```
1. a) T(v)=(V,+V2, V,+3v2, V,+V3)
                                                                               T(av+bu) = (av,+bu,+av,+bu,,
av,+bu,+3(av,+bu,)
2(av,+bu,)+5(av,+bu,))
                                                                          N(T) = {vell 3: Tv=0}
                                                                      N(T) = \{ v \in \mathbb{R}^3 : v_1 + v_2 = 0 \\ v_1 + 3v_2 = 0 \}
                                                                                                                                                                       T_{V} = 0 \rightarrow V'' - 2v - 3 = 0
\lambda^{2} - 2\lambda - 3 = 0
(\lambda+1)(\lambda-3) = 0
V(l) = c, e^{-\frac{t}{2}} + c_{2} e^{\frac{3t}{2}}
V(\tau) = \{ l, e^{-\frac{t}{2}} + c_{2} e^{\frac{3t}{2}} : c_{1}, c_{2} \in |\mathcal{K}| \}
= gen \{ e^{-\frac{t}{2}}, e^{\frac{3t}{2}} \}
Recorrigion
                                                                                                   2V_1 + 3V_2 = 0
\begin{bmatrix} V_1 & V_2 \end{bmatrix} \begin{bmatrix} 0 \end{bmatrix}
                                                                            1 10][N.
                                                                            1 3 D
                                                                    0 20 0
                                                  fs+fe
                                                                           0 3
                                                                                          10 31/5=D -1/5=D

\begin{array}{c}
\downarrow 2V_c = 0 \rightarrow V_c = 0 \\
V_1 + V_2 = 0 \rightarrow V_1 = 0
\end{array}

                                                        N(T) = {(90,0)}
                           Records: R(T) = \{ w \in \mathbb{R}^3 : w = Tv, para algun v \in \mathbb{R}^3 \}
                                     R(T) = (welk3: w= (v,+v2, v,+3v2, 2v,+3v3), v,v2, v3 elk)
                                               = \left\{ w \in \mathbb{R}^{3} : w = (1, 1, 2) v_{1} + (1, 3, 0) v_{2} + (0, 0, 3) v_{3}, v_{1}, v_{2}, v_{3} \in \mathbb{R}^{3} \right\}
                                             = gen{(1,1,2), (1,3,0), (0,0,3)}
                      Mobrie T (0,00), (0,1,0), (0,0,1)}
                     T(e_1) = (1,1,2)

T(e_2) = (1,3,0) \longrightarrow \begin{bmatrix} 1 & 1 & 2 \\ 1 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}
Acotado:
                           \|Tv\|_{z}^{2} = (v_{1}+v_{2})^{2} + (v_{1}+3v_{2})^{2} + (2v_{1}+3v_{3})
                                       = 1,2+2v, 16+1, + 1,2+61, v2+ 1,2+ 4,12+12v, v3+9, V3
                                      =6v_1^2+10v_2^2+9v_3^2+8v_1v_2+12v_1v_3
                                     = 6x2+10x2+9x3+87x2+x2)+121x12x2)
                                     = 26v_1^2 + |9v_2^2 + 2|v_3^2 \le 26(v_1^2 + v_2^2 + v_3^2)
                  ||Tv||_{2}^{2} \le 26 ||v||_{2}^{2}
||Tv||_{2} \le 26 ||v||_{2}
```

1 = 12 3

 $b) \ T: \mathcal{C}^{\ell}[a,b] \longrightarrow \mathcal{C}[a,b]$ 

N(T) = {vec [a,b]: Tv = 0}

R(T) = {w \( \) [a, b] : w = \( \) pana algun \( v \) (2[a, b] \( \)

R(7) = { w ∈ C[a,b] : w = v"-2v'-3v, para alin ( v∈(16,b) }

Nulo

Tu = u'' - 2u' - 3u T(au+bv) = (au+bv)' - 2(au+bv)' - 3(au+bv) = au'' + bv'' - 2au' - 2bv' - 3au - 3bv = a(u'' - 2u' - 3u) + b(v'' - 2v' - 3v) = aTu + bTv

```
e) TA = A-AT
         T(aA+bB)= aA+bB-(aA+bB)<sup>T</sup>
= a(A-A<sup>T</sup>)+b(B-B<sup>T</sup>)
                             =aTA+bTB
     Note:
N(T)={A=R"" | TA=0}
             N(T) = \left\{ A \in \mathbb{R}^{nrn} \middle| A = A^T \right\}
\downarrow flavings
simptriess.
                       b
R(T)=|We|R<sup>nvn|</sup>W=TA pana
algun Ae|R<sup>nvn</sup>|
           W = A - A^{T}, A \in \mathbb{R}^{n \times n}
W^{T} = A^{T} - A = -(A - A^{T}) = -W
         Luego, W es una matriz
antissimátrica.
R(T) = matrices antisimátricas
    a) T: P+P3
T(p(H) = p"(f)
T(ap(H)+bg(H))"
= ap"(H)+bg(H)"
= aT(p(H) +bT(g(H))
     <u>Nub:</u>
N(T)=
R(\tau) = \mathcal{P}_{q}

R(\tau) = \{q \in \mathcal{P}^{\dagger} | q = T(q(H), p(H) \in \mathcal{P}^{\dagger}\}
                                                    = \frac{d}{dt_{3}} \left[ \sum_{r'=0}^{3} (r'+1) b_{r'+1} t' \right]
                                                            "(r+1)br+1 tr-1
                                                   laudando confs:

as = 0 - No bay

az = 4.3 by grado 3
                                           a, = 3.26,
a, = 2.16,
                                                                      Li Polinamios
de grado 2º
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