

# Path-based depth-first search for strong and biconnected components

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# Outline

## 1 Introduction

## 2 Strong Components

- Thinking about Strong Components
- Purdom and Munro's high-level algorithm
- Contribution



# Characterastics of Gabow's Algorithms

- **One-pass algorithm.** But for the algorithm of strong components, what we have learned from the textbook is a two-pass algorithm, by which we must traverse the whole graph twice.



# Several Questions

- LOWPOINT?
- Ear decomposition?
- Compele version?
- Robbin's Theorem?



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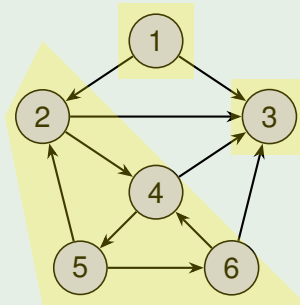


# Review: What have we learned from the textbook?

## Concepts of Strong Components

- Two **mutually reachable** vertices are in the same *strong component*.

### Example



# Review: What have we learned from the textbook?

## Algorithms to Find Strong Components

- Idea: Run DFS twice. Once on the original graph  $G$ , once on the *transposition* of  $G^T$ .
- Trick: Using *finishing times* of each vertex computed by the first DFS.
- Linear time complexity:  $O(V + E)$



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# Pseudo-Code

```
1  H = G;  
2  while H still has a vertex v  
3      start a new path P = (v);  
4      while P is not empty  
5          if the last vertex vk of P has an edge (vk, w)  
6              if w belongs to P  
7                  contract the cycle vi(w), ... , vk, both  
                        in H and in P; /* w and vi are  
                        identical. */  
8              else  
9                  add w to P, as the new last vertex of P;  
10             end if
```

- Note that *contracting* means selecting one vertex as a representation and **merging** others rather than deleting them.



# Pseudo-Code (Continued)

```
11     else
12         output v_k as a vertex of the strong component
           graph;
13         delete v_k from both H and P;
14     end if
15 end
16 end
```



# Assessment

- The time consumption of each statement in the pseudo-code is clear. Total time complexity is linear, except the statement in line 7:

```
7 contract the cycle v_i(w), ... , v_k, both in H and in  
  P; /* w and v_i are identical. */
```

- Problem is how to merge in linear time while keeping the next time accessing this vertex still in constant time.
- Therefore, a good data structure for disjoint set merging is needed.



# Outline

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- Contribution



# His Contribution

- He gave a simple list-based implementation that achieves linear time.
- Use only stacks and arrays as data structure.



# New algorithm to discover strong components

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## Procedure 1: STRONG(G)

---

empty stacks S and B;

**for**  $v \in V$  **do**

$I[v] = 0$ ;

$c = n$ ;

**for**  $v \in V$  **do**

**if**  $I[v] = 0$  **then**

        DFS( $v$ );

---



# New algorithm to discover strong components

---

## Procedure 2: DFS( $v$ )

---

```
PUSH( $v, S$ );  $I[v] = TOP(S)$ ; PUSH( $I[v], B$ );  
/* add  $v$  to the end of  $P$  */  
for  $edges(v, w) \in E$  do  
    if  $I[v] = 0$  then  
        DFS( $w$ );  
    else /* contract if necessary */  
        while  $I[w] < B[TOP[B]]$  do  
            POP( $B$ );  
        if  $I[v] = B[TOP(B)]$  then  
            /* number vertices of the next strong component */  
            POP( $B$ );  
            increase  $c$  by 1;  
            while  $I[v] \leq TOP[S]$  do  
                 $I[POP(S)] = c$ ;
```

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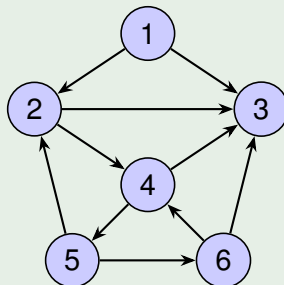
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S		I
		1	0
		2	0
		3	0
		4	0
		5	0
		6	0

## Graph H



- Call Stack: STRONG()
- This state is the first after initialized. DFS(1) is going to be called.





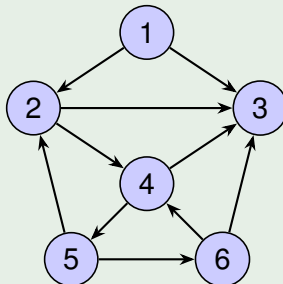
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I
1	1	1
		2
		3
		4
		5
		6

## Graph H



- Call Stack:  $\text{STRONG}() \rightarrow \text{DFS}(1)$
- Code: **for** edges  $(v, w) \in E$  **do** ...
- $w = 2$ .



