Lecture 13 Heaps and priority queues

EECS-214

Queues

- Simplified sequence data structure
 - Insertions only at the end ("tail")
 - Deletions only from the beginning ("head")
- First-in, first out
 - Objects are dequeued in the order they were enqueued
- Simple API
 - Enqueue: add item to the end of the queue
 - Dequeue: remove item from the front



Priority queues

- Like normal queues
 - Objects wait in line to be processed
- However, items have an associated numeric priority
 - Priority specified when added to queue
 - Objects removed from queue in order of priority
- Slightly different API
 - Insert(object, priority)
 - Adds object with specified priority
 - ExtractMax()
 - Returns highest priority object



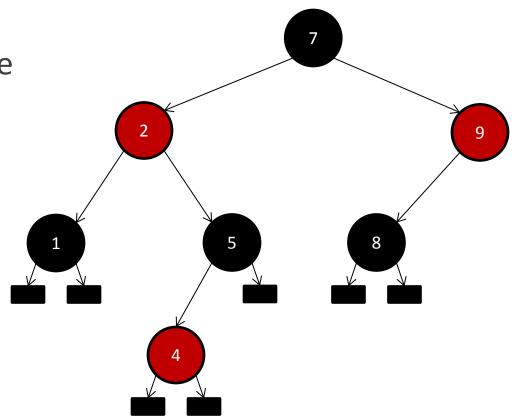
Priority queues

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 - Objects wait in line to be processed
- However, items have an associated numeric priority
 - Priority specified when added to queue
 - Objects removed from queue in order of priority
- Slightly different API
 - Insert(object, priority)
 - Adds object with specified priority
 - ExtractMin()
 - Returns **lowest** priority object



Implementing priority queues

- We can use a balanced tree (e.g. a red/black tree) as a priority queue
 - Insert using the normal RBT insert
 - $O(\log n)$ time
 - Extract max is
 - Get the maximum element
 - $O(\log n)$
 - Delete it
 - Also $O(\log n)$



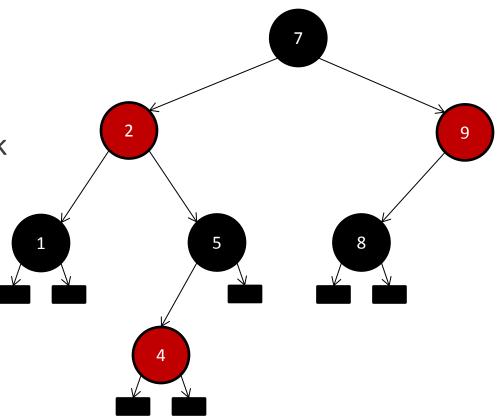
• $O(\log n)$ time

Implementing priority queues

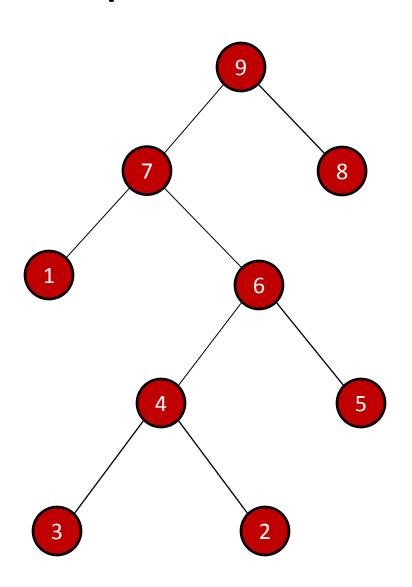
 Unfortunately, red/black trees are pretty complicated

> They go to a lot of work to keep all the items perfectly sorted

 Is there something simpler we could do?

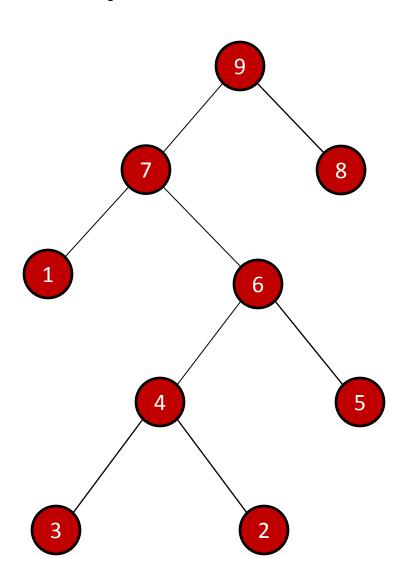


Heaps



- Heaps are a simple tree structure for implementing priority queues
- Rather than requiring their inorder traversal to be sorted
 - We just require that parent nodes
 be larger than their child nodes
 - Or smaller, if it's a min heap
- There are lots of exotic types of heaps
 - We'll focus on binary heaps
 - Which are complete binary trees with the heap property
 - We'll get to the completeness thing in a minute...

Heaps



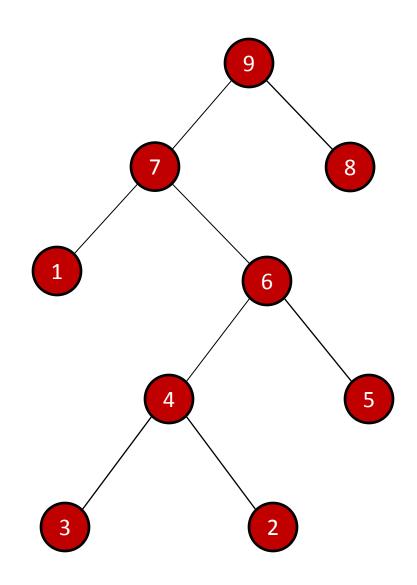
Proposition: the largest element of a heap is always its root

Proof:

- Suppose some other element is the largest element
- Since it isn't the root, it must have a parent
- Since it's the largest element, it must be larger than its parent
- But that contradicts the definition of a heap
- So the largest element must be the root

