



BABEȘ-BOLYAI UNIVERSITY

Faculty of Mathematics and Computer Science



Algorithms and Programming

Lecture 10 – Problem solving methods (I)

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Course content

Programming in the large

- Introduction in the software development process
- Procedural programming
- Modular programming
- Abstract data types
- Software development principles
- Testing and debugging

Programming in the small

- Recursion
- Complexity of algorithms
- Search and sorting algorithms
- **Problem solving methods**
 - **Generate and test, Backtracking**
 - **Divide et impera**

Last time

- Search
 - Sequential search
 - Binary search
- Sort
 - Selection sort
 - Insert sort
 - Bubble sort
 - Quick sort

Today

- Problem solving methods
 - Types
 - Techniques
 - Exact methods
 - Heuristic methods
 - Algorithms
 - Backtracking
 - Divide and conquer

Problem solving methods

- Strategies for solving difficult problems
- General algorithms that can be applied to solve certain type of problem (the problem needs to satisfy certain required criteria)
- Problem characteristics
 - Structure
 - Number of solutions
 - Search, optimization, simulation, etc

Problem types

- **By structure**

- Problems that can be divided in sub-problems
e.g. search for an element in a list
- Problems that can not be divided in sub-problems
e.g. place queens on a chessboard

- **By number of solutions**

- Problems with a single solution
e.g. sort a list
- Problems with several solutions
e.g. generate permutations

- **By solving possibilities**

- Problems that can be deterministically solved
e.g. compute the sin or the square root of a number
- Problems that can be solved stochastically (heuristics)
e.g. Real-world problems such as vehicle routing optimization
Need to *search* for a solution

Problem types

- **By run time complexity**

- Problems from class P – can be solved in polynomial time (n^2 , n^3 ,...)
e.g. sorting problems
- Problems from class NP – can not be solved in polynomial time ($n!$, 2^n ,...)
e.g. the shortest path in a graph of cities

- **By scope**

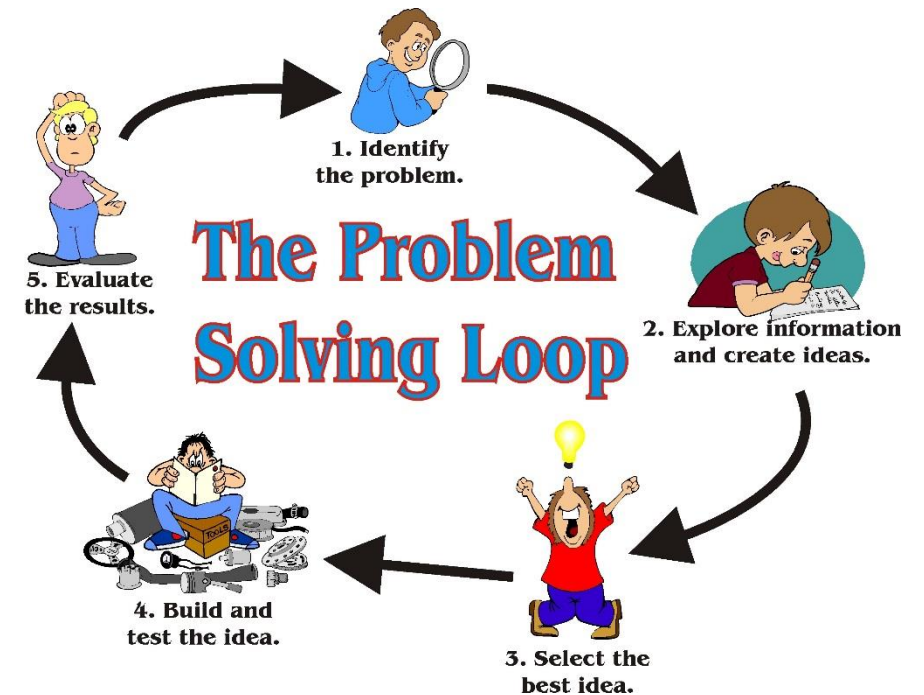
- Search / optimization problems
e.g. planning, scheduling, resource allocation
- Modeling problems
e.g. forecasting, classification, prediction
- Simulation
e.g. economic game theory

Problem solving

- Identification of a solution
 - Computer science – search process
 - Engineering and mathematics – optimization process
- How?
 - Representation of (partial) solutions – points in the search space
 - Design of search operators – transform a possible solution in a new solution

The problem solving loop

- Problem definition
- Problem analysis
- Choose problem solving technique
 - **Search**
 - Knowledge representation
 - Abstraction



Problem solving steps

- Choose a problem solving technique
 - Solve using rules (and a control strategy) to move in the search space until a path from the initial state to the final one is identified
 - Solve using search
 - Sistematically analyse states in order to identify:
 - A path from initial state to the final one
 - An optimal state
 - Search space – all possible states and the operators that allow moving from a state to another
 - How to choose the search strategy?
 - Computational complexity (run time and space)
 - Completeness – the algorithm always ends and finds a solution if one exists
 - Optimality – the algorithm finds the optimal solution

Problem solving by search

- Many search strategies – how to choose one?
 - Computational complexity
 - Performance depends on:
 - Time needed to run the algorithm
 - Space (memory) needed for the run
 - Size of the input data
 - Computer speed
 - Processor quality
- Measured using complexity – **Computational Efficiency**
 - **Space** – memory needed to identify the solution
 - $S(n)$ – quantity of memory used by the best algorithm A which solves a decision problem f with input data of size n
 - **Time** – time needed to identify the solution
 - $T(n)$ – running time (number of steps) used by the best algorithm A for a decision problem f with input data of size n

Problem solving by search

- Solving problems by search can mean:
 - Build the solution step by step
 - Identify the potential optimal solution

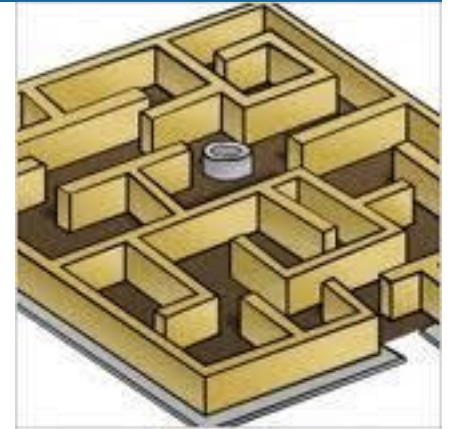


Problem solving by search

- Solving problems by search using standard methods
 - Exact methods
 - **Generate and test**
 - **Backtracking**
 - **Divide and conquer**
 - Dynamic programming
 - Heuristic methods
 - Greedy method

