

1 Lesson Objectives

2 The z-Transform

3 Properties of the z-Transform

4 Inverse z-Transform

At the end of this lesson, you should be able to

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

Lesson Objectives

Digital Signal
Processing

TRAN
Hoang Tung

At the end of this lesson, you should be able to

- 1** calculate the z-Transform of any given signals/systems

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

Lesson Objectives

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

At the end of this lesson, you should be able to

- 1 calculate the z-Transform of any given signals/systems
- 2 understand basic properties of the z-Transform

Lesson Objectives

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

At the end of this lesson, you should be able to

- 1 calculate the z-Transform of any given signals/systems
- 2 understand basic properties of the z-Transform
- 3 find any signals knowing its z-Transform

1 Lesson Objectives

2 The z-Transform

- The Direct z-Transform
- Region Of Convergence (ROC)

3 Properties of the z-Transform

4 Inverse z-Transform

The Direct z-Transform

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

Definition

The z-transform of a discrete-time signal $x(n)$ is defined as

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

where z is a complex variable.

Fourier Trans: $X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x(n) \cdot e^{-jn\omega}$

Definition

The z-transform of a discrete-time signal $x(n)$ is defined as

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

where z is a complex variable.

Notations

The z-transform of a signal $x(n)$ is denoted by

$$X(z) \equiv Z[x(n)]$$

and the relationship between $x(n)$ and $X(z)$ is indicated by

$$x(n) \xleftrightarrow{z} X(z)$$

1 Lesson Objectives

2 The z-Transform

■ The Direct z-Transform

■ Region Of Convergence (ROC)

3 Properties of the z-Transform

4 Inverse z-Transform

Region Of Convergence (ROC)

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

Definition

ROC of $X(z)$ is the set of all values of z for which $X(z)$ attains a finite value.

z-Trans: $\left\{ \begin{array}{l} X(z) \\ \text{ROC} \end{array} \right.$

$f[n]$ D_f

Region Of Convergence (ROC)

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

Definition

ROC of $X(z)$ is the set of all values of z for which $X(z)$ attains a finite value.

Exercises

Determine the z-transforms and the corresponding ROCs of the following signals:

Region Of Convergence (ROC)

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

Definition

ROC of $X(z)$ is the set of all values of z for which $X(z)$ attains a finite value.

Exercises

Determine the z-transforms and the corresponding ROCs of the following signals:

$$1 \quad x_1(n) = [0, 0, 3, 1, 6]$$

$$\Rightarrow X_1(z) = \sum_{n=-\infty}^{\infty} x(n) \cdot z^{-n} = x(0) + x(1) \cdot z^{-1} + x(2) \cdot z^{-2} + \dots$$

$$= 3 \cdot z^{-2} + z^{-3} + 6 \cdot z^{-4}$$

$$\text{ROC: } z \neq 0$$

$$C \setminus \{0\}$$


Definition

ROC of $X(z)$ is the set of all values of z for which $X(z)$ attains a finite value.

Exercises

Determine the z-transforms and the corresponding ROCs of the following signals:

1 $x_1(n) = [0, 0, 3, 1, 6]$

2 $x_2(n) = [1, 2, 5, 0, 0]$ 

$$\mathbb{C} \setminus \{\infty\} \quad z \neq \infty$$

Definition

ROC of $X(z)$ is the set of all values of z for which $X(z)$ attains a finite value.

Exercises

Determine the z-transforms and the corresponding ROCs of the following signals:

$$1 \quad x_1(n) = [0, 0, 3, 1, 6]$$

↑

$$2 \quad x_2(n) = [1, 2, 5, 0, 0]$$

↑

$$3 \quad x_3(n) = [2, 1, 2, 5]$$

↑

Region Of Convergence (ROC)

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

Definition

ROC of $X(z)$ is the set of all values of z for which $X(z)$ attains a finite value.

Exercises

Determine the z-transforms and the corresponding ROCs of the following signals:

$$1 \quad x_1(n) = [0, 0, 3, 1, 6]$$

↑

$$2 \quad x_2(n) = [1, 2, 5, 0, 0]$$

↑

$$3 \quad x_3(n) = [2, 1, 2, 5]$$

↑

ROC of *finite-duration* signals

Entire z-plane, except possibly the point $z = 0$ and/or $z = \infty$

Region Of Convergence (ROC)

$$1 + q + q^2 + q^3 + \dots = \frac{1 - q^{n+1}}{1 - q}$$

$$\left\{ \begin{array}{l} 1 + q + q^2 + \dots = \frac{1}{1 - q} \\ |q| < 1 \end{array} \right.$$

Digital Signal
Processing

TRAN
Hoang Tung

What about *infinite-duration* signals?

