

Module - IV Vector Calculus

* Vector:-

* Position of vector:-

\vec{AB} = position vector of B - position vector of A

* unit vector:-

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\hat{A} = \frac{\vec{r}}{|\vec{r}|} = \frac{x\hat{i} + y\hat{j} + z\hat{k}}{\sqrt{x^2 + y^2 + z^2}}$$

Product:-

① Dot / scalar product $\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$

$$\vec{a} \cdot \vec{b} = (\vec{a}) |(\vec{b})| \cos \theta$$

$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$$

$$\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = 0$$

② Cross / vector product $\vec{a} \times \vec{b}$

$$\vec{a} \times \vec{b} = \vec{a} | \vec{b} | \sin \theta$$

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix}$$

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = [\vec{a} \vec{b} \vec{c}]$$

* vector differentiation operation (∇) (del)

$$\nabla = \hat{i} \frac{\delta}{\delta x} + \hat{j} \frac{\delta}{\delta y} + \hat{k} \frac{\delta}{\delta z}$$

* Gradient of a scalar function :-

let $\phi(x, y, z)$ be a scalar function

$$\text{then grad } \phi = \nabla \phi = \left(\hat{i} \frac{\delta}{\delta x} + \hat{j} \frac{\delta}{\delta y} + \hat{k} \frac{\delta}{\delta z} \right) \phi$$

Q If $\phi = 3x^2y - y^3z^2$ find the grad ϕ at the point $(1, -2, -1)$

Sol we have $\phi = 3x^2y - y^3z^2$

observed

$$\text{grad } \phi = \nabla \phi = \left(\hat{i} \frac{\delta}{\delta x} + \hat{j} \frac{\delta}{\delta y} + \hat{k} \frac{\delta}{\delta z} \right)$$

$$(3x^2y - y^3z^2)$$

$$\nabla \phi = \hat{i}(6xy) + \hat{j}(3x^2 - 3y^2z^2) + \hat{k}(-2y^3z)$$

~~$\nabla \phi$~~ = grad ϕ at $(1, -2, -1)$

$$= 6(1)(-2)\hat{i} + \hat{j}(3(1)^2 - 3(-2)^2(-1)^2) + \hat{k}(-2(-2)^2(-1))$$

$$\Rightarrow -12\hat{i} - 9\hat{j} - 16\hat{k} \quad \text{Ans}$$

Normal: If $\phi(x, y, z) = c$ represent a family of surfaces for different c , then $\nabla \phi$ is vector normal to the surface $\phi(x, y, z) = c$.

the direction derivative of $\phi(x, y, z) = \langle$
 in the direction of vector \vec{d} is
 equal to $\nabla \phi \cdot \vec{d}$.

Q3 Find the directional derivative of $x^2 y^2 z^2$ at the point $(1, 1, -1)$ in the direction of the tangent to the curve, $x = e^t$, $y = \sin 2t + 1$, $z = 1 - \cos t$

at ~~$t=0$~~ $t=0$ $\rightarrow \vec{v} = \nabla \phi$

for we have $\phi = x^2 y^2 z^2$ i.e., ϕ

$$\text{grad } \phi = \nabla \phi$$

$$= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) (x^2 y^2 z^2)$$

$$\hat{i}(2x) + \hat{j}(2y)$$

$$\rightarrow \hat{i}(2x y^2 z^2) + \hat{j}(2y x^2 z^2) + \hat{k}(2z x^2 y^2)$$

grad ϕ at point $(1, e^1, -1)$

$$\begin{aligned} \text{grad } \phi &= \hat{i}(2x \cdot 1 \cdot 1) + \hat{j}(2x \cdot 1 \cdot 1) + \hat{k}(-2x \cdot 1 \cdot 1) \\ &= 2\hat{i} + 2\hat{j} - 2\hat{k} \end{aligned}$$

~~At $t=0$ curve is~~

$$x = e^0 - 1$$

$$y = \sin 0 + 1 - 1$$

$$z = 0$$

$$\vec{r} = e^t \hat{i} + (\sin 2t - 1) \hat{j} + (1 - \cos t) \hat{k}$$

$$\text{tangent vector } \left(\frac{d\vec{r}}{dt} \right) = e^t \hat{i} + 2 \cos 2t \hat{j} + \sin t \hat{k}$$

$$\text{tangent vector } \left(\frac{d\vec{r}}{dt} \right) \Big|_{t=0} = \hat{i} + 2\hat{j}$$

$$\vec{d} = \hat{i} + 2\hat{j}$$

$$\hat{d} = \frac{\hat{i} + 2\hat{j}}{\sqrt{1+2^2}} = \frac{\hat{i} + 2\hat{j}}{\sqrt{5}}$$

Required direction derivative of x^2y^2z
along the tangent vector.

$$\begin{aligned} & \nabla \phi \cdot \hat{d} \\ &= (2\hat{i} + 3\hat{j} - 2\hat{k}) \cdot \frac{\hat{i} + 2\hat{j}}{\sqrt{5}} \\ &= \frac{2x_1 + 2x_2 + 2x_3}{\sqrt{5}} \end{aligned}$$

$$= \frac{6}{\sqrt{5}}$$

Q: Find the unit normal vector
to the surface $x^2y^3z^2 = 4$ at
 $(-1, -1, 2)$.

Sol: we have
 $\phi = x^2y^3z^2 - 4$

normal vector of $\phi = \nabla \phi$

$$= \left(\hat{i} \frac{\partial f}{\partial x} + \hat{j} \frac{\partial f}{\partial y} + \hat{k} \frac{\partial f}{\partial z} \right) (x^2y^3z^2 - 4)$$

$$\Rightarrow \hat{i}(y^3z^2) + \hat{j}(3x^2y^2z^2) + \hat{k}(2x^2y^3z)$$

normal vector of ϕ at $(-1, -1, 2)$

$$\Rightarrow -4\hat{i} - 12\hat{j} + 4\hat{k}$$

unit normal vector of at $(-1, -1, 2)$

$$\begin{aligned}& \Rightarrow \frac{-4\hat{i} - 12\hat{j} + 4\hat{k}}{\sqrt{16 + 144 + 16}} = \frac{-4}{4\sqrt{11}} (\hat{i} + 3\hat{j} - \hat{k}) \\& = \frac{1}{\sqrt{11}} (\hat{i} + 3\hat{j} - \hat{k}) \text{ my}\end{aligned}$$

Q) Find the angle between the surfaces
 $x^2 + y^2 + z^2 = 9$ and $z = x^2 + y^2 - 3$
at the point $(2, -1, 2)$.

Sol Normal vector of surface

$$x^2 + y^2 + z^2 - 9 = 0$$

$$\nabla \phi = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) (x^2 + y^2 + z^2 - 9)$$

$$\Rightarrow 2x\hat{i} + 2y\hat{j} + 2z\hat{k}$$

$$\text{Normal vector at } (2, -1, 2) = 4\hat{i} - 2\hat{j} + 4\hat{k} \quad \text{--- (1)}$$

and normal vector of surface

$$x^2 + y^2 - z - 3 = 0$$

$$\nabla \phi = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) (x^2 + y^2 - z - 3)$$

$$= 2x\hat{i} + 2y\hat{j} - \hat{k}$$

normal vector at point $(2, -1, 2)$

$$= 4\hat{i} - 2\hat{j} - \hat{k} \quad \text{--- (2)}$$

Let θ be angle between \vec{r}_1 & \vec{r}_2

$$\Rightarrow \frac{(\vec{r}_1 - 2\hat{i} + 4\hat{k}) \cdot (4\hat{i} - 2\hat{j} - \hat{k})}{\sqrt{16+4+16} \sqrt{16+4+1}} \cos \theta$$

$$\Rightarrow 16+4-4 = 6\sqrt{2} \cos \theta$$

$$16 = 6\sqrt{2} \cos \theta$$

$$\cos \theta = \frac{8}{3\sqrt{2}}$$

$$\theta = \cos^{-1} \frac{8}{3\sqrt{2}} \text{ M}$$

Q) find the directional derivative of $\frac{1}{r}$ in the direction \vec{r} .

Sol: where $\vec{r} = xi + y\hat{j} + z\hat{k}$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$r^2 = x^2 + y^2 + z^2$$

we have

$$\nabla \phi = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \left(\frac{1}{r} \right)$$

$$\Delta \phi = \hat{i} \left(-\frac{1}{r^2} \frac{\partial r}{\partial x} \right) + \hat{j} \left(-\frac{1}{r^2} \frac{\partial r}{\partial y} \right) + \hat{k} \left(-\frac{1}{r^2} \frac{\partial r}{\partial z} \right)$$

$$\Delta \phi = -\frac{1}{r^2} \left(x \hat{i} + y \hat{j} + z \hat{k} \right)$$

$$\Delta \phi = -\frac{1}{r^2} (xi + y\hat{j} + z\hat{k})$$

$$= \frac{-\vec{r}}{r^3}$$

So directional derivative - $\frac{\vec{r}}{|\vec{r}|^3} \cdot \frac{\vec{r}}{|\vec{r}|}$

$$\boxed{\vec{r} \cdot \vec{r} = r^2}$$

$$\Rightarrow \frac{-r^2}{r^4} = -\frac{1}{r^2}, \underline{\text{Ans}}$$

~~Q~~ find the directional

Q If $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ then show
that (i) $\text{grad } r = \frac{\vec{r}}{r}$

