

# Robot grocery shopping (in partially observable settings)

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Rodrigo Gomes, Xiaomin Wang, Dustin Tran

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1. Background on POMDPs
2. Grocery shopping as planning in a POMDP
3. Results!

background on POMDPs

the planner we used

the task in the POMDP framework

the task in the POMDP framework

Play with it!



[github.com/dustinvtran/bayesrl](https://github.com/dustinvtran/bayesrl)