Generate and test

- Basic idea
 - Generate a possible solution and verify if it's correct
 - Trial and error
 - Exhaustive search
- Mechanism
 - Generate: determine all possible solutions
 - Test: search solutions that are correct (satisfy some conditions)
- When to use it?
 - Problems that can have multiple solutions
 - Problems with restrictions (solutions need to satisfy some conditions)



Generate and test

- Algorithm

```
#D = D(D1) = D(D1(D2))...  
def generate_test(D):  
    while (True):  
        sol = generate_solution()  
        if (test(sol) == True):  
            return sol
```

1. Generate a possible solution
2. Test if solution is correct
3. Quit if a solution is found, return to step 1 otherwise

➤ This is not backtracking

Generate and test

- Example: generate permutations with $n=3$ elements

```
def permut3():
    for i in range(1,4):
        for j in range(1,4):
            for k in range(1,4):
                # generate
                possibleSolution = [i,j,k]
                #test
                if i!=j and j!=k and k!=i:
                    yield possibleSolution

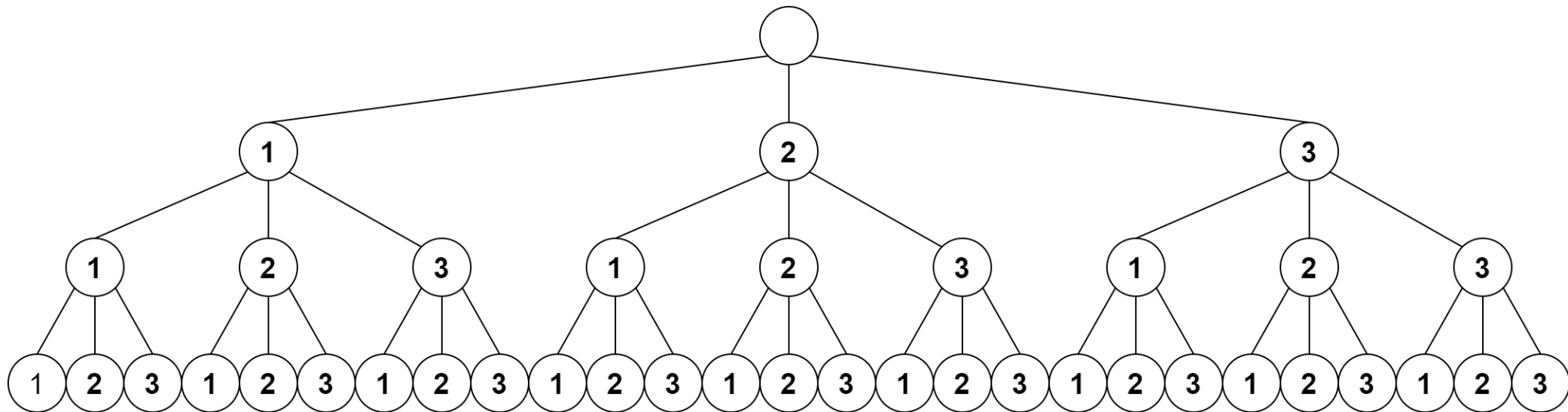
def callPermut3():
    for p in permut3():
        print(p)

callPermut3()
```

```
[1, 2, 3]
[1, 3, 2]
[2, 1, 3]
[2, 3, 1]
[3, 1, 2]
[3, 2, 1]
```


Generate and test

- Example: generate permutations with $n=3$ elements
- Complexity
 - Number of possible solutions: 3^3 (which is n^n)



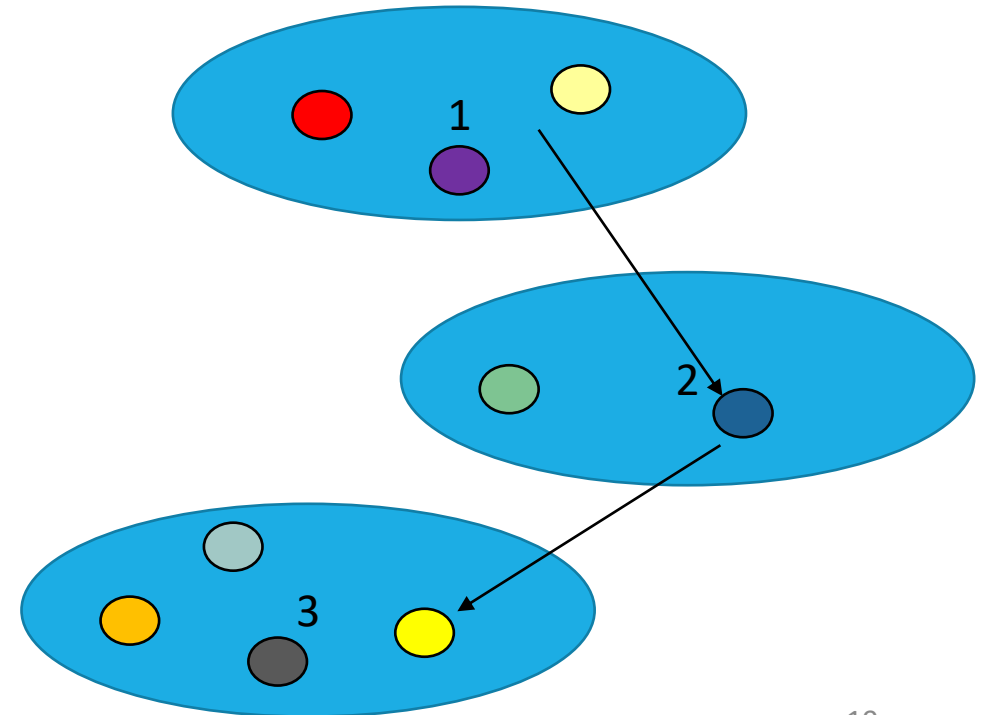
Generate and test

- Possible improvements
 - Do not explore all possible solutions
 - Example: when $i = 1$ there is no point to verify $j = 1$ and $k = 1$ because this can not lead to a possible solution
 - Build (partially) correct solutions
 - That satisfy certain conditions

```
#D = D(D1) = D(D1(D2))...  
def generate_test(D):  
    while (True):  
        sol = generate_solution_cond()  
        if (test(sol) == True):  
            return sol
```

