

$$1. \quad v_1 = (1, -1, 0), \quad v_2 = (2, 1, 1), \quad v_3 = (1, 5, 2)$$

(i) v_1, v_2, v_3 - lin. dep. and det. rel.

(ii) v_1, v_2 - lin. indep.

$$(i) \quad k_1 v_1 + k_2 v_2 + k_3 v_3 = k_1(1, -1, 0) + k_2(2, 1, 1) + k_3(1, 5, 2) = \\ = (k_1 + 2k_2 + k_3, -k_1 + k_2 + 5k_3, 0k_1 + k_2 + 2k_3) = (0, 0, 0) \Leftrightarrow$$

$$\Leftrightarrow S \begin{cases} k_1 + 2k_2 + k_3 = 0 \\ -k_1 + k_2 + 5k_3 = 0 \\ 0 \cdot k_1 + k_2 + 2k_3 = 0 \end{cases}$$

$$\det(S) = \begin{vmatrix} 1 & 2 & 1 \\ -1 & 1 & 5 \\ 0 & 1 & 2 \end{vmatrix} = 2 - 1 + 0 - 0 - 5 + 4 = 6 - 6 = 0 \rightarrow$$

\rightarrow The system has multiple sol. $\rightarrow v_1, v_2, v_3$ - lin. dep.

$$k_3 = \alpha \in \mathbb{R}$$

$$\begin{cases} k_1 + 2k_2 = -\alpha \Rightarrow k_1 = -\alpha - 2k_2 \\ -k_1 + k_2 = -5\alpha \quad | \quad -\alpha - 2k_2 + k_2 = -5\alpha \\ \hline 3k_2 = -6\alpha \Rightarrow k_2 = -2\alpha \quad | \quad k_1 = -\alpha - 2(-2\alpha) = \alpha + 4\alpha = 5\alpha \end{cases}$$

$$k_1 - 4\alpha = -\alpha \Rightarrow k_1 = 3\alpha$$

$$\alpha = 1 \rightarrow 3v_1 - 2v_2 = -v_3$$

$$(ii) \quad k_1 v_1 + k_2 v_2 = (k_1 + 2k_2, -k_1 + k_2, 0 + k_3) = (0, 0, 0)$$

$$\left. \begin{cases} k_1 + 2k_2 = 0 \\ -k_1 + k_2 = 0 \\ k_3 = 0 \end{cases} \right\} \rightarrow -k_1 + 0 = 0 \Rightarrow k_1 = 0$$

$$\left. \begin{cases} k_1 + 2k_2 = 0 \\ -k_1 + k_2 = 0 \\ k_3 = 0 \end{cases} \right\} \rightarrow v_1, v_2 \text{ - lin. indep.}$$

n -vectors in K^n $\begin{cases} \det = 0 \rightarrow \text{lin. dep.} \\ \det \neq 0 \rightarrow \text{lin. indep.} \end{cases}$

2 vectors in K^n : $\frac{1}{2} \neq \frac{-1}{1} \neq \frac{0}{1} \rightarrow \text{lin. indep.}$

2. - Hw

3. $v_1 = (1, 0, 0)$, $v_2 = (0, 1, 1)$, $v_3 = (1, 0, \alpha)$

$\alpha = ?$ s.t. v_1, v_2, v_3 - lin indep

$$\begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & \alpha \end{vmatrix} = \alpha + 0 + \alpha - 0 - 0 - 0 = \alpha^2 = -\alpha^2 + 2\alpha = 0 \quad (-\alpha + 2)$$

$$v_1, v_2, v_3 - \text{lin indep} \Leftrightarrow \alpha(-\alpha + 2) \neq 0 \quad \left. \begin{array}{l} \alpha \neq 0 \\ -\alpha^2 + 2\alpha \neq 0 \Rightarrow \alpha^2 \neq 2 \end{array} \right\} \rightarrow$$

$$\rightarrow \alpha \in \mathbb{R} \setminus \{-\sqrt{2}, 0, \sqrt{2}\}$$

4. $v_1 = (1, -2, 0, -1)$, $v_2 = (2, 1, 1, 0)$, $v_3 = (0, 0, 1, 2)$

$\alpha = ?$ s.t. v_1, v_2, v_3 - lin dep.