(ii) $\text{grad}\left(\frac{1}{r}\right) = -\frac{\vec{r}}{r^3}$

Sol (i) $\text{grad } r = \Delta r$

$$\Delta r = \left(\hat{i} \frac{\delta}{\delta x} + \hat{j} \frac{\delta}{\delta y} + \hat{k} \frac{\delta}{\delta z} \right) (r)$$

$$= \hat{i} \frac{x}{r} \hat{i} + \hat{j} \frac{y}{r} \hat{j} + \hat{k} \frac{z}{r} \hat{k}$$

$$\Rightarrow \frac{x\hat{i} + y\hat{j} + z\hat{k}}{r}$$

$$\Rightarrow \frac{\vec{r}}{r} \quad \text{Hence proved}$$

(ii) $\text{grad}\left(\frac{1}{r}\right) = \Delta \frac{1}{r}$

$$\Delta\left(\frac{1}{r}\right) = \left(\hat{i} \frac{\delta}{\delta x} + \hat{j} \frac{\delta}{\delta y} + \hat{k} \frac{\delta}{\delta z} \right) \left(\frac{1}{r}\right)$$

$$\Rightarrow \hat{i} \left(-\frac{1}{r^2} \frac{\delta r}{\delta x} \right) + \hat{j} \left(-\frac{1}{r^2} \frac{\delta r}{\delta y} \right) + \hat{k} \left(-\frac{1}{r^2} \frac{\delta r}{\delta z} \right)$$

$$= \vec{a} - \frac{x}{r^3} \hat{i} - \frac{y}{r^3} \hat{j} - \frac{z}{r^3} \hat{k}$$

$$\Rightarrow -\frac{1}{r^3} (x \hat{i} + y \hat{j} + z \hat{k})$$

$$\Rightarrow -\frac{\vec{r}}{r^3} \quad \underline{\text{Hence proved}}$$

* Divergence of a vector point function:-

The divergence of a vector point function

$\vec{F} = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$ is defined as

$$\operatorname{div} \vec{F} = \nabla \cdot \vec{F}$$

$$= \left(i \frac{\delta}{\delta x} + j \frac{\delta}{\delta y} + k \frac{\delta}{\delta z} \right) \cdot (F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k})$$

$$\left[\operatorname{div} \vec{F} = \frac{\delta F_1}{\delta x} + \frac{\delta F_2}{\delta y} + \frac{\delta F_3}{\delta z} \right]$$

($\operatorname{div} \vec{F}$ is a scalar function)

* Solenoidal vector function:-

A vector \vec{V} is said to be solenoidal if $\operatorname{div} \vec{V} = 0$.

Q) If $\mathbf{u} = x^2 \mathbf{i} + y^2 \mathbf{j} + z^2 \mathbf{k}$ and $\mathbf{g} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$
then find the $\text{div}(\mathbf{u} \cdot \mathbf{g})$.

Sol we have

$$\text{div}(\mathbf{u} \cdot \mathbf{g}) = \nabla \cdot (\mathbf{u} \cdot \mathbf{g})$$

$$= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot ((x^2 + y^2 + z^2) \mathbf{i} \cdot (\mathbf{i} + \mathbf{j} + \mathbf{k}))$$

$$= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (x(x^2 + y^2 + z^2) \mathbf{i} + y(x^2 + y^2 + z^2) \mathbf{j} + z(x^2 + y^2 + z^2) \mathbf{k})$$

$$\Rightarrow \hat{i} \frac{\partial}{\partial x} (x^3 + xy^2 + xz^2) + \hat{j} \frac{\partial}{\partial y} (yx^2 + y^3 + yz^2) \\ + \hat{k} \frac{\partial}{\partial z} (zx^2 + zy^2 + z^3)$$

$$\Rightarrow (3x^2 + y^2 + z^2) + (x^2 + 3y^2 + z^2) + (x^2 + y^2 + 3z^2)$$

$$\Rightarrow 5(x^2 + y^2 + z^2)$$

$$= \frac{5}{5} (x^2 + y^2 + z^2)$$

Q) Find the value of n for which
the vector $\mathbf{g}^n \mathbf{g}$ is solenoidal
where $\mathbf{g} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$.

Sol $\text{div } \mathbf{v} = \text{div}(\mathbf{g}^n \mathbf{g})$

$$\nabla(\vec{r}^n \vec{r}) = \left(i \frac{\delta}{\delta x} + j \frac{\delta}{\delta y} + k \frac{\delta}{\delta z} \right) (r_i x_i + r_j y_j + r_k z_k)$$

$$\Rightarrow \frac{\delta}{\delta x} (\vec{r}^n x) + \frac{\delta}{\delta y} (\vec{r}^n y) + \frac{\delta}{\delta z} (\vec{r}^n z)$$

$$\Rightarrow r^n + nr^{n-1} \frac{\delta r}{\delta x} \cdot x + r^n + nr^{n-1} \frac{\delta r}{\delta y} \cdot y$$

$$+ \left(r^n + nr^{n-1} \frac{\delta r}{\delta z} \cdot z \right)$$

$$\Rightarrow 3r^n + nr^{n-1} \left[\frac{n}{r} \cdot x + \frac{1}{r} \cdot y + \frac{1}{r} \cdot z \right]$$

$$= 3r^n + nr^{n-1} (x^2 + y^2 + z^2)$$

$$\text{div } \vec{v} = 3r^n + \frac{nr^{n-1}}{r} r^2$$

$$= 3r^n + nr^n = (3+n)r^n$$

for $\vec{v} \in \mathcal{R}$ is a solenoidal $\text{div } \vec{v} = 0$

$$\Rightarrow (3+n)r^n = 0$$

$$\Rightarrow 3+n=0$$

$$n = -3$$

Q) If $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ and $a = |\vec{r}|$

. = $\sqrt{x^2 + y^2 + z^2}$, then show that

$$\textcircled{1} \quad \text{div} \left(\frac{\vec{r}}{a^2} \right) = \frac{1}{a^2}$$

$$\textcircled{2} \quad \text{div} \left(\frac{\vec{r}}{|a|^3} \right) = 0$$

③ $\operatorname{div}(\operatorname{grad} \varphi^n) = n(n+1) \varphi^{n-2}$ Hence
show that $\nabla^2 \left(\frac{1}{\varphi} \right) = 0$

Step ① $\operatorname{div} \left(\frac{\vec{r}}{\varphi^2} \right)$

$$\operatorname{div}(\vec{r} \cdot \vec{r}) = \Delta (\varphi \cdot \vec{r})$$

$$\Rightarrow \left(i \frac{\delta}{\delta x} + j \frac{\delta}{\delta y} + k \frac{\delta}{\delta z} \right) (\varphi x^i + \varphi y^j + \varphi z^k)$$

$$\Rightarrow \varphi + \frac{\delta \varphi}{\delta x} \cdot x + \varphi + \frac{\delta \varphi}{\delta y} \cdot y + \varphi + \frac{\delta \varphi}{\delta z} \cdot z$$

$$\Rightarrow 3\varphi + \frac{\varphi}{\varphi} \cdot x + \frac{\varphi}{\varphi} \cdot y + \frac{\varphi}{\varphi} \cdot z$$

$$\Rightarrow \frac{3\varphi}{\varphi} (x^2 + y^2 + z^2)$$

$$\Rightarrow 3\varphi + \frac{\varphi^2}{\varphi}$$

$$\Rightarrow 3\varphi + \varphi(r + \varepsilon)$$

Q) Find the directional derivative of divergence of $\vec{V} = x^4 \hat{i} + y^4 \hat{j} + z^4 \hat{k}$ at the point (1, 2, 2) in the direction of outer normal of the sphere $x^2 + y^2 + z^2 = 9$.

Sol $\text{Div } \vec{V} = \nabla \cdot \vec{V} = \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right)$

$$(x^4 \hat{i} + y^4 \hat{j} + z^4 \hat{k})$$

$$= \frac{\partial x^4}{\partial x} + \frac{\partial y^4}{\partial y} + \frac{\partial z^4}{\partial z}$$

$$\Rightarrow 4x^3 + 4y^3 + 4z^3$$

Directional derivative of ~~div \vec{V}~~

$$\text{div } \vec{V} = \Delta (4x^3 + 4y^3 + 4z^3) = \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right)$$

$$(4x^3 + 4y^3 + 4z^3)$$

$$= 12x^2 \hat{i} + 12y^2 \hat{j} + 12z^2 \hat{k}$$

Directional Derivative at (1, 2, 2)

$$= 12 \hat{i} + 48 \hat{j} + 48 \hat{k}$$

↳ In vector field we write a vector with three components

$\vec{V} = V_x \hat{i} + V_y \hat{j} + V_z \hat{k}$ = \vec{V} is a function

and write with three components (V_x, V_y, V_z) having three dimensions x, y, z & V_x, V_y, V_z are three more numbers

$$(\vec{V}_x, \vec{V}_y, \vec{V}_z) = (\vec{V}_x, \vec{V}_y, \vec{V}_z)$$

* Curl :- Curl of a vector point function \vec{V} is defined as

$$\text{curl } \vec{V} = \nabla \times \vec{V}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_1 & V_2 & V_3 \end{vmatrix}$$

If $\text{curl } \vec{V} = 0$ then \vec{V} is irrotational

Q.S. $\vec{V} = V_x \hat{i} + V_y \hat{j} + V_z \hat{k}$

$$\vec{V} = V_x \hat{i} + V_y \hat{j} + V_z \hat{k}$$

(Solved) find solution for \vec{V} given below

$$\vec{V} = V_x \hat{i} + V_y \hat{j} + V_z \hat{k}$$

Q) find the divergences and curl of the $\vec{V} = xyz\hat{i} + 3x^2y\hat{j} + (xz^2 - yz)\hat{k}$ at $(2, -1, 1)$

$$\text{sol} \quad \text{div } \vec{V} = \nabla \cdot \vec{V} = \left(\frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right)$$

$$\text{div } \vec{V} = -1 \times 1 + 3(2)^2 + 2 \times 2(1) - (-1)^2 = 14$$

$$\text{and curl } \vec{V} = \nabla \times \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xyz & 3x^2y & xz^2 - y^2z \end{vmatrix}$$

$$= \hat{i} \left[\frac{\partial}{\partial y} (xz^2 - y^2z) - \frac{\partial}{\partial z} (3x^2y) \right] - \hat{j} \left[\frac{\partial}{\partial x} (xz^2 - y^2z) \right. \\ \left. - \frac{\partial}{\partial z} xyz \right]$$

$$\text{curl } \vec{V} = \hat{i}[-2yz] - \hat{j}[z^2 - xy] + \hat{k}[6xy - xz]$$

at $(2, -1, 1)$

$$\text{curl } \vec{V} = \hat{i}[-2x - 1 \times 1] - \hat{j}[1^2 - 2 \times 1] + \hat{k}[6 \times 7 - 1]$$

$$\geq 2\hat{i} - 3\hat{j} + (14\hat{k})$$

Q) If $\vec{r} = xi + yj + zk$ & $|\vec{r}|^2 = x^2 + y^2 + z^2$
then show that the vector \vec{r} is irrotational.