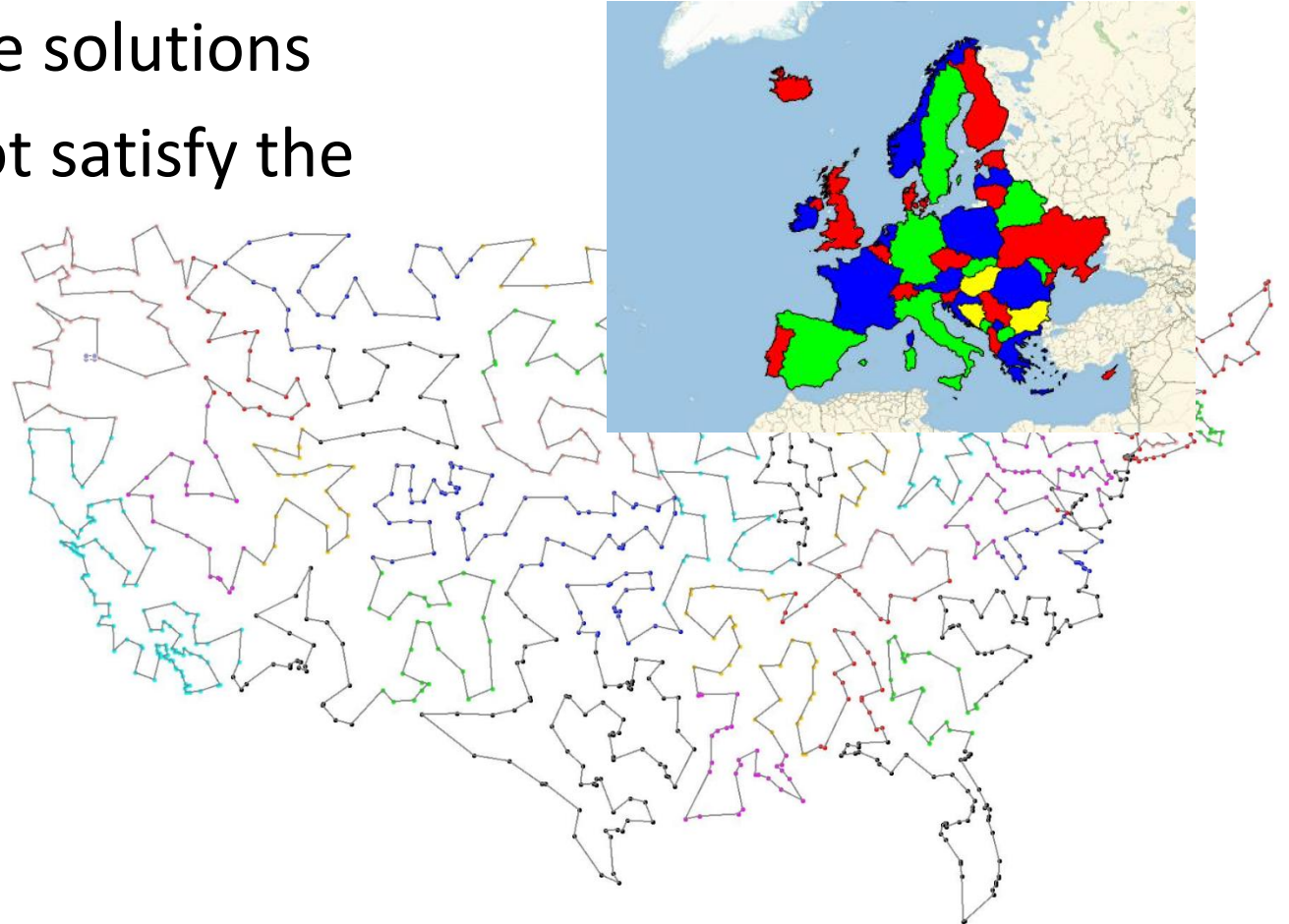
Backtracking

- Brute-force technique for finding solutions, with the main characteristic that it has the ability to undo – *backtrack* – when a potential solution is not valid
- Basic idea:
 - Try every possibility to see if it's a solution
 - unless we already know it's not valid
 - Sequence of choices
 - Once a choice is selected....another choice
 - If bad choice => backtrack
 - Until the solution is perfectly valid



Backtracking

- Problems with many candidate solutions
- Many of these solutions do not satisfy the given constraints
- Examples of problems:
 - N-Queens Problem
 - Sudoku
 - K-colouring maps of (n regions)
 - Traveling Salesperson Problem



Backtracking

- Search space of a solution \mathbf{s} is \mathbf{S} (definition domain)
- A solution is formed of several elements $s[0], s[1], s[2], \dots$
- *init*: function that generates an empty value for the definition domain of the solution
- *getNext*: function that returns the next element from the definition domain
- *isConsistent*: function that verifies if a (partial) solution is consistent
- *isSolution*: function that verifies if a (partial) solution is a final (complete) solution of the problem

Backtracking: Iterative version

Generate permutations with n elements

```
def init():
    return 0

def getNext(sol, pos):
    return sol[pos] + 1

def isConsistent(sol):
    isCons = True
    i = 0
    while (i < len(sol) - 1) and (isCons == True):
        if (sol[i] == sol[len(sol) - 1]):
            isCons = False
        else:
            i = i + 1
    return isCons

def isSolution(solution, n):
    return len(solution) == n
```

```
def permut_back(n):
    k = 0; solution = []
    initValue = init()
    solution.append(initValue)
    while (k >= 0):
        isSelected = False
        while (isSelected == False) and (solution[k] < n):
            solution[k] = getNext(solution, k)
            isSelected = isConsistent(solution)
        if (isSelected == True):
            if (isSolution(solution, n) == True):
                yield solution
            else:
                k = k + 1
                solution.append(init())
        else:
            del(solution[k])
            k = k - 1

def callPermut():
    for p in permut_back(3):
        print(p)

callPermut()
```

Backtracking: Recursive version

Generate permutations with n elements

```
def init():
    return 0

def getNext(sol, pos):
    return sol[pos] + 1

def isConsistent(sol):
    isCons = True
    i = 0
    while (i < len(sol) - 1) and (isCons == True):
        if (sol[i] == sol[len(sol) - 1]):
            isCons = False
        else:
            i = i + 1
    return isCons

def isSolution(solution, n):
    return len(solution) == n
```

