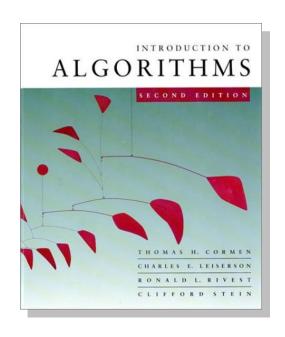
Introduction to Algorithms 6.046J/18.401J



LECTURE 17

Shortest Paths I

- Properties of shortest paths
- Dijkstra's algorithm
- Correctness
- Analysis
- Breadth-first search

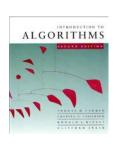
Prof. Erik Demaine



Paths in graphs

Consider a digraph G = (V, E) with edge-weight function $w : E \to \mathbb{R}$. The *weight* of path $p = v_1 \to v_2 \to \cdots \to v_k$ is defined to be

$$w(p) = \sum_{i=1}^{k-1} w(v_i, v_{i+1}).$$

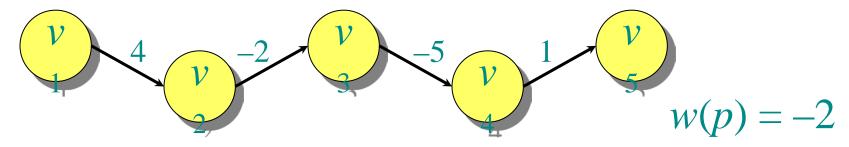


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Example:





Shortest paths

A shortest path from u to v is a path of minimum weight from u to v. The shortest-path weight from u to v is defined as

 $\delta(u, v) = \min\{w(p) : p \text{ is a path from } u \text{ to } v\}.$

Note: $\delta(u, v) = \infty$ if no path from u to v exists.



Well-definedness of shortest paths

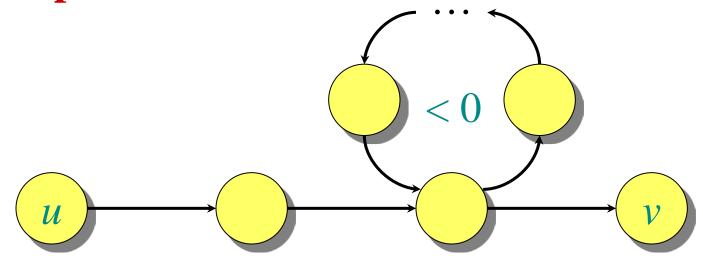
If a graph *G* contains a negative-weight cycle, then some shortest paths do not exist.



Well-definedness of shortest paths

If a graph *G* contains a negative-weight cycle, then some shortest paths do not exist.

Example:





Optimal substructure

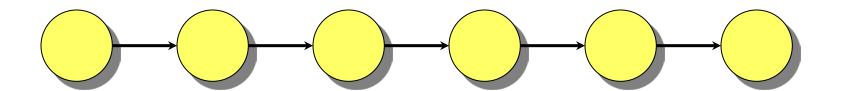
Theorem. A subpath of a shortest path is a shortest path.



Optimal substructure

Theorem. A subpath of a shortest path is a shortest path.

Proof. Cut and paste:

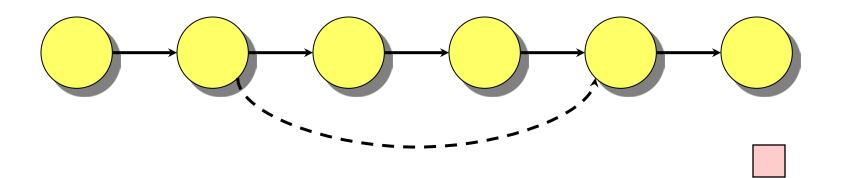




Optimal substructure

Theorem. A subpath of a shortest path is a shortest path.

Proof. Cut and paste:





Triangle inequality

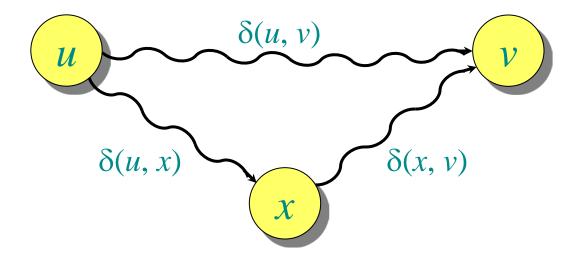
Theorem. For all $u, v, x \in V$, we have $\delta(u, v) \leq \delta(u, x) + \delta(x, v)$.



Triangle inequality

Theorem. For all $u, v, x \in V$, we have $\delta(u, v) \leq \delta(u, x) + \delta(x, v)$.

Proof.



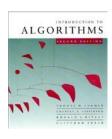


Single-source shortest paths (nonnegative edge weights)

Problem. Assume that $w(u, v) \ge 0$ for all $(u, v) \in E$. (Hence, all shortest-path weights must exist.) From a given source vertex $s \in V$, find the shortest-path weights $\delta(s, v)$ for all $v \in V$.

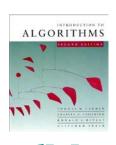
IDEA: Greedy.

