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Experiment 5a		
AIM	To perform filtering of Long Data Sequence using Overlap Add Method.	
OBJECTIVE:	To Develop a function to implement Fast Overlap Add Algorithm .	
INPUT SPECIFICATIONS:	 Length of first Signal L and Signal values Length of impulse response of FIR filter Signal M and Signal values. 	
PROBLEM DEFINITION:	Take long input sequence $x[n]$ and short length sequence $h[n]$ Find $y[n] = x[n] * h[n]$ using FFT based Overlap Add method	
RESULT:	Input: x[n] = { 1, 2, 3, 4, 5, 6, 1, 1, 1, 1, 1, 1, 0, 1, 2, 3, 4, 5 } h[n] = { 1, 1, 1 } Length M=3 Overlap Add Method For N=8, and M=3, Let L = 6 Then, x 1 [n] = { 1,2,3,4,5,6, 0, 0} x 2 [n] = { 1,1,1,1,1,1, 0, 0 } x 3 [n] = { 0, 1,2,3,4,5,0,0 } Output: y[n] = { 1, 3, 6, 9, 12, 15, 12, 8, 3, 3, 3, 2, 2, 3, 6, 9, 12, 9, 5 }	

```
P-LG4IQEFB MINGW64 ~/OneDrive/FOSIP/EXPERIMENTS/05. Linear Filtering using OAM and OSM
$ ./a.exe
   Enter the length of x[n] = : 18
 Enter the values of x[n] : 1 2 3 4 5 6 1 1 1 1 1 1 0 1 2 3 4 5
 Enter the length of h[n] M = : 3
  Enter the values of h[n] : 1 1 1
 0.00
 h[n] = 1.00 1.00 1.00
   length of decomposed input Signal : L = 5
  length of decomposed output Signal : N = 8
 x1[n] = 1.00
                                                                2.00
                                                                                              3.00
                                                                                                                           4.00
                                                                                                                                                        5.00
                                                                                                                                                                                      0.00
                                                                                                                                                                                                                    0.00
                                                                                                                                                                                                                                                 0.00
 y1[n] = 1.00
                                                            3.00
                                                                                                6.00
                                                                                                                            9.00
                                                                                                                                                          12.00
                                                                                                                                                                                           9.00
                                                                                                                                                                                                                       5.00
                                                                                                                                                                                                                                                   -0.00
 x2[n] = 6.00
                                                                    1.00
                                                                                                  1.00
                                                                                                                               1.00
                                                                                                                                                             1.00
                                                                                                                                                                                           0.00
                                                                                                                                                                                                                        0.00
                                                                                                                                                                                                                                                      0.00
 y2[n] = 6.00
                                                                     7.00
                                                                                                  8.00
                                                                                                                                3.00
                                                                                                                                                              3.00
                                                                                                                                                                                           2.00
                                                                                                                                                                                                                        1.00
                                                                                                                                                                                                                                                      -0.00
 x3[n] = 1.00
                                                                    1.00
                                                                                                  0.00
                                                                                                                               1.00
                                                                                                                                                             2.00
                                                                                                                                                                                           0.00
                                                                                                                                                                                                                        0.00
                                                                                                                                                                                                                                                      0.00
 y3[n] = 1.00
                                                                     2.00
                                                                                                  2.00
                                                                                                                                2.00
                                                                                                                                                              3.00
                                                                                                                                                                                           3.00
                                                                                                                                                                                                                        2.00
                                                                                                                                                                                                                                                       -0.00
  x4[n] = 3.00
                                                                     4.00
                                                                                                  5.00
                                                                                                                             0.00
                                                                                                                                                             0.00
                                                                                                                                                                                          0.00
                                                                                                                                                                                                                       0.00
                                                                                                                                                                                                                                                  0.00
  y4[n] = 3.00
                                                                     7.00
                                                                                                  12.00
                                                                                                                                   9.00
                                                                                                                                                                5.00
                                                                                                                                                                                              -0.00
                                                                                                                                                                                                                               -0.00
  Linear Convolution Output using Over Add Method y[n] = 1.00 \quad 3.00 \quad 6.00 \quad 9.00 \quad 12.00 \quad 2.00 \quad 3.00 \quad 6.00 \quad 9.00 \quad 12.00 \quad 9.00 \quad
                                                                                                                                                                                           15.00
                                                                                                                                                                                                                           12.00
                                                                                                                                                                                                                                                            8.00
                                                                                                                                                                                                                                                                                                                                                    3.00
                                                                                                                                                                                                                                                                                                                                                                                3.00
                                                                                                                                                                                                                                                                                                                                                                                                                2.00
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Experiment 5b	
AIM	To perform filtering of Long Data Sequence using Overlap Save Method
OBJECTIVE:	To Develop a function to implement Fast Overlap Save Algorithm.
INPUT SPECIFICATIONS:	 Length of first Signal L and Signal values Length of impulse response of FIR filter Signal M and Signal values.
PROBLEM DEFINITION:	Take long input sequence $x[n]$ and short length sequence $h[n]$ Find $y[n] = x[n] * h[n]$ using FFT based Overlap Save method
RESULT:	Input:

```
x[n] = \{1, 2, 3, 4, 5, 6, 1, 1, 1, 1, 1, 1, 0, 1, 2, 3, 4, 5\}
h[n] = \{1, 1, 1\} Length M = 3
Overlap Save Method: For N = 8, and M = 3 Let L = 6
Then, x 1 [n] = \{0, 0, 1, 2, 3, 4, 5, 6\}
x 2 [n] = \{ 5, 6, 1, 1, 1, 1, 1, 1 \}
x 3 [n] = \{1, 1, 0, 1, 2, 3, 4, 5\}
x 4 [n] = \{ 4, 5, 0, 0, 0, 0, 0, 0 \}
Output:
y[n] = \{1, 3, 6, 9, 12, 15, 12, 8, 3, 3, 3, 2, 2, 3, 6, 9, 12, 9, 5\}
  $ gcc OSM.c -lm
  $ ./a.exe
   Enter the length of x[n] = : 18
   Enter the values of x[n] : 1 2 3 4 5 6 1 1 1 1 1 1 0 1 2 3 4 5
   Enter the length of h[n] M = : 3
   Enter the values of h[n]: 111
          1.00
                 2.00
                        3.00
                               4.00
          1.00
                 1.00
   length of decomposed input Signal : L = 6
   length of decomposed output Signal : N = 8
          0.00
                                             4.00
                                                    5.00
                                                           6.00
  y1[n] =
          11.00
                   6.00
                                3.00
                                              9.00
                                                     12.00
                                                             15.00
  x2[n] =
          5.00
                 6.00
                               1.00
                         1.00
                                             1.00
                                                    1.00
                                                           1.00
           1.00
                  1.00
                               1.00
                                             3.00
                                                    4.00
                                                           5.00
          10.00
                   7.00
                                2.00
                                                            12.00
  Linear Convolution Output using Over Save Method
                                             15.00
                                                                                                2.00
                 3.00
                                                     12.00
          1.00
                       6.00
                              9.00
                                      12.00
          3.00
                               12.00
```

Conclusion:

- 1. The Overlap-Add and Overlap-Save Method is an efficient practical way to evaluate the discrete convolution of long input signal x[n] and finite length signal h[n].
- 2. The Overlap-Add and Overlap-Save Method can be implemented using FIR filters and can not be implemented using IIR filters.
- 3. The Overlap-Add and Overlap-Save Method is a Block Processing Technique.