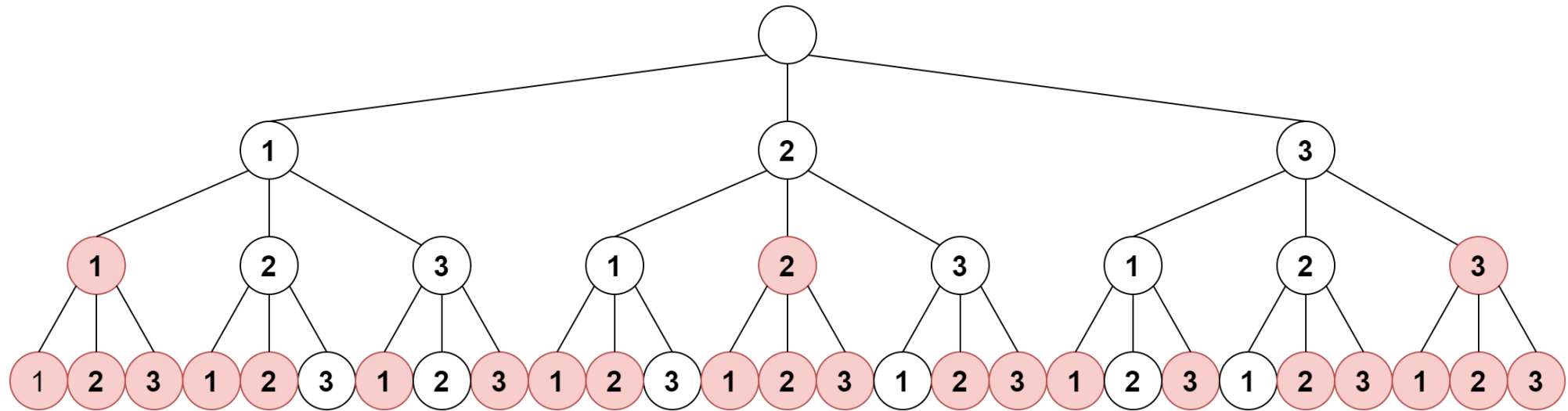
```
def permut_back_rec(n, solution):
    initValue = init()
    solution.append(initValue)
    elem = getNext(solution, len(solution) - 1)
    while (elem <= n):
        solution[len(solution) - 1] = elem
        if (isConsistent(solution) == True):
            if (isSolution(solution, n) == True):
                yield solution
            else:
                yield from permut_back_rec(n, solution[:])
        elem = getNext(solution, len(solution) - 1)

def callPermutRec():
    for p in permut_back_rec(3, []):
        print(p)

callPermutRec()
```

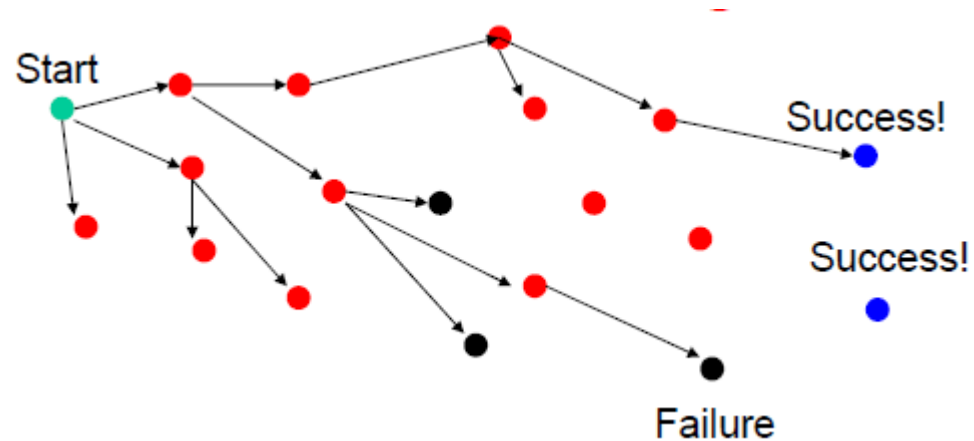
Backtracking

- Nodes explored for generating permutations with $n=3$ elements



Recap: How to use backtracking

- Represent the solution as a vector: $s[0], s[1], s[2], \dots$
- Define what a valid solution candidate is
(filter out candidates that will not lead to a solution)



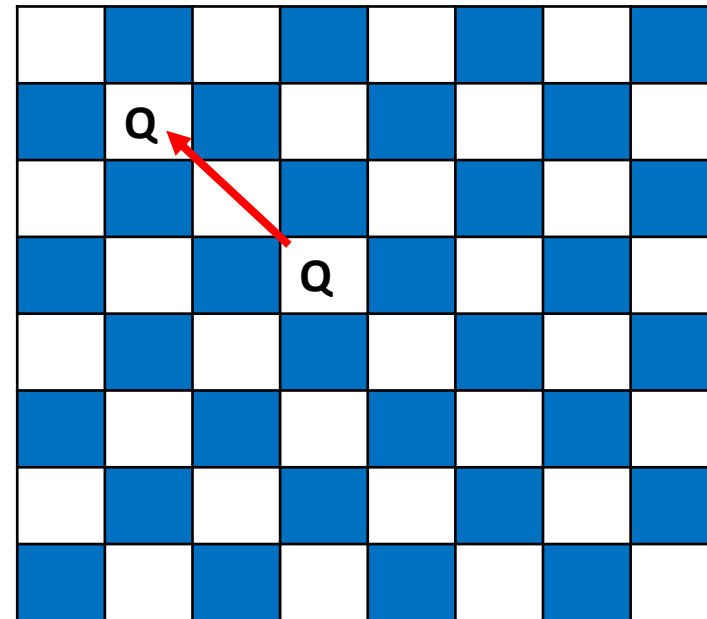
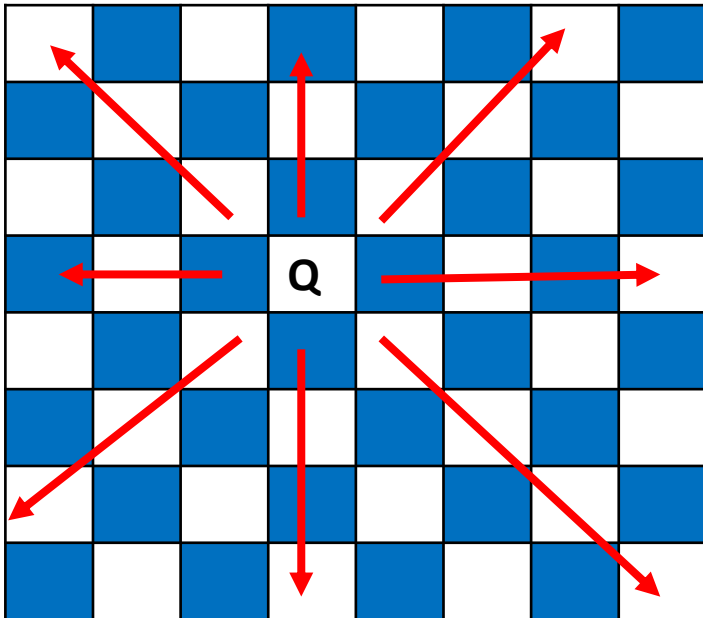
Remember:

- Problem space: states (nodes) and actions (paths that lead to new states)
- If a node leads to failure go back and try other alternatives

Backtracking: Example

8 queens

- 8 queens
 - Classic backtracking problem
 - Place 8 queens on an 8x8 chessboard so that no queen can attack another



Backtracking: Example

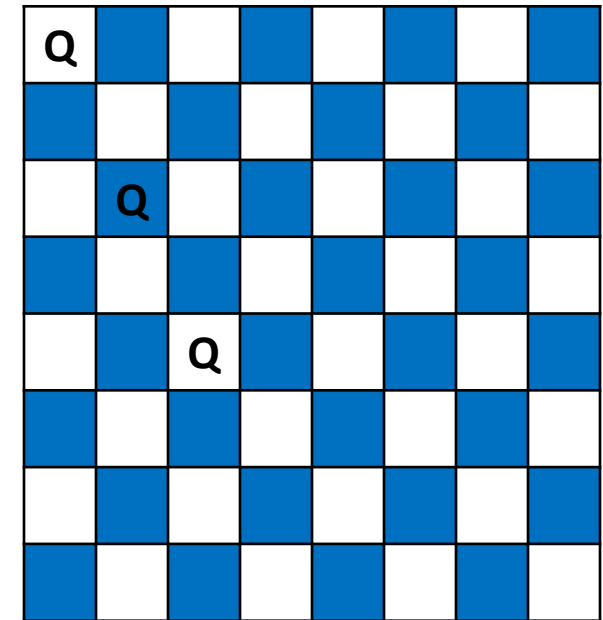
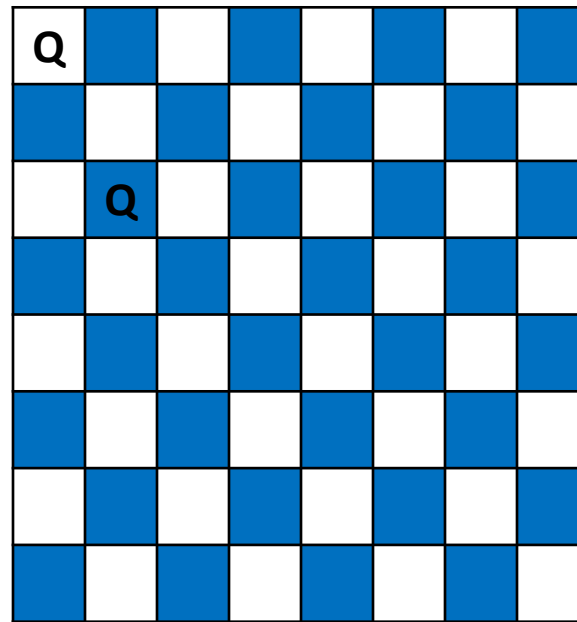
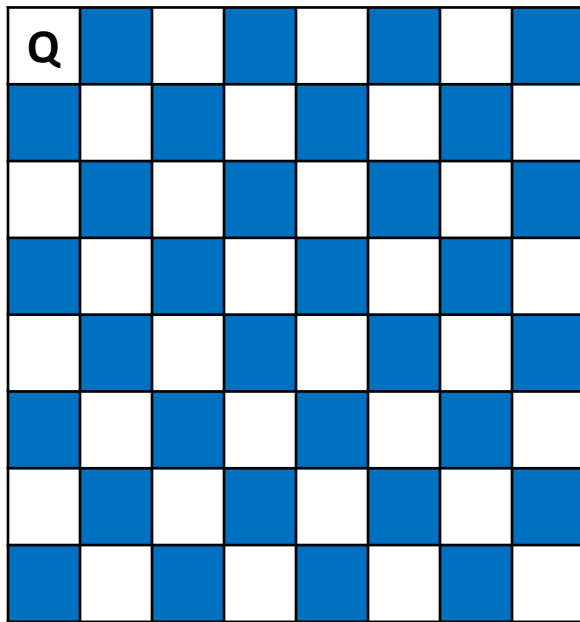
8 queens

- 8x8 chessboard => 64 locations
 - After placing one queen => 63 locations to choose from
 -
 - $64 \cdot 63 \cdot 62 \cdot 61 \cdot 60 \cdot 59 \cdot 58 \cdot 57 = 178,462,987,637,760$ possibilities
- However:
 - A valid solution has:
 - exactly 1 queen in each row and exactly 1 queen in each column
 - Explore 1 queen per column (not per cell)
 - Possibilities reduced to $8^8 = 16,777,216$

Backtracking: Example

8 queens

- Make a choice for first column
- The second choice is affected by the first choice, etc



Backtracking: Example

N queens

```
def isConsistent(solution, row, column):
    # check the row
    for j in range(column):
        if solution[row][j] == 1:
            return False

    # check the first diagonal to left (up)
    for i,j in zip(range(row,-1,-1), range(column,-1,-1)):
        if solution[i][j] == 1:
            return False

    # check the second diagonal to left (down)
    i = row + 1
    j = column - 1
    while (i < len(solution)) and (j >= 0):
        if solution[i][j] == 1:
            return False
        i = i + 1
        j = j - 1

    return True
```

```
def initSolution():
    solution = [[0 for i in range(n)] for j in range(n)]
    return solution

def printSolution(solution):
    for row in solution:
        print(row)
```

