

Lösungen

① a $f(x,y) = y - x = z$

$$H_c = \{(x,y) \in \mathbb{R}^2 \mid y - x = c\}$$

$$y - x = c \Leftrightarrow y = x + c$$

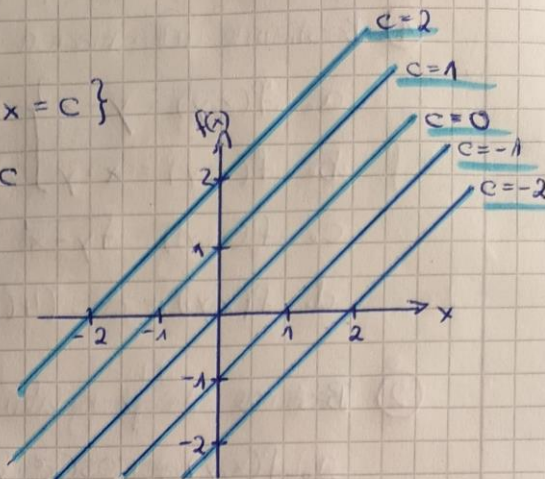
$$c = -2 : y = x - 2$$

$$c = -1 : y = x - 1$$

$$c = 0 : y = x$$

$$c = 1 : y = x + 1$$

$$c = 2 : y = x + 2$$



b $f(x,y) = x \cdot y = z$

$$H_c = \{(x,y) \in \mathbb{R}^2 \mid x \cdot y = c\}$$

$$x \cdot y = c \Leftrightarrow y = \frac{c}{x} = c \cdot \frac{1}{x}$$

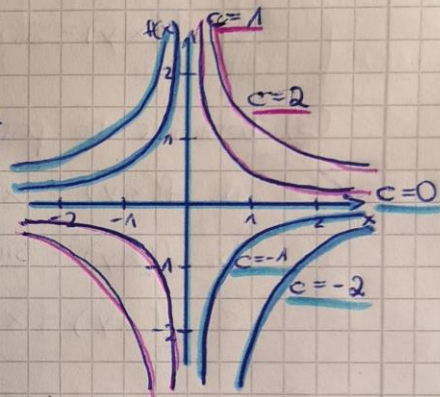
$$c = -2 : y = -2 \cdot \frac{1}{x}$$

$$c = -1 : y = -\frac{1}{x}$$

$$c = 0 : y = 0 \vee x = 0$$

$$c = 1 : y = \frac{1}{x}$$

$$c = 2 : y = 2 \cdot \frac{1}{x}$$



c $f(x,y) = \sqrt{y-x} = z$

$$H_c = \{(x,y) \in \mathbb{R}^2 \mid \sqrt{y-x} = c\}$$

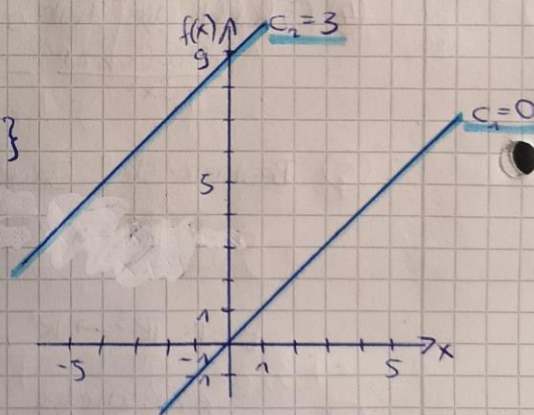
$$\sqrt{y-x} = c \mid ()^2 \text{ da } c > 0$$

$$y - x = c^2$$

$$y = x + c^2$$

$$c_1 = 0 : y = x$$

$$c_2 = 3 : y = x + 3^2 = x + 9$$



d $f(x,y) = \cos(4(x^2+y^2) - 2\pi) = z$

$$H_c = \{(x,y) \in \mathbb{R}^2 \mid \cos(4(x^2+y^2) - 2\pi) = 1\}$$

$$\cos(\alpha) = 1 \Leftrightarrow \alpha = k \cdot 2\pi, k \in \mathbb{Z}$$

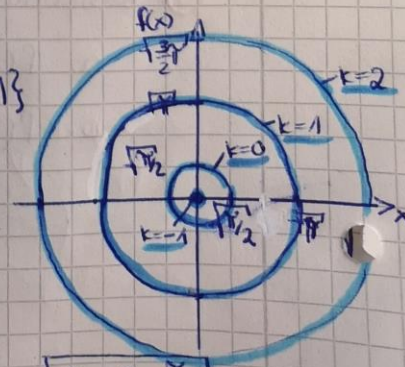
$$4(x^2+y^2) - 2\pi = k \cdot 2\pi$$

$$4(x^2+y^2) = k \cdot 2\pi + 2\pi$$

$$x^2+y^2 = (k+1) \cdot \frac{\pi}{2} \cdot \frac{1}{4}$$

$$x^2+y^2 = (k+1) \cdot \frac{\pi}{2}, k \in \mathbb{Z}$$

→ Kreise um den Ursprung mit Radius $r_k = \sqrt{(k+1) \cdot \frac{\pi}{2}}, k \in \mathbb{Z}$



