

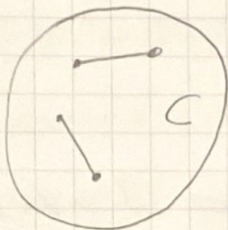
Elements of convex optimization

(1) Convex sets / convex functions

$$x_1, x_2 \in \mathbb{R}^n \quad \begin{array}{c} \nearrow x_2 \\ \nwarrow x_1 \end{array} \quad \{x \in \mathbb{R}^n : x = (1-\theta)x_1 + \theta x_2 \text{ for } \theta \in [0,1]\}$$

$C \subset \mathbb{R}^n$ is a convex set if $\forall x_1, x_2 \in C, \forall \theta \in [0,1]$

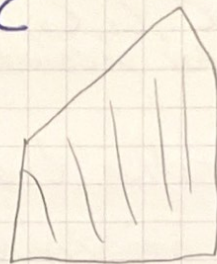
$$(1-\theta)x_1 + \theta x_2 \in C$$



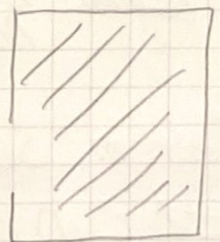
convex



not convex

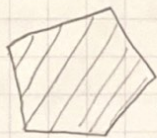


convex



not convex

$x_1, \dots, x_m \in \mathbb{R}^n$, the convex combination of x_1, \dots, x_m is the set

$$\theta_1 x_1 + \theta_2 x_2 + \dots + \theta_m x_m, \quad \theta_i \geq 0, \quad \theta_1 + \theta_2 + \dots + \theta_m = 1$$


x_1, x_2, x_3

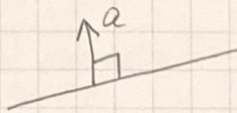
$$\theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3$$

$$\longrightarrow S \subset \mathbb{R}^n$$

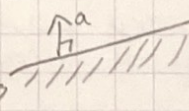
$\text{conv } S = \text{smallest convex set that contains } S$
 \uparrow
 convex hull
 $= \text{all possible convex combinations of points in } S$

Key examples:

• hyperplane $\{x : a^T x = b\}$



• half space $\{x : a^T x \leq b\}$
 convex sets

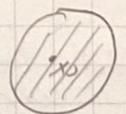


• Ellipsoids $E = \{x \in \mathbb{R}^n : (x - x_0)^T A (x - x_0) \leq 1\}$

A symmetric positive-definite matrix

In particular, if $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ ball $\|x - x_0\|_2 \leq 1$

of radius 1 is also convex



- Polyhedron is the solution of finitely many linear equalities/inequalities

$$\{x \in \mathbb{R}^n, Ax \leq b, Cx = d\}$$

$\underbrace{\quad}_m \underbrace{\quad}_n$ m inequalities $\underbrace{\quad}_p$ p equalities

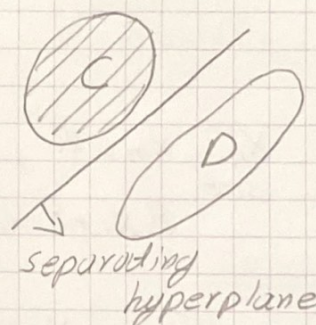
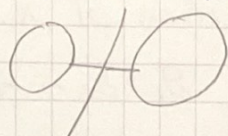
- Polyhedra are convex sets. This follows from

Lemma: If C_1, C_2, C_3, \dots are convex, then $\bigcap C_i$ is convex.
Also for uncountable functions

Theorem: Separation thm

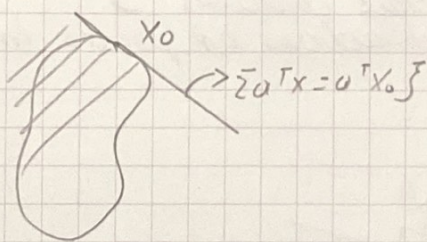
If $C, D \subset \mathbb{R}^n$ are convex and disjoint, then $\exists \alpha \neq 0, b$ s.t.
 $\alpha^T x \leq b \quad \forall x \in C$ and $\alpha^T x \geq b \quad \forall x \in D$

If C is compact then there is a strict separation (both inequalities are strict)



Supporting hyperplane of a set C

$x_0 \in \partial C$ if $\exists \alpha$ s.t. $\alpha^T x \leq \alpha^T x_0 \quad \forall x \in C$



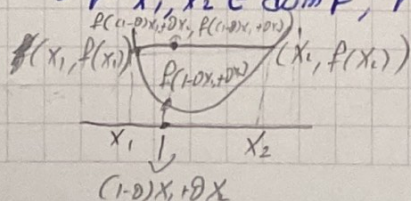
Cor: Through every point at the boundary of a convex set passes a supporting hyperplane

Convex functions: $f: \mathbb{R}^n \rightarrow \mathbb{R}$ (dom f domain of f)

f is convex if:

- dom f is convex

• $\forall x_1, x_2 \in \text{dom } f, \forall \theta \in [0, 1], f((1-\theta)x_1 + \theta x_2) \leq (1-\theta)f(x_1) + \theta f(x_2)$ (*)