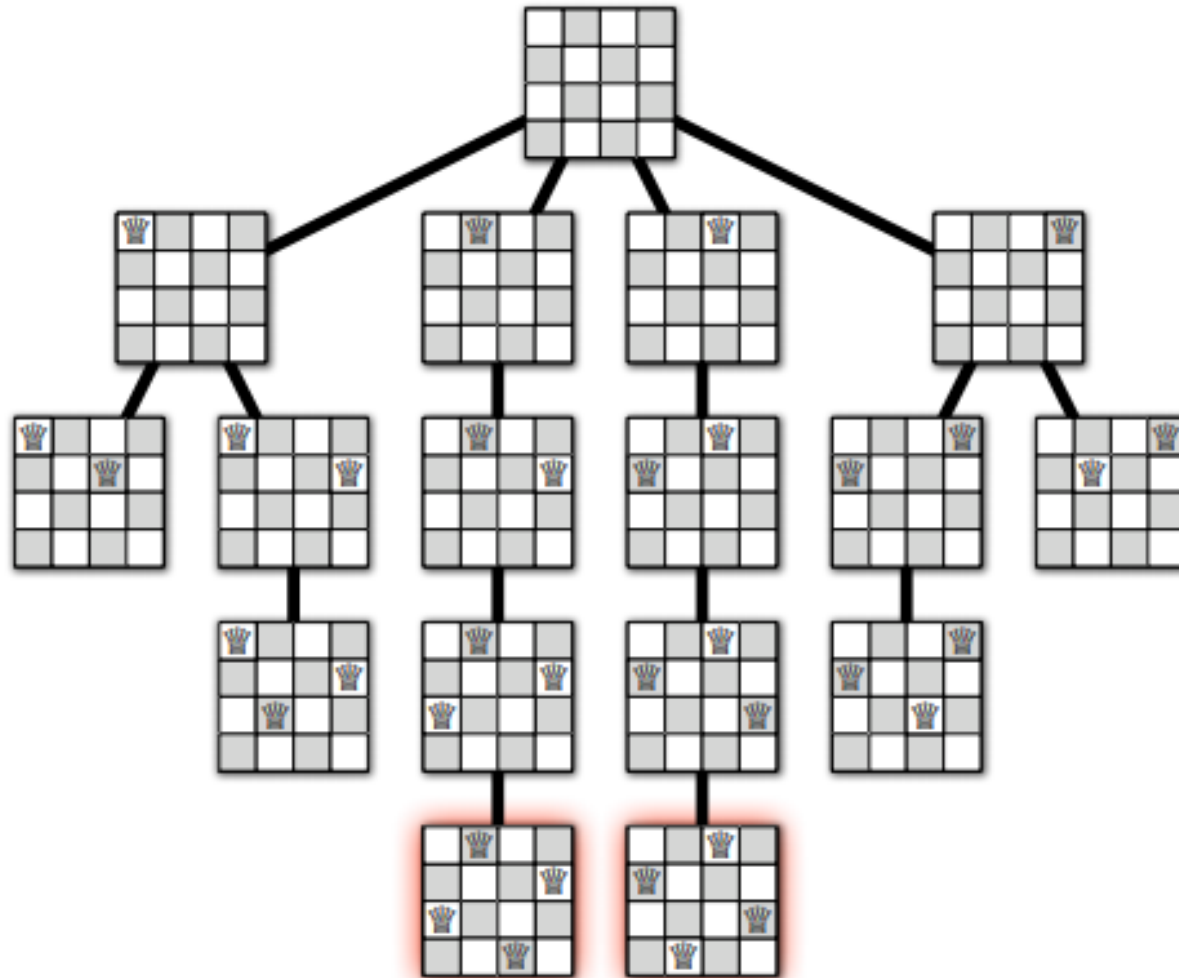
```
def solveProblem(solution, column):
    if column >= n:
        print("COMPLETE solution:")
        printSolution(solution)
        return True

    for i in range(n):
        if isConsistent(solution, i, column):
            solution[i][column] = 1
            print("Partial correct solution:")
            printSolution(solution)
            if solveProblem(solution, column + 1) == True:
                return True
            else:
                solution[i][column] = 0

    return False

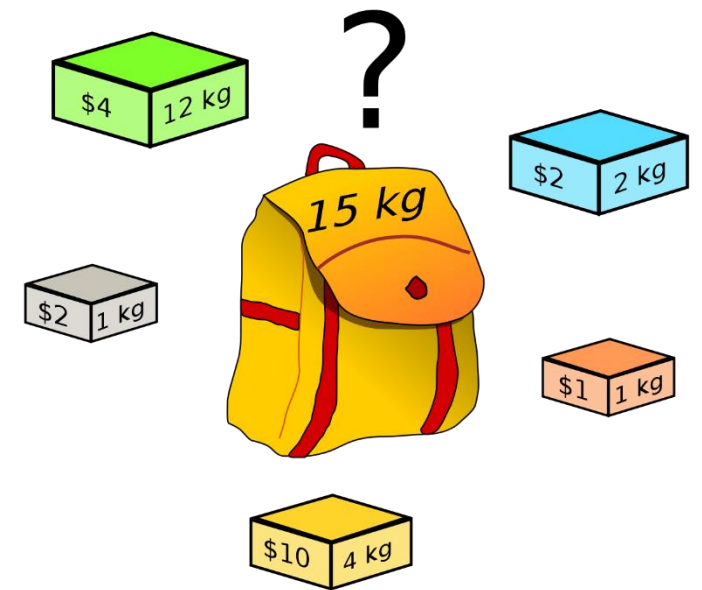
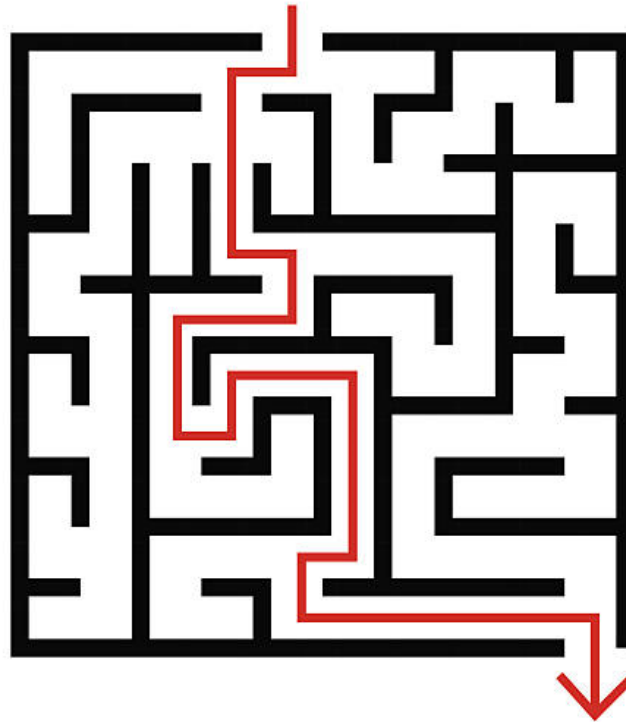
n=8
solveProblem(sol, 0)
```