Determine the z-transform of the signal:

$$x(n) = \left[\underset{\uparrow}{1}, \left(\frac{1}{2}\right), \left(\frac{1}{2}\right)^2, \left(\frac{1}{2}\right)^3, \dots, \left(\frac{1}{2}\right)^n, \dots \right]$$

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

$$X(z) = \sum x(n) \cdot z^{-n} = 1 + \frac{1}{2} \cdot z^{-1} + \left(\frac{1}{2}\right)^2 z^{-2} + \dots$$

$$= 1 + \frac{1}{2z} + \left(\frac{1}{2z}\right)^2 + \left(\frac{1}{2z}\right)^3 + \dots$$

$$= \frac{1}{1 - \frac{1}{2z}} \quad \left(\text{if } \left| \frac{1}{2z} \right| < 1 \right)$$

$$X(z) = \frac{2z}{2z - 1}$$

ROC: $|z| > \frac{1}{2}$

Region Of Convergence (ROC)

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

What about *infinite-duration* signals?

Determine the z-transform of the signal:

$$x(n) = \left[1_{\uparrow}, \left(\frac{1}{2}\right), \left(\frac{1}{2}\right)^2, \left(\frac{1}{2}\right)^3, \dots, \left(\frac{1}{2}\right)^n, \dots \right]$$

Solution

$$X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}}, \text{ ROC: } |z| > \frac{1}{2}$$

Region Of Convergence (ROC)

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

What about *infinite-duration* signals?

Determine the z-transform of the signal:

$$x(n) = \left[1_{\uparrow}, \left(\frac{1}{2}\right), \left(\frac{1}{2}\right)^2, \left(\frac{1}{2}\right)^3, \dots, \left(\frac{1}{2}\right)^n, \dots \right]$$

Solution

$$X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}}, \text{ ROC: } |z| > \frac{1}{2}$$

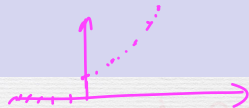
Plot the ROC?



Exercise

Determine the z-transform of the signal:

$$x(n) = \alpha^n u(n) = \begin{cases} \alpha^n & \text{if } n \geq 0 \\ 0 & \text{if } n < 0. \end{cases}$$



Exercise

Determine the z-transform of the signal:

$$x(n) = \alpha^n u(n) = \begin{cases} \alpha^n & \text{if } n \geq 0 \\ 0 & \text{if } n < 0. \end{cases}$$

Solution

$$X(z) = \frac{1}{1 - \alpha z^{-1}}, \text{ ROC: } |z| > |\alpha|$$

Exercise

Determine the z-transform of the signal:

$$x(n) = -\alpha^n u(-n-1) = \begin{cases} 0 & \text{if } n \geq 0 \\ -\alpha^n & \text{if } n < 0. \end{cases}$$

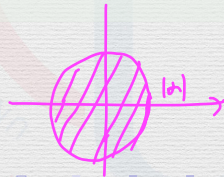
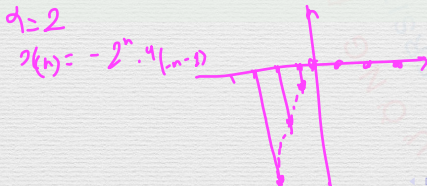
Exercise

Determine the z-transform of the signal:

$$x(n) = -\alpha^n u(-n-1) = \begin{cases} 0 & \text{if } n \geq 0 \\ -\alpha^n & \text{if } n < 0. \end{cases}$$

Solution

$$X(z) = \frac{1}{1 - \alpha z^{-1}}, \text{ ROC: } |z| < |\alpha|$$



Exercise

Determine the z-transform of:

$$x(n) = \alpha^n u(n) + \beta^n u(-n - 1)$$

Exercise

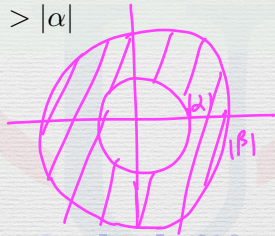
Determine the z-transform of:

$$x(n) = \alpha^n u(n) + \beta^n u(-n - 1)$$

Solution

There are two cases:

- $|\beta| < |\alpha|$: two ROCs do not overlap, $X(z)$ does not exist
- $|\beta| > |\alpha|$: ROC of $X(z)$ is $|\beta| > |z| > |\alpha|$



ROC Summary

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The z-Transform

The Direct
z-Transform

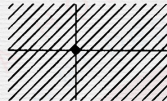
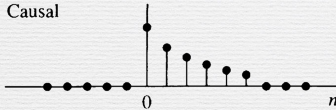
Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

