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OS - special layer

=> including: Kernel - sys calls  
Build-in library - C lib  
Drivers  
Shell

Shell is terminal => Bash

Process in hierarchy

Sys call / lib calls

↓ stack FILO

↑ heap

Data segment  
Consect  
Text segment

Segmentation

File Allocation Table  
FAT 32

-> 4 G =  $2^{32}$

NTFS

New Technology File system

malloc()

=> OS 分配虚拟内存

L2

register / cache / main memory

DMA => direct Memory Access

Kernel data struct

· 单链表 · 双链表  
· 环形链表 · 二叉搜索树  
· 哈希表 · B+树

① Thread.

single unique execution context.

fully describe program state

[PC, Reg, Execution Flags, Stack]

② Address space.  $2^{32} = 4 G$

set of accessible addresses

& state associate with them.

Switch context. => PC, SP, reg.

③ Protection (process)

1. Reliability
2. Security
3. Privacy
4. Fairness

code	data	file
reg stack	reg stack	reg stack
{	}	}

④ Dual mode Kernel / User.

Mode switch

- Sys call
- interrupt 中断向量
- Trap / Exception

L3 fork() return child pid / 0 (in parent)

exec\*() 清空原来地址空间  
新命令 return 后不再回老命令

wait() 等待子进程 SIG CHILD  
若子进程已返回, 直接返回

waitpid()

init() - first pid.

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PCB Process Control Block.

User time CPU time in User mode.

Sys time ——— kernel mode

fork()

In kernel

update PID / runtime. / Point to parent  
In child. and list of children  
in parent.

user space. All copy  
opened File 0 stdin 1 stdout  
2 stderr

exec()

user space:

clear local var, Dynamic alloc mem  
Reset Global var, Code/Constants

exit()

free All In user space.

But Not in kernel. self have entry

In PCB,

父进程接收 SIGCHLD 因收处理子进程

signal handlers 清理返回清理的 pid.

未清理的 linux 会标 defunct

Re-parenting by pid 1 => init  
更新 parent pointer / list of children

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SIGSEGV SIGCHLD

SIGINT SIGTERM SIGSTP  
+ C KILL + Z

SIGCONT | SIGKILL

同步/异步异常 SIGFPE 溢点

signal() 信号注册 alarm() 信号定时.

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Context switch

1. reg

2. address space (expensive)

[3. TLB / cache / buff reload]

Real 实际时间

Sys - kernel mode

User - user mode

user  $\geq$  sys bound by CPU  
user < sys bound by I/O

PCB 用双链表管理

调度算法 1. Short Job first

2. round robin 3. Priority ~

wait Time: TASK (开始 - 到达) + 等待

Turnround: TASK (完成 - 到达)

Turnround - wait = 实际运行

Preemptive 抢占式

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Inter process Communication

1. Pipe / named pipe

2. signal POSIX

3. Message

4. share mem

5. semaphore

6. socket

Race Condition 竞争状态

Solution 须满足

1. Mutual exclusion 独一

2. Bounded waiting 有限时

3. Progress 一定有

解决方案:

1. CS 互斥屏蔽上段切换

2. Basic spin lock 忙

3. Peterson solution

4. semaphore

5. POSIX semaphore 读 => post +1

6. mutex - lock wait -1

share obj. multi process, concurrency