so we have

$$(\text{curl}(\vec{r})) = \nabla \times \vec{r}$$

$$\Rightarrow \left(i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) \times (x^2 i + y^2 j + z^2 k)$$

$$\vec{i} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 & y^2 & z^2 \end{vmatrix}$$

$$\Rightarrow i \left[\frac{\partial}{\partial y} z^2 - \frac{\partial}{\partial z} y^2 \right] - j \left[\frac{\partial}{\partial x} z^2 - \frac{\partial}{\partial z} x^2 \right]$$

$$+ k \left[\frac{\partial}{\partial x} y^2 - \frac{\partial}{\partial y} x^2 \right]$$

$$\Rightarrow i = 0$$

$y^2 i$ is irrotational

Q) find the divergent and curl of
 $\vec{V} = (x^2 - y^2)i + 2xyj + (y^2 - xy)k$

Q Prove that for every vector field \vec{v}

$$\boxed{\operatorname{div}(\operatorname{curl} \vec{v}) = 0}$$

Sol We have

$$\operatorname{curl} \vec{v} = \nabla \times \vec{v}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix}$$

$$\Rightarrow i \left[\frac{\partial}{\partial y} v_3 - \frac{\partial}{\partial z} v_2 \right] + j \left[\frac{\partial}{\partial x} v_3 - \frac{\partial}{\partial z} v_1 \right] + k \left[\frac{\partial}{\partial x} v_2 - \frac{\partial}{\partial y} v_1 \right]$$

$$\operatorname{div}(\text{curl } \vec{V}) = \left(i \frac{\delta}{\delta x} + j \frac{\delta}{\delta y} + k \frac{\delta}{\delta z} \right) \cdot \left[i \left(\frac{\delta V_3}{\delta y} - \frac{\delta V_2}{\delta z} \right) - j \left(\frac{\delta V_3}{\delta x} - \frac{\delta V_1}{\delta z} \right) + k \left(\frac{\delta V_2}{\delta x} - \frac{\delta V_1}{\delta y} \right) \right]$$

$$\Rightarrow \frac{\delta^2 V_3}{\delta x \delta y} - \frac{\delta^2 V_2}{\delta x \delta z} - \frac{\delta^2 V_3}{\delta y \delta x} + \frac{\delta^2 V_1}{\delta y \delta z} + \frac{\delta^2 V_2}{\delta z \delta x} - \frac{\delta^2 V_1}{\delta z \delta y} \rightarrow 0 \quad \text{performed}$$

* Line Integral :- Let $\vec{F}(x, y, z)$ be a vector function and AB is given curve then Line integral

$$= \int_C \vec{F} \cdot d\vec{r} \quad \boxed{0 = (\text{Work}) \text{ v/t}}$$

work :- If \vec{F} represent the variable force acting on a particle along curve AB then the total work done

$$= \int_A^B \vec{F} \cdot d\vec{r}$$

$$= \left[F_x \frac{dx}{dt} + F_y \frac{dy}{dt} + F_z \frac{dz}{dt} \right] dt$$

Q) If a force $\vec{F} = 2x^2\hat{i} + 3xy\hat{j}$ displaces a particle in xy -plane from $(0,0)$ to $(1,y)$ along a curve $y = 4x^2$. Find the work done.

Sol: Work done = $\int_C \vec{F} \cdot d\vec{r}$

$$= \int_{(0,0)}^{(1,4)} (2x^2\hat{i} + 3xy\hat{j}) \cdot (dx\hat{i} + dy\hat{j})$$

$$\Rightarrow \int_{(0,0)}^{(1,4)} [2x^2y \, dx + 3xy \, dy]$$

$$= \int_0^1 [2x^2(4x^2) \, dx + 3x(4x^2) \, 8x \, dx]$$

$$= \int_0^1 (8x^4 + 96x^3) \, dx \quad \left[\begin{array}{l} y = 4x^2 \\ dy = 8x \, dx \end{array} \right]$$

$$= \int_0^1 104x^4 \, dx$$

$$\Rightarrow 104 \left[\frac{x^5}{5} \right]_0^1$$

$$\Rightarrow 104 \times \frac{1}{5}$$

$$\Rightarrow \frac{104}{5}$$

Q) A Vector field is given by \vec{F}

$$\vec{F} = (2y+3)\hat{i} + xz\hat{j} + (yz-x)\hat{k}$$

Sol) Evaluate $\int_C \vec{F} \cdot d\vec{r}$ along the path

C is $x=2t$, $y=t$, $z=t^3$, from $t=0$ to $t=1$.

Sol)

$$\int_C \vec{F} \cdot d\vec{r} = \int_C [(2y+3)\hat{i} + xz\hat{j} + (yz-x)\hat{k}] \cdot [dx\hat{i} + dy\hat{j} + dz\hat{k}]$$

$$\Rightarrow \int_C (2y+3)dx + xzdy + (yz-x)dz$$

We have $x=2t \Rightarrow dx = 2dt$

$$y=t \Rightarrow dy = dt$$

$z=t^3 \Rightarrow dz = 3t^2dt$ & limit of t , from $t=0$ to $t=1$

$$\Rightarrow \int_C \vec{F} \cdot d\vec{r} = \int_0^1 [(2t+3)2dt + (2t^4+3t^3-2t)dt + (t^4-t^2)3t^2dt]$$

$$\Rightarrow \int_0^1 [4t+6+2t^4+3t^3-6t^3]dt = \left[\frac{4t}{2} + 6t + \frac{2t^5}{5} + \frac{3t^4}{7} - \frac{6t^4}{4} \right]_0^1$$

$$\Rightarrow \frac{4}{2} + 6 + \frac{2}{5} + \frac{3}{7} - \frac{6}{9}$$

$$\Rightarrow 2 + 6 + \frac{2}{5} + \frac{3}{7} - \frac{3}{2}$$

$$\Rightarrow 8 + \frac{2}{5} + \frac{3}{7} - \frac{3}{2}$$

$$\Rightarrow \frac{560 + 28 + 30 - 105}{70}$$

$$\Rightarrow \frac{513}{70} \text{ (Ans)}$$

use green's theorem to evaluate \oint_C
 $(x^2 + xy) dx + (x^2 + y^2) dy$ where C is
 the square formed by line $x = \pm 1, y = \pm 1$

So we have know that Green's theorem

$$\int_C \phi dx + \psi dy = \iint_R \left(\frac{\partial \psi}{\partial x} - \frac{\partial \phi}{\partial y} \right) dx dy$$

$$\int_C (x^2 + xy) dx + (x^2 + y^2) dy = \iint_R (2x - x) dx dy$$

$$\Rightarrow \int_{-1}^1 \int_{-1}^1 x dx dy$$

$$\Rightarrow \int_{-1}^1 x dx \int_{-1}^1 dy = \int_{-1}^1 x dx [y]_{-1}^1$$

$$= \int_{-1}^1 2x dx = 2 \left[\frac{x^2}{2} \right]_{-1}^1 = (1)^2 - (-1)^2 = 0$$

we have $\int_C x^2 y dx + x^2 dy$

$$= \int x^2 y dx + x^2 dy + \int x^2 y dx + x^2 dy$$

also A
 i.e. $y = 0$

$$+ \int x^2 y dx + x^2 dy$$

$y = x$

$$\begin{aligned}
 &= 0 + \int_0^1 dy + \int_{x^3}^{x^2} x^2 \cdot x dx + x^2 dx \\
 &= \int_0^1 dy + \int_0^{\Phi} (x^3 + x^2) dx \\
 &= [y]_0^1 + \left[\frac{x^4}{4} + \frac{x^3}{3} \right]_0^{\Phi}
 \end{aligned}$$

$$\Rightarrow 1 + \left[-\frac{1}{4} - \frac{1}{3} \right]_0^{\Phi} + k b (\Phi^4 + \Phi^3)$$

$$\Rightarrow \frac{5}{12} \pi b$$

Q Verify Green's theorem for $\int (xy + y^2) dx + x^2 dy$ where C is bounded by $y = x$

$$y = x^2$$

$$\text{Sol } \int_C (xy + y^2) dx + x^2 dy$$

$$= \iint_R [2x - (x + 2y)] dx dy$$

$$= \iint_R (x - 2y) dx dy$$

$$= \int_0^1 dx \int_{x^2}^x (x - 2y) dy$$

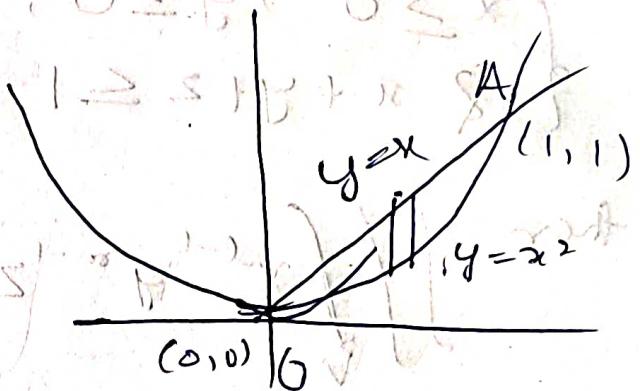
$$= \int_0^1 dx \left[-xy - \frac{2y^2}{2} \right]_{x^2}^x$$