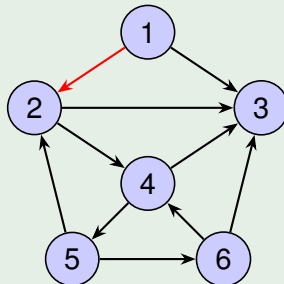
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
		3	0
		4	0
		5	0
		6	0

## Graph H



- Call Stack:  $\text{STRONG}() \rightarrow \text{DFS}(1) \rightarrow \text{DFS}(2)$
- Code: **for** edges  $(v, w) \in E$  **do** ...
- $w = 3$ .



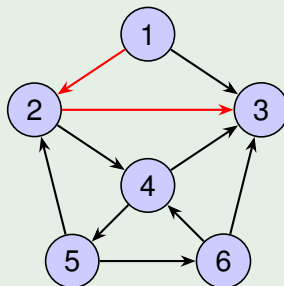
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I
1	1	1
2	2	2
3	3	3
		4 0
		5 0
		6 0

## Graph H



- Call Stack: STRONG()→DFS(1)→DFS(2)→DFS(3)
- Code: **if**  $I[v] = B[TOP(B)]$  **then** ...
- Go back.



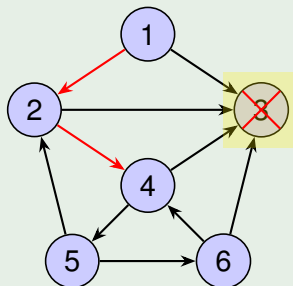
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
3	4	3	7
		4	3
		5	0
		6	0

## Graph H



- Call Stack: STRONG()→DFS(1)→DFS(2)→DFS(4)
- Code: **for** edges  $(v, w) \in E$  **do** ...
- $w = 5$ .



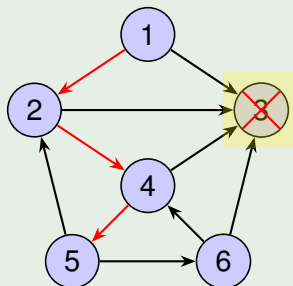
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
3	4	3	7
4	5	4	3
		5	4
		6	0

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(1) \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4) \rightarrow \text{DFS}(5)$
- Code: **for** edges  $(v, w) \in E$  **do**  $\dots$
- $w = 2$ .



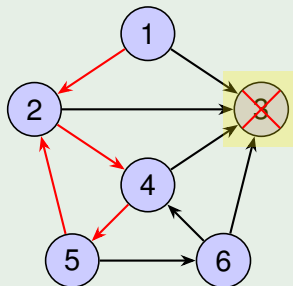
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
3	4	3	7
4	5	4	3
		5	4
		6	0

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(1) \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4) \rightarrow \text{DFS}(5)$
- Code: **while**  $I[w] < B[\text{TOP}(B)]$  **do**  $\text{POP}(B)$  ;
- Now,  $w = 2$ , contract!



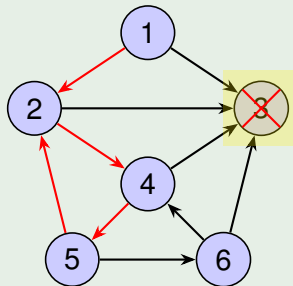
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
	4	3	7
	5	4	3
		5	4
		6	0

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(1) \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4) \rightarrow \text{DFS}(5)$
- Code: **while**  $I[w] < B[\text{TOP}(B)]$  **do**  $\text{POP}(B)$  ;
- Now,  $w = 2$ , contract!



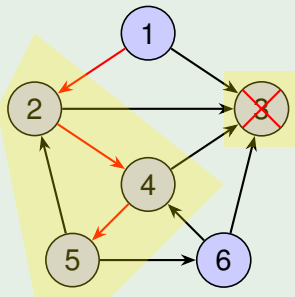
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
	4	3	7
	5	4	3
		5	4
		6	0

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(1) \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4) \rightarrow \text{DFS}(5)$
- Code: **if**  $I[w] = 0$  **then**  $\text{DFS}(w)$  ;
- $w = 6$ .





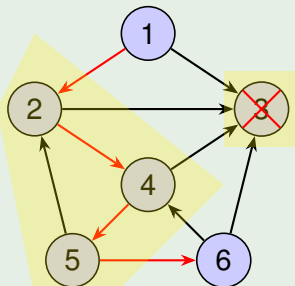
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
5	4	3	7
	5	4	3
	6	5	4
		6	5

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4) \rightarrow \text{DFS}(5) \rightarrow \text{DFS}(6)$
- Code: **for** edges  $(v, w) \in E$  **do**  $\dots$
- $w = 4$ .



