A GUIDE TO USE NET_DIFF

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1 General

Net_Diff is a software for GNSS Download, Positioning and Analysis.

It provides functions of SPP/PPP/DSPP/DPPP/RTK, it can also applied in SPP/PPP with BeiDou augmentation information.

It provides data analysis, including coordinate plotting, satellite number, PDOP, satellite skyview, satellite number, omc, positioning residuals and so on.

It also provides IGS data and products download.

The software is available on GitHub: https://github.com/YizeZhang/Net_Diff. You can find the latest version on the website.

2 How to Install

After you download files from GitHub, please follow the steps to install Net_Diff.

1 Click *gzip-1.3.12-1-setup.exe* and install gzip. For example, after install it, gzip.exe is under C:\Program Files (x86)\GnuWin32\bin\

2

a) If you have installed MATLAB R2017a or MATLAB Runtime version 9.2 (R2017a) in your computer.

Open /for_redistribution_files_only/ and click Net_Diff.exe

b) If not.

Open /for_redistribution/ and click **Net_Diff_Installer_web.exe** to install MATLAB Runtime and Net_Diff. Please keep your computer connected to internet while installing. It will take a few minutes to download MATLAB Runtime, please be patient.

After finish installing, you can find the execute file from the installed program directory, like C:\Program Files\Net_Diff\. If your Windows OS is under C:\, Net_Diff may can't read and write files under C:\. In this case, it is recommended to copy C:\Program Files\Net_Diff\ to other disk.

3 Copy C:\Program Files (x86)\GnuWin32\bin\gzip.exe to the folder of Net Diff.

3 How to Run

After install the software properly, you can start to run it.

Click **Net_Diff.exe**, a dos-like window will appear, then after a few seconds, the main GUI of Net_Diff will show as below.



Fig. 1 Main GUI of Net_Diff

The dos-like widow is also the processing status window. It gives you the information of the software processing status information.

Generally, the information can be divided into 3 kinds, i.e. INFO, WARN, ERROR. INFO just tells you the action you did in the software. WARN is a warning information of the when you use this software. It is not a severe problem. ERROR is the error information, which is a big issue and will certainly affect your positioning result if you don't handle it properly. Only after you solve the errors, you can get best positioning results.