$$\Rightarrow \int_0^1 (x^2 - x^2) - (x^3 - x^4) dx$$

$$= \int_0^1 x^4 - x^3 dx$$

$$= \left[\frac{x^5}{5} - \frac{x^4}{4} \right]_0^1$$

$$= \frac{1}{5} - \frac{1}{4} = -\frac{1}{20} \text{ by}$$



we have $\int (xy + y^2) dx + x^2 dy$

$$= \int_C (xy + y^2) dx + x^2 dy + \int_{C_2} (xy + y^2) dx + x^2 dy$$

$$= \int_0^1 (x^2 + x^4) dx + x^2(0x dx) + \int (x^2 + x^4) dx + x^2 dx$$

$$= \int_0^1 (x^3 + x^4 + 2x^3) dx + \int_0^1 3x^2 dx$$

$$\Rightarrow \left[\frac{5x^4}{4} + \frac{x^5}{5} \right]_0^1 + \left[\frac{3x^3}{3} \right]^0_1$$

$$\Rightarrow \left(\frac{3}{4} + \frac{1}{5} \right) + (0 - 1)$$

$$= \frac{15 + 4 - 20}{20} = -\frac{1}{20} \text{ by}$$

* Duichilef's theorem:-

$$\left\{ \begin{array}{l} x \geq 0, y \geq 0, z \geq 0 \\ x + y + z \leq 1 \end{array} \right\}$$

then

$$\int \int \int x^{d-1} y^{m-1} z^{n-1} dx dy dz$$

~~$$\frac{1}{d+m+n+1} = \frac{1}{d} + \frac{1}{m} + \frac{1}{n}$$~~

$$\Rightarrow \frac{\Gamma d \Gamma m \Gamma n}{\Gamma d+m+n+1}$$

$$= \frac{1}{(d+m+n+1)!}$$

Q> Find the mass of an octant of the

$$\text{ellipsoid } \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1 \text{ and the}$$

density at a point being $kxyz$.

$$x^2(a^2+x^2+y^2) + (kb)^2(y^2+z^2) + (kc)^2(z^2+x^2)$$

$$= x^2 \left(\frac{a^2}{a^2+x^2+y^2} + \frac{b^2}{b^2+y^2+z^2} + \frac{c^2}{c^2+z^2+x^2} \right)$$

$$= \left[\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} \right]$$

$$= \left(1 - \frac{1}{a^2} \right) + \left(\frac{1}{b^2} + \frac{1}{c^2} \right)$$

$$= \frac{a^2-1}{a^2} + \frac{b^2-1}{b^2} + \frac{c^2-1}{c^2}$$

$$\sigma V = 2.68 \times 10^8 \text{ m/s}$$

Module - II

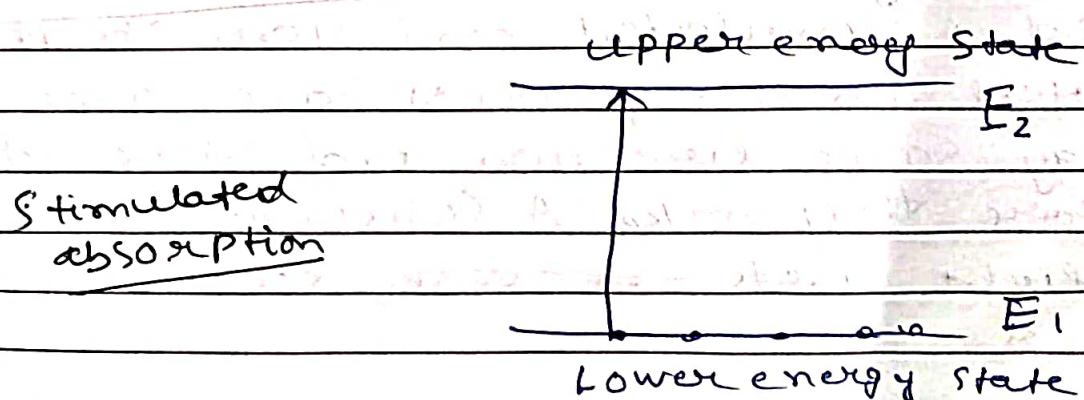
Laser

laser stands for light amplification by stimulated emission of radiation.

property of laser

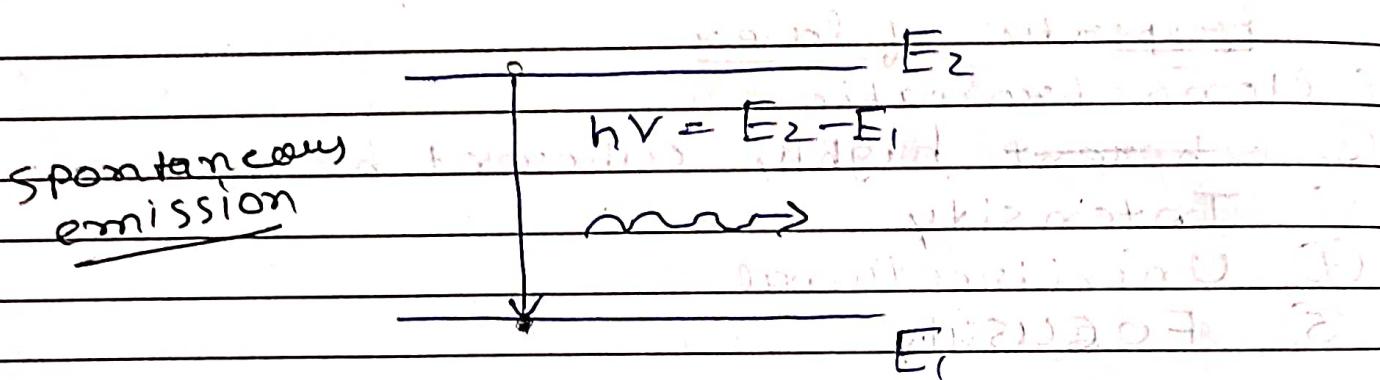
- (1) Mono chromatic
- (2) coherent highly coherent beam.
- (3) Intensity
- (4) Unidirectional
- (5) Focusable

(D) Stimulated Absorption:- In normal condition most of the atoms exist in ground state if we provide energy to them, atoms will get excited and jump to upper energy level this transition is called stimulated absorption.



② Spontaneous emission.

The atom can exist in excited state only for 10^{-8} seconds. After that they return to lower energy state by emitting a photon of energy $h\nu = E_2 - E_1$. This transition is called Spontaneous emission. The photons emitted by a spontaneous emission process have random direction and random phase. They make an incoherent light beam.



③ Stimulated emission

Let an atom exist in excited state and an incoming photon of energy ~~$h\nu$~~ $h\nu = E_2 - E_1$ forces the atom to return lower energy state. Two photons of energy $h\nu$ are emitted. This is called Stimulated emission. The photons emitted in this process have same energy, same direction and same phase. Therefore they make a coherent beam of light made of these known as laser.

Stimulated emission

Date 1/1/

Page _____

$$\text{hv} = E_2 - E_1$$

$$\text{hv} = E_2 - E_1$$

$$\text{hv}$$

$$\text{hv}$$

$$E_1$$

Population Inversion

① In ordinary condition number of atom N_1 in lower energy state is greater than number of atom N_2 in upper state. therefore probability of stimulated emission is very low.

If by some technique the number of atom in excited state is made much larger than lower state, probability of stimulated emission increases.

The situation in which number of atom in upper state is greater than number of atom in lower state is called population inversion.

$$N_2 > N_1$$

* Pumping

The method used to increase number of atom in excited state is called pumping. Several techniques are used to provide energy to the ground state atom. Commonly used methods are

① Optical pumping → if energy is provided in the form of photon pumping is called optical pumping. the light source gives light in the form of pulses - the energy of excitation photon is greater than energy of emitted photon
e.g. → Red Ruby laser.

② Electric discharge pumping

In this method accelerated electrons produced by electric discharge give their energy to the atom so that atoms get excited to upper limit level.
e.g. → Helium neon laser

③ Chemical pumping:- In this process chemical reaction is used to excite the atoms.

e.g. → Carbon dioxide laser.

④ X-ray pumping → X-ray photons are use for pumping process.
e.g. → dye laser

Meta Stable State:-

This energy state is a known long lived energy state in which atom can stay for 10^{-3} sec. the atoms do not return to lower state immediately thus the probability of spontaneous emission is quite negligible.

Active System

A material in which population inversion is achieved is called active system of laser. It contains collection of atom molecules or ions which is responsible for laser action. It can be a liquid, solid or gas.

- e.g. i) In ruby laser Chromium works as active system.
 ii) In helium Neon laser, Neon works as active system.

* Condition necessary to achieve laser action.

- i) There must be population inversion.
- ii) There must exist a metastable state in which atom can stay for 10^{-3} sec.
- iii) We must use a Resonator (cavity).
 → There must be a pair of mirror at the ends of active system. One mirror is fully silvered and the other is partially silvered. The pair of mirrors is called resonator or cavity.

Relation between Einstein coefficient

Let N_1 be the no. of atom in lower energy state E_1 and N_2 be the no. of atom in upper energy state E_2 . Let a radiation of frequency

beam incident such that $h\nu = E_2 - E_1$

$\propto u(\nu) \rightarrow$ energy density of radiation

- ① The no. of absorption per unit volume per unit time $\propto N_1 u(\nu)$

$$= B_{12} N_1 u(\nu)$$

$B_{12} \rightarrow$ Einstein coefficient for absorption

- ② the no. of spontaneously emission per unit volume per unit time $\propto N_2$

$$= A_{21} N_2$$

$A_{21} \rightarrow$ Einstein coefficient for spontaneous emission

- ③ the no. of stimulated emission per unit time per unit volume $\propto N_2 u(\nu)$

$$= B_{21} N_2 u(\nu)$$

$B_{21} \rightarrow$ Einstein coefficient for stimulated emission.

In thermal equilibrium

rate of absorption = rate of emission

$$B_{12} N_1 u(\nu) = A_{21} N_2 + B_{21} N_2 u(\nu)$$

$$u(\nu) [B_{12} N_1 - B_{21} N_2] = A_{21} N_2$$

$$u(v) = \frac{A_{21} N_2}{B_{12} N_1 - B_{21} N_2} = \frac{A_{21} N_2}{k_B \left[B_{12} \frac{N_1}{N_2} - B_{21} \right]}$$

$$u(v) = \frac{A_{21}}{B_{12} \left[\frac{N_1}{N_2} - \frac{B_{21}}{B_{12}} \right]} \quad \text{--- (4)}$$

According to Boltzmann distribution law

$$N = N_0 e^{-E/kT}$$

$N_0 \rightarrow$ Total no. of atoms.

