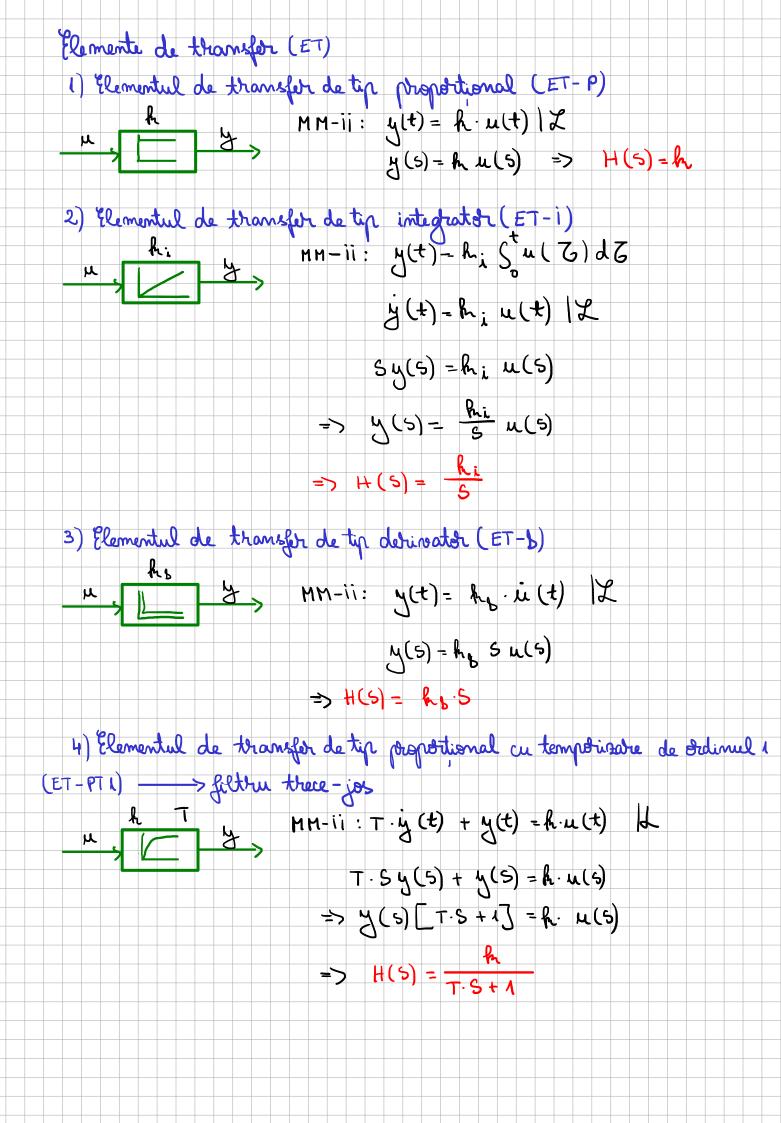


```
H(5) = lom 5 + lom 15 + ... + los + lo

an 5 + an 15 + ... + a15 + a0
                                                      m < M
2) MM-11 in time discret
  am y (k+m) +an-, y (k+m-1) +...+ a, y (k+1) + a o y (k) =
               = &m u( k+m) + &m-1 (h+m-1) +... + b, u( h+1) + bo u(h)
 Je aplică tran sprimata Z
 am = y(z) +am-, = y(z)+ - + a, = y(z)+ao y(z) =
              = 6m^{2}u(2) + 6m^{-1}2u(2) + ... + 6, 2u(2) + 60u(2)
 y(2) [an2+...+a,2+a] = u(2) [bm2+...+b,2+bo]
           H (2) = 4(2)
 => H(2) = 6 m 2 t ... + b, 2 + bo
               a_{1} a_{1} a_{1} a_{2} a_{0}
Modela matematice intrare-stare-ierire
 1) MM-151 antimp continue
 \begin{cases} \dot{x}(t) = A \cdot x(t) + Lr \cdot u(t) \\ y(t) = c^{T} \cdot x(t) \end{cases}
                                                 se aplico Laplace
 => S.x(s) - A x(s) - b.u(s)
      = \begin{cases} S \cdot i \cdot x(s) - A \cdot x(s) - B \cdot \mu(s) \\ \mu(s) - C^{T} \cdot x(s) \end{cases}
          \begin{cases} \times (5) \left[ S \cdot i - A \right] = b \cdot u(5) \\ y(5) = c \cdot x(5) \end{cases}
```