② a $f(x,y) = \cos(x^2+y)$
 $f_x(x,y) = -\sin(x^2+y) \cdot 2x$
 $f_y(x,y) = -\sin(x^2+y) \cdot 1$

c $f(x,y) = \sin(x^2 \cdot e^{3y})$
 $f_x(x,y) = 2xe^{3y} \cos(x^2 \cdot e^{3y})$
 $f_y(x,y) = x^2 \cdot 3 \cdot e^{3y} \cos(x^2 \cdot e^{3y})$

b $f_x(x,y,z) = e^{x^2y} \cdot 2xy^3$
 $f_y(x,y,z) = x^2 e^{x^2y} y^2 + 2ye^{x^2y}$
 $f_z(x,y,z) = 1$
 $f_{xy}(x,y,z) = e^{x^2y} \cdot x^2 \cdot 2xy^3 + e^{x^2y} \cdot 6xy^2$
 $= f_{yx}(x,y,z)$
 $f_{xz}(x,y,z) = 0$
 $= f_{zx}(x,y,z)$
 $f_{yz}(x,y,z) = 0$
 $= f_{zy}(x,y,z)$

③ a $f(x,y) = x^2 3y + x^3$
 $f_x(x,y) = 6xy + 3x^2$
 $f_y(x,y) = 3x^2$
 $f_{xy}(x,y) = 6x$
 $= f_{yx}(x,y)$
 $f_{xx}(x,y) = 6y + 6x$
 $f_{yy}(x,y) = 0$

b $f(x,y) = \sin(x^2 \cdot 3y)$
 $f_x(x,y) = 6xy \cos(3x^2y)$
 $f_y(x,y) = 3x^2 \cos(3x^2y)$
 $f_{xy}(x,y) = 6x \cos(3x^2y) - 18x^3y \sin(3x^2y)$
 $= f_{yx}(x,y)$
 $f_{xx}(x,y) = 6y \cos(3x^2y) - 36x^2y^2 \sin(3x^2y)$
 $f_{yy}(x,y) = -9x^4 \sin(3x^2y)$

c $f(x,y) = xe^{xy}$
 $f_x(x,y) = e^{xy} + xye^{xy}$
 $f_y(x,y) = x^2 e^{xy}$
 $f_{xy}(x,y) = 2xe^{xy} + yx^2 e^{xy} = f_{yx}(x,y)$
 $f_{xx}(x,y) = ye^{xy} + ye^{xy} + xy^2 e^{xy}$
 $f_{yy}(x,y) = x^3 e^{xy}$

④ $\frac{\partial^2 \omega(x,y,z)}{\partial x^2}$, $\frac{\partial^2 \omega(x,y,z)}{\partial z^2}$, $\frac{\partial^2 \omega(x,y,z)}{\partial y \partial z}$ berechnen
 $= \omega_{xx}(x,y,z)$ $= \omega_{zz}(x,y,z)$ $= \omega_{yz}(x,y,z) = \omega_{zy}(x,y,z)$
da stetig

$\omega_x(x,y,z) = 2x$, $\omega_{xx}(x,y,z) = 2$
 $\omega_z(x,y,z) = y$, $\omega_{zz}(x,y,z) = 0$
 $\omega_{zy}(x,y,z) = 1$

$\omega_{xx} - (\omega_{zz} + \omega_{yz}) = 0$

$2 - (0 + 1) = 1 \neq 0$

→ Gleichung nicht erfüllt

⑤ a $f_1(x_1, x_2) = x_1 - x_2$
 $f_2(x_1, x_2) = 3x_1 + x_2 - 1$
 $f_3(x_1, x_2) = x_1^2 + 7x_2$

$$J_f(\vec{x}) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(\vec{x}) & \frac{\partial f_1}{\partial x_2}(\vec{x}) \\ \frac{\partial f_2}{\partial x_1}(\vec{x}) & \frac{\partial f_2}{\partial x_2}(\vec{x}) \\ \frac{\partial f_3}{\partial x_1}(\vec{x}) & \frac{\partial f_3}{\partial x_2}(\vec{x}) \end{pmatrix}$$

$$J_f(\vec{x}) = \begin{pmatrix} 1 & -1 \\ 3 & 1 \\ 2x_1 & 7 \end{pmatrix}, J_f\left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right) = \begin{pmatrix} 1 & -1 \\ 3 & 1 \\ 2 & 7 \end{pmatrix}$$

b $f_1(x_1, x_2, x_3) = x_1^2 - \sqrt{x_2} \cdot x_3^3 = x_1^2 - x_2^{1/2} \cdot x_3^3$
 $f_2(x_1, x_2, x_3) = 3\cos(x_1 + x_2) + \sqrt{x_3^3} = 3\cos(x_1 + x_2) + x_3^{3/2}$