- 1. Maintain a set *S* of vertices whose shortest-path distances from *s* are known.
- 2. At each step, add to S the vertex $v \in V S$ whose distance estimate from S is minimum.
- 3. Update the distance estimates of vertices adjacent to ν .



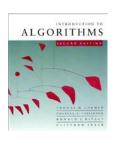
Dijkstra's algorithm

$$d[s] \leftarrow 0$$
for each $v \in V - \{s\}$
do $d[v] \leftarrow \infty$
 $S \leftarrow \emptyset$
 $Q \leftarrow V$
 $\Rightarrow Q$ is a priority queue maintaining $V - S$, keyed on $d[v]$



Dijkstra's algorithm

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d[s] \leftarrow 0
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                   \triangleright Q is a priority queue maintaining V-S,
                     keyed on d[v]
while Q \neq \emptyset
    do u \leftarrow \text{Extract-Min}(Q)
         S \leftarrow S \cup \{u\}
         for each v \in Adj[u]
             do if d[v] > d[u] + w(u, v)
                      then d[v] \leftarrow d[u] + w(u, v)
```

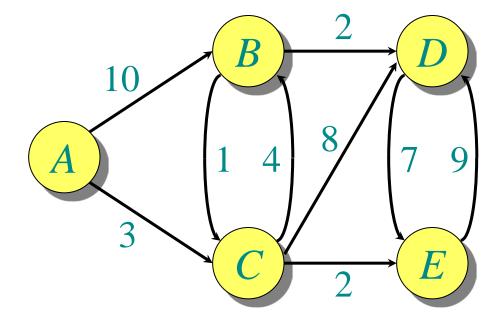


Dijkstra's algorithm

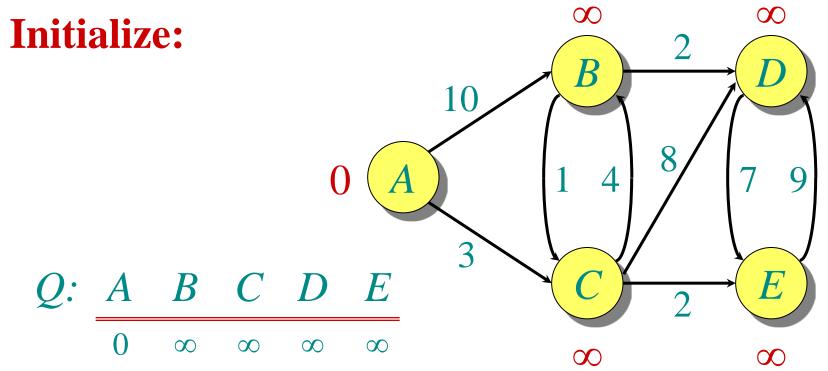
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while Q \neq \emptyset
    do u \leftarrow \text{Extract-Min}(Q)
        S \leftarrow S \cup \{u\}
        for each v \in Adi[u]
                                                            relaxation
             do if d[v] > d[u] + w(u, v)
                     then d[v] \leftarrow d[u] + w(u, v)
                                       Implicit Decrease-Key
```



Graph with nonnegative edge weights:

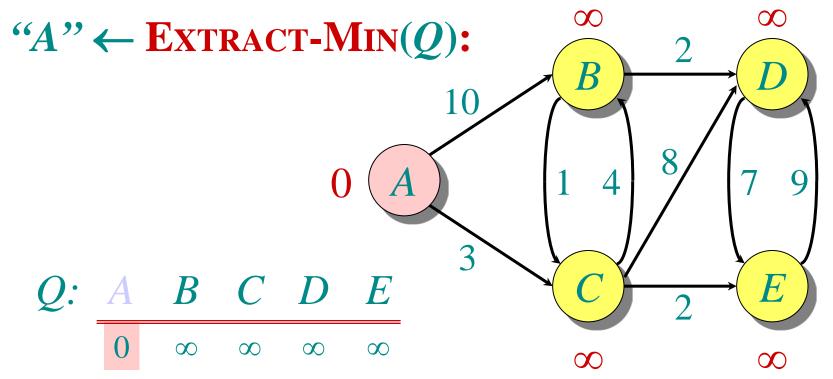






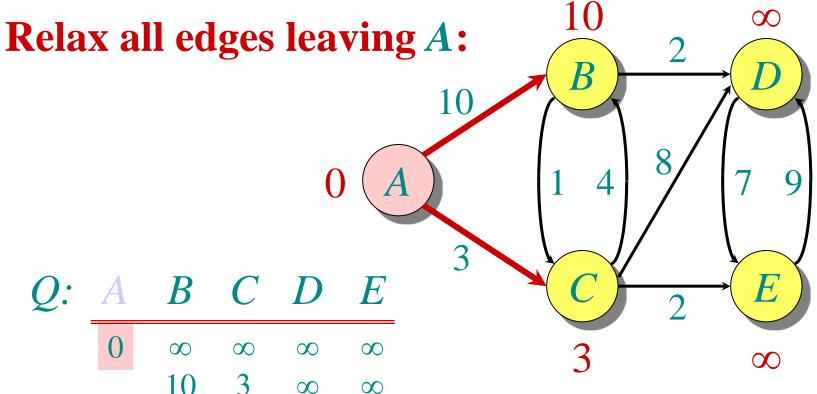
S: {}





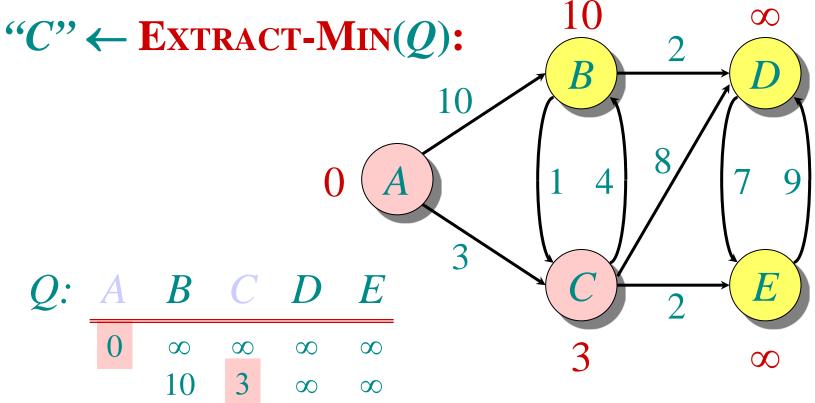
S: { A }





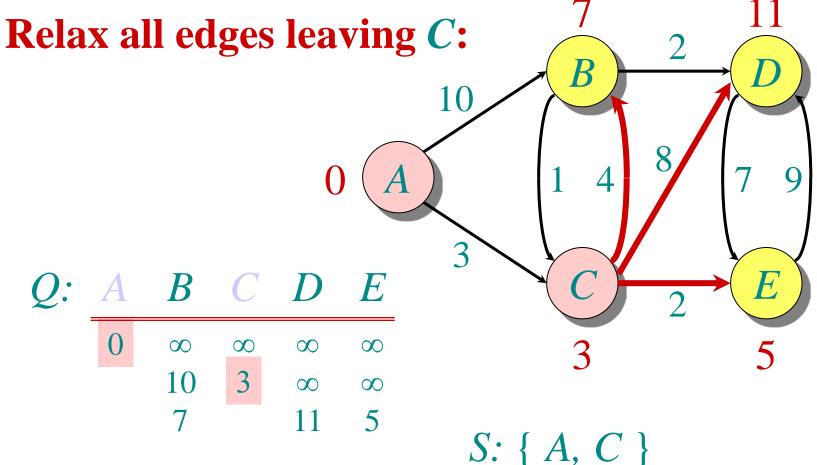
S: { A }



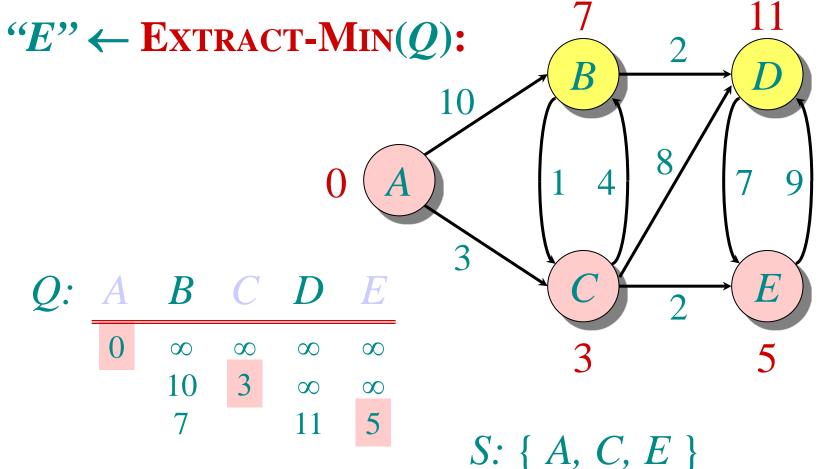


S: { A, C }

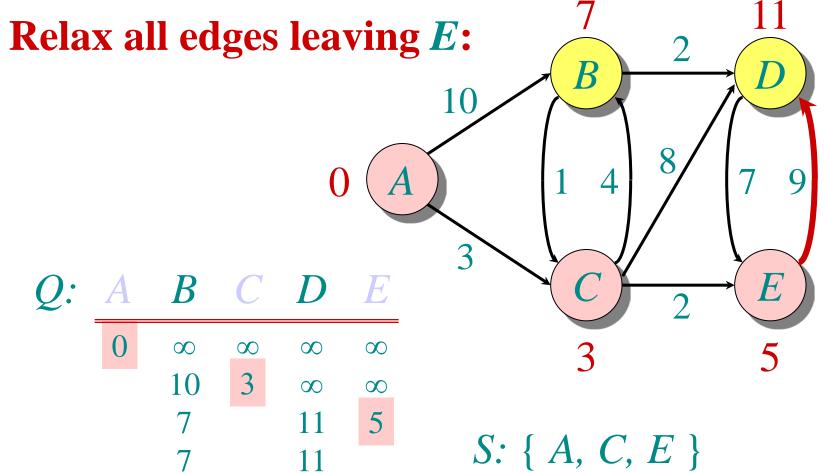




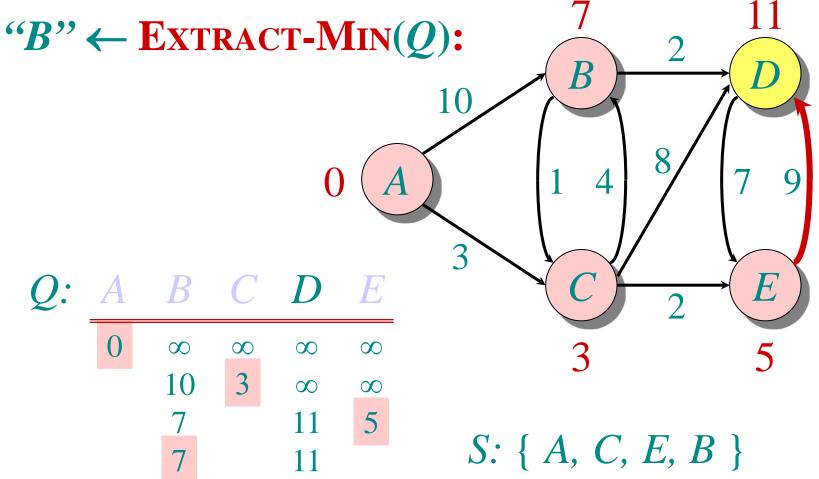




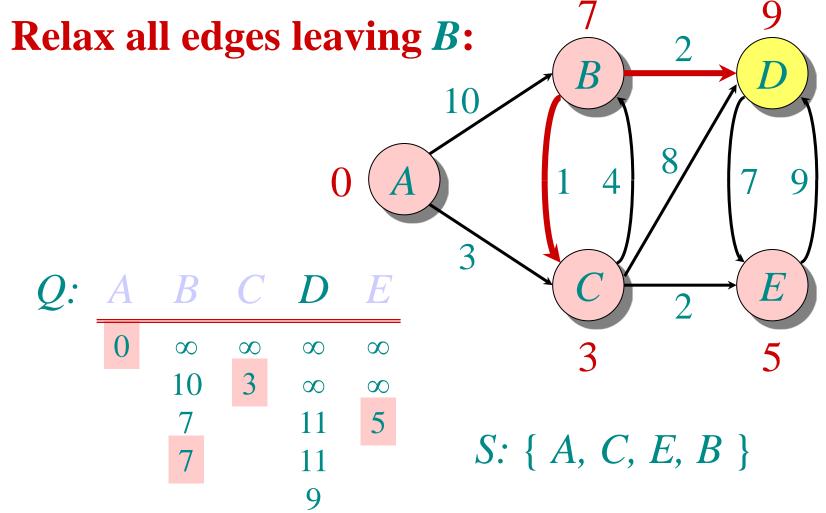




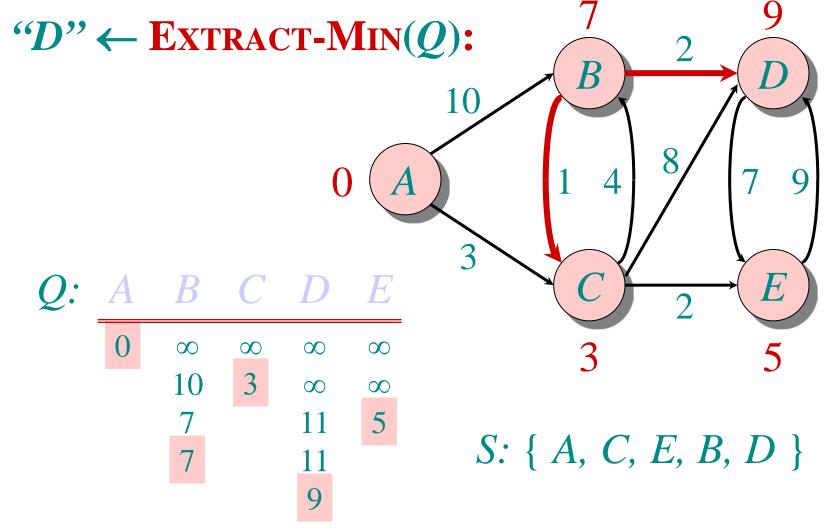








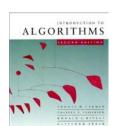






Correctness — Part I

Lemma. Initializing $d[s] \leftarrow 0$ and $d[v] \leftarrow \infty$ for all $v \in V - \{s\}$ establishes $d[v] \ge \delta(s, v)$ for all $v \in V$, and this invariant is maintained over any sequence of relaxation steps.



Correctness — Part I

Lemma. Initializing $d[s] \leftarrow 0$ and $d[v] \leftarrow \infty$ for all $v \in V - \{s\}$ establishes $d[v] \ge \delta(s, v)$ for all $v \in V$, and this invariant is maintained over any sequence of relaxation steps.

Proof. Suppose not. Let v be the first vertex for which $d[v] < \delta(s, v)$, and let u be the vertex that caused d[v] to change: d[v] = d[u] + w(u, v). Then,

$$d[v] < \delta(s, v)$$
 supposition
 $\leq \delta(s, u) + \delta(u, v)$ triangle inequality
 $\leq \delta(s, u) + w(u, v)$ sh. path \leq specific path
 $\leq d[u] + w(u, v)$ v is first violation

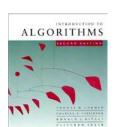
Contradiction.