$$= \begin{cases} \times (5) = [5 \cdot i - A]^{-1} \cdot b \cdot u(5) \\ y(5) = c^{-1} \cdot [5 \cdot i - A]^{-1} \cdot b \cdot u(5) \\ y(6) = c^{-1} \cdot [5 \cdot i - A]^{-1} \cdot b \cdot u(5) \\ y(6) = \frac{y(6)}{u(6)} = c^{-1} \cdot [5 \cdot i - A]^{-1} \cdot b \cdot u(5) \\ y(6) = \frac{y(6)}{u(6)} = c^{-1} \cdot [5 \cdot i - A]^{-1} \cdot b \cdot u(5) \\ y(6) = \frac{y(6)}{u(6)} = c^{-1} \cdot [5 \cdot i - A]^{-1} \cdot b \cdot u(5) \\ y(6) = \frac{y(6)}{u(6)} = c^{-1} \cdot (2i - A)^{-1} \cdot b \cdot u(5) \\ y(6) = c^{-1} \cdot x(6) \\ y(6) = c^$$



ET- D: derivator

ET-PT1: proportional ou temporcitore de ordinal 1

-ET-PD-T1: proportional derivator ou temportizone de ordinal 1

ET - DT1: derivater ou temperatione de sidimul 1

ET - PI : proportional integrator

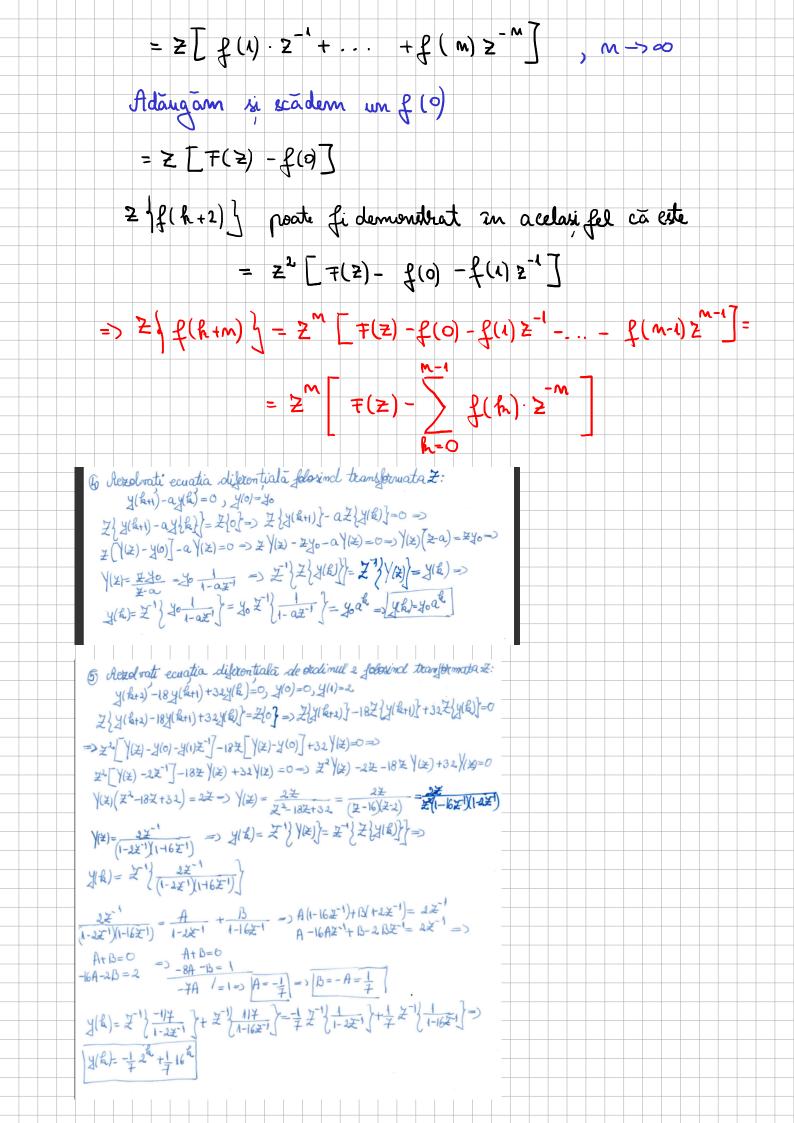