Backtracking Example



Backtracking: other examples

5	3			7				
6			1	9	5			
	9	8					6	
8				6				3
4			8		3			1
7				2				6
	6					2	8	
			4	1	9			5
				8			7	9



Divide et impera – Divide and conquer

- Basic idea
 - Divide the problem in several independent sub-problems similar to the initial problem but smaller in size and determine the final solution by combining sub-solutions
- Mechanism
 - **Divide**: breaking the problem in sub-problems
 - **Conquer**: solve the sub-problems
 - **Combine**: combine sub-solutions to obtain final solution
- When it can be used
 - A problem **P** with the input data **D** can be solved by solving the same problem **P** but with input data **d** , where **$d < D$**

Divide et impera – Divide and conquer

- Algorithm

```
#D = d1 U d2 U d3...U dn
def div_imp(D):
    if (size(D) < lim):
        return rez
    rez1 = div_imp(d1)
    rez2 = div_imp(d2)
    ...
    rezn = div_imp(dn)
    return combine(rez1, rez2, ..., rezn)
```

Divide et impera – Divide and conquer

- Example: find the maximum of a list
 - Size of problem = n
 - First version
 - Size of sub-problem 1 = $n-1$
 - Size of sub-problem 2 = $n-2$
 - ...
 - *meaning:*
 - $D = l = [l_1, l_2, \dots, l_n]$
 - $d_1 = [l_2, \dots, l_n]$
 - $d_2 = [l_3, \dots, l_n]$
 - ...
 - $O(n)$

```
def findMax(l):  
    '''  
    Descr: finds the maximum elem of a list  
    Input: a list  
    Output: the maximum elem of list  
    '''  
    if (len(l) == 1):  
        return l[0]  
    max = findMax(l[1:])  
    if (max > l[0]):  
        return max  
    else:  
        return l[0]  
  
def test_findMax():  
    assert findMax([2,5,3,6,1]) == 6  
    assert findMax([12,5,3,2,1]) == 12  
    assert findMax([2,5,3,6,11]) == 11  
  
test_findMax()
```

Divide et impera – Divide and conquer

- Example: find the maximum of a list

- Size of problem = n

- Second version

- Size of sub-problem 1 = $n/2$
- Size of sub-problem 2 = $n/2$

- *meaning:*

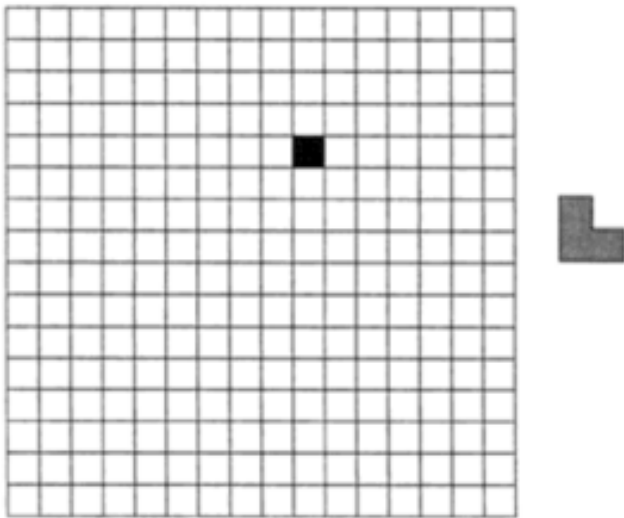
- $D = I = [l_1, l_2, \dots, l_n]$
- $d_1 = [l_2, \dots, l_{n/2}]$
- $d_2 = [l_{n/2+1}, \dots, l_n]$

- $O(n)$

```
def findMax_v2(l):  
    '''  
    Descr: finds the maximum elem of a list  
    Data: a list  
    Res: the maximal elem of list  
    '''  
  
    if (len(l) == 1):  
        return l[0]  
    middle = len(l) // 2  
    max_left = findMax_v2(l[0:middle])  
    max_right = findMax_v2(l[middle:len(l)])  
    if (max_left < max_right):  
        return max_right  
    else:  
        return max_left  
  
def test_findMax_v2():  
    assert findMax_v2([2,5,3,6,1]) == 6  
    assert findMax_v2([12,5,3,2,1]) == 12  
    assert findMax_v2([2,5,3,6,11]) == 11  
  
test_findMax_v2()
```

Divide et impera – Example

- Consider a chessboard of size 2^m (with $2^m \times 2^m$ cells) that contains a hole (one random cell is removed)
- We have several shapes L
- Objective: cover the chessboard with L shapes (any orientation)