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                         Wet_Diff, v1.0
 software for GNSS Download, Positioning and Analysis
https://github.com/YizeZhang/Net_Diff/
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                                23:12:57 Load configuration file done.
23:13:16 Incorrect year and doy, please check!
23:13:44 Writing configuration file...
           INFO-
           ERROR-
           INFO-
                                23:13:47 Finish writing Control File!
23:14:08 No DCB file. DCB will set as 0
23:14:08 Writing configuration file...
           INFO:
           INFO
                                 23:14:12 Start processing...
```

Fig. 2 INFO, WARN and ERROR information in processing status window

3.1 Download

Click **Process** → **Download** or **Ctrl+D** to change to download page.

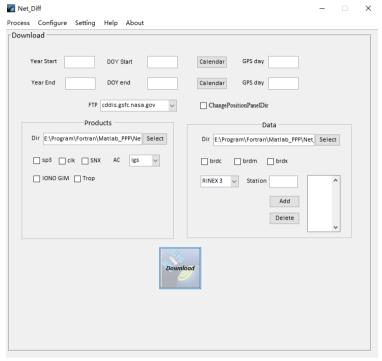


Fig. 3 Download Page

In this page, you can download the IGS data and products you want.

Please check the hint information on each uicontrol to know their functions.

What should be noticed is that:

- (1) When download IGS observation data, the station name is a four-character name. Although the file name of RINEX 3 has adopts the long name format, the software will transform it into a RINEX 2-like file name.
- (2) When download IGS final clock, although the clock file name is end up with .clk_30s, the software will delete _30s and rename it as .clk. This is to unify the file name of all clock products.
- (3) Please keep in mind that you have install gzip and have copy gzip.exe to the same folder of Net_Diff.exe, otherwise Net_Diff would not uncompress the downloaded file.
- (4) If you check *ChangePositionPanelDir*, and change to **Positioning panel** from **Download panel**, the directory of observation data, orbit, clock and output would also change to the same directory of products and data in *Download panel*.

3.2 Positioning

Net_Diff Process Configure Setting Help About Positioning Setting File Year 2018 DOY 157 Calendar GPST:20043 EOP File Input\FOP txt Select Update Start 2018-06-06 00:00:00 End 2018-06-06 23:59:59 Ant File Input\igs14 2000.atx Select Update Obs Type RINEX V Select GLO&Leap test\data\ Input\GLOFre.txt Orbit Bro... V Select Iono Type KIo... E:\Program\Fortra Select test\data\ Select P1C1 DCB Input/P1C11806.DCB test\data\ Select Update Elevation Lim 10 Download GNSS BSX Select Update E:\data\dcb\ Max PDOP 100 Coordinate Tropsphere GPT2_... V SAAS V VMF1 V Rover wtza XYZ... V 4075578.148 931853.028 4801570.166 XYZ... U.0000 0.000 DownRNX SINEX Header ☑ GPS ☐ GLONASS ☐ BDS ☐ GAL ☐ QZSS ☐ IRNSS ~ Frequency L1L2 Mode SPP/PPP V Observation Code Estimation KF ~ Combination Iono-Fr... V CycleSlip GF MW LLI P1L1 Est. Io... Code&Phase Error (m) 1 0.01 SPP Temp. PPP Temp. Wt. & RUN Smooth No V Hatch V 300 sec

Click **Process** - **Positioning** or **Ctrl+P** to change to positioning page.

Fig. 4 Positioning Page

In this page, you can set your settings for positioning.

An easier way to start positioning is use positioning template firstly. When click pushbutton *SPP Temp*, it provides a basic SPP template. When click pushbutton *PPP Temp*, it provides a basic PPP template. When click pushbutton *RTK Temp*, it provides a basic RTK template. Based on the template, you can change the settings according to your own requirement.

There are some regulations or points when you change the settings:

- (1) The **Start time** and **End time** should strictly follow the format like: 2017-06-07 00:00:00. It is a 19-character string.
- (2) As mentioned above, the name of RINEX observation file strictly follows RINEX 2. So if you are using the long-name RINEX 3 file or from your own receiver, please change the file name following the format of RINEX 2.11.
- (3) When processing RTK or DSPP/DPPP, the file of rover station and base station should under the same observation file directory.
- (4) The default *observation file type* is RINEX. If you choose X71_I, X71_Q, or X11, you should have these types of data. If you don't have, please ignore them and don't choose these types.
- (5) When the *Orbit* or *Clock* type is SP3 or CLK, please add IGS ACs name after the file directory.

For example, your sp3 file is E:\products\igs20000.sp3, please make sure that the file directory is E:\products\igs. In fact, when you change *Orbit* or *Clock* type from broadcast to SP3 or CLK, or then select a directory using *Select* pushbutton, the directory will automatically add gbm. As gbm provides most satellites products, the default precise orbit and clock product is from gbm.

(6) Similarly, for *ION Type*, when you choose *GIM* model, please add IGS ACs name after the file directory. For example, your GIM file is E:\products\igsg0010.18i, please make sure that the file directory is E:\products\igsg. In fact, when you change *Iono Type* from others to GIM, or then select a directory using *Select* pushbutton, the directory will automatically add codg. Considering update latency and precision, the default GIM product is from cod.

If you choose **GIM** model, you can **download** the GIM file.

If you choose *Klobuchar* model, the software will find brdm file in orbit directory if the Orbit type is broadcast ephemeris. If it is SP3, then the software will find brdm file in Ionosphere file directory.

If you choose **BeiDou 14** or **BeiDou Grid** model, you should have a standard BeiDou 14 parameter or grid file. If you don't have, please ignore it and don't use this model.

- (7) Please update EOP file and Antenna File when you are processing PPP/DPPP/Long Baseline RTK. If you use GLONASS data, please update GLONASS Frequency & Leap second file. Although most of time, these files doesn't update frequently or don't have so much influence on the result.