ET-PD: proportional desivator

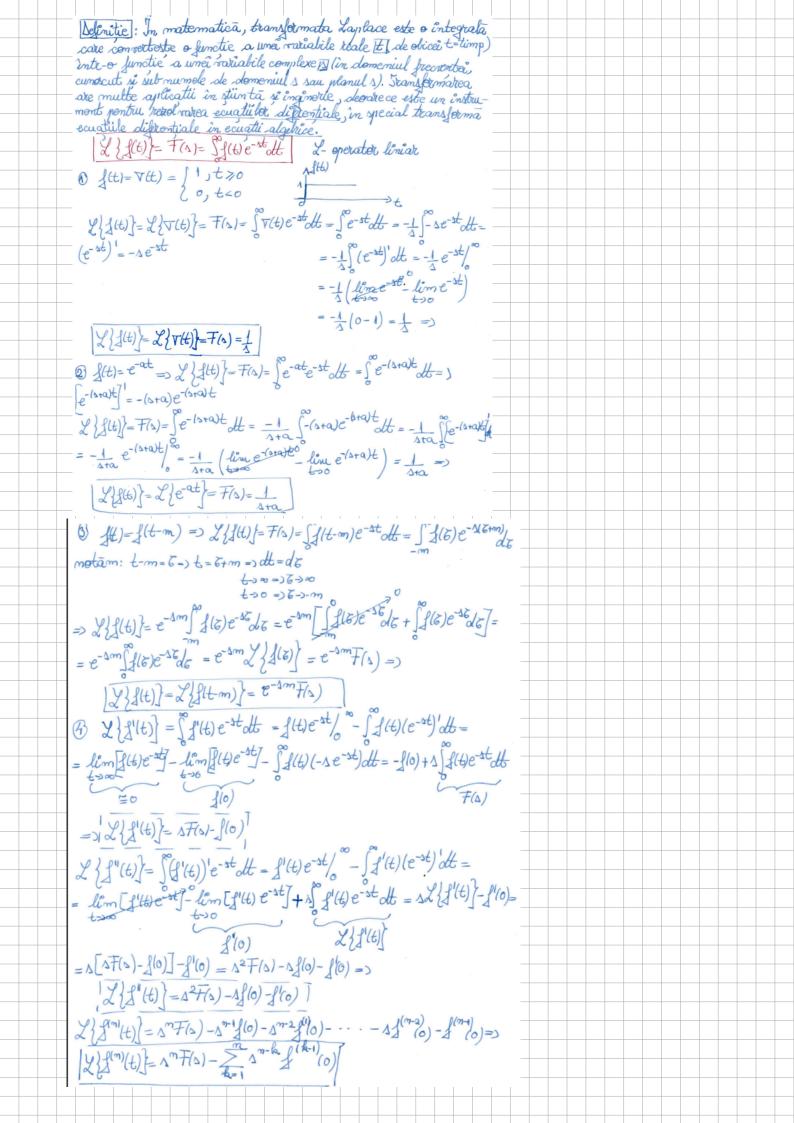
- ET-PID: proportional integrates derivates

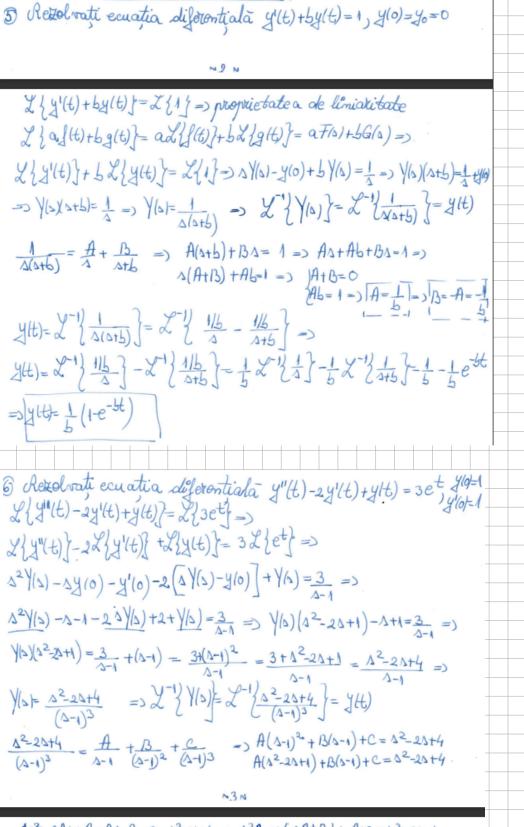
ET-PT2: propositional cu tempéritaire de sédimul 2

Transformata 2

$$T(z) = 2 + (1) = 2 + (1) = 2 + (1) + 2 + (1) = 2 + (1) + 2$$







$$A\Delta^{2} - 2A\Delta + A + B\Delta - B + C = \Delta^{2} - 2\Delta + 4 \implies \Delta^{2}A + \Delta(-2A + B) + A + C = \Delta^{2} - 2\Delta + 4 \implies \Delta^{2}A + B = -2 \implies \Delta^{2}A + B = -2 \implies \Delta^{2}A + B = -2 \implies \Delta^{2}A + C = 4$$

$$Y(t) = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A + C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A + C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A - C = 4 \end{pmatrix} = \begin{pmatrix} \Delta^{2} - 2A + 4 \\ A -$$