$k \rightarrow$ Boltzmann Constant

$$N_1 = N_0 e^{-E_1/kT}$$

$$N_2 = N_0 e^{-E_2/kT}$$

$$\frac{N_1}{N_2} = \frac{N_0 e^{E_1/kT}}{N_0 e^{-E_2/kT}} = e^{(E_2 - E_1)/kT}$$

$$\frac{N_1}{N_2} = e^{hv/kT} \quad \text{--- (5)}$$

Putting eq (5) in (4)

$$u(v) = \frac{A_{21}}{B_{12} \left[e^{hv/kT} - \frac{B_{21}}{B_{12}} \right]} \quad \text{--- (6)}$$

According to Planck's law of radiation

$$u(v) = \frac{8\pi h v^3}{c^3 [e^{hv/kT} - 1]} \quad \text{--- (7)}$$

Comparing ⑥ and ⑦

$$\frac{B_{21}}{B_{12}} = 1 \rightarrow B_{12} = B_{21}$$

$$\boxed{\frac{A_{21}}{B_{12}} = \frac{8\pi h\nu^3}{c^3}}$$

~~✓ Ruby laser (3-level laser)~~

Construction - 1:- Active System

It consist a pink Ruby rod of cylindrical shape. Ruby is a crystal of Aluminium Oxide (Al_2O_3) doped with 0.05 percent Chromium Oxide (Cr_2O_3).

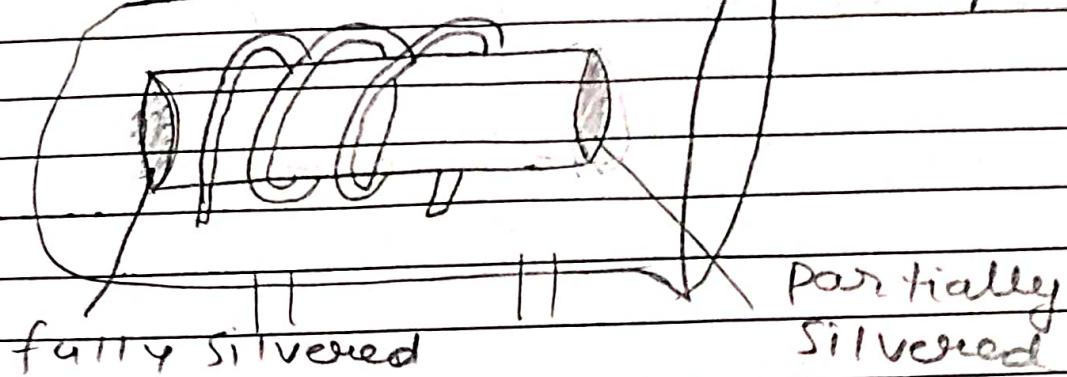
Construction 2:- of Pumping

Optical pumping used A Coiled lamp filled with Xenon is bounded over the rod it gives light of wavelength 5500\AA in the form of flash.

Construction 3:- Resonator

Both ends of the rod are made optically flat and parallel. One end ~~and partially~~ is fully silvered and the other is partially silvered.

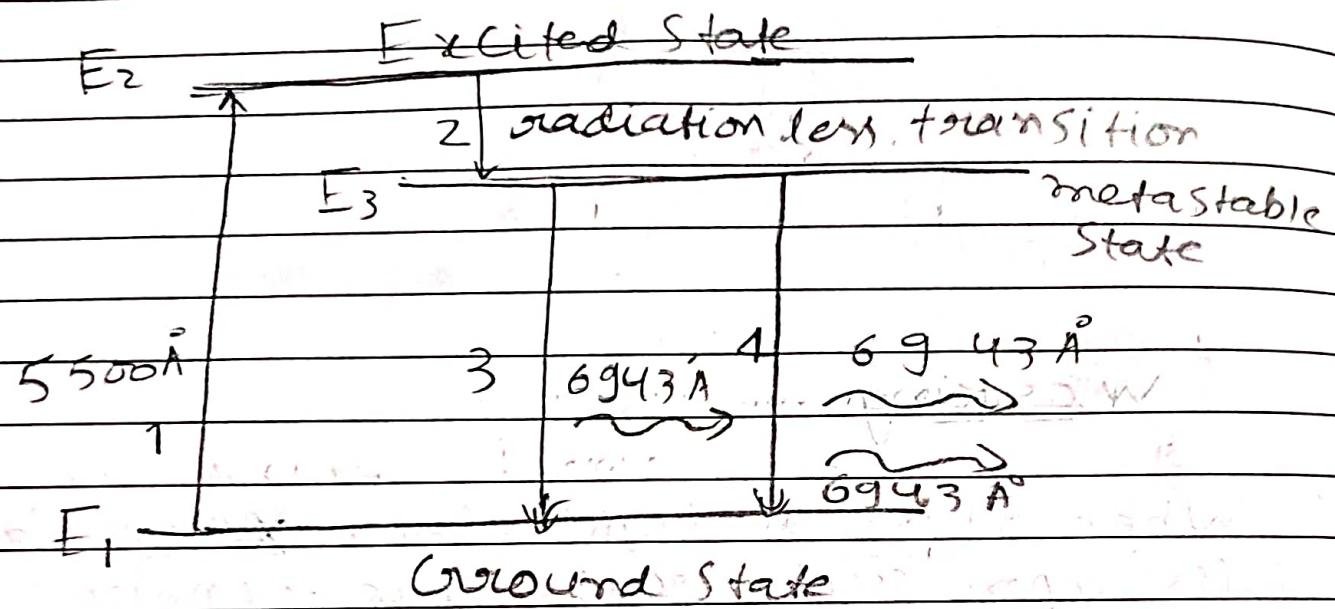
Xe-coated flash lamp.



Working

- When flash of light from ~~xenon lamp~~ falls upon ruby rod, cerium ions (Ce^{+++}) absorb photon of wavelength 5500 \AA and move to excited state E_2 . (Transition 1)
- The excited ion gives some part of energy to the crystal and moves to metastable state E_3 (Transition 2)
- One ion transitions to ground state by spontaneous emission emitting a photon of wavelength 6943 \AA (Transition 3)
- This photon travels through the rod and is reflected back and forth until it stimulates an ion in E_3 to stimulated emission. (Transition - 4) Hence two photons are emitted
- Process 4 is repeated again and again

when heat becomes intense, laser comes out
the partially on silvered end.



Drawback

the laser light emitted is in the form of
pulses.

* Helium-Neon laser (4-level laser)

Construction 1:- Active System

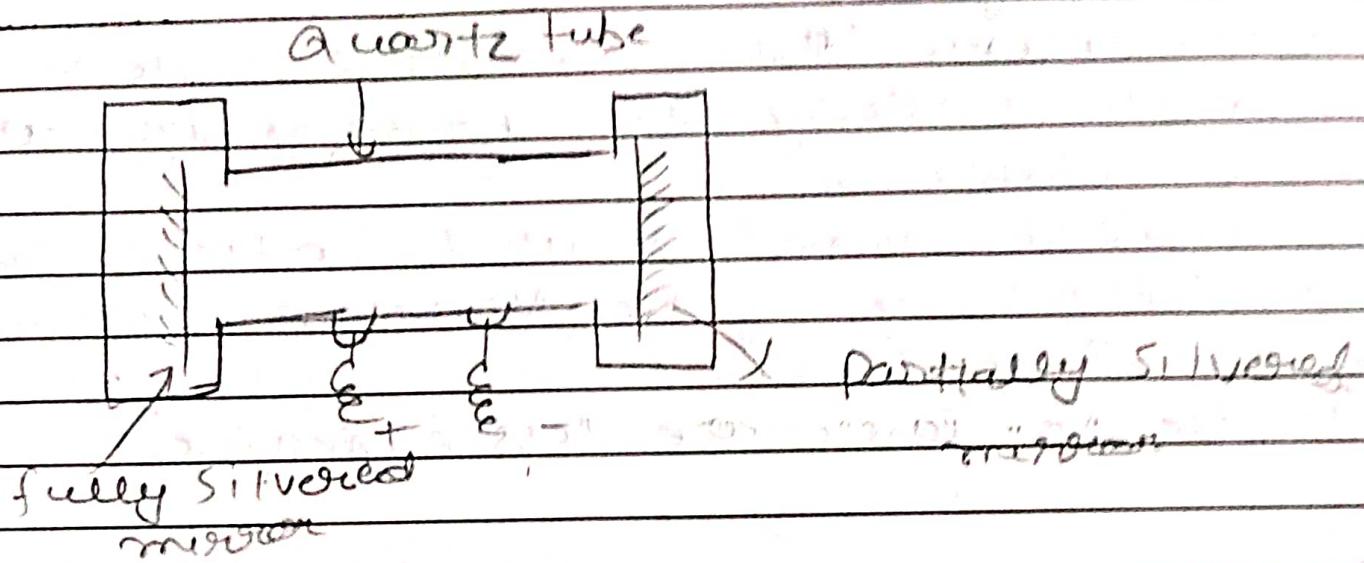
it consist a narrow discharge tube of
Chordy quartz filled with Helium &
and Neon in the ratio 7:1 at low
pressure.

Construction 2:- Inelastic atom pumping

Inelastic atom atom is used two
electrode are connected to high frequency
alternating current.