$$v_1, v_2, v_3 - \text{lin dep} \rightarrow k_1 v_1 + k_2 v_2 + k_3 v_3 = 0 \text{ and } k_{1,2,3} \text{ not all}$$

$$(k_1 + 2k_2 + 0k_3; -2k_1 + k_2 + 0k_3; 0k_1 + k_2 + k_3; -k_1 + 0k_2 + 2k_3) = (0, 0, 0, 0)$$

$$\hookrightarrow \begin{cases} k_1 + 2k_2 = 0 \\ -2k_1 + k_2 + 0k_3 = 0 \\ k_2 + k_3 = 0 \\ -k_1 + 2k_3 = 0 \end{cases} \rightarrow \begin{cases} k_2 = -k_3 \\ k_1 = 2k_3 \\ k_3(0 - 5) = 0 \end{cases} \rightarrow -4k_3 - k_3 + \alpha k_3 = 0$$

k_3 can't be 0 because if $k_3 = 0 \rightarrow k_1 = k_2 = 0 \rightarrow$ lin indep.

$$\rightarrow 0 - 5 \neq 0 \rightarrow \alpha = 5$$

5. $v_1 = (1, 1, 0)$, $v_2 = (-1, 0, 2)$, $v_3 = (1, 1, 1)$

(i) (v_1, v_2, v_3) - basis \mathbb{R}^3

(ii) express (e_1, e_2, e_3) as a linear combination of v_1, v_2, v_3

(iii) Det $a = (1, -1, 2)$ in each of the 2 bases

$v = v$ s. over K

$B = (v_1, \dots, v_n)$ is v is a basis for V if:

(i) v_1, \dots, v_n are lin indep

(ii) v_1, \dots, v_n are a system of generators for V , $V = \langle B \rangle$

• $B = (v_1, \dots, v_n)$ is a basis of V if every vector in V can be uniquely written as a lin. combination of v_1, \dots, v_n .

$\forall v \in V, \exists! k_1, \dots, k_n \in \mathbb{R} \text{ s.t. } v = k_1 v_1 + \dots + k_n v_n$

k_1, \dots, k_n = coordinates of v in the basis B

(i) Let $k_1, k_2, k_3 \in \mathbb{R}$ & $(x, y, z) \in \mathbb{R}^3$

$$(x, y, z) = k_1 v_1 + k_2 v_2 + k_3 v_3$$

$$(x, y, z) = (k_1 - k_2 + k_3, k_1 + k_3, 2k_2 + k_3)$$

$$\begin{cases} k_1 - k_2 + k_3 = x \\ k_1 + k_3 = y \\ 2k_2 + k_3 = z \end{cases} \rightarrow \begin{cases} k_2 = k_1 - k_2 - x \\ k_3 = y - x \\ k_1 = z - 2(y - x) = z - 2y + 2x \end{cases}$$

$$k_1 = y - (z - 2y + 2x) = -z + 3y + 2x$$

\rightarrow unique sol $\rightarrow (v_1, v_2, v_3)$ - basis \mathbb{R}^3

$$(ii) e_1 = (1, 0, 0) = k_1 v_1 + k_2 v_2 + k_3 v_3 = -2v_1 - v_2 + 2v_3$$

$$k_1 = -0 + 3 \cdot 0 - 2 \cdot 1 = -2$$

$$k_2 = 0 - 1 = -1$$

$$k_3 = 0 - 0 + 2 = 2$$

$$e_2 = (0, 1, 0) = k'_1 v_1 + k'_2 v_2 + k'_3 v_3 = 3v_1 + v_2 - 2v_3$$

$$k'_1 = -0 + 3 \cdot 1 - 2 \cdot 0 = 3$$

$$k'_2 = 1 - 0 = 1$$

$$k'_3 = 0 - 2 \cdot 1 + 2 \cdot 0 = -2$$

$$e_3 = (0, 0, 1) = k''_1 v_1 + k''_2 v_2 + k''_3 v_3 = -v_1 + 0 \cdot v_2 + v_3$$

$$k''_1 = -1 + 0 - 0 = -1$$

$$k''_2 = 0 - 0 = 0$$

$$k''_3 = 1 - 0 + 0 = 1$$

$$(iii) \quad u = (1, -1, 2)$$

$$u = k_1 v_1 + k_2 v_2 + k_3 v_3 = -2v_1 - 2v_2 + 6v_3$$

$$k_1 = 3 \cdot (-1) - 2 - 2 \cdot 1 = -7$$

$$k_2 = -1 - 1 = -2$$

$$k_3 = 2 - 2 \cdot (-1) + 2 \cdot 1 = 2 + 2 + 2 = 6$$

$$u = k_1' e_1 + k_2' e_2 + k_3' e_3 = (k_1', k_2', k_3') \rightarrow$$

$$\rightarrow k_1' = 1$$

$$k_2' = -1$$

$$k_3' = 2$$

6. $n \in \mathbb{N}^*$

$$v_1 = (1, \dots, 1, 1, 1)$$

$$v_2 = (1, \dots, 1, 1, 2)$$

$$v_3 = (1, \dots, 1, 2, 3)$$

$$v_n = (1, 2, \dots, n-1, n)$$

form a basis in \mathbb{R}^n and write the coord of
 $x = (x_1, \dots, x_n)$ in this base

