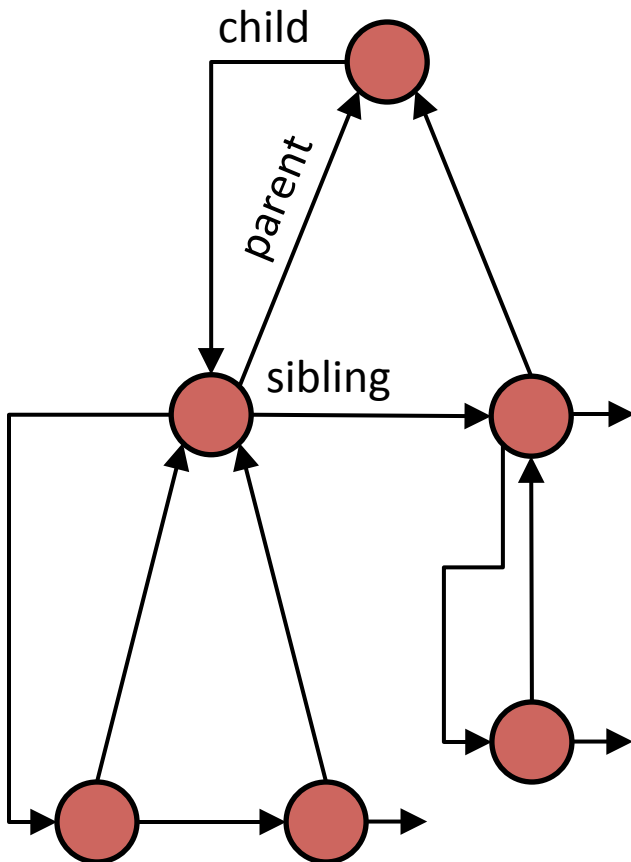


```
class BTreeNode {
    BTreeNode parent;
    BTreeNode leftChild;
    BTreeNode rightChild;
}
```

- Don't even bother with an array or linked list
 - Just put pointers in the node for both children
 - Leave them null if they aren't used

Why are binary trees popular?