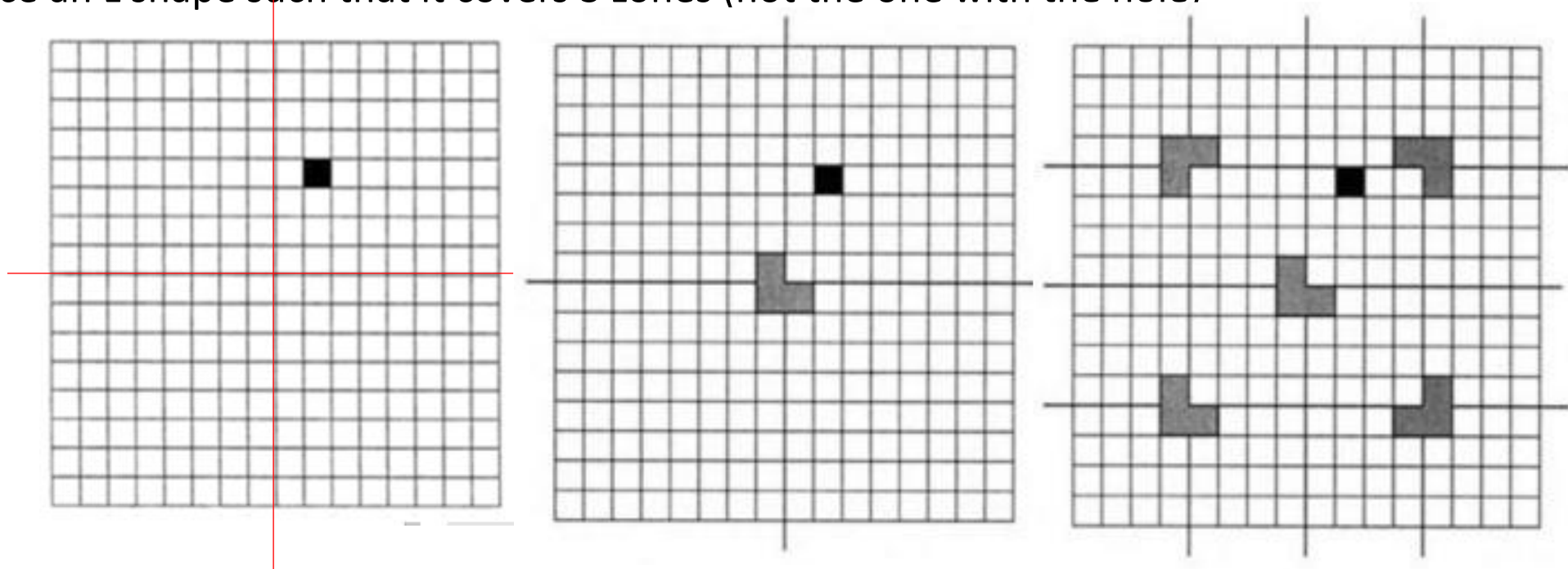


$m=4 \Rightarrow$ chessboard 16×16

- ✓ Search space: possible arrangements of L shapes on the board
- ✓ D&C is an ideal method

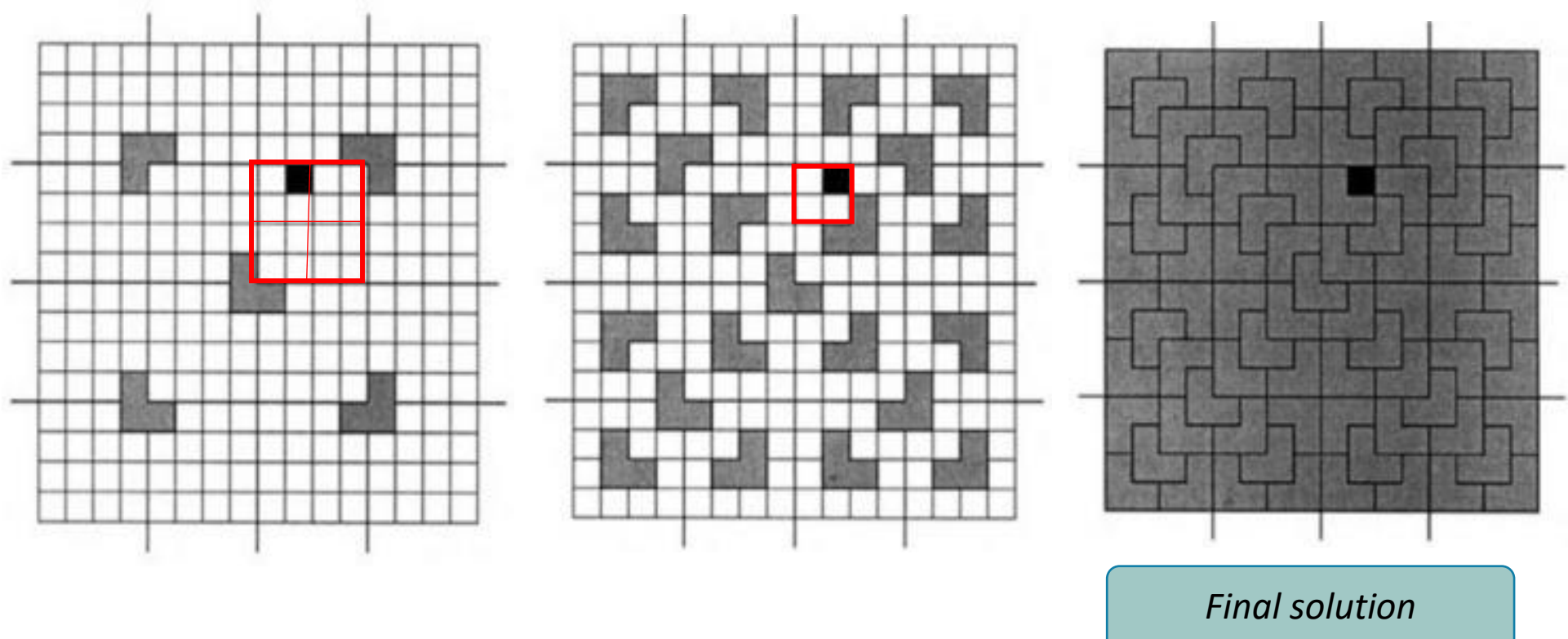
Divide et impera – Example

- Divide the chessboard in 4 equal zones
- Only one will contain the hole
- Place an L shape such that it covers 3 zones (not the one with the hole)



Divide et impera – Example

- Each square has a single black cell



Recap today

- Problem solving methods
- Generate and test
 - Exhaustive
 - Backtracking
- Divide and conquer

Next time

- Algorithms
 - Dynamic programming
 - Greedy method

Reading materials and useful links

1. The Python Programming Language - <https://www.python.org/>
2. The Python Standard Library - <https://docs.python.org/3/library/index.html>
3. The Python Tutorial - <https://docs.python.org/3/tutorial/>
4. M. Frentiu, H.F. Pop, Fundamentals of Programming, Cluj University Press, 2006.
5. MIT OpenCourseWare, Introduction to Computer Science and Programming in Python, <https://ocw.mit.edu>, 2016.
6. K. Beck, Test Driven Development: By Example. Addison-Wesley Longman, 2002. http://en.wikipedia.org/wiki/Test-driven_development
7. M. Fowler, Refactoring. Improving the Design of Existing Code, Addison-Wesley, 1999. <http://refactoring.com/catalog/index.html>