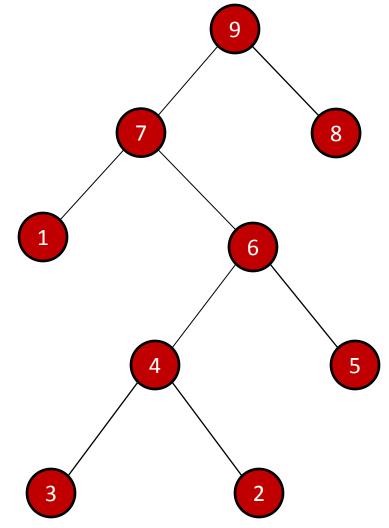
ExtractMax (version 1)

- We know the root is the maximal element
- So we want to delete it and return it
- But we need to replace it with its largest child
 - So we find the largest child
 - And recursively delete it from its subtree



ExtractMax (version 1)

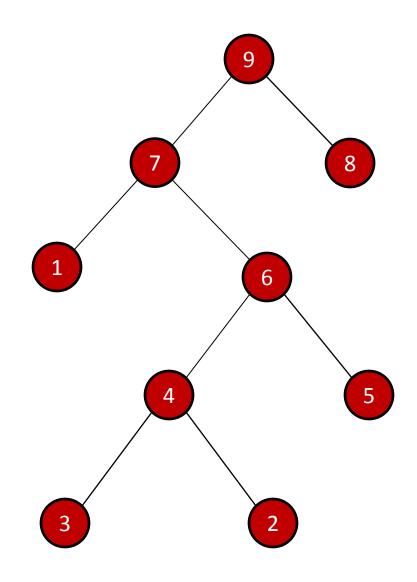
- We know the root is the maximal element
- So we want to delete it and return it
- But we need to replace it with its largest child
 - So we find the largest child
 - And recursively delete it from its subtree



However, this is going to turn out to not to be the most convenient algorithm

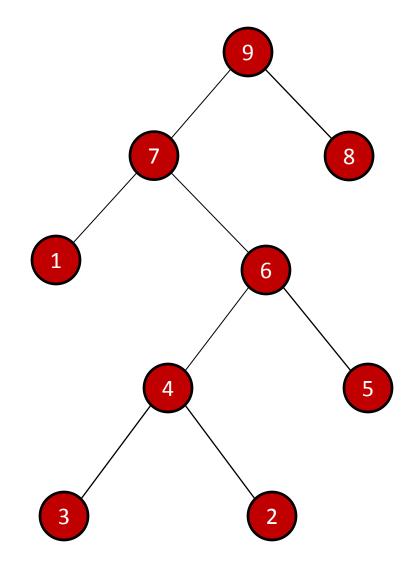
ExtractMax (verison 2)

- Replace the root with a leaf node
 - Getting to a leaf will turn out to be easy
- The leaf node is probably too small
- So move it downward in the tree to make it be a proper heap again

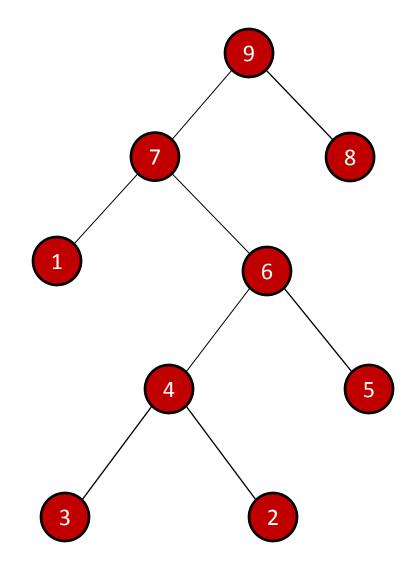


ExtractMax(heap)

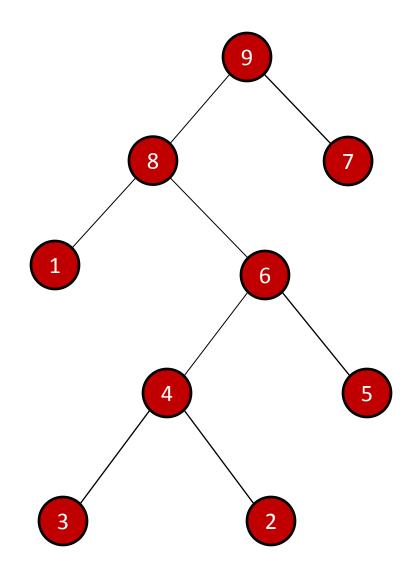
result = root of heap replace root with leaf Heapify(heap) return result



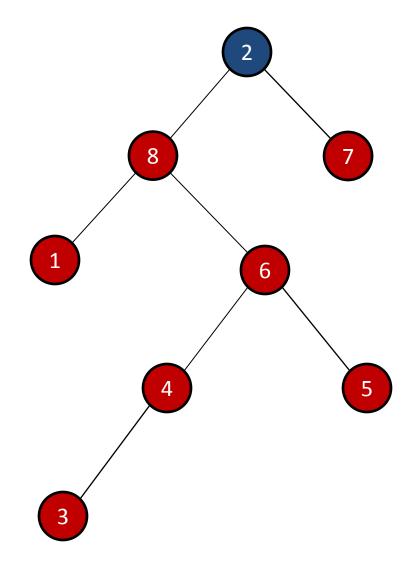
```
Heapify(root)
  if root > children
    done
  else if left child > root and
        left child > right child
    swap root and left child
    Heapify(left child)
  else
    swap root and right child
    Heapify(right child)
```