Correctness — Part II

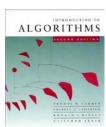
Lemma. Let u be v's predecessor on a shortest path from s to v. Then, if $d[u] = \delta(s, u)$ and edge (u, v) is relaxed, we have $d[v] = \delta(s, v)$ after the relaxation.



Correctness — Part II

Lemma. Let u be v's predecessor on a shortest path from s to v. Then, if $d[u] = \delta(s, u)$ and edge (u, v) is relaxed, we have $d[v] = \delta(s, v)$ after the relaxation.

Proof. Observe that $\delta(s, v) = \delta(s, u) + w(u, v)$. Suppose that $d[v] > \delta(s, v)$ before the relaxation. (Otherwise, we're done.) Then, the test d[v] > d[u] + w(u, v) succeeds, because $d[v] > \delta(s, v) = \delta(s, u) + w(u, v) = d[u] + w(u, v)$, and the algorithm sets $d[v] = d[u] + w(u, v) = \delta(s, v)$.



Correctness — Part III

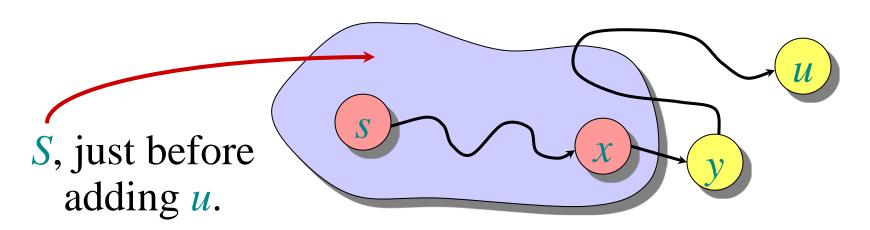
Theorem. Dijkstra's algorithm terminates with $d[v] = \delta(s, v)$ for all $v \in V$.



Correctness — Part III

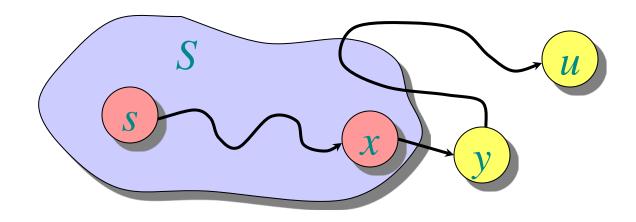
Theorem. Dijkstra's algorithm terminates with $d[v] = \delta(s, v)$ for all $v \in V$.

Proof. It suffices to show that $d[v] = \delta(s, v)$ for every $v \in V$ when v is added to S. Suppose u is the first vertex added to S for which $d[u] > \delta(s, u)$. Let y be the first vertex in V - S along a shortest path from s to u, and let x be its predecessor:





Correctness — Part III (continued)



Since u is the first vertex violating the claimed invariant, we have $d[x] = \delta(s, x)$. When x was added to S, the edge (x, y) was relaxed, which implies that $d[y] = \delta(s, y) \le \delta(s, u) < d[u]$. But, $d[u] \le d[y]$ by our choice of u. Contradiction.



Analysis of Dijkstra

```
while Q \neq \emptyset

\mathbf{do} \ u \leftarrow \text{Extract-Min}(Q)

S \leftarrow S \cup \{u\}

\mathbf{for} \ \text{each} \ v \in Adj[u]

\mathbf{do} \ \mathbf{if} \ d[v] > d[u] + w(u, v)

\mathbf{then} \ d[v] \leftarrow d[u] + w(u, v)
```



Analysis of Dijkstra



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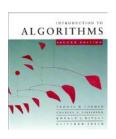
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Analysis of Dijkstra

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|V|
times
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Handshaking Lemma $\Rightarrow \Theta(E)$ implicit Decrease-Key's.



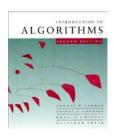
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```

Handshaking Lemma $\Rightarrow \Theta(E)$ implicit Decrease-Key's.

Time =
$$\Theta(V \cdot T_{\text{EXTRACT-MIN}} + E \cdot T_{\text{DECREASE-KEY}})$$

Note: Same formula as in the analysis of Prim's minimum spanning tree algorithm.



$$Time = \Theta(V) \cdot T_{\text{EXTRACT-MIN}} + \Theta(E) \cdot T_{\text{DECREASE-KEY}}$$

T_{EXTRACT-MIN} T_{DECREASE-KEY}

Total

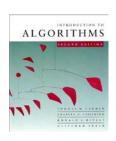


$$Time = \Theta(V) \cdot T_{\text{EXTRACT-MIN}} + \Theta(E) \cdot T_{\text{DECREASE-KEY}}$$

TEXTRACT-MIN TDECREASE-KEY

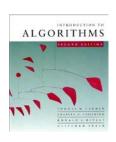
Total

array



Time =
$$\Theta(V) \cdot T_{\text{EXTRACT-MIN}} + \Theta(E) \cdot T_{\text{DECREASE-KEY}}$$

Q $T_{\mathrm{EXTRACT\text{-}MIN}}$ $T_{\mathrm{DECREASE\text{-}KEY}}$ Total array O(V) O(1) $O(V^2)$ binary heap $O(\lg V)$ $O(\lg V)$ $O(\lg V)$ $O(\lg V)$

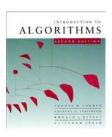


Time =
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Total TEXTRACT-MIN TDECREASE-KEY O(1)array binary $O(\lg V)$ $O(\lg V)$ $O(E \lg V)$ heap **Fibonacci** $O(E + V \lg V)$ $O(\lg V)$ amortized amortized heap worst case



Suppose that w(u, v) = 1 for all $(u, v) \in E$. Can Dijkstra's algorithm be improved?