Construction:- Resonator

Two plane parallel mirrors are attached with a tube. distance between mirror is integral multiple of laser wavelength



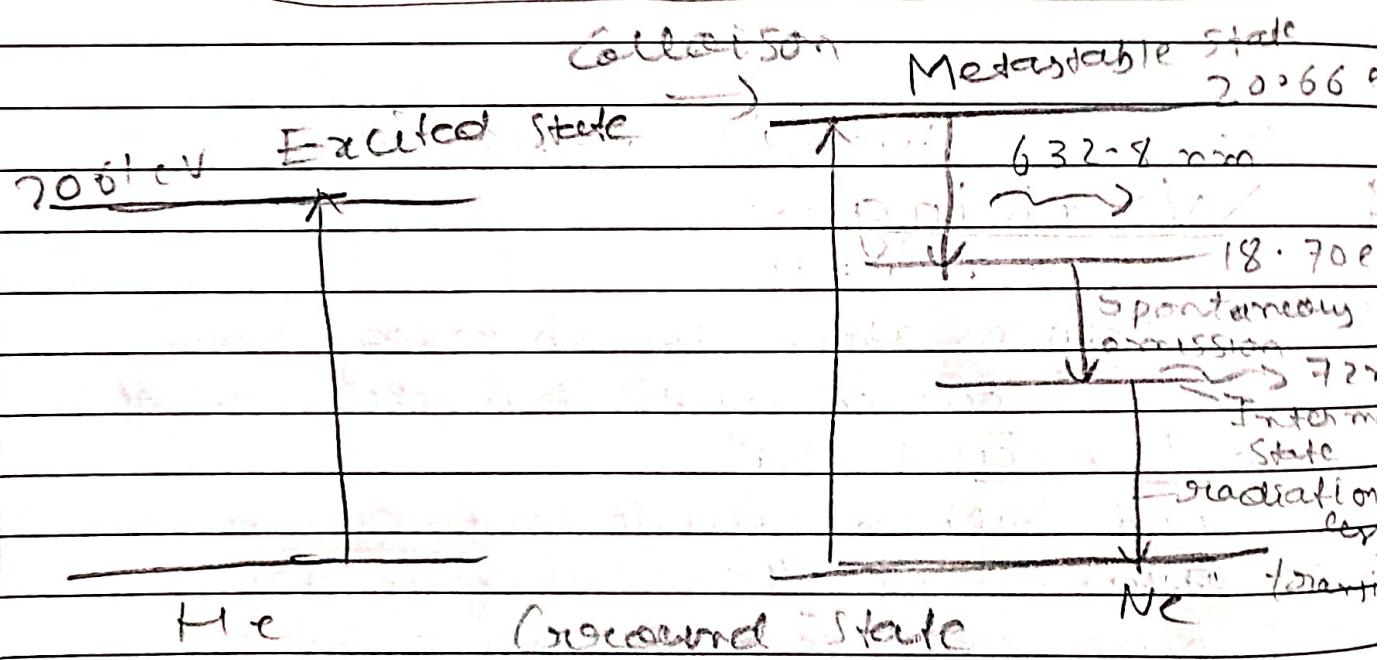
Working

1. the helium atoms absorb energy from electrons produced by electric discharge and move to excited state.
2. Excited helium collide with ground state neon and transfer their energy to neon. So that neon moves to metastable state.
3. When population inversion is achieved, laser action takes place between metastable state and excited state. At $(18-70 \text{ eV})$
4. Another transition due to Spontaneous emission from excited to intermediate state gives in coherent photon of wavelength 72 nm Nm
5. The stereo

5. the remaining exciting energy is lost in collision with tube's walls and neon refers to ground state.

Advantage :-

1. Confinement layer is emitted in He-Ne laser while in Ruby laser pulses of light are emitted.
2. Coolant is not required in He-Ne laser.
3. efficiency of He-Ne is greater than Ruby laser.
4. He-Ne laser are less expensive.



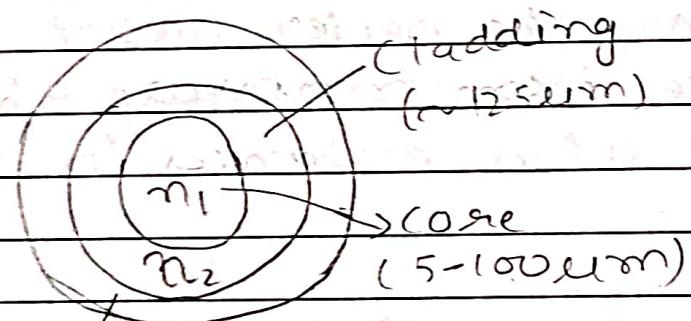
Fibre optics

fundamental idea about optical fibre

* it is a ~~hair~~ thin flexible transparent medium of wire shape usually made by glass or plastic Data can be send using optical fibre cables through light way. This cable can carry use amount of information in the form of light wave from one place to other with negligible loss and width bandwidth.

Basic Structure

(cross-sectional view)



outer shield

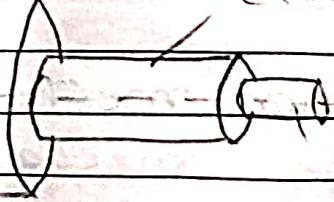
or jacket

→ 250 μm

Side view

outer shield

cladding



Fibre axis

Fibre structure has three ~~in~~ ⁱⁿ section
Sections

- i) Core :- It is the innermost section made by pure glass or plastic. It has diameter from 5 - 100 μm .
- ii) Cladding :- Core is surrounded by another layer of glass with slightly lesser refractive index than core. It is called cladding and has a diameter about 125 μm .
- iii) Outer shield or jacket :- It is made by plastic or polymer with diameter 250 μm . The outer jacket protects the fibre from moisture absorption and also enhances its tensile strength.

Principle of operation

An optical fibre is a cylindrical wave guide that propagates information coded in the form of light along its length by the process of total internal reflection.

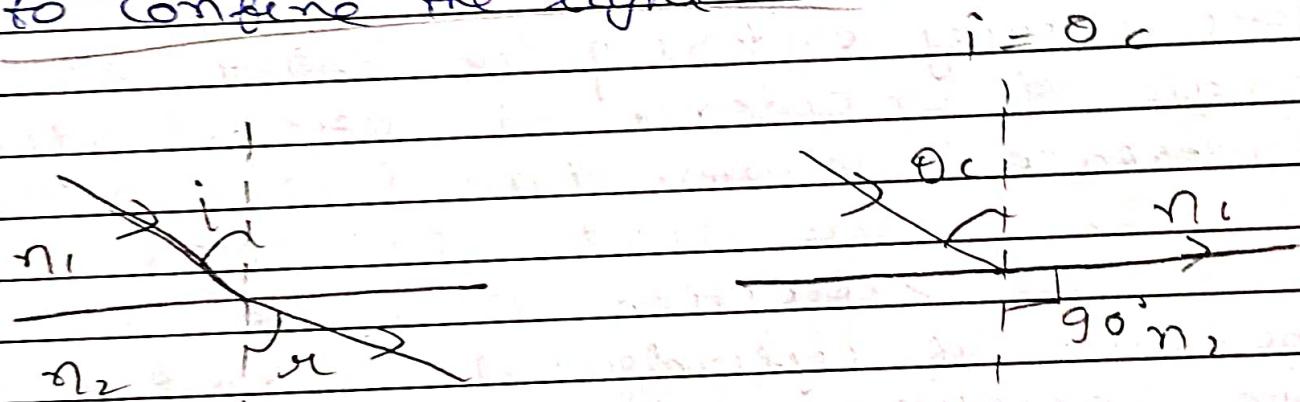
Propagation mechanism in optical fibre: Propagation mechanism is based on total internal reflection.

i) When light passes from denser to rarer medium it bends away from the normal if $i > i'$ in concaves are also increased because $n = \frac{\sin i}{\sin r}$ is constant.

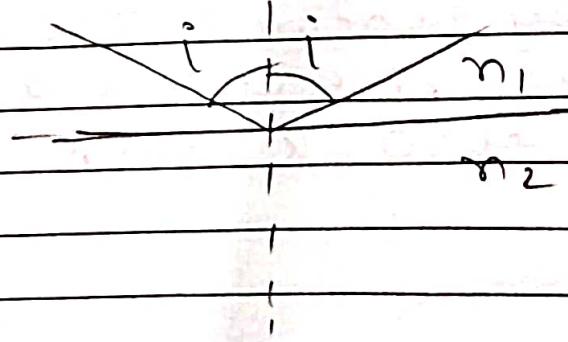
ii) At a particular angle of incidence θ_c , the refracted ray makes 90° with the normal. θ_c is called critical angle.

iii) When angle of incidence is further increased the refracted ray turns back into the same medium this is called total internal reflection.

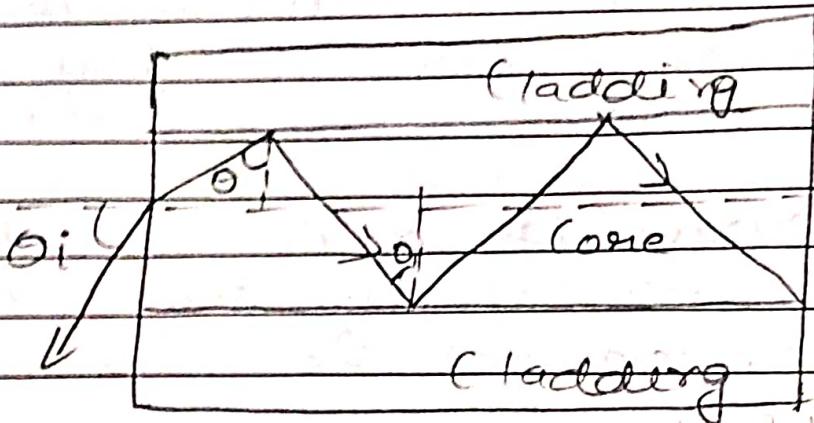
This effect is used in optical fibres to confine the light.



$$i > \theta_c$$



Communication in optical fibres



The effect of TIR is used to communicate via-optical fibre. The refractive index of a Core is slightly greater than refractive index of Cladding so that Core is denser than Cladding.