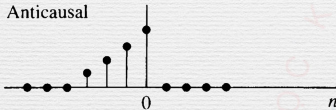
Finite-Duration Signals

Causal



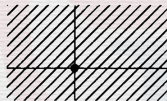
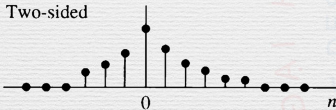
Entire z-plane
except $z = 0$

Anticausal



Entire z-plane
except $z = \infty$

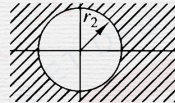
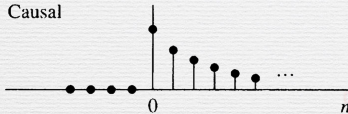
Two-sided



Entire z-plane
except $z = 0$
and $z = \infty$

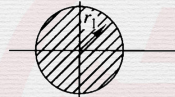
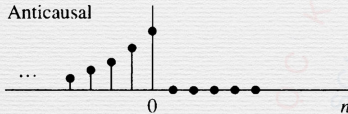
Infinite-Duration Signals

Causal



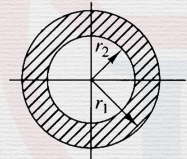
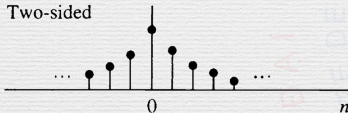
$$|z| > r_2$$

Anticausal



$$|z| < r_1$$

Two-sided



$$r_2 < |z| < r_1$$

Some Common z-Transform Pairs

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

The Direct
z-Transform

Region Of
Convergence
(ROC)

Properties
of the
z-Transform

Inverse
z-Transform

	Signal, $x(n]$	z-Transform, $X(z)$	ROC
1	$\delta(n)$	1	All z
2	$u(n)$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
3	$a^n u(n)$	$\frac{1}{1 - az^{-1}}$	$ z > a $
4	$na^n u(n)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $
5	$-a^n u(-n - 1)$	$\frac{1}{1 - az^{-1}}$	$ z < a $
6	$-na^n u(-n - 1)$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z < a $

1 Lesson Objectives

2 The z-Transform

3 Properties of the z-Transform

4 Inverse z-Transform

The z-transform is a **very powerful tool** for the study of discrete-time signals thanks to some of its very important properties:

- Linearity
- Time shifting
- Scaling in the z-domain
- Time reversal
- Differentiation in the z-domain
- Convolution

$$x_1(n) * x_2(n)$$

$$X_1(z) \cdot X_2(z)$$

Linearity

If $x_1(n) \xrightarrow{z} X_1(z)$ and $x_2(n) \xrightarrow{z} X_2(z)$ then

$$x(n) = a_1 x_1(n) + a_2 x_2(n) \xrightarrow{z}$$

$$a_1 X_1(z) + a_2 X_2(z)$$

Linearity

If $x_1(n) \xrightarrow{z} X_1(z)$ and $x_2(n) \xrightarrow{z} X_2(z)$ then

$$x(n) = a_1 x_1(n) + a_2 x_2(n) \xrightarrow{z} X(z) = a_1 X_1(z) + a_2 X_2(z)$$

$$\begin{aligned} X(z) &= \sum x(n) \cdot z^{-n} \\ &= \sum (a_1 \dots + a_2 \dots) z^{-n} \\ &= a_1 \cdot \sum \dots z^{-n} + a_2 \sum \dots z^{-n} \\ &= a_1 \cdot X_1(z) + a_2 X_2(z) \end{aligned}$$

Linearity

If $x_1(n) \xleftrightarrow{z} X_1(z)$ and $x_2(n) \xleftrightarrow{z} X_2(z)$ then

$$x(n) = a_1 x_1(n) + a_2 x_2(n) \xleftrightarrow{z} X(z) = a_1 X_1(z) + a_2 X_2(z)$$

Time Shifting

If

$$x(n) \xleftrightarrow{z} X(z)$$

then

$$x(n - k) \xleftrightarrow{z}$$

Linearity

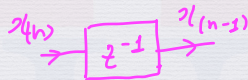
If $x_1(n) \xleftrightarrow{z} X_1(z)$ and $x_2(n) \xleftrightarrow{z} X_2(z)$ then

$$x(n) = a_1 x_1(n) + a_2 x_2(n) \xleftrightarrow{z} X(z) = a_1 X_1(z) + a_2 X_2(z)$$