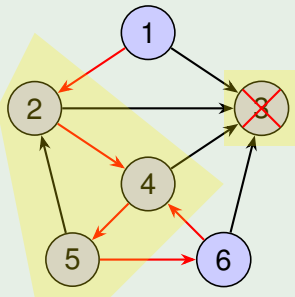
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
5	4	3	7
	5	4	3
	6	5	4
		6	5

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4) \rightarrow \text{DFS}(5) \rightarrow \text{DFS}(6)$
- Code: **while**  $I[w] < B[\text{TOP}(B)]$  **do**  $\text{POP}(B)$  ;
- Now,  $w = 4$ , contract!



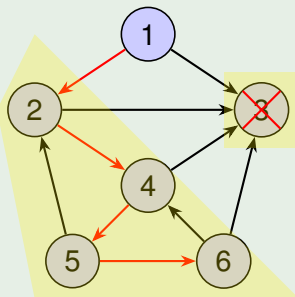
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I
1	1	1
2	2	2
	4	3
	5	4
	6	5
		6

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4) \rightarrow \text{DFS}(5) \rightarrow \text{DFS}(6)$
- Code: **if**  $I[v] = B[\text{TOP}(B)]$  **then** ...
- Go back.



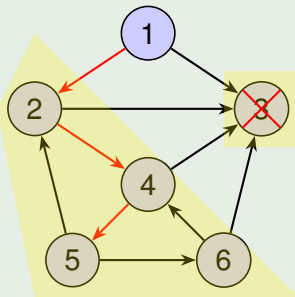
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I
1	1	1
2	2	2
	4	3
	5	4
	6	5
		6

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4) \rightarrow \text{DFS}(5)$
- Code: **if**  $I[v] = B[\text{TOP}(B)]$  **then** ...
- Go back.



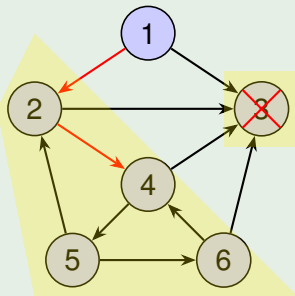
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I
1	1	1
2	2	2
	4	3
	5	4
	6	5
		6

## Graph H



- Call Stack:  $\dots \rightarrow \text{DFS}(2) \rightarrow \text{DFS}(4)$
- Code: **if**  $I[v] = B[\text{TOP}(B)]$  **then**  $\dots$
- Go back.



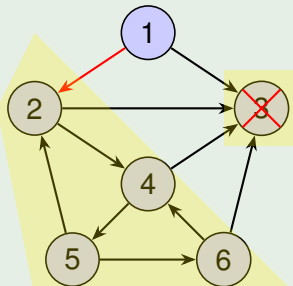
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I	I
1	1	1	1
2	2	2	2
	4	3	7
	5	4	3
	6	5	4
		6	5

## Graph H



- Call Stack: STRONG()→DFS(1)→DFS(2)
- Code: **if**  $I[v] = B[TOP(B)]$  **then** ...
- Go back. But this time, **Condition in last line is satisfied!**



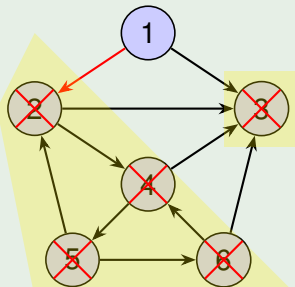
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S		I
1	1	1	1
		2	8
		3	7
		4	8
		5	8
		6	8

## Graph H



- Call Stack:  $\text{STRONG}() \rightarrow \text{DFS}(1) \rightarrow \text{DFS}(2)$
- Code: **while**  $I[v] \leq \text{TOP}(S)$  **do**  $I[\text{POP}(S)] = c$ ;
- Pop 2 from B, while 2, 4, 5, 6 in S are also popped.



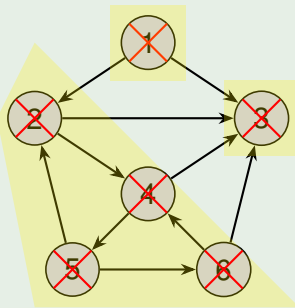
# Demo: Gabow's strong components algorithm

## Data in memory

B and S: stack. I: array.

B	S	I
		1 9
		2 8
		3 7
		4 8
		5 8
		6 8

## Graph H



- Call Stack:  $\text{STRONG}() \rightarrow \text{DFS}(1)$
- Code: **while**  $I[v] \leq \text{TOP}(S)$  **do**  $I[\text{POP}(S)] = c$ ;
- Pop the last one both in B and in S. *Finished!!*





# Summary

- The **first main message** of your talk in one or two lines.
- The **second main message** of your talk in one or two lines.
- Perhaps a **third message**, but not more than that.
- Outlook
  - Something you haven't solved.
  - Something else you haven't solved.



# For Further Reading I



A. Author.

*Handbook of Everything.*

Some Press, 1990.



S. Someone.

On this and that.

*Journal of This and That*, 2(1):50–100, 2000.