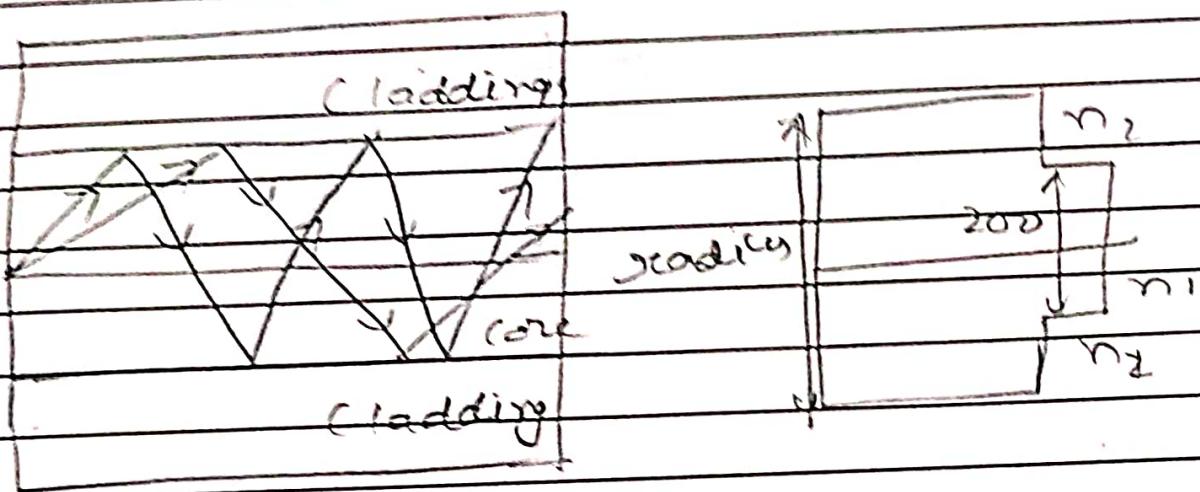
for a ray entering the fibre, if angle of incidence at core cladding interface is greater than critical angle $\theta > \theta_c$, the light gets total internal reflection into the core. because of cylindricical symmetry in the structure of fibre this ray will suffer TIR from lower interface also.

therefore the light get guided through the core by repeated TIR. thus an optical fibre act as a light guide and is also known as wave guide.

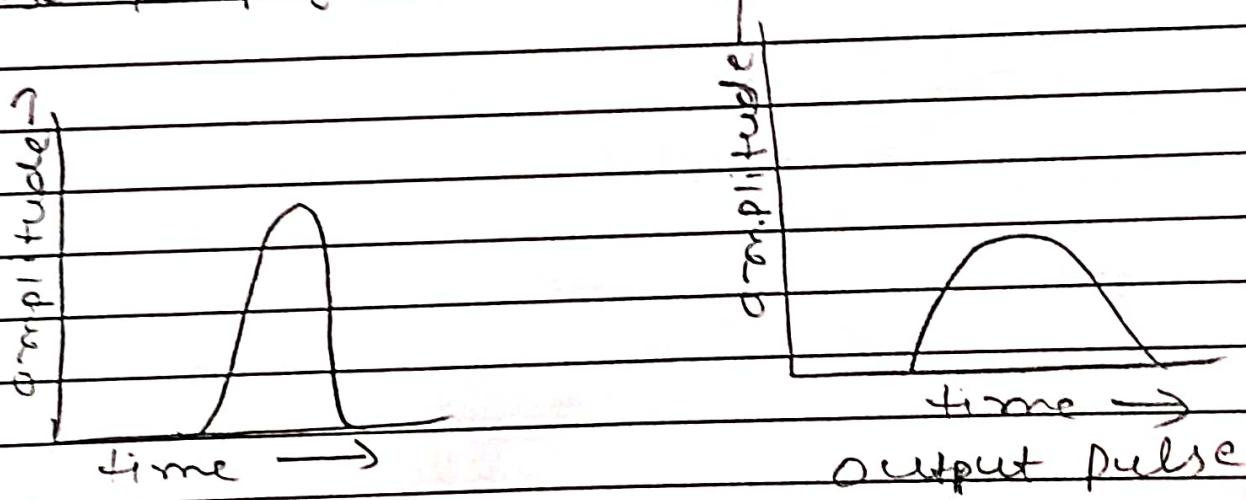
Types of optical fiber

On the basis of refractive index and refractive index modes the fibers can be divided into three types.

Step-index multimode fiber

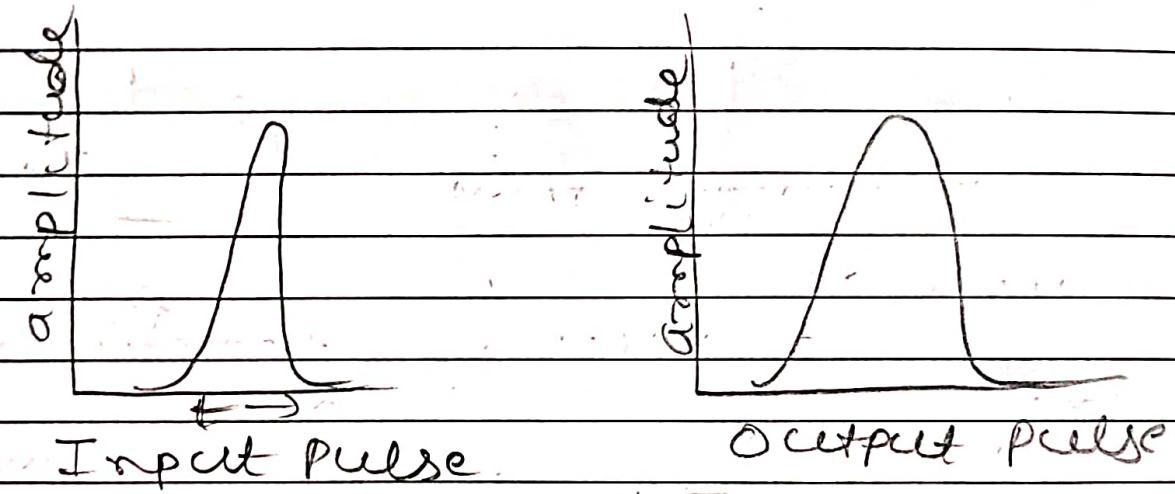
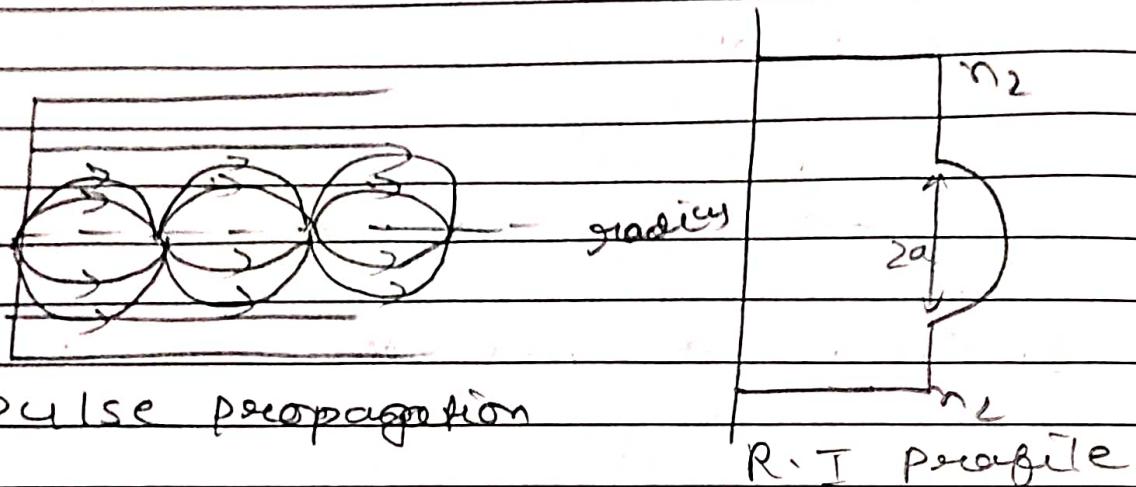


pulse propagation



Input pulse

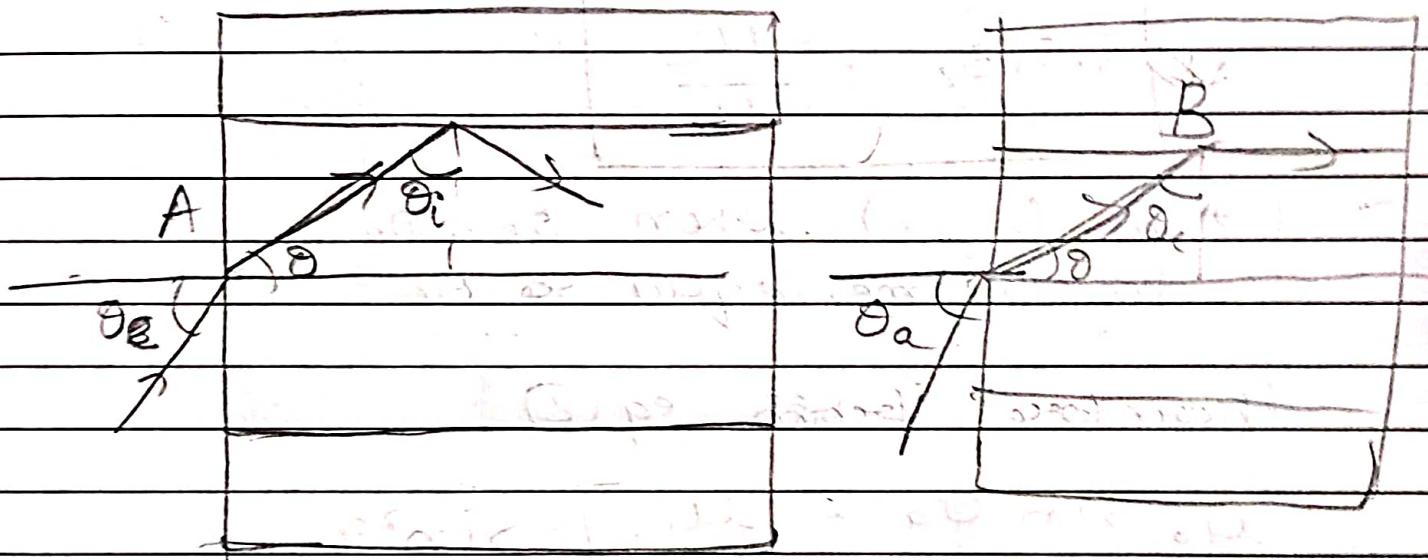
Graded index multi mode fibre



- In this fibre the R.I of core decreases gradually from maximum value at the core to the minimum constant value at the core cladding interface. R.I of grading is constant.
- A ray entering the fibre continuously bent towards the core of fibre.
- the path of ray is smooth sinusoidal
- all the rays take same time to reach the receiving end. therefore modal dispersion is greatly minimized in ~~geo~~ GRIN.

