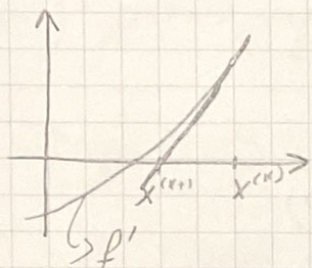


II Second order methods:

► Newton method: $x^{(k+1)} = x^{(k)} - \alpha \mathcal{H}(x^{(k)})^{-1} \nabla f(x_k)$

In \mathbb{R} , Newton method is equivalent of finding roots of f' :

$$x^{(k+1)} = x^{(k)} - \alpha \frac{f'(x^{(k)})}{f''(x^{(k)})} \sim 1D \text{ Hor...}$$



• Newton method is quadratic in convergence near local minima

► Quasi-Newton method:

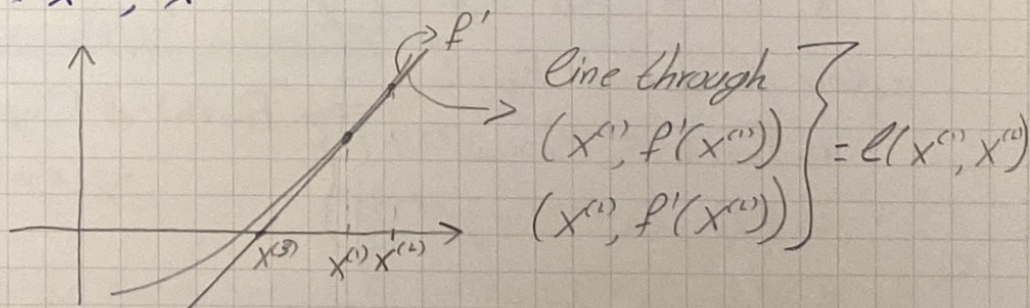
① $\mathbb{R} \rightarrow$ second method: $f \rightarrow \min \leftrightarrow f' = 0$

Suppose I don't want to compute 2nd derivative, then I do approximation of it instead.

$$f''(x^{(k)}) \approx \frac{f'(x^{(k)}) - f'(x^{(k-1)})}{x^{(k)} - x^{(k-1)}}$$

$$\Rightarrow x^{(k+1)} = x^{(k)} - \frac{f'(x^{(k)}) (x^{(k)} - x^{(k-1)})}{f'(x^{(k)}) - f'(x^{(k-1)})}$$

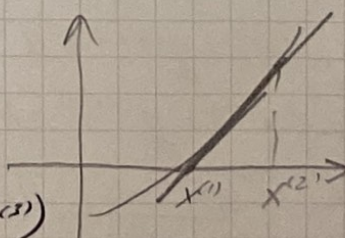
Input: $x^{(1)}, x^{(2)}$

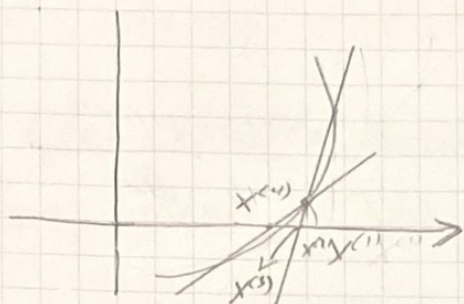


If either $x^{(1)}$ or $x^{(2)}$ is a root of f' , then

$x^{(3)} = \ell(x^{(1)}, x^{(2)}) \cap \text{x-axis}$ is again the root

Otherwise $(x^{(1)}, x^{(2)}) \rightarrow (x^{(2)}, x^{(3)})$ and proceed,





Then: If $x^{(k)}, x^{(k+1)}$ is sufficiently close to a , $f'(a) = 0$, then $x^{(k)} \xrightarrow[k \rightarrow \infty]{} a$ and this convergence is quadratic

⑥ \mathbb{R}^n , $x^{(k+1)} = x^{(k)} - \alpha Q^{(k)} g^{(k)}$

\hookrightarrow positive definite matrix $\sim H(x^{(k)})$

- Davidson - Fletcher - Powell (DFP)
- Broyden - Fletcher - Goldfarb - Shanno (BFGS)
- Variations of BFGS method

$$z^{(k)} = f(x^{(k)}), \quad g^{(k)} = \nabla f(x^{(k)})$$

Define: $F_k(x) = z^{(k)} + g^{(k)}(x - x^{(k)}) + \frac{1}{2}(x - x^{(k)})^T H^{(k)}(x - x^{(k)})$

We want to find $H^{(k)}$ as an approximation to the hessian $H(x^{(k)})$

- $H^{(1)} = \text{id}$, $k \rightarrow k+1$
- Do the line search for F_k this gives $\alpha^{(k)}$:

$$x^{(k+1)} = x^{(k)} - \alpha^{(k)} (H^{(k)})^T g^{(k)}$$

- How to define F_{k+1} ?

