

# Hashing

Method of searching in which searching is independent of no. of elements

## Hash Table:

It's an array addressed via Hash function.

## Hash Function:

Converts the key into cor. location in Hash Table

Two types of Hash function:

1) Distribution-dependent

2) Distribution-independent

⇒ Distr. dependent:

Obtained by examining subset of key values cor. to desired results records.

⇒ Distr. independent:

Does not utilize distr. of keys in HashTable to compute location of desired record.

## Most pop. distribution-independent functions:

- 1) Division method      2) Mod-square
- 3) Folding      4) Digit analysis
- 5) Length dependent method

Main Idea:

→ Find 1-1 correspondence bet<sup>n</sup> key value & index

Criteria to decide Hash func<sup>n</sup>:

- Easy & quick to compare
- Achieve even distr. of keys, that occur across range of indices

### 1) Division Method:

- Convert key to integer
- mod size of index range
- Remainder as result

Hash func<sup>n</sup>:

$H(K) = K \% i$  if index start from 0

$H(K) = (K \% i) + 1$  index start from 1



E.g. Size of Hash table = 97

key = 2763

$$H(2763) = 2763 \% 97$$

= 48      index starts from 0

= 49      " ——— " ——— 1

### e) Med-Square method

$H(k) = x$ , where  $x$  is obtained by selecting appropriate no. of digits from middle of square of key-value  $k$ .

E.g. select 3 digits at even pos. & starting from rightmost digit in the sq.

K:	1234	2345	3456
$K^2$ :	1522756	5499025	11943936
$H(k)$ :	525	492	933

Drawback: Time consuming computation

Advantage: Uniform Distr. of Keys

### 3) Folding method:

→ Partition the key into no. of parts  $k_1, k_2, k_3, \dots, k_n$ , where each part, except possibly the last, has possibly same no. of digits or reqd. add. width.

→ The parts are added together ignoring the last carry.

$$H(K) = K_1 + K_2 + K_3 + \dots + K_n$$

Last carry if any, is ignored

If keys are in binary form, EX-OR operation may be sub. for add<sup>n</sup>.

Fold shifting → Even parts are  $K_2, K_4, \dots$  are each reversed before add<sup>n</sup>.

Fold boundary → Two boundary parts  $K_1$  &  $K_n$  each reversed & added with all other parts.

E.g.

K:	1522756	5499025	11943936
Chopping:			
Chopping:	01 52 27 56 + + +	05 49 90 25 + + +	11 94 39 36 + + +
Pure	: 136	169	= 180
foldng			
Fold	: 01 + 25 + 27 + 65	05 + 94 + 90 + 52	11 + 49 + 39 + 63
shifting	= 118	= 241	= 162
Fold	: 10 + 52 + 27 + 65	50 + 49 + 90 + 52	11 + 94 + 39 + 63
boundary	= 154	= 241	= 207



Useful in converting multi-word keys into a single word, so that other hashing func<sup>n</sup>.

#### 4) Digit Analysis Method

Form hash addresses by extracting and/or shifting the extracted digits or bits of the original key.

E.g.: Key value: 6732541

can be transformed to hash add. 427 by extracting the digits in even pos. & then reversing it.

For a given set of keys, the pos<sup>n</sup> in the keys & same rearrangement pattern must be used consistently.

Useful in case of static files where the key values of all the records.

### Collision Resol<sup>n</sup>

Size = 10      Indices: 0, 1, 2, ... 8, 9

Keys: 10, 19, 35, 43, 62, 59, 31, 49, 77, 33

Allocation of more than one key values in one value in one location in Hash table is called collision.

Two methods to resolve collision:

- 1) Closed Hashing (also called <sup>Open Addr.</sup> ~~linear~~ <sup>probing</sup>)
- 2) Open Hashing (Chaining)

Closed Hashing:

→ Linear Probing

→ Quadratic Probing

→ Double Hashing

Linear Probing:

Size of table =  $n$

Addr. of mapping =  $i$

Start with at loc<sup>n</sup> where collision occurs.  
Let it be  $i$ , then do sequential search until,

$i, i+1, i+2, \dots, n, 1, 2, \dots, i-1$

- Desired index is empty
- If des. loc<sup>n</sup> not empty then find empty loc<sup>n</sup> is encountered
- It reaches loc<sup>n</sup> where search st.



Hash table is considered to be circular, hence technique is called closed hashing. Probe means key comparison.

~~Size of Hash Table =~~

Size of Hash Table: 10

No. of elements: 8

Keys:

16, 66, 77, 31, 42, 52, 76, 67

Hash function:  $H(K) = K \% \text{size}$

~~S-1(16)~~

Index:	S-1(16)	S-2(66)	S-3(77)	S-4(31)	S-5(42)
0					
1				31	31
2					42
3					
4					
5					
6	16	16	16	16	16
7		66 *	66	66	66
8			77 *	77	77
9					

~~S-~~

S-2: Collision at index: 6

S-3: Collision at index: 7

Index	S-6 (52)	S-7 (76)	<del>S-8 (67)</del>	S-8 (67)
0			<del>67</del>	67*
1	31	31	<del>67</del>	31
2	42	42	/	42
3	52*	52		52
4				
5				
6	16	16	/	16
7	66	66		66
8	77	77		77
9		76*		76

S-6: Collision at Index: 2

S-7: Collision at Index: 6, 7, 8

S-8: Collision at Index: 7, 8, 9

### c) Quadratic Probing

→ Quadratic probing is a coll. resol. method that eliminates primary clustering.

→ For linear probing, If there is a coll. at loc.  $i$  then next  $i+1, i+2, i+3$  etc. loc<sup>n</sup> are to be probed, but in quad., the next loc. to be probed are  $i+1^2, i+2^2, i+3^2$ .



If  $H(K) \% S$  is full

then try  $H(K) = (H(K) + i^2) \% S$   
where  $(i = 0, 1, 2, \dots, n)$

### Primary Clustering

- Linear probing
- Create long runs of filled slots near the hash pos<sup>n</sup>
- If primary index is  $x$ , subseq. probes go to  $x+1, x+2, x+3, \dots$
- Reduces searching time & perf.

### Secondary Clustering:

- Quadratic probing
- Create long runs of filled slots away from the hash pos<sup>n</sup> of keys.
- primary index =  $i$ , subsequent searches go to  $i+1, i+4, i+9, i+16$