GCS	PLUGIN
GLOBAL_POSITION_INT	**I_State**
time_boot_ms (unsigned int)	time_boot_ms (unsigned int)
lat (int)	lat (int)
lon (int)	lon (int)
alt (int)	alt (int)
relative_alt (int)	relative_alt (int)
vx (int)	vx (int)
vy (int)	vy (int)
vz (int)	vz (int)
hdg (unsigned int)	hdg (unsigned int)
ATTITUDE	**I_Rotation**
time_boot_ms (unsigned int)	data status (byte)
roll (float)	data quality (byte)
pitch (float)	timestamp (timestampType)
yaw (float)	roll (double)
rollspeed (float)	pitch (double)
pitchspeed (float)	yaw (double)
yawspeed (float)	attitudeType (EAttitudeType)
	deviceID (string)
MISSION_ITEM	**I_Waypoint**
target_system (unsigned int)	target_system (unsigned int)
target_component (unsigned int)	target_component (unsigned int)
seq (unsigned int)	seq (unsigned int)
frame (unsigned int)	frame (unsigned int)
command (unsigned int)	command (unsigned int)
current (unsigned int)	current (unsigned int)
autocontinue (unsigned int)	autocontinue (unsigned int)
param1 (float)	param1 (float)
param2(float)	param2(float)
param3 (float)	param3 (float)
param4 (float)	param4 (float)
x (float)	x (float)
y (float)	y (float)
z (float)	z (float)
COMMAND_LONG	**I_Command**
target_system (unsigned int)	target_system (unsigned int)
target_component (unsigned int)	target_component (unsigned int)
command (unsigned int)	command (unsigned int)
confirmation (unsigned int)	confirmation (unsigned int)
param1(float)	param1(float)
param2(float)	param2(float)
param3(float)	param3(float)
param4(float)	param4(float)
param5(float)	param5(float)
param6(float)	param6(float)
param7(float)	param7(float)
STATUSTEXT	**I_Error**
Severity (unsigned int)	errorMessage (string)
Text (char[50])	id (string)
	level (ECriticalityLevel)
	timestamp (timeStampType)