$$J_f(\vec{x}) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(\vec{x}) & \frac{\partial f_1}{\partial x_2}(\vec{x}) & \frac{\partial f_1}{\partial x_3}(\vec{x}) \\ \frac{\partial f_2}{\partial x_1}(\vec{x}) & \frac{\partial f_2}{\partial x_2}(\vec{x}) & \frac{\partial f_2}{\partial x_3}(\vec{x}) \end{pmatrix}$$

$$= \begin{pmatrix} 2x_1 & -\frac{1}{2} \cdot \frac{1}{\sqrt{x_2}} x_3^3 & -3\sqrt{x_2} x_3^2 \\ 3\cos(x_1 + x_2) & 3\cos(x_1 + x_2) & \frac{3}{2}x_3^{1/2} \end{pmatrix}$$

$$J_f\left(\begin{pmatrix} 2 \\ 8 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 4 & -\frac{1}{2 \cdot \sqrt{8}} & -3\sqrt{8} \\ 3\cos(8) & 3\cos(8) & \frac{3}{2} \end{pmatrix}$$

$$J_f\left(\begin{pmatrix} -1 \\ 1 \\ 3 \end{pmatrix}\right) = \begin{pmatrix} -2 & -\frac{27}{2} & -27 \\ 3 & 3 & \frac{3\sqrt{3}}{2} \end{pmatrix}$$

⑥ $X: [\alpha, \beta] \subseteq \mathbb{R} \rightarrow \mathbb{R}^2, t \mapsto X(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix}$

a $f(x) = (x-3)^2, x \in [-1, 4]$

1. $x_1 = t$

$$x_2 = f(x) = (t-3)^2$$

$$X: [-1, 4] \rightarrow \mathbb{R}^2, t \mapsto X(t) = \begin{pmatrix} t \\ (t-3)^2 \end{pmatrix}$$

▽ Anfangspunkt: $x_1 = -1 = t$
 $\Rightarrow \begin{pmatrix} -1 \\ 16 \end{pmatrix} = X(-1)$

○ Endpunkt: $x_1 = 4 = t$
 $\Rightarrow X(4) = \begin{pmatrix} 4 \\ 1 \end{pmatrix}$

2. $t = x_1 - 3 \rightarrow x_1 = t + 3$

$$x_2 = f(x) = t^2$$

$$X: [-1, 4] \rightarrow \mathbb{R}^2, t \mapsto X(t) = \begin{pmatrix} t+3 \\ t^2 \end{pmatrix}$$

Anfangspunkt: $x_1 = -1 \rightarrow t = -4$
 berechnen $\Rightarrow \begin{pmatrix} -1 \\ 16 \end{pmatrix} = X(-4) = x_1 - 3$

Endpunkt: $x_1 = 4 \rightarrow t = x_1 - 3 = 1$
 $X(1) = \begin{pmatrix} 4 \\ 1 \end{pmatrix}$

b $f(x) = m(x - \alpha) + b, x \in [0, |\alpha|]$

1. $x_1 = t$

$x_2 = f(x) = m(t - \alpha) + b$

$X: [0, |\alpha|] \rightarrow \mathbb{R}^2, t \mapsto X(t) = \begin{pmatrix} t \\ m(t - \alpha) + b \end{pmatrix}$

2. $t = x_1 - \alpha \rightarrow x_1 = t + \alpha$

$x_2 = f(x) = mt + b$

$X: [0, |\alpha|] \rightarrow \mathbb{R}^2, t \mapsto X(t) = \begin{pmatrix} t + \alpha \\ mt + b \end{pmatrix}$

▽ Anfangspunkt: $x_1 = 0 = t$ mit 1.: $X(0) = \begin{pmatrix} 0 \\ -\alpha m + b \end{pmatrix}$

oder

$x_1 = 0 \rightarrow t = 0 - \alpha$ mit 2.: $X(-\alpha) = \begin{pmatrix} -\alpha + \alpha \\ m \cdot (-\alpha) + b \end{pmatrix} = \begin{pmatrix} 0 \\ -\alpha m + b \end{pmatrix}$

0 Endpunkt: $x_1 = |\alpha| = t$ mit 1.:

$X(|\alpha|) = \begin{pmatrix} |\alpha| \\ m(|\alpha| - \alpha) + b \end{pmatrix} = \begin{cases} \begin{pmatrix} \alpha \\ b \end{pmatrix}, \alpha \geq 0 \\ \begin{pmatrix} -\alpha \\ -2m\alpha + b \end{pmatrix}, \alpha < 0 \end{cases}$

oder

$x_1 = |\alpha| \rightarrow t = |\alpha| - \alpha = \begin{cases} 0, \alpha \geq 0 \\ -2\alpha, \alpha < 0 \end{cases}$ mit 2.:

$X(|\alpha| - \alpha) = \begin{cases} \begin{pmatrix} \alpha \\ b \end{pmatrix}, \alpha \geq 0 \\ \begin{pmatrix} -\alpha \\ -2m\alpha + b \end{pmatrix}, \alpha < 0 \end{cases}$

Hinweis: beide Parameterdarstellungen beschreiben immer dieselbe Kurve, es ist also jeweils egal und bringt dasselbe Ergebnis, ob man mit 1. oder 2. Anfangs- und Endpunkt berechnet