Left child/right sibling is technically a binary tree

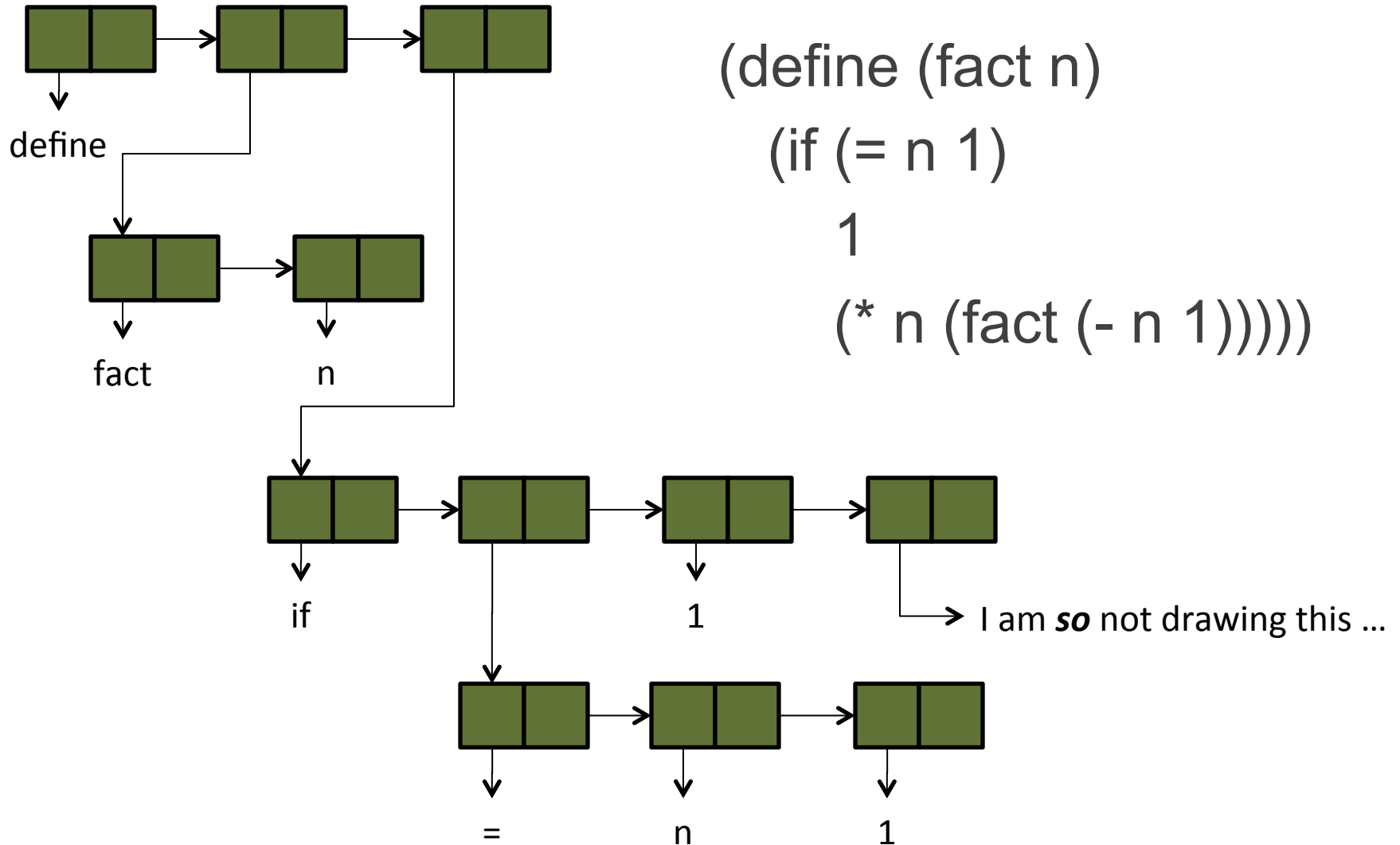


```
class TreeNode {  
    TreeNode parent;  
    TreeNode firstChild; leftChild  
    TreeNode nextSibling; rightChild  
    ... other data ...  
}
```

The CLR book calls this
the left child/right sibling
representation

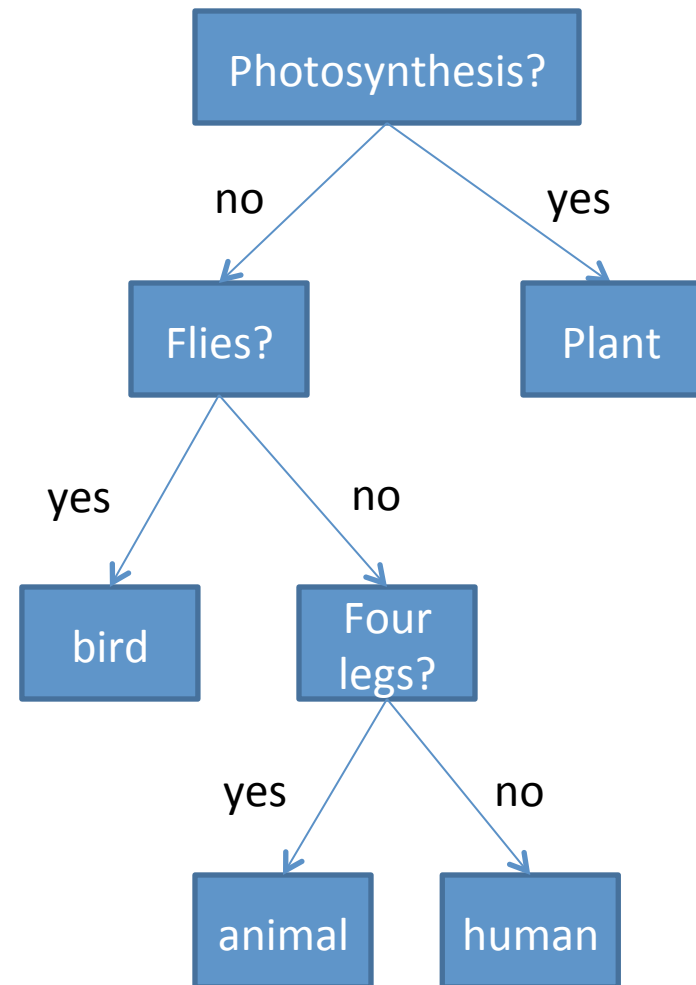
Scheme lists are binary trees

(without parent pointers)