Time Shifting

If

$$x(n) \xleftrightarrow{z} X(z)$$



then

$$x(n-k) \xleftrightarrow{z} z^{-k} X(z)$$

Scaling in the z-domain

For any constant a , if

$$x(n) \xrightarrow{z} X(z), \quad \text{ROC} : r_1 < |z| < r_2$$

then

$$a^n x(n) \xrightarrow{z}$$

Scaling in the z-domain

For any constant a , if

$$x(n) \xleftrightarrow{z} X(z),$$

$$ROC : r_1 < |z| < r_2$$

then

$$a^n x(n) \xleftrightarrow{z} X(a^{-1}z),$$

$$ROC : |a|r_1 < |z| < |a|r_2$$

$$X\left(\frac{z}{a}\right)$$

Exercise

$$1 + q + q^2 + \dots + q^{N-1} = \frac{1 - q^N}{1 - q}$$

Digital Signal
Processing

TRAN
Hoang Tung

Exercise

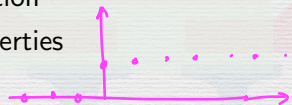
Determine the z-transform of the signal:

$$x(n) = \begin{cases} 1, & 0 \leq n \leq N-1 \\ 0, & \text{elsewhere} \end{cases}$$



using

- Direct approach: z-transform definition
- Indirect approach: z-transform properties



Time Reversal

If

$$x(n) \xleftrightarrow{z} X(z), \quad \text{ROC} : r_1 < |z| < r_2$$

then

$$x(-n) \xleftrightarrow{z}$$

Time Reversal

If

$$x(n) \xleftrightarrow{z} X(z), \quad \text{ROC} : r_1 < |z| < r_2$$

then

$$x(-n) \xleftrightarrow{z} X(z^{-1}), \quad \text{ROC} : \frac{1}{r_2} < |z| < \frac{1}{r_1}$$

Differentiation in the z-domain

If

$$x(n) \xleftrightarrow{z} X(z)$$

then

$$nx(n) \xleftrightarrow{z} -z \frac{dX(z)}{dz}$$

Recall: Discrete Convolution

$$y[n] \equiv (x * h)[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

Convolution Property

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

Recall: Discrete Convolution

$$y[n] \equiv (x * h)[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

Convolution of Two Sequences

If $x_1(n) \xleftrightarrow{z} X_1(z)$ and $x_2(n) \xleftrightarrow{z} X_2(z)$ then

$$x(n) = x_1(n) * x_2(n) \xleftrightarrow{z}$$

Recall: Discrete Convolution

$$y[n] \equiv (x * h)[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

Convolution of Two Sequences

If $x_1(n) \xleftrightarrow{z} X_1(z)$ and $x_2(n) \xleftrightarrow{z} X_2(z)$ then

$$x(n) = x_1(n) * x_2(n) \xleftrightarrow{z} X(z) = X_1(z)X_2(z)$$

Computing the Convolution using z-Transform

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

Step-by-step

- 1 Compute the z-transform of the two signals
- 2 Multiply the two z-transforms $X(z) = X_1(z)X_2(z)$
- 3 Find the inverse z-transform of $X(z)$

Computing the Convolution using z-Transform

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

Step-by-step

- 1 Compute the z-transform of the two signals
- 2 Multiply the two z-transforms $X(z) = X_1(z)X_2(z)$
- 3 Find the inverse z-transform of $X(z)$

Exercise

Compute the convolution $x(n)$ of the signals:

$$x_1(n) = [1, -2, 1]$$

$$x_2(n) = \begin{cases} 1, & 0 \leq n \leq 5 \\ 0, & \text{elsewhere} \end{cases}$$

Computing the Convolution using z-Transform

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

1 Lesson Objectives

2 The z-Transform

3 Properties of the z-Transform

4 Inverse z-Transform

Partial-Fraction Expansion

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

- 1 Express $X(z)$ as a linear combination

$$X(z) = \alpha_1 X_1(z) + \alpha_2 X_2(z) + \cdots + \alpha_K X_K(z)$$

where $X_k(z)$ are in the table of z-Transform pairs.

- 2 Use the table and get

$$x(n) = \alpha_1 x_1(n) + \alpha_2 x_2(n) + \cdots + \alpha_K x_K(n)$$

Example

Determine the partial-fraction expansion of:

$$X(z) = \frac{1}{1 - 1.5z^{-1} + 0.5z^{-2}}$$

Partial-Fraction Expansion

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

Example

Determine the partial-fraction expansion of:

$$X(z) = \frac{1}{1 - 1.5z^{-1} + 0.5z^{-2}}$$

Hint

$$\frac{X(z)}{z} = \frac{A_1}{z - 1} + \frac{A_2}{z - 0.5}$$

Partial-Fraction Expansion

Digital Signal
Processing

TRAN
Hoang Tung

Objectives

The
z-Transform

Properties
of the
z-Transform

Inverse
z-Transform

Example

Determine the partial-fraction expansion of:

$$X(z) = \frac{1}{1 - 1.5z^{-1} + 0.5z^{-2}}$$

Hint

$$\frac{X(z)}{z} = \frac{A_1}{z - 1} + \frac{A_2}{z - 0.5}$$

Attention: Be careful with the ROC