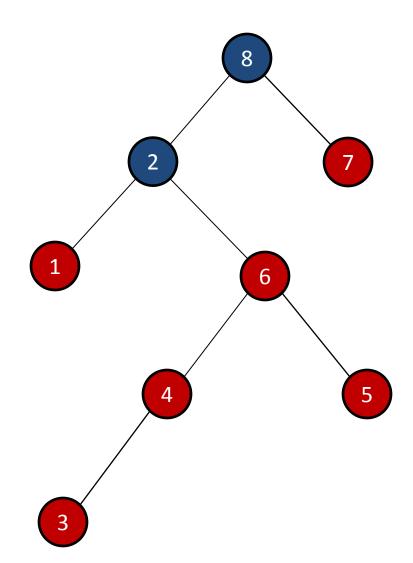
• Starting configuration



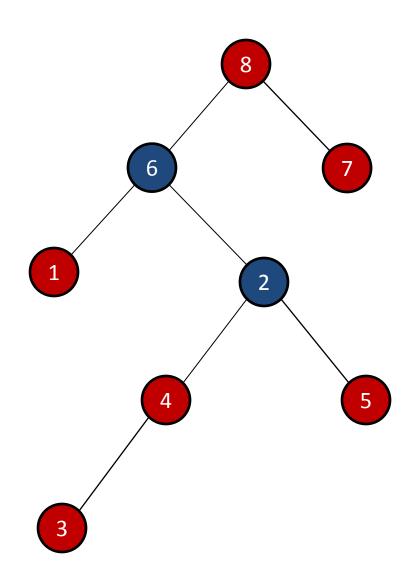
- Replace root with leaf
 - Violates heap property



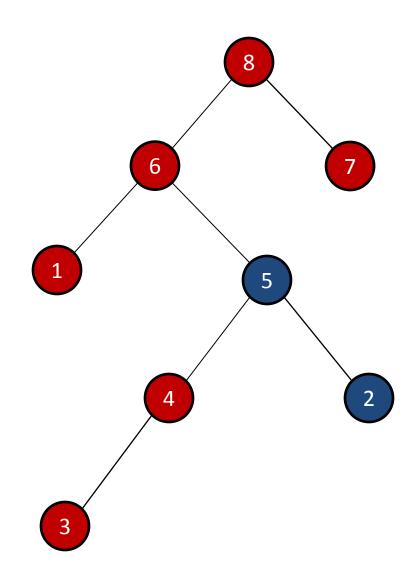
- Replace root with leaf
- Swap with largest child
 - Still violates heap property



- Replace root with leaf
- Swap with largest child
- Swap with largest child again
 - Still violates heap property

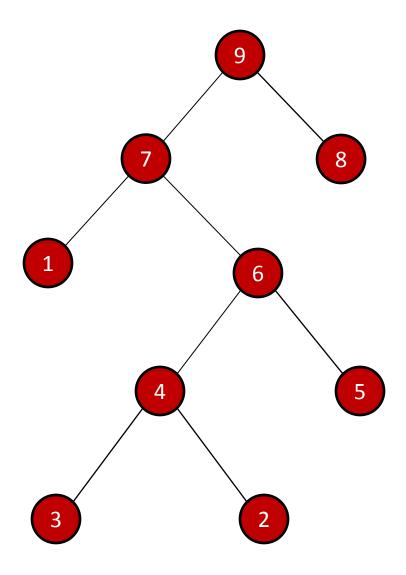


- Replace root with leaf
- Swap with largest child
- Swap with largest child again
- Swap with largest child again
 - Now a proper heap



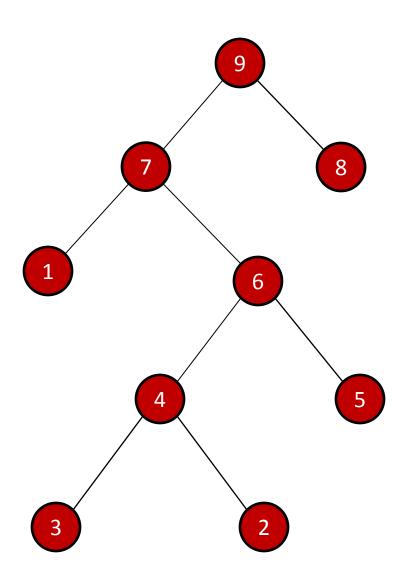
Insert(item)

- Add item as a leaf
 - Again, trust us, this will turn out to be easy
- While item > its parent
 - Swap with parent
 - Compare it to the next level up



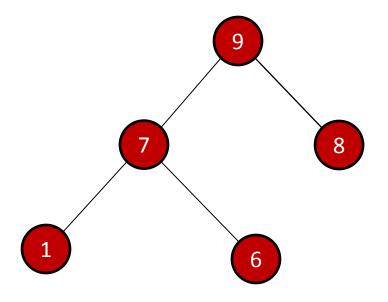
Analysis

- Both algorithms
 - Move nodes up/down tree
 - Perform a constant amount of work at each level
- So their execution time is
 O(h)
 - Where h is the tree's height
- Again, this is good, if the tree is balanced, bad otherwise



Complete binary trees

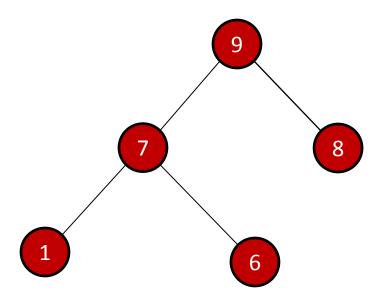
- A complete binary tree is a binary tree in which
 - Every level of the tree is full,
 except possibly the last
 - Can't add anymore nodes
 - Every node is shifted as far to the left as possible



 Complete trees are optimally balanced

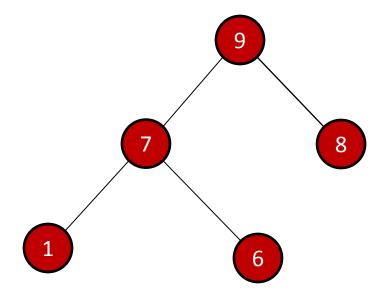
Binary heaps

- A binary heap is a
 - Complete binary tree
 - That satisfies the heap property
- Great!
- How do we ensure that the heap is a complete binary tree?