Decision trees

- A decision tree is a binary tree in which
 - The leaf nodes are decisions
 - The interior nodes are yes/no questions for deciding between decisions



A very bad decision tree for classifying lifeforms

Depth-first traversals of binary trees

- Suppose you want to print all the nodes in a binary tree
 - You could use a depth-first traversal
 - But there are actually three different DFTs you could use
- We call these three versions the **preorder**, **postorder**, and **inorder** traversals of the tree

```
Preorder(node) {  
    print node  
    Preorder(node.leftChild)  
    Preorder(node.rightChild)  
}
```

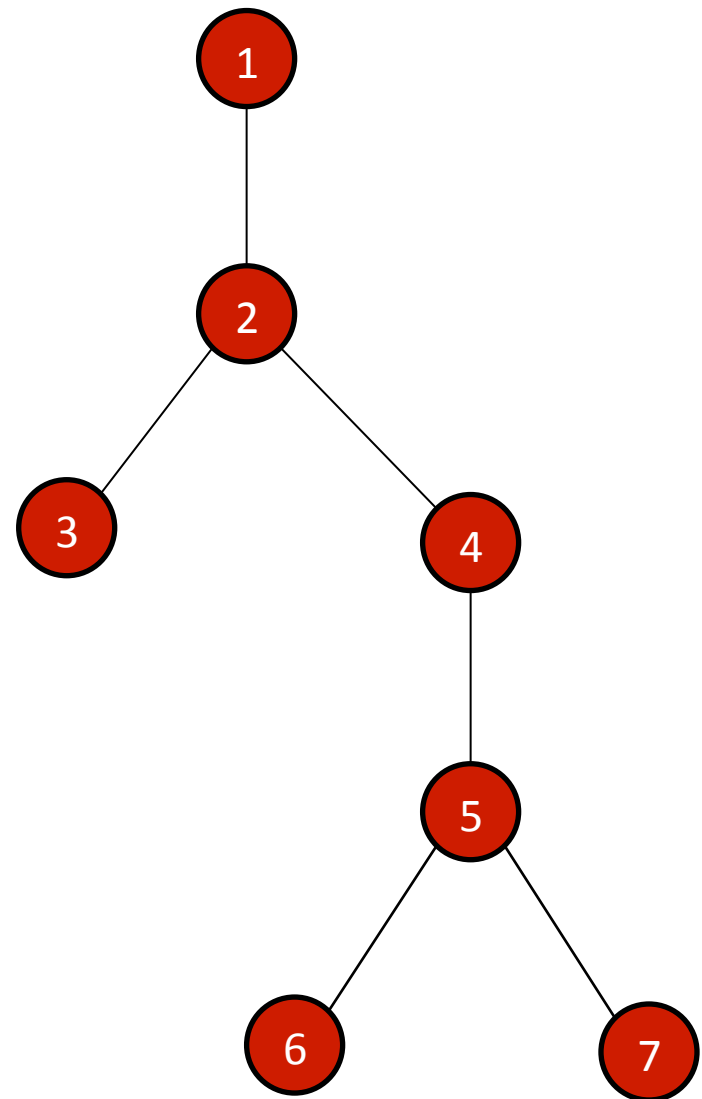
```
Postorder(node) {  
    Postorder(node.leftChild)  
    Postorder(node.rightChild)  
    print node  
}
```

```
Inorder(node) {  
    Inorder(node.leftChild)  
    print node  
    Inorder(node.rightChild)  
}
```

Preorder traversal

```
Preorder(node) {  
    print node  
    Preorder(node.leftChild)  
    Preorder(node.rightChild)  
}
```

Output:

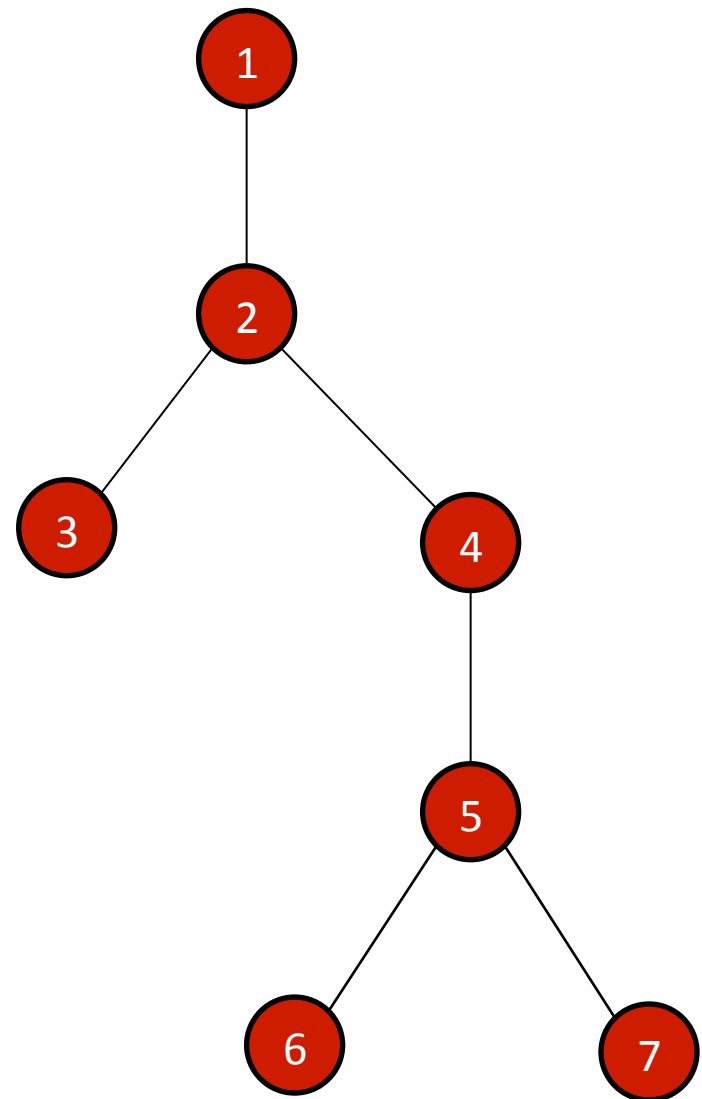


Preorder traversal

```
Preorder(node) {  
    print node  
    Preorder(node.leftChild)  
    Preorder(node.rightChild)  
}
```

Output:

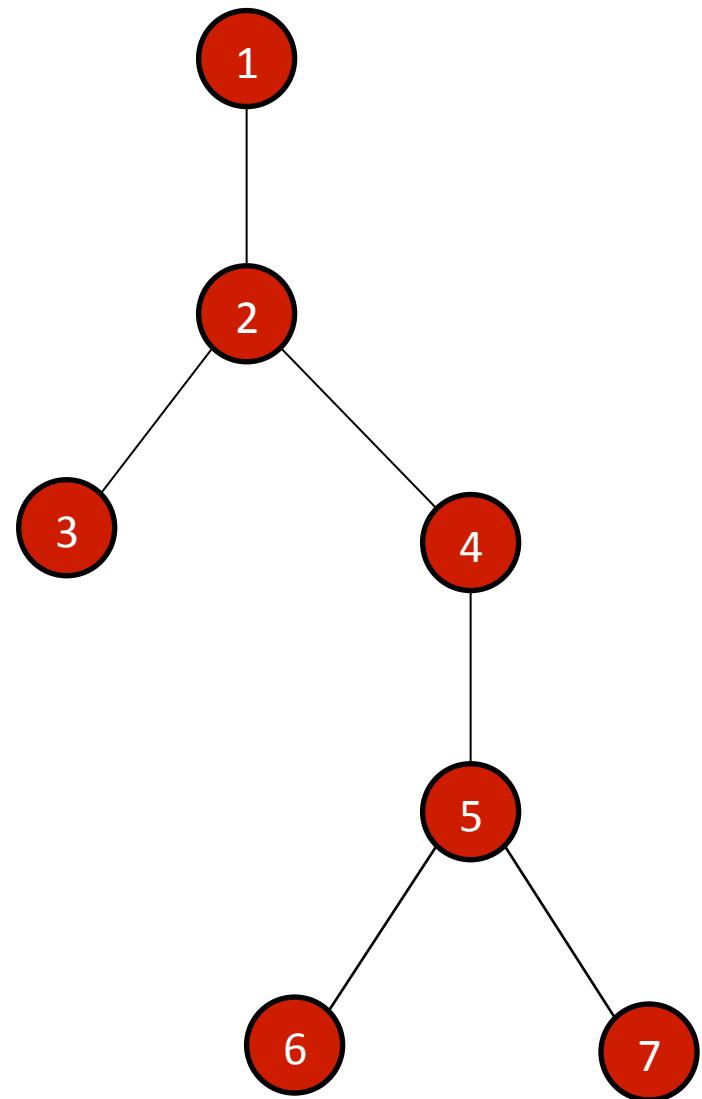
1 2 3 4 5 6 7



Postorder traversal

```
Postorder(node) {  
    Postorder(node.leftChild)  
    Postorder(node.rightChild)  
    print node  
}
```

Output:

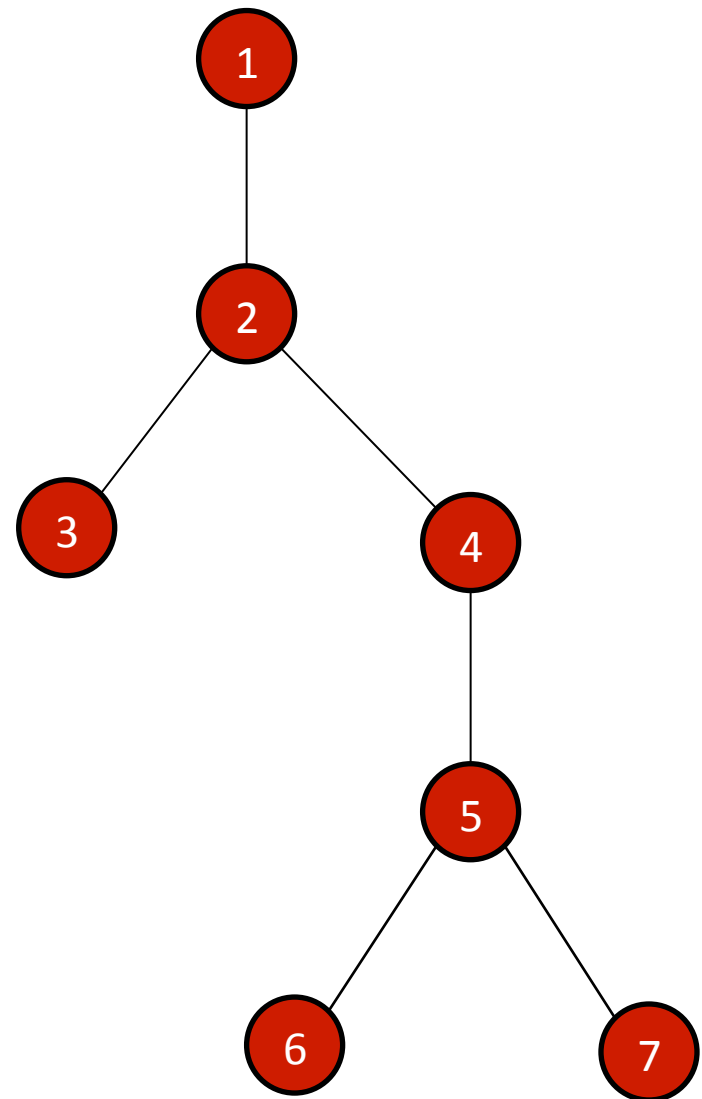


Postorder traversal

```
Postorder(node) {  
    Postorder(node.leftChild)  
    Postorder(node.rightChild)  
    print node  
}
```

Output:

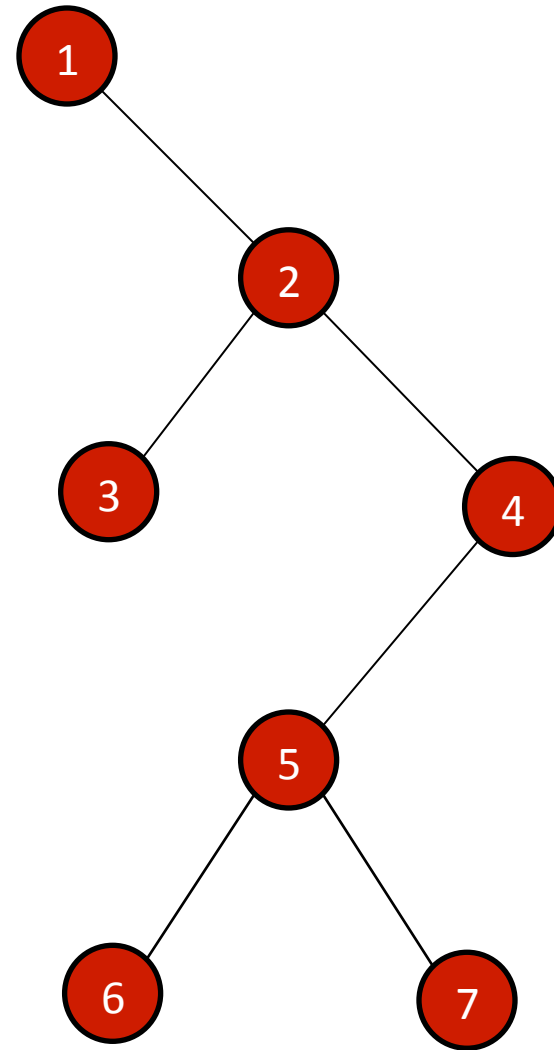
3 6 7 5 4 2 1



Inorder traversal

```
Inorder(node) {  
    Inorder(node.leftChild)  
    print node  
    Inorder(node.rightChild)  
}
```

Output:

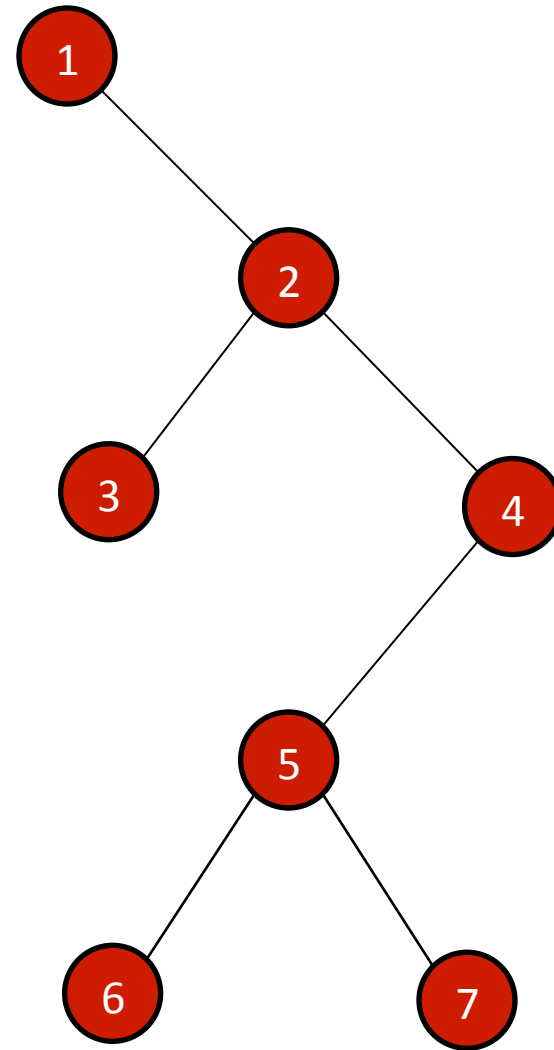


Inorder traversal

```
Inorder(node) {  
    Inorder(node.leftChild)  
    print node  
    Inorder(node.rightChild)  
}
```

Output:

1 3 2 6 5 7 4



Reading

- CLRS chapter 10, section 4 “Representing rooted trees”