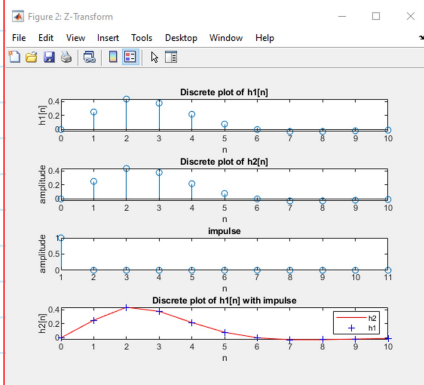


Lab3

October 27, 2020 1:03 AM



Q₁ a) h_1 is plotted above on first row

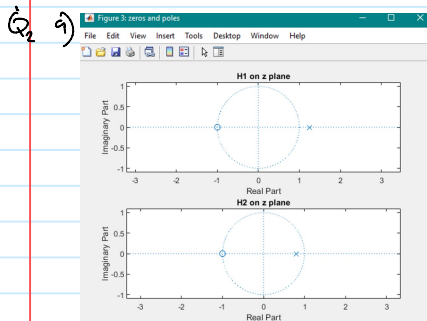
$$b) h_1(n) = n(0.1)^n \sin\left(\frac{\pi n}{2}\right) u(n)$$

using the ztrans function in Matlab,

We get
$$\frac{z(4z^2 - 1)}{(4z^2 - 2\sqrt{5}z + 1)^2} = \frac{N(z^{-1})}{D(z^{-1})} = \frac{N(z^{-1})}{D(z^{-1})}$$

c) h_2 is plotted above on row 2
and is the impulse of h_1 .

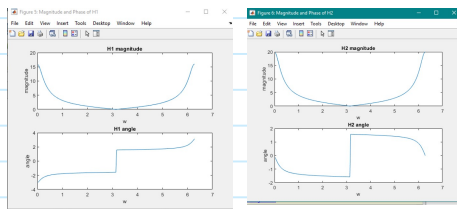
d) n is plotted, and the comparison of h_1 and h_2 are plotted



For the stability of h_1 , the pole is on the outside of the unit circle, thus it does not converge, or otherwise is not stable

For the stability of h_2 , the pole is on the inside of the unit circle, thus it does converge, or otherwise it is stable

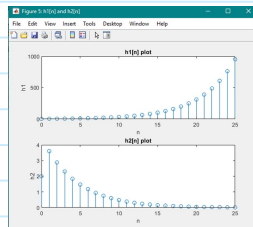
b)



using Matlab to find angle and magnitude.

$$c) \quad H_1(z) = \frac{2 + 2z^{-1}}{1 - 1.25z^{-1}} = \frac{2z}{z - 1.25} + \frac{2z^{-1}}{z - 1.25} \quad h_1(n) = 2 \cdot 1.25^n u(n) + 2 \cdot 1.25^{n-1} u(n-1)$$

$$H_2(z) = \frac{2 + 2z^{-1}}{1 - 0.8z^{-1}} = \frac{2z}{z - 0.8} + \frac{2z^{-1}}{z - 0.8} \quad h_2(n) = 2 \cdot 0.8^n u(n) + 2 \cdot 0.8^{n-1} u(n-1)$$



h_1 compared to h_2 , h_1 goes to infinity, h_2 goes to 0.
thus h_1 is not bounded while h_2 is bounded.