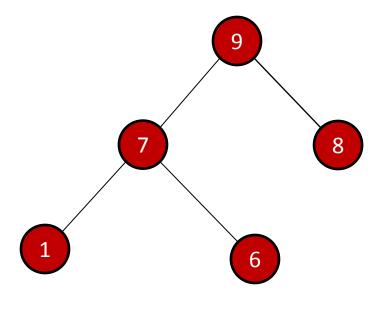
Embedding in an array

- It turns out that any complete binary tree can be embedded an array in a particularly cleaver way
- We can compute
 - The position of its parent in the array,
 - and the positions of its children,
 - directly from its own position



Embedding in an array

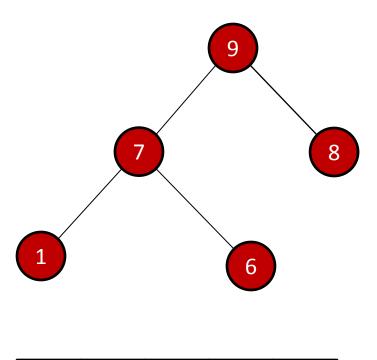
- Store the root in the first element (element 0)
- For any node
 - Let i be its position in the array (for the root, i = 0)
 - Store its **left child** at position 2i + 1
 - Store its **right child** at position 2i + 2
 - Its parent can be found at position $\lfloor (i-1)/2 \rfloor$
- Trust me that this works :-)





Why is this a good representation?

- Very fast
 - Can just allocate a big array and then never have to call new again
- Last element is always a leaf
 - Remember our algorithms needed to add/remove leaves?

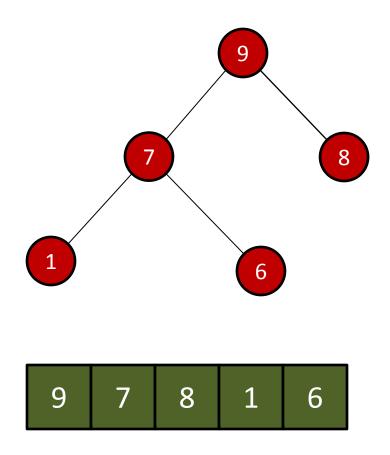




Representing a heap using an array

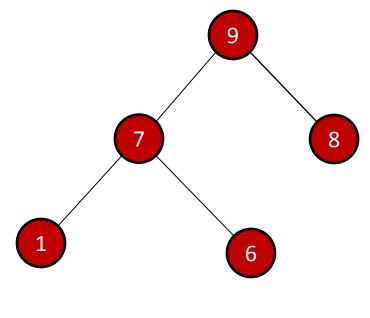
- Assume we have an extra field for the array to keep track of the size of the heap
- Define the following utility procedures:

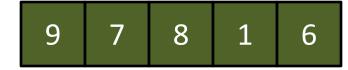
```
Parent(int i)
  return (i-1)/2
Left(int i)
  return 2*i+1
Right(int i)
  return 2*i+2
```



Heap insertion using the array representation

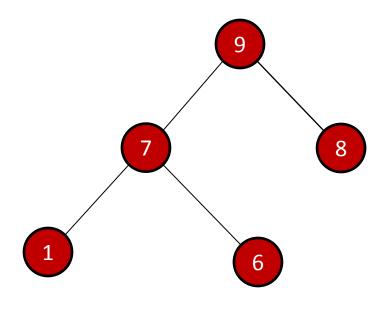
```
HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
        A[Parent(i)] < key
    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```

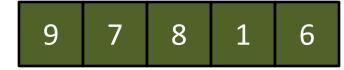




Inserting 10

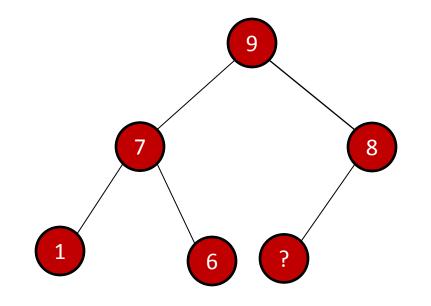
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    A[i] = A[Parent(i)]
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```

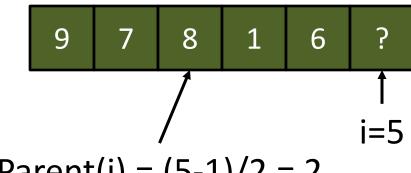




Check parent

```
HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
        A[Parent(i)] < key
    A[i] = A[Parent(i)]
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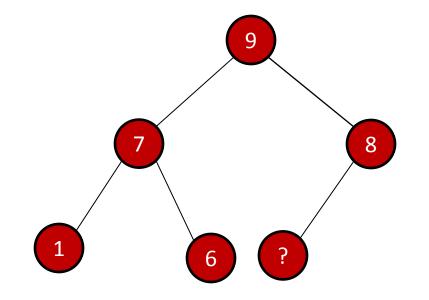