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• Use a simple FIFO queue instead of a priority queue.



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Breadth-first search

while Q \neq \emptyset

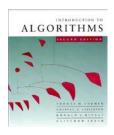
do u \leftarrow \text{Dequeue}(Q)

for each v \in Adj[u]

do if d[v] = \infty

then d[v] \leftarrow d[u] + 1

Enqueue(Q, v)
```



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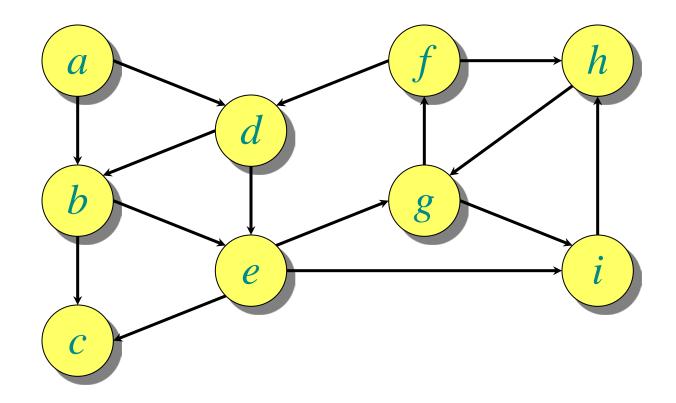
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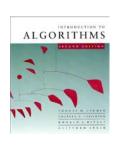