$$\begin{aligned} \hookrightarrow F_{k+1}(x^{(k+1)}) &= z^{(k+1)} \\ \hookrightarrow \nabla F_{k+1}(x^{(k+1)}) &= g^{(k+1)} \end{aligned} \quad \left. \vphantom{\begin{aligned} \hookrightarrow F_{k+1}(x^{(k+1)}) &= z^{(k+1)} \\ \hookrightarrow \nabla F_{k+1}(x^{(k+1)}) &= g^{(k+1)} \end{aligned}} \right\} \begin{aligned} F_{k+1}(x) &= z^{(k+1)} + g^{(k+1)}(x - x^{(k+1)}) \\ &\quad + \frac{1}{2}(x - x^{(k+1)})^T H^{(k+1)}(x - x^{(k+1)}) \end{aligned}$$

$$\hookrightarrow \nabla F_{k+1}(x^{(k)}) = g^{(k)}$$

$$\Rightarrow \nabla F_{k+1}(x) = g^{(k+1)} + H^{(k+1)}(x - x^{(k+1)})$$

$$\Rightarrow \nabla F_{k+1}(x^{(k)}) = g^{(k+1)} + H^{(k+1)}(x^{(k)} - x^{(k+1)}) = g^{(k)}$$

$$\Rightarrow H^{(k+1)}(\underbrace{x^{(k)} - x^{(k+1)}}_{s^{(k)}}) = \underbrace{g^{(k)} - g^{(k+1)}}_{g^{(k)}} \quad (\text{Notation})$$

\rightarrow

Second Equation ~ discrete second derivative^{in \mathbb{R}}

$$H^{(k+1)} S^{(k)} = y^{(k)}$$

where, $S^{(k)} = x^{(k)} - x^{(k+1)}$

$$y^{(k)} = g^{(k)} - g^{(k+1)}$$

We want:

- $H^{(k+1)}$ symmetric
- $H^{(k+1)}$ positive definite

$$(S^{(k)})^T H^{(k+1)} S^{(k)} = (S^{(k)})^T y^{(k)} > 0$$

curvature condition (either has to be checked or forced)

Let's look for $H^{(k+1)}$ in the following form:

$$H^{(k+1)} = H^{(k)} + a u u^T + b v v^T, \quad a, b > 0, \quad u, v \in \mathbb{R}^n$$

*Note: $u u^T$ is positive definite: $w^T (u u^T) w = (u^T w)^T u^T w = \langle u, w \rangle^2 > 0$ if $w \neq 0$

Take $u = y^{(k)} = g^{(k)} - g^{(k+1)}$, $v = H^{(k)} S^{(k)} = H^{(k)} (x^{(k)} - x^{(k+1)})^n \perp n$

Then a, b are derived from the second equation

$$a = \frac{1}{(y^{(k)})^T S^{(k)}}, \quad b = - \frac{1}{(S^{(k)})^T (H^{(k)})^T S^{(k)}}$$

$$H^{(k+1)} = H^{(k)} + \frac{y^{(k)} (y^{(k)})^T}{(y^{(k)})^T S^{(k)}} - \frac{H^{(k)} S^{(k)} (S^{(k)})^T (H^{(k)})^T}{\underbrace{(S^{(k)})^T (H^{(k)})^T S^{(k)}}_{\forall H^{(k)} > 0}}$$

Stochastic Gradient Descent

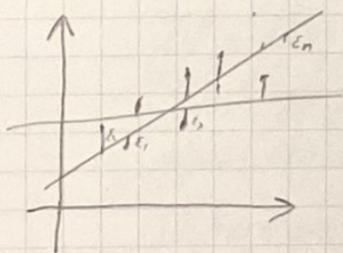
$$\min_x \frac{1}{n} \sum_{i=1}^n f_i(x), \quad x \in \mathbb{R}^m, \quad f_i: \mathbb{R}^m \rightarrow \mathbb{R}$$

$$x_1, \dots, x_m$$

$$y_1, \dots, y_m$$

*Least-squares optimization: $\frac{1}{n} \|Ax - b\|_2^2 = \frac{1}{n} \sum_{i=1}^n (a_i^T x + b_i)^2$

$$e_1^2 + e_2^2 + \dots + e_n^2 \rightarrow \min$$

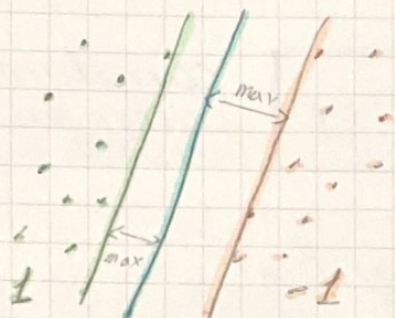


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$$* \frac{1}{n} \|Ax - b\|_2^2 + \gamma \|x\|_1 = \frac{1}{n} \sum_{i=1}^n (a_i x + b_i)^2 + \sum_{j=1}^m |x_j|$$

ℓ_1 - least squares

* SVM - Support Vector Machine



$$\frac{1}{2} \|x\|_2^2 + \frac{1}{n} \sum_{i=1}^n \min_{y \in \{-1, 1\}} \max \{0, 1 - y_i (x^T a_i - b)\}$$

* Deep Neural Networks (DNN)

$$\frac{1}{n} \sum_{i=1}^n \text{loss}(y_i, \text{DNN}(x, a_i))$$

↑ training data
↓ weights
objective to find

$$x^{(k+1)} = x^{(k)} - \alpha^{(k)} \nabla P = x^{(k)} - \alpha^{(k)} \frac{1}{n} \sum_{i=1}^n \nabla P_i(x)$$

↑ steepest descent

→ [Robbins, Monro, 1951]

$$x^{(k+1)} = x^{(k)} - \alpha^{(k)} \nabla \underline{P_{i(k)}}(x), i(k) \text{ we choose at random}$$

Example of stochastic gradient