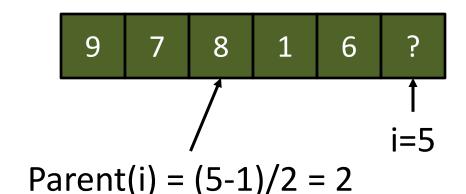


Parent(i) =
$$(5-1)/2 = 2$$

8 < 10, so A[Parent(i)] < key

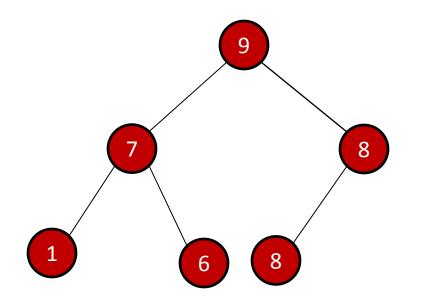
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HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
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    A[i] = A[Parent(i)]
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  A[i] = key
```

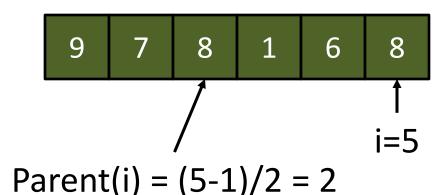




Copy parent down

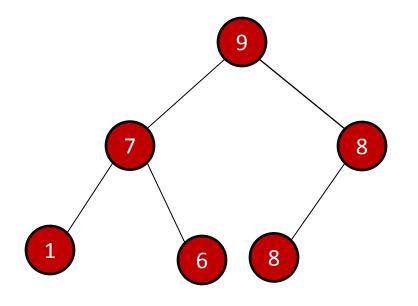
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HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
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    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```

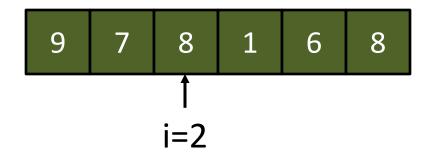




And move up tree

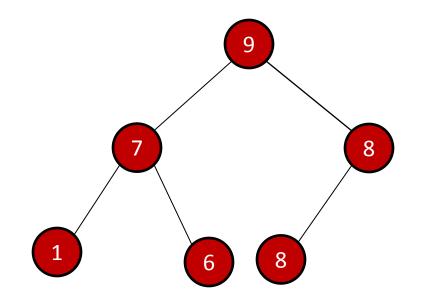
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  A.size = A.size + 1
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  while i>0 and
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    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```

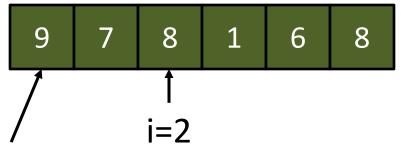




Check parent

```
HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
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    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```



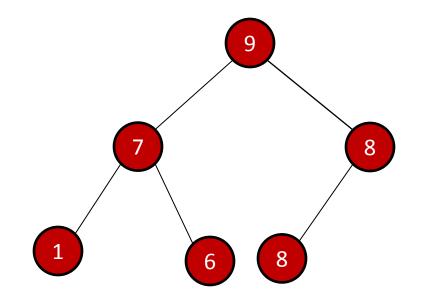


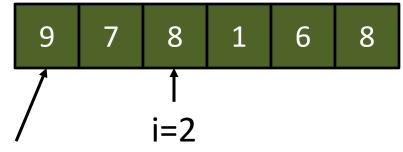
Parent(i) =
$$(2-1)/2 = 0$$

(remember int arithmetic rounds down)

9 < 10, so A[Parent(i)] < key

```
HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
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  A[i] = key
```



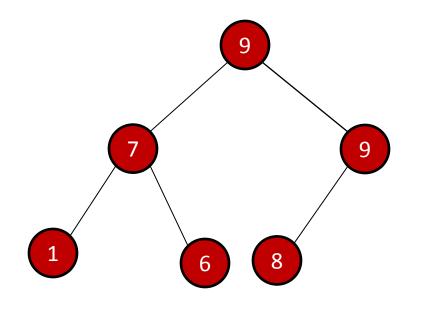


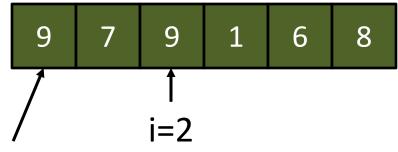
Parent(i) =
$$(2-1)/2 = 0$$

(remember int arithmetic rounds down)

Copy parent down

```
HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
        A[Parent(i)] < key
    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```



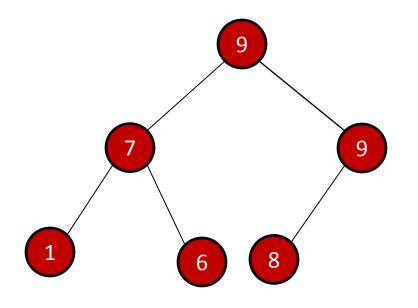


Parent(i) =
$$(2-1)/2 = 0$$

(remember int arithmetic rounds down)

Move up

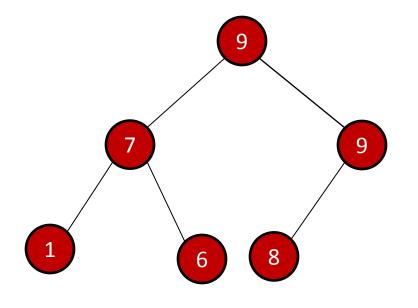
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HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
        A[Parent(i)] < key
    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```

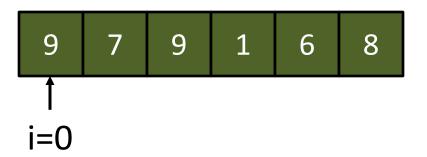




Can't move farther

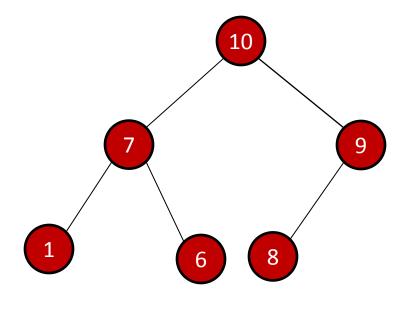
```
HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
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    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```

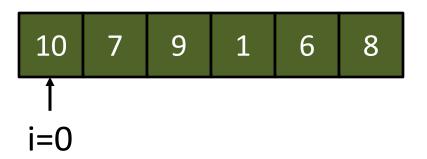




Store the new key

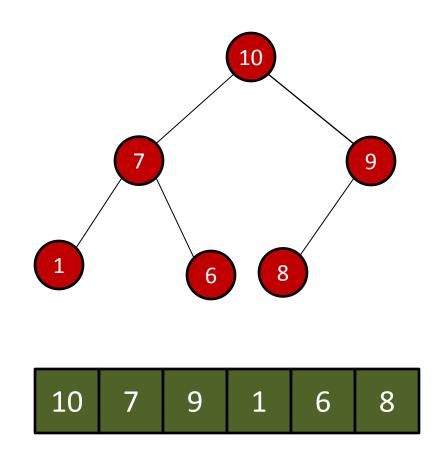
```
HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
        A[Parent(i)] < key
    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```





Done!