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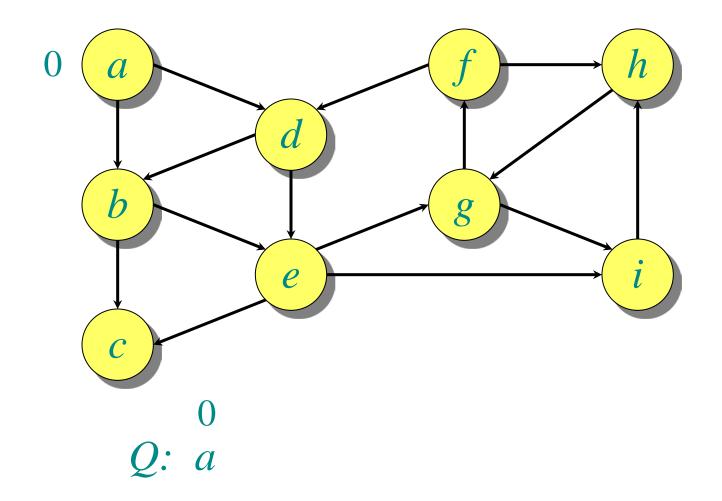
Analysis: Time = O(V + E).



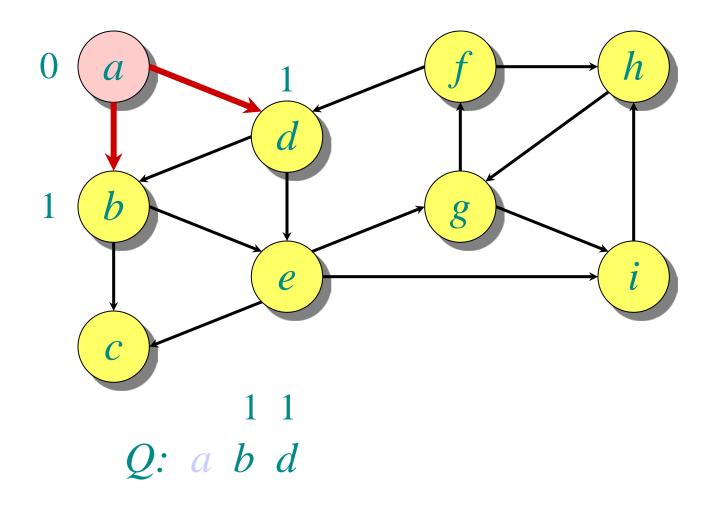


Q:

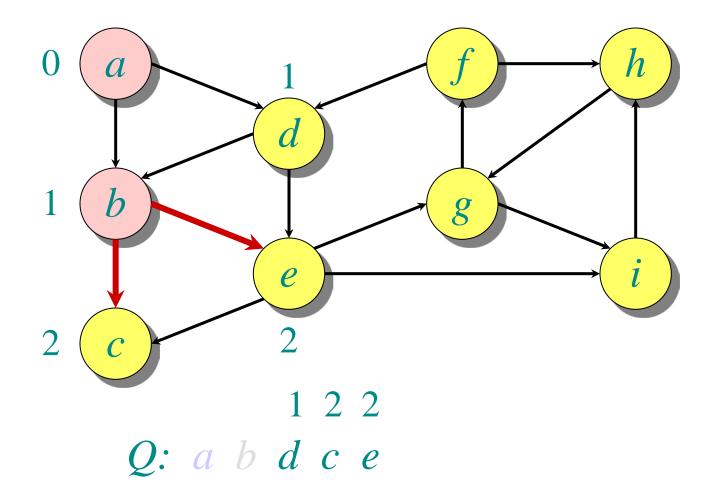




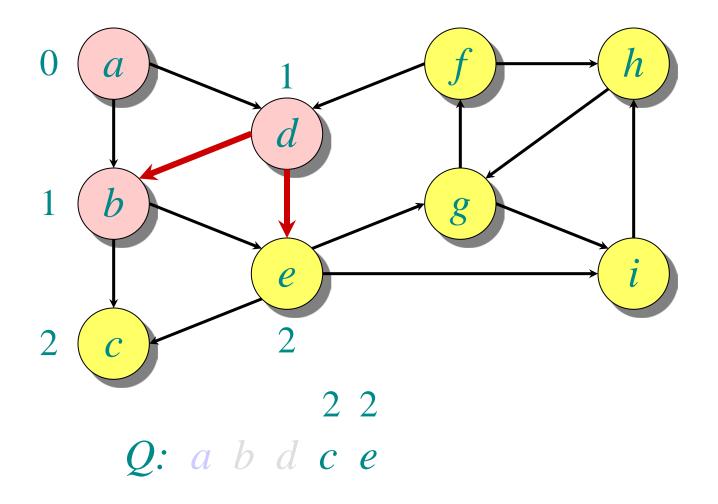




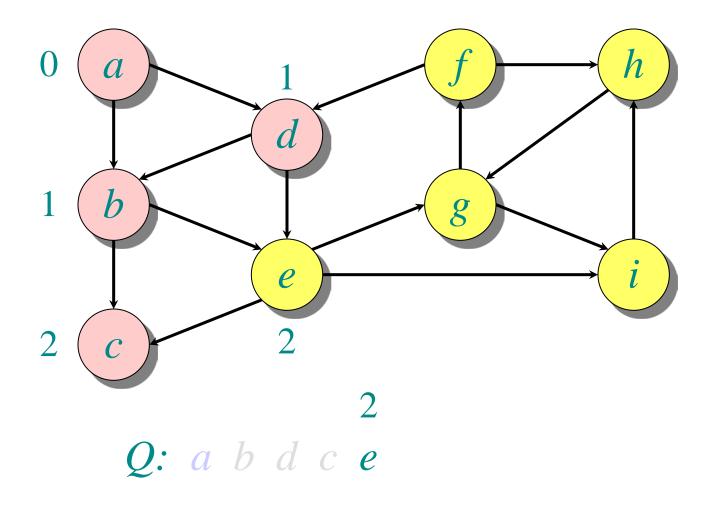


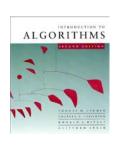


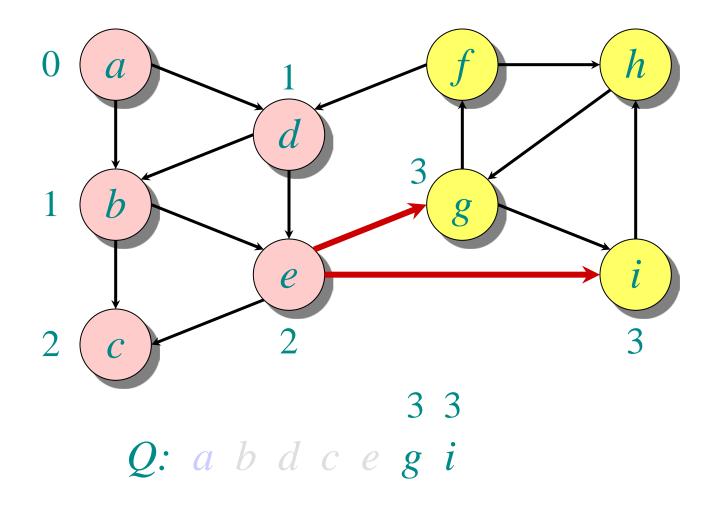


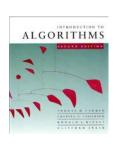


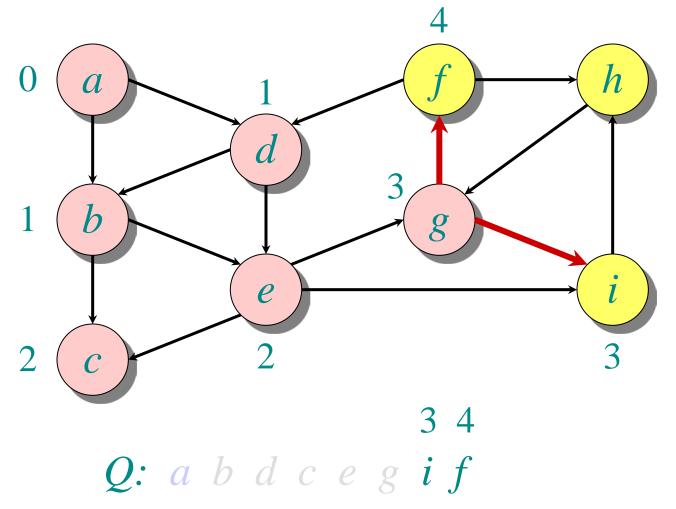




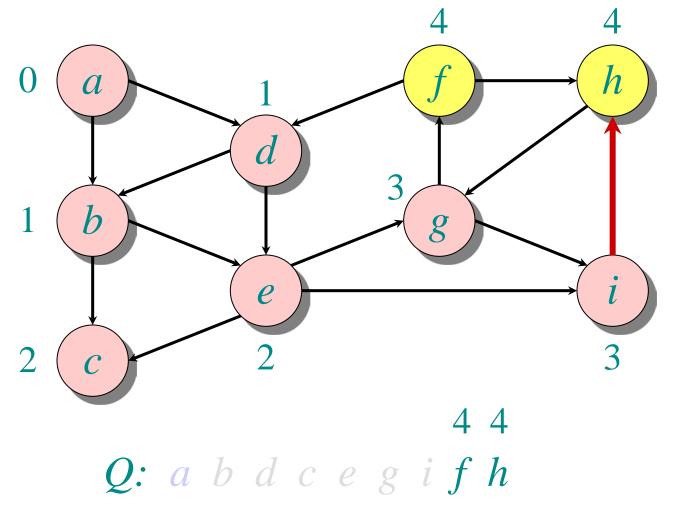


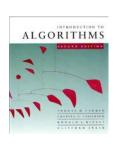