$\rightarrow f$ is strictly convex if (*) is $<$

$\rightarrow f$ is (strictly) concave if $-f$ is (strictly) convex

Examples: $(\mathbb{R}) ax+b, e^x, |x|^p, p \geq 1, x \log x$

$$(\mathbb{R}^n) a^T x + b, \|x\|_p = \sqrt[p]{\sum |x_i|^p}, p \geq 1$$

$$\|x\|_\infty = \max_k |x_k|$$

Lemma: $f: \mathbb{R}^n \rightarrow \mathbb{R}$ convex $\Leftrightarrow g: \mathbb{R} \rightarrow \mathbb{R}$ convex

$$\text{Extension } \tilde{f}(x) = \begin{cases} f(x), & x \in \text{dom } f \\ +\infty, & x \notin \text{dom } f \end{cases} \quad \begin{aligned} g(t) &= f(x+tv) \\ \text{dom } g &= \{t: x+tv \in \text{dom } f\} \end{aligned}$$

$$\tilde{f}: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$$

f is convex $\Leftrightarrow \tilde{f}$ satisfies

$$\tilde{f}((1-\theta)x_1 + \theta x_2) \leq (1-\theta)\tilde{f}(x_1) + \theta\tilde{f}(x_2) \quad \forall x_1, x_2 \in \mathbb{R}^n \\ \forall \theta \in [0, 1]$$

(2) Convexity and optimality

Theorem: f convex

$$C_\alpha = \{x \in \text{dom } f: f(x) \leq \alpha\} \text{ is convex}$$

$$\blacktriangleright x, y \in C_\alpha, f((1-\theta)x + \theta y) \leq (1-\theta)f(x) + \theta f(y) \leq (1-\theta)\alpha + \theta\alpha = \alpha \\ \Rightarrow (1-\theta)x + \theta y \in C_\alpha$$

In particular C_0 is convex

$$\text{Epigraph } \text{epi}(f) = \{(x, t) \in \mathbb{R}^n, x \in \text{dom } f, f(x) \leq t\}$$

Theorem: f is convex $\Leftrightarrow \text{epi}(f)$ convex
(proof using the idea above)

$\Rightarrow \forall x \in \text{epi}(f)$ there exists a supporting hyperplane

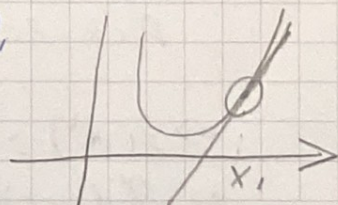
Assume f is smooth \rightarrow supporting hyperplane is tangent

Theorem: (1st order condition) f smooth, $\text{dom } f$ is convex

$$f \text{ convex} \Leftrightarrow f(y) \geq f(x) + \nabla f(x)^T (y-x)$$

from local data (rhm)

global condition



Theorem (2nd order condition): f smooth, $\text{dom } f$ convex
(positive semi-definite) $\forall x \in \text{dom } f$

$$f \text{ convex} \Leftrightarrow \nabla^2 f(x) \succeq 0$$

If $\nabla^2 f(x) \succ 0$, then f is strictly convex

Examples:

(1) $f(x) = \frac{1}{2} x^T A x + b^T x + c$ quadratic function

$$\nabla f(x) = Ax + b, \quad \nabla^2 f(x) = A \quad \text{convex} \Leftrightarrow A \succeq 0$$

(2) Least squares objective:

$$f(x) = \|Ax - b\|_2^2 \quad \begin{matrix} \rightarrow \text{squared} \\ \rightarrow \text{euclidean} \end{matrix}$$

$$\nabla f(x) = 2A^T(Ax - b)$$

$$\nabla^2 f(x) = 2A^T A \leftarrow \text{positive semi-definite}$$

(3) Soft maximum

$$f(x) = \log\left(\sum_{i=1}^n e^{x_i}\right) \quad x = (x_1, \dots, x_n)$$

This is a convex function? $z = (e^{x_1}, e^{x_2}, \dots, e^{x_n})$

$$\text{diag}(z) = \begin{pmatrix} z_1 & & 0 \\ & \ddots & \\ 0 & & z_n \end{pmatrix}$$

$$\text{claim: } \nabla^2 f(x) = \frac{1}{z_1 + z_2 + \dots + z_n} \text{diag}(z) - \frac{1}{(z_1 + \dots + z_n)^2} z z^T$$

$$v^T \nabla^2 f(x) v = \frac{(\sum z_i v_i^2)(\sum z_i) - (\sum z_i v_i)^2}{(\sum z_i)^2} \geq 0 \quad \text{by Cauchy-Schwarz Ineq.}$$

(4) geometric mean $x_i \geq 0$ $f(x) = \sqrt[n]{x_1 \dots x_n}$ convex function

Theorem: f convex function. Then every local minimum x^* is to a local minimum

$$\square f(x) \geq f(x^*) \quad \forall x \in B(x^*, \epsilon) \cap \text{dom } f$$

$$\text{Pick } z \in \text{dom } f, \quad (1-\theta)x^* + \theta z \in \text{dom } f \cap B(x^*, \epsilon)$$

$$0 \in [0, 1]$$

\hookrightarrow choose θ sufficiently small

$$\Rightarrow f(x^*) \leq f((1-\theta)x^* + \theta z) \leq (1-\theta)f(x^*) + \theta f(z)$$

$$\Rightarrow \theta f(x^*) \leq \theta f(z) \quad \square$$

Cor: x^* global minimum $\Leftrightarrow \nabla f(x^*) = 0$
(if f is smooth)

(3) Operations w/ convex functions

Prop: (1) f convex, $a > 0$, then af is convex

(2) If f_1, f_2 convex, then $f_1 + f_2$ is convex

(3) ~~If~~ If $f(x)$ convex, then $f(Ax+b)$ convex
(Example: barrier functions, $f(x) = -\sum_{i=1}^n \log(b_i - a_i^T x)$)

(4) $f(x) = \max_k \{f_1(x) \dots f_k(x)\}$, f_i convex.

(5) $f(x, y)$ is convex in x for any $y \in A$, then
 $g(x) = \sup_{y \in A} f(x, y)$ is convex