```
HeapInsert(A, key)
  A.size = A.size + 1
  i = A.size
  while i>0 and
        A[Parent(i)] < key
    A[i] = A[Parent(i)]
    i = Parent(i)
  A[i] = key
```



Notice that this is once again a valid heap

Extracting an element

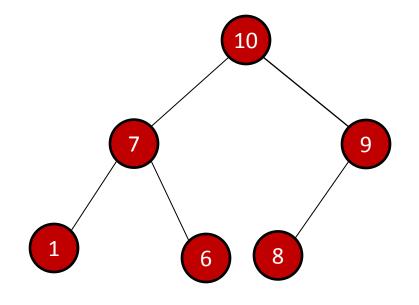
HeapExtractMax(A)

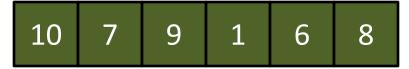
max = A[0]

A[0] = A[A.size]

A.size--

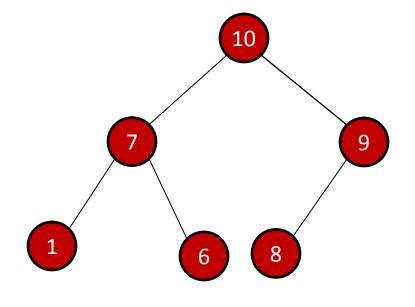
Heapify(A,0)

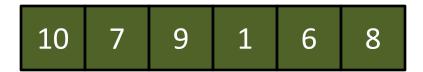




Extracting an element

```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```





Here we go!

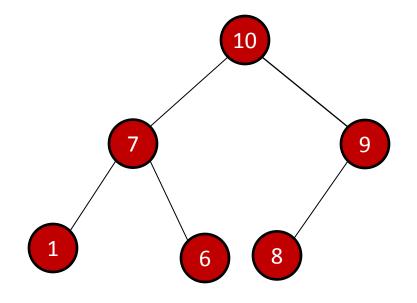
HeapExtractMax(A)

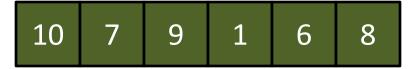
max = A[0]

A[0] = A[A.size]

A.size--

Heapify(A,0)





Remember the max (the root)

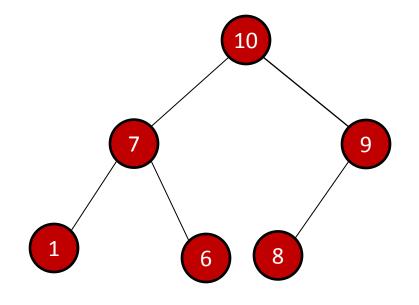
HeapExtractMax(A)

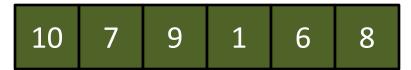
max = A[0]

A[0] = A[A.size]

A.size--

Heapify(A,0)





Move the last leaf to the root

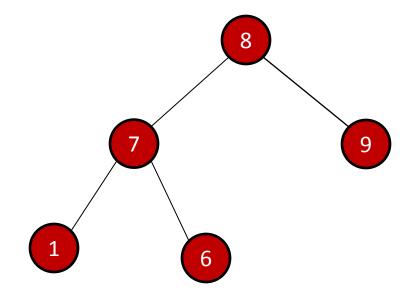
HeapExtractMax(A)

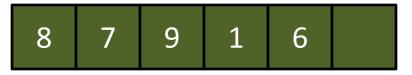
max = A[0]

A[0] = A[A.size]

A.size--

Heapify(A,0)





Move the last leaf to the root

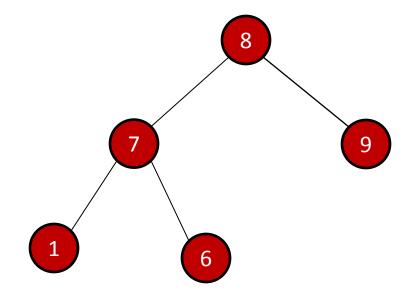
HeapExtractMax(A)

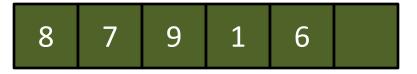
max = A[0]

A[0] = A[A.size]

A.size--

Heapify(A,0)





Re-heapify

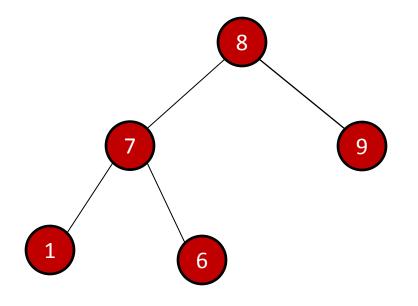
HeapExtractMax(A)

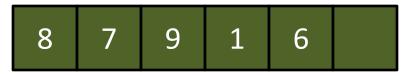
max = A[0]

A[0] = A[A.size]

A.size--

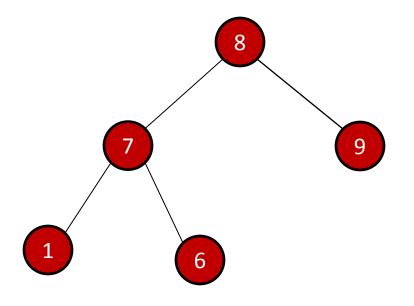
Heapify(A,0)