$$x = k_1 v_1 + k_2 v_2 + \dots + k_n v_n$$

$$\left\{ \begin{array}{l} k_1 + k_2 + \dots + k_n = x_1 \\ k_1 + k_2 + \dots + k_{n-1} + 2k_n = x_2 \\ k_1 + k_2 + \dots + k_{n-2} + 2k_{n-1} + 3k_n = x_3 \\ \dots \\ k_1 + 2k_2 + \dots + nk_n = x_n \end{array} \right.$$

$$e_1$$

$$e_2$$

$$e_3$$

$$e_n$$

$$e_2 - e_1 \rightarrow k_2 = x_2 - x_1$$

$$e_3 - e_2 \rightarrow k_{n-1} + k_n = x_3 - x_2 \Rightarrow k_{n-1} = x_3 - x_2 - (x_2 - x_1) \\ = x_3 - 2x_2 + x_1$$

$$e_1 - e_2 \rightarrow k_{n-2} = x_1 - 2x_2 + x_1$$

$$\begin{cases} k_j = x_{n-j+2} - 2x_{n-j+1} + x_{n-j}, & j=1, n-i \\ k_n = x_2 - x_1 \end{cases} \quad (\text{castea sunt si coordanatele lui } x)$$

\rightarrow unique sol \rightarrow basis

9. Det. the nr. of bases of the v.s. \mathbb{Z}_2^3 over \mathbb{Z}_2

$$\mathbb{Z}_2^3 = \{(0,0,0), (0,0,1), (0,1,0), (1,0,0), (0,1,1), (1,0,1), (1,1,0), (1,1,1)\}$$

$$\text{card}(\mathbb{Z}_2^3) = 8$$

We have to determine in how many ways we can choose 3 linearly independent vectors

$$B = (v_1, v_2, v_3), \quad v_1, v_2, v_3 - \text{lin. indep.}$$

$v_1 \rightarrow$ 7 options ($(0,0,0)$ nu poate fi in nici o baza
pentru ca daca ar fi, multilinear f.
lin. dependent)

$$v_2 \rightarrow 6 \text{ op.}, \quad v_2 \neq \underbrace{k_1 v_1}_{0}, \quad \rightarrow v_2 \neq v_1$$

$$v_3 \rightarrow 4 \text{ op.}, \quad v_3 \neq \underbrace{k_1 v_1}_{0} + \underbrace{k_2 v_2}_{0}$$

$$\text{total basis} = 4 \cdot 6 \cdot 7 = 168$$

10. the nr. of el. $(GL_3(\mathbb{Z}_2), \cdot)$ of invertible 3×3 -matrices over \mathbb{Z}_2

A is invertible \leftrightarrow its columns are lin. indep.

Columns of A are the vectors from ex 9 ~ 168 elem.

$$\gamma. E_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad E_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad E_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad E_4 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$A_1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad A_2 = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, \quad A_3 = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \quad A_4 = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$(E_i)_{i=1,4} \rightarrow$ bases of $\mathbb{R}^{M_2(\mathbb{R})}$

$(A_i)_{i=1,4} \rightarrow \underline{\quad} \quad \underline{\quad} \quad \underline{\quad}$

Det. card of $B = \begin{pmatrix} ? & ? \\ ? & ? \end{pmatrix}$ in these bases

$$\forall \begin{pmatrix} x & y \\ z & t \end{pmatrix} = k_1 E_1 + k_2 E_2 + k_3 E_3 + k_4 E_4 =$$

$$= \begin{pmatrix} k_1 & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & k_2 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ k_3 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & k_4 \end{pmatrix} = \begin{pmatrix} k_1 & k_2 \\ k_3 & k_4 \end{pmatrix}$$

$$x = k_1$$

$$y = k_2$$

$$z = k_3$$

$$t = k_4$$

k_1, k_2, k_3, k_4 - unique $\rightarrow (E_i)_{i=1,4}$ - basis

$$\forall \begin{pmatrix} x & y \\ z & t \end{pmatrix} = k_1 A_1 + k_2 A_2 + k_3 A_3 + k_4 A_4 = \begin{pmatrix} k_1 + k_2 + k_3 + k_4 & k_2 + k_3 + k_4 \\ k_3 + k_4 & k_4 \end{pmatrix}$$

$$x = k_1 + k_2 + k_3 + k_4$$

$$y = k_2 + k_3 + k_4$$

$$z = k_3 + k_4$$

$$t = k_1 + k_4$$

$$k_1 = x - y$$

$$k_2 = y - z$$

$$k_3 = x - y + z - t$$

$$k_4 = t - k_1 = t - x + y$$

k_1, k_2, k_3, k_4 - unique $\rightarrow (A_i)_{i=1,4}$ - basis

$$(E_i)_{i=1,4} : \begin{pmatrix} k_1 & k_2 \\ k_3 & k_4 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 0 \end{pmatrix} \quad , \quad k_1 = 2$$