- (8) If you are processing PPP/DPPP/Long Baseline RTK, please check that if you have *Ocean Load Coefficient* of the station in Tide.txt. The Tide.txt is under the folder of Input and not shown in GUI, you have to update it by hand. Although most of time, ocean load tide doesn't have so much influence on the result.
- (9) **P1C1 DCB** file only provide the P1C1 DCB of GPS. As its value is very stable, you can **Update** it even once a year.
- (10) **GNSS BSX** file contains not only GPS P1C1 DCB, but also Multi-GNSS and Multi-frequency DCB. If you are processing single frequency or other combinations except L1L2 combination and not use broadcast file(As DCB/TDG contains in broadcast file), you can **Update** GNSS BSX file
- (11) When you set **Wet delay** as 0, it means the software will not estimate troposphere parameter. If it is greater than 0, troposphere parameter will be estimated. If the estimation mode is LS(Least Square), the troposphere will be estimated every wet delay time. If it is KF(Kalman Filter), it will be estimated as a random walk model, with a 1cm/sqrt(hour) walk step.
- (12) When the processing modes are *PCOR/PCOR+Orb/Zone PPP*, the BDS WADS PPP panel will show and you should have corresponding files. If you don't know these, please ignore them and don't choose these processing modes.
- (13) When the processing mode is RTK, the RTK panel will show and you can choose proper RTK Mode and AR Mode. As for Partial AR, although the software provides three options of Yes 1, Yes 2 and No, it is always recommended that you choose Yes 2, although it may takes a little

more time to process RTK, but it is worthy in aspect of fix rate and precision.

- (14) If you use *Long Baseline RTK* mode, please remember to check *Est. Iono* (Estimate Ionosphere). If you don't estimate ionosphere parameter, it is very hard to fix the ambiguity for long baseline.
- (15) If you want to forbidden the use of some satellites, you can click *Sat. Health* (Satellite Health) and uncheck the satellites you want.
- (16) The pushbutton of *SINEX* and *Header* means reading approximate station coordinate from a SINEX file or header of observation file.

When click pushbutton *Write*, it writes preparation file of Control.txt and Coor_Table.txt for positioning. This would be useful if you want to debug the source code of Net_Diff. When click pushbutton *Wt.& Run*, it writes preparation file of Control.txt and Coor_Table.txt and start positioning.

You can check the hint information on each uicontrol to know their functions. However, as there are so many combinations of positioning settings, it is recommended to have your own try using your data.

3.3 Analysis

Click **Process** Analysis or **Ctrl+A** to change to analysis page. If you are from positioning page, the coordinate file and log file will automatically change to the results you just processed.

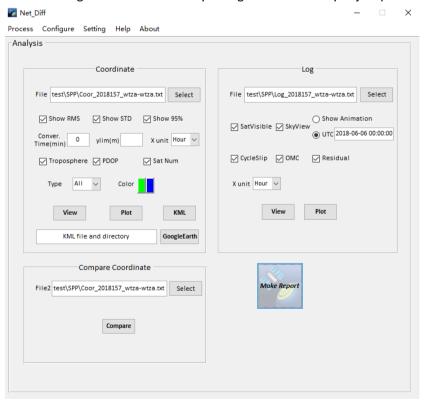


Fig. 5 Analysis Page

In this page, you can get analysis the positioning results and make positioning report through

pushbutton of Plot and Make Report.

You can also make kml file in pushbutton *KML* and check the real positioning location on Google earth using pushbutton *GoogleEarth*(Make sure that you have installed Google Earth).

You can compare two positioning results in *Compare Coordinate* panel.

Please check the hint information on each uicontrol to know their functions.

3.4 Others

In the Configure menu, you can select **Save Configuration** or **Ctrl+S** to save your settings in positioning panel as a .cfg file. And you can select **Load Configuration** or **Ctrl+L** to load the existed .cfg file. This would be helpful if you want to do the same or similar positioning next time.

In the Setting menu, you can select voice hint in Chinese (*Voice(中文*)) or English (*Voice(English)*). If you don't want to use this function, please uncheck it.

In the Help menu, you can also open this help document using **How to use** or **Ctrl+H**. You can also find some resource website on **DataSource**. Besides, you can find **Website** of Net_Diff on GitHub, the latest version of Net_Diff will be uploaded on it, please remember to update it.

There are some examples in the folder of test on GitHub, including data, results and .cfg file. You can load the .cfg file and test them in your Net_Diff.

4 How to Debug

If you have bugs when processing Net_Diff, you can turn to debug it.

The GUI is in fact to generate two files, Control.txt and Coor_Table.txt. And then the core execute file **Net_Diff.dll** in Input folder will read these two files and start processing.

To start debug Net_Diff:

- (1) Download the src of Net_Diff from GitHub, which is under the src branch.
- (2) Use Visual Studio to make a new solution of Net_Diff, and then load all src into the solution. Please make sure that you have installed Visual Fortran Compiler.
- (3) Copy the Control.txt and Coor_Table.txt to your solution directory, or set your working directory the same as Net_Diff.
- (4) Start to debug it!

5 Others

Please keep an eye on processing status window when you are using Net_Diff, which will tell you your processing status. Or open voice hint so that you can turn to do other things while waiting.

If the processing status window doesn't refresh, try to press enter in processing status window to refresh.

If the positioning processing doesn't work, check if Net_Diff.dll from last operation is still working in your task management window. If yes, please kill it and then retry Net_Diff. If it still doesn't work, close Net_Diff and restart it. So it is recommended to save the configuration every time.

If you have any questions or suggestions, please contact me: zhyize@163.com.

Thank you for using Net_Diff.