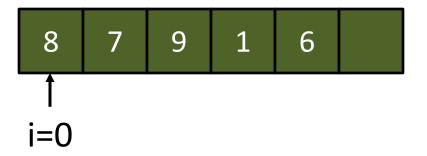




Re-heapify

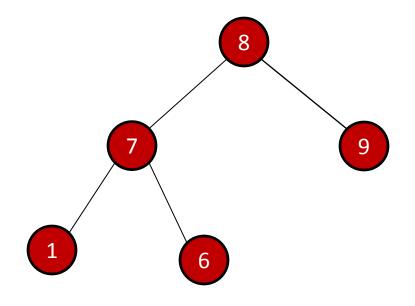
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

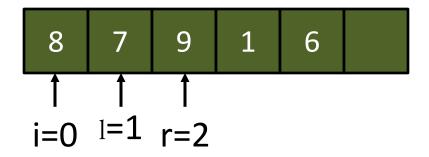




Find the left- and right-children

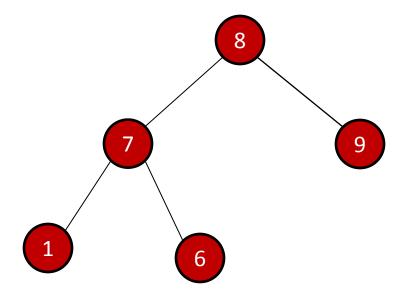
```
Heapify(A, i)
 I = Left(i)
  r = Right(i)
  if I≤A.size and A[I]>A[i]
   largest = 1
  else
   largest = i
  if r \le A.size and A[r] > A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

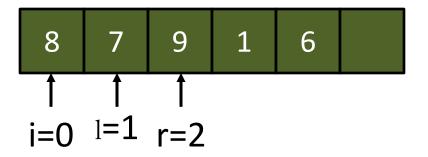




A[I] not > A[i]

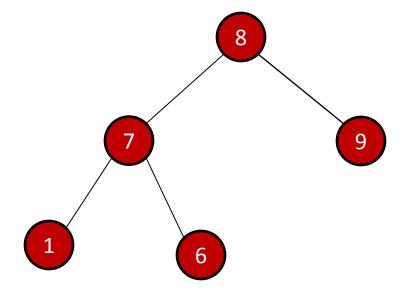
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

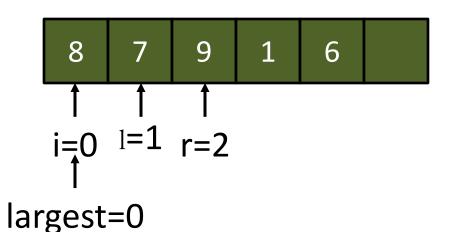




So largest = i

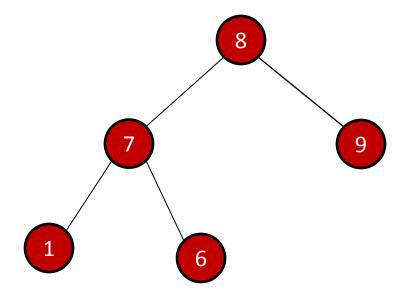
```
Heapify(A, i)
 I = Left(i)
  r = Right(i)
  if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
  if r \le A.size and A[r] > A[largest]
   largest = r
  if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

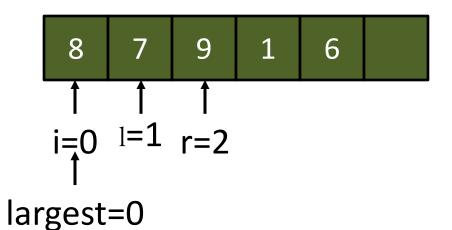




A[r] > A[largest]

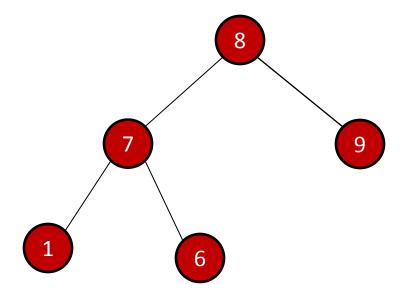
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

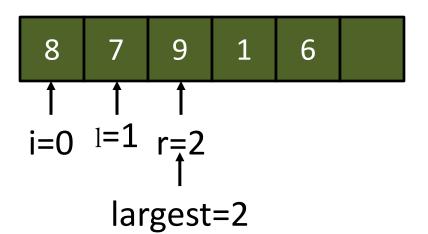




So update largest

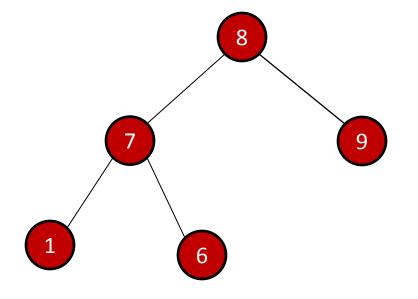
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

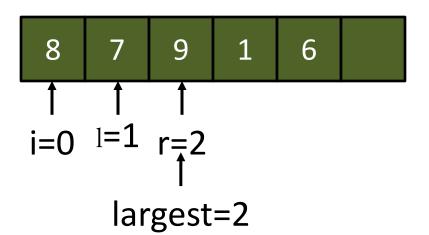




largest isn't i

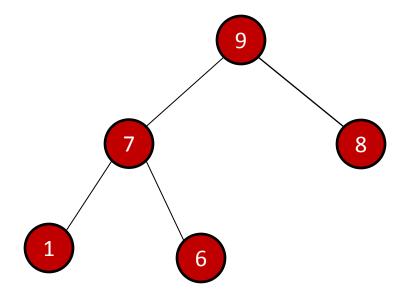
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