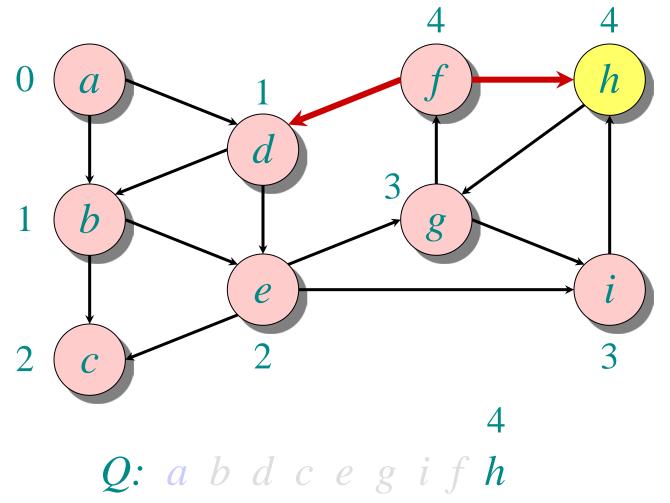




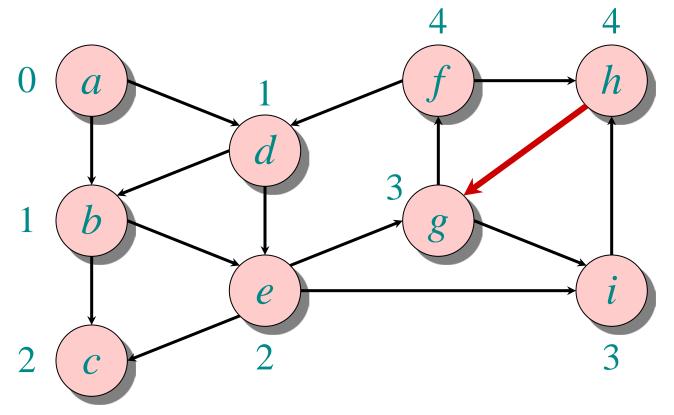






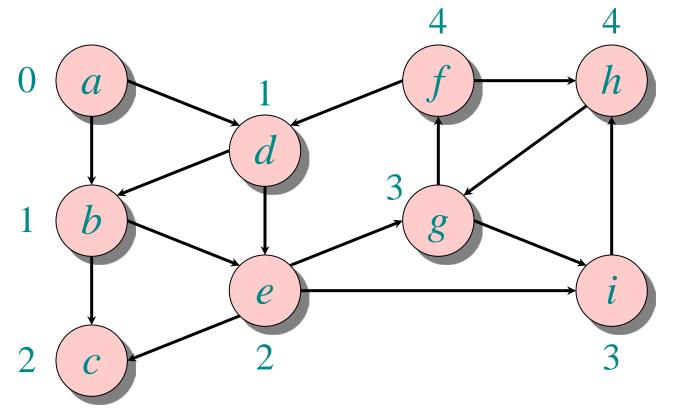






Q: abdcegifh





Q: abdcegifh



Correctness of BFS

```
while Q \neq \emptyset

\mathbf{do} \ u \leftarrow \mathrm{DEQUEUE}(Q)

\mathbf{for} \ \mathrm{each} \ v \in Adj[u]

\mathbf{do} \ \mathbf{if} \ d[v] = \infty

\mathbf{then} \ d[v] \leftarrow d[u] + 1

\mathrm{ENQUEUE}(Q, v)
```

Key idea:

The FIFO *Q* in breadth-first search mimics the priority queue *Q* in Dijkstra.

• Invariant: v comes after u in Q implies that d[v] = d[u] or d[v] = d[u] + 1.