* Acceptance Angle - the rays transmitted by TIR must have angle of incident greater than critical angle at the core cladding interface.

"the light ray should incident on the core with in a maximum external angle θ_a to have the condition ($\theta_i > \theta_c$) for propagating down the core. This angle θ_a is known as Acceptance angle for the fibre. It depends upon refractive index of core and cladding."



$$\sin \theta_e = n_1, \quad \theta + \theta_i = 90^\circ$$

$$\sin \theta = n_2, \quad \theta_i = 90^\circ - \theta$$

Using Snell's law for point A, (fig 1)

$$\frac{\sin \theta_e}{\sin \theta} = \frac{n_1}{n_2}$$

$$\frac{\sin \theta_e}{\sin \theta} = \frac{1.5}{1.0}$$

$$1.5 \sin \theta = 1.0 \sin \theta \quad \text{--- (1)}$$

$$\therefore \theta + \theta_i = 90^\circ$$

$$\theta = 90^\circ - \theta_i$$

$$u_0 \sin \theta_c = u_1 \sin(90^\circ - \theta_i)$$

$$u_0 \sin \theta_c = u_1 \cos \theta_i$$

$$u_0 \sin \theta_c = u_1 \sqrt{1 - \sin^2 \theta_i} \quad \text{--- (1)}$$

using Snell's law for point B (fig 2)

$$\frac{\sin \theta_c}{\sin \theta_i} = \frac{u_2}{u_1}$$

$$\boxed{\sin \theta_c = \frac{u_2}{u_1} \sin \theta_i}$$

From fig(2), when $\theta_c = \theta_a$
 θ_i becomes equal to θ_c

therefore from eq (2)

$$u_0 \sin \theta_a = u_1 \sqrt{1 - \sin^2 \theta_a}$$

for Air $u_0 = 1$

$$\sin \theta_a = u_1 \sqrt{1 - \frac{u_2^2}{u_1^2}}$$

$$\boxed{\sin \theta_a = \sqrt{u_1^2 - u_2^2}}$$

for another medium

$$\boxed{\sin \theta_a = \sqrt{u_1^2 - u_2^2}}$$

Numerical Aperture

Numerical Aperture is a number which defines the light gathering capacity of a fibre when light is emitted from source only a fraction $(NA)^2$ of the total amount of light can be collected by the fibre.

$$NA = \sin \theta_a = \frac{\sqrt{e_1^2 - e_2^2}}{e_0}$$

In air $e_0 = 1$

$$NA = \sin \theta_a = \sqrt{e_1^2 - e_2^2}$$

Relative Refractive index difference

$$\Delta = \frac{e_1 - e_2}{e_1}$$

$$\Delta = \frac{e_1 - e_2}{e_1} \times \frac{(e_1 + e_2)}{(e_1 + e_2)}$$

$$\Delta = \frac{e_1^2 - e_2^2}{e_1 \cdot 2e_1}$$

$\therefore e_1 - e_2$ is very small

$$\therefore e_1 + e_2 \approx 2e_1$$

$$\Delta = \frac{u_1^2 - u_2^2}{2u_1^2}$$

$$u_1^2 - u_2^2 = 2\Delta u_1^2$$

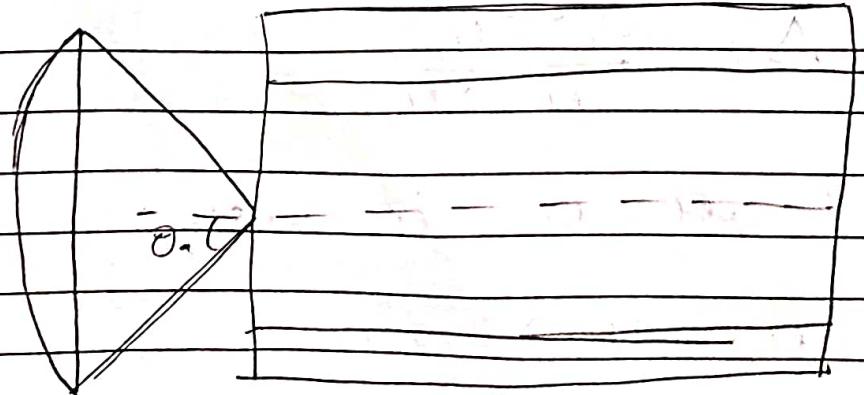
$$\sqrt{u_1^2 - u_2^2} = u_1 \sqrt{2\Delta}$$

$$NA = u_1 \sqrt{2\Delta}$$

* Acceptance Cone

the rays incident at angle greater than θ_a would be reflecting refracted including planing only the rays falling at angle θ to θ_a would propagate to the fibre.

The cone formed with acceptance angle θ_a as vertex angle is called acceptance cone. All the rays falling within the cone can propagate to the fiber through the fibre.



* Numbers of modes & Cut-off parameter (V-number)

The various structural parameters of fibre can be combined into a normalised parameter known as V number or normalised frequency off cut-off.

$$V = \frac{2\pi a}{\lambda_0} (NA)$$

$$V = \frac{2\pi a}{\lambda_0} \sqrt{\epsilon_r^2 - \epsilon_s^2}$$

If fibre is in a medium of R.I. μ_0 ,

$$V = \frac{2\pi a}{\lambda_0} \mu_0 \sqrt{\epsilon_r^2 - \epsilon_s^2}$$

For MMF

$$\text{No of mode} = \frac{V^2}{2}$$

For GRIN

$$\text{No of mode} = \frac{V^2}{4}$$

For SMF

$$\text{No of mode} = 1$$

For SMF, $V < 2.405$

For MMF, $V \geq 2.405$

out of all, only those modes will be propagated for which cut off freq is less than V number.

* Attenuation

the reduction in amplitude/intensity of fibre or power of a signal as it is propagated. In optical fibre is called

\Rightarrow Attenuation.

Attenuation loss is measured in decibels. A decibel is express as base 10 log logarithm of ratio of output power to input power.

$$dB = 10 \log_{10} \frac{P_{out}}{P_{in}}$$

$$dB = 10 \log_{10} \frac{P_{out}}{P_{in}}$$

Attenuation coefficient is expressed in dB/km.

$$\alpha = -\frac{1}{L} \log_{10} \frac{P_{out}}{P_{in}} \text{ dB/km}$$

-ve sign indicates loss

* Signal losses in optical fibre

1. Absorption Loss :- the absorption of light by the core and cladding is the main source of Attenuation. Light is absorbed by material itself or impurities and imperfection. When glass molecule interact with electron neutron gamma rays, X-rays etc. Structure of glass molecule changes and absorption loss occurs.

2. Rayleigh scattering loss :-

Glass has microscopic inhomogeneities such as bubble, impurity particle etc. Light is scattered by these object. Fibre with large N.A. exhibit greater scattering loss. This loss is more prominent in the wavelength range 500 to 1550 nm.

3. Waveguide Scattering loss :-

Irregularities in geometry of optical fibre is the main source of wave guide scattering loss. This losses can be minimised by putting third layer of pure silica around them cladding. refractive index of

refractive index is higher than cladding
but lower than core.

4) bending loss: it is of two types:

i) micro bending \Rightarrow this loss occurs when core surface has small variation in shape. Shows the incident angle changes at the core cladding interface and light reflects back in cladding.

ii) Macro bending: \Rightarrow this loss occurs due to scrapping the fibre or pulling the fibre cable around corner. Larger core radius and smaller bending radius increases bending loss.

Dispersion

The information which is to be transmitted is coded in the form of light pulse then these pulses are fed into the fibre. The pulse broadens in time as it passes through fibre.

"The phenomenon of broadening or spreading of pulse is known as dispersion". It occurs because the rays are sent at the same time but after travelling through fibre, they reach output end at different times. The types of dispersion are as follows:-

i) Intermodal dispersion or modal dispersion:-

it occurs in multimode fibres. Since each path of light has a different length therefore some of light reaches receiving end sooner than the others this leads to pulse spreading. If broadening is large, the adjacent pulses will overlap at the output end and may not be resolved.

(ii) Intra-modal dispersion or chromatic dispersion:-

Since optical source do not emit just a single frequency but a band of frequency. Each wavelength travels with different speed in the core. This causes broadening of pulse in each single mode. It is further divided into two categories.

a) material dispersion

a) material dispersion:- Pulse of light usually contains several wavelengths. The speed of different wavelengths are different in core. Causing the spreading of light pulse.

b) wave guide dispersion:- Wave guide dispersion it is cause because some light travels in the cladding also. Velocity of light is higher in cladding than core (since $\epsilon_1 > \epsilon_2$). Wave guide

dispersion depends on the difference of n_1 and n_2 and core diameter.

Advantage of fibre optics

- i) Optical fibre have lower transmission losses. thus more data can be send over long distances.
- ii) light beam has a very high information carrying capacity due to high frequency therefore transmission at higher data rate is possible.
- iii) light weight and small ~~size~~ ~~size~~ having thin size dimension.
- iv) Optical fibre can withstand environmental conditions better and have a long life than copper wires.
- v) Optical fibre cable are cheaper.
- vi) Bandwidth of optical fibre is higher.

Disadvantage of fibre optics

- i) working with fibres carelessly may face hazards of glass shards.
- ii) it requires a new set of skills for installation and maintenance.