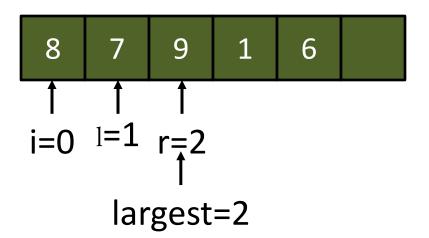




So swap with i

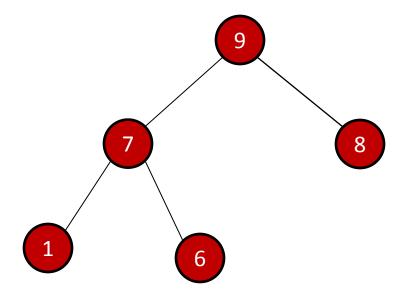
```
Heapify(A, i)
 I = Left(i)
  r = Right(i)
  if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
  if r \le A.size and A[r] > A[largest]
   largest = r
  if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

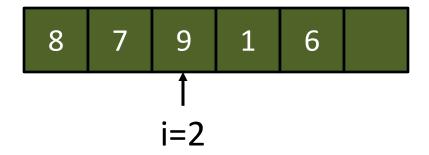




And recurse

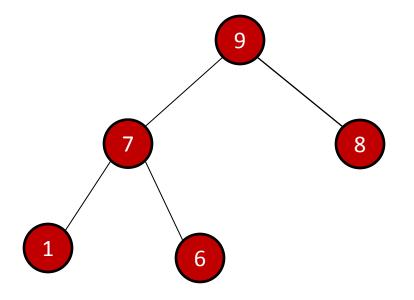
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

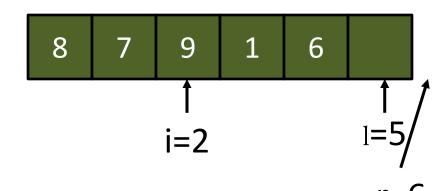




Find children

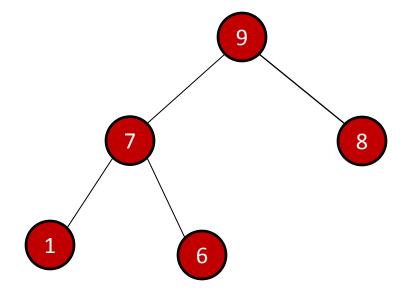
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

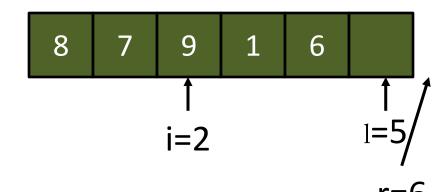




I is off the end of the heap

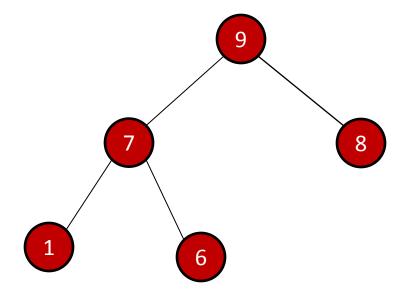
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

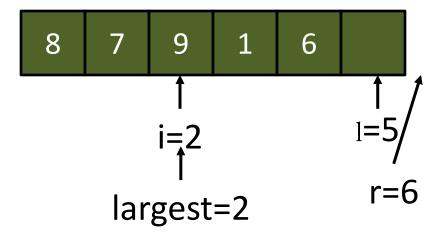




So largest is i

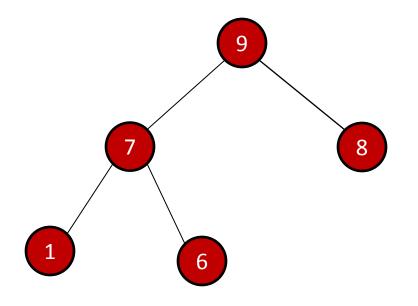
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

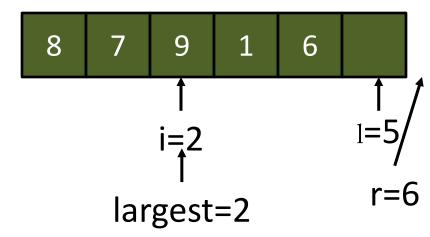




r is also off the end of the heap

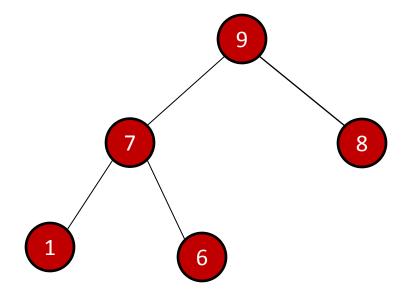
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

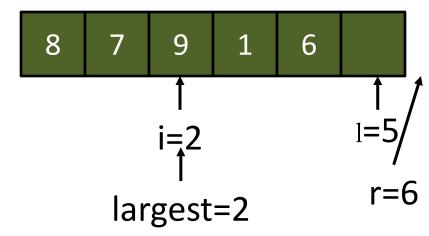




largest=i

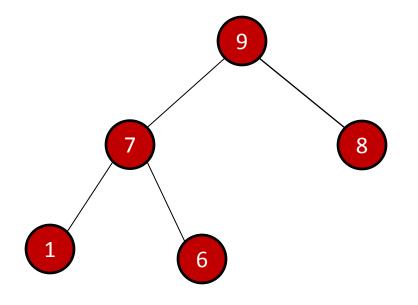
```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```

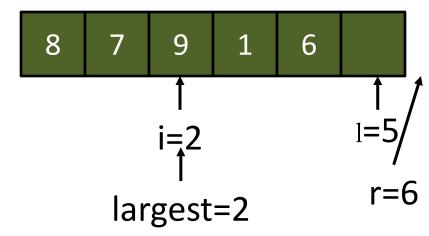




So we're done

```
Heapify(A, i)
 I = Left(i)
 r = Right(i)
 if I≤A.size and A[I]>A[i]
   largest = I
 else
   largest = i
 if r≤A.size and A[r]>A[largest]
   largest = r
 if largest≠i
   swap A[i] and A[largest]
   Heapify(A, largest)
```





next time: applications of binary heaps