$$k_2 = 1$$

$$k_3 = 1$$

$$k_4 = 0$$

$$(A_i)_{i=1,4} \quad k_1 = 2 - 1 = 1$$

$$k_2 = 1 - 1 = 0$$

$$k_3 = 2 - 1 + 1 - 0 = 2$$

$$k_4 = 0 - 2 + 1 = -1$$

$$2. (i) \quad v_1 = (1, 0, 2), \quad v_2 = (-1, 2, 1), \quad v_3 = (3, 1, 1)$$

$$\begin{vmatrix} 1 & 0 & 2 \\ -1 & 2 & 1 \\ 3 & 1 & 1 \end{vmatrix} = 2 - 2 + 0 - (-12) - (-1) - 0 = -13 \neq 0 \rightarrow v_1, v_2, v_3 \text{ linearly independent}$$

$$(ii) \quad v_1 = (1, 2, 3, 4); \quad v_2 = (2, 3, 4, 1), \quad v_3 = (3, 4, 1, 2), \quad v_4 = (4, 1, 2, 3)$$

$C_1 + C_2 + C_3 + C_4 \rightarrow C_1$

$$\begin{vmatrix} 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 1 \\ 3 & 4 & 1 & 2 \\ 4 & 1 & 2 & 3 \end{vmatrix} = \begin{vmatrix} 10 & 2 & 3 & 4 \\ 10 & 3 & 4 & 1 \\ 10 & 4 & 1 & 2 \\ 10 & 1 & 2 & 3 \end{vmatrix} = 10 \begin{vmatrix} 1 & 2 & 3 & 4 \\ 1 & 3 & 4 & 1 \\ 1 & 4 & 1 & 2 \\ 1 & 1 & 2 & 3 \end{vmatrix} = 10 \cdot (-1)^{1+1+1+1} \begin{vmatrix} 1 & 1 & -3 \\ 2 & -2 & -2 \\ -1 & 1 & -1 \end{vmatrix} = 10 \cdot (-1) \cdot 1 \cdot (-1) \cdot (-1) = 10$$

$C_2 - 2C_1$

$$= 10 \cdot (2 - 8 + 2 + 6 + 2 + 2) = 60 \neq 0 \rightarrow v_1, v_2, v_3, v_4 \text{ linearly independent.}$$

$$8. \quad \mathbb{R}_2[x] = \{ f \in \mathbb{R}[x] \mid \deg(f) \leq 2 \}$$

$$E = (1, x, x^2)$$

$$B = (1, x-a, (x-a)^2), \quad a \in \mathbb{R}$$

• E basis of $\mathbb{R}_2[x]$

$$\hookrightarrow \forall a + bx + cx^2 \in \mathbb{R}_2[x], \quad a + bx + cx^2 = k_1 \cdot 1 + k_2 \cdot x + k_3 \cdot x^2 \rightarrow$$

$$\rightarrow k_1 = a$$

$$k_2 = b$$

$$k_3 = c$$

$$f = a_0 + a_1 x + a_2 x^2 \rightarrow f = a_0 \cdot 1 + a_1 \cdot x + a_2 \cdot x^2 = a_0 \cdot e_0 + a_1 \cdot e_1 + a_2 \cdot e_2$$

• B basis of $\mathbb{R}_2[x]$

$$\forall a + bx + cx^2 \in \mathbb{R}_2[x], \quad a + bx + cx^2 = k_1 \cdot 1 + k_2(x-a) + k_3(x-a)^2$$

$$\hookrightarrow a + bx + cx^2 = k_1 + k_2 x - k_2 a + k_3 x^2 - 2k_3 x \cdot a + k_3 a^2$$

$$\hookrightarrow a + bx + cx^2 = (k_1 - k_2 a) + (k_2 - 2k_3 a) x + k_3 a^2 x^2$$

$$k_1 - k_2 a + k_3 a^2 = a \rightarrow k_1 = a + ba + 3c(a)^2$$

$$k_2 - 2k_3 a = b \rightarrow k_2 = b + 2c \cdot a$$

$$k_3 = c$$

$$f = a_0 + a_1 x + a_2 x^2 \Rightarrow \begin{cases} k_1 = a_0 + a_1 a^1 + 3 a_2 (a^1)^2 \\ k_2 = a_1 + 2 a_2 a^1 \\ k_3 = a_2 \end{cases} \rightarrow$$

$$\rightarrow f = (a_0 + a_1 a^1 + 3 a_2 (a^1)^2) b_1 + (a_1 + 2 a_2 a^1) b_2 + a_2 b_3$$