HK3

December 2, 2024

```
[1]: import numpy as np
     import matplotlib.pyplot as plt
[2]: def centering_step(Q, p, A, b, t, v0, eps, alpha=0.1, beta=0.7):
         Implements the centering step using Newton's method with logarithmic \sqcup
      ⇒barriers and backtracking line search.
         Parameters:
             Q (numpy.ndarray): Positive semidefinite matrix of quadratic terms.
             p (numpy.ndarray): Linear term vector.
             A (numpy.ndarray): Constraint matrix.
             b (numpy.ndarray): Constraint vector.
             t (float): Barrier method parameter.
             v0 (numpy.ndarray): Initial variable.
             eps (float): Target precision.
             alpha (float): Line search parameter (typically small, e.g., 0.01).
             beta (float): Line search parameter (step size reduction factor, ⊔
      \hookrightarrow typically 0.5).
         Returns:
             list: Sequence of variable iterates (vi).
         def objective(v):
             """Barrier objective function."""
             return t * (v.T @ Q @ v + p.T @ v) - np.sum(np.log(b - A @ v))
         def backtracking_line_search(v, dv, grad):
             """Backtracking line search to find step size."""
             step\_size = 1.0
             while True:
                 new_v = v + step_size * dv
                 if np.all(b - A @ new_v > 0) and objective(new_v) <= objective(v) +
      →alpha * step_size * grad.T @ dv:
                     break
                 step_size *= beta
             return step_size
```

```
vi = [v0]
v = v0
i = 0
while True and i < 100:
    gradient = t * (2 * Q @ v + p) + A.T @ (1 / (b - A @ v))
    D = np.diag(1 / (b - A @ v)**2)
    \texttt{hessian} = 2 * \texttt{t} * \texttt{Q} + \texttt{A.T} @ \texttt{D} @ \texttt{A}
    # Solve the Newton step (Hessian * dv = -grad)
    dv = np.linalg.solve(hessian, -gradient)
    decrement = np.sqrt(gradient.T @ -dv)
    # Check for convergence
    if decrement**2 / 2 <= eps:</pre>
         break
    step_size = backtracking_line_search(v, dv, gradient)
    v = v + step_size * dv
    vi.append(v)
    i += 1
return vi
```

```
[3]: def barr_method(Q, p, A, b, v0, eps, mu=10, t0=1):
    """
    Implements the barrier method to solve QP using the centering_step function.

Parameters:
    Q (numpy.ndarray): Positive semidefinite matrix of quadratic terms.
    p (numpy.ndarray): Linear term vector.
    A (numpy.ndarray): Constraint matrix.
    b (numpy.ndarray): Constraint vector.
    v0 (numpy.ndarray): Initial feasible point.
    eps (float): Precision criterion.
    mu (float): Scaling parameter for barrier method (e.g., mu > 1).
    t0 (float): Initial value of t (e.g., t0 > 0).

Returns:
    list: Sequence of variable iterates (vi).
"""

t = t0
```

```
v = v0
vi_seq = [v0]
seq_t = [t0]

while True:

vi = centering_step(Q, p, A, b, t, v, eps)
v = vi[-1]  # Final iterate of centering step
vi_seq.extend(vi[1:])
seq_t += [t] * len(vi[:-1])

# Check for convergence
precision_criterion = len(b) / t
if precision_criterion <= eps:
    break

t *= mu

return vi_seq, seq_t</pre>
```

```
[4]: def test_barrier_method_dual(mu_values, Q, p, A, b, v0, eps):
         f_value_per_mu = []
         gap_per_mu = []
         final_v_per_mu = []
         t_per_mu = []
         surrogate_f_star = None
         for mu in mu_values:
             vi_seq, seq_t = barr_method(Q, p, A, b, v0, eps, mu=mu)
             final_v = vi_seq[-1]
             final_v_per_mu.append(final_v)
             t_per_mu.append(seq_t)
             f_vt = [v.T @ Q @ v + p.T @ v for v in vi_seq]
             f_value_per_mu.append(f_vt)
             f_min = min(f_vt)
             if surrogate_f_star is None or f_min < surrogate_f_star:</pre>
                 surrogate_f_star = f_min
         for f_vt in f_value_per_mu:
             gap_per_mu.append([f - surrogate_f_star for f in f_vt])
         return final_v_per_mu, f_value_per_mu, t_per_mu, gap_per_mu,_

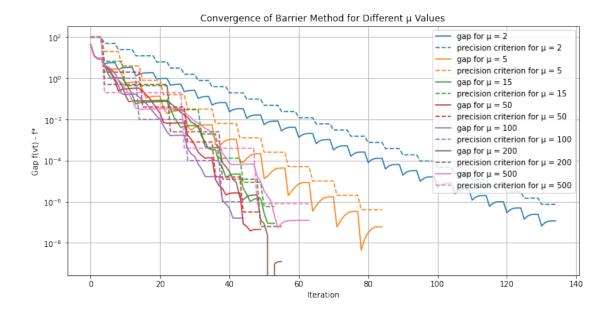
¬surrogate_f_star
```

```
[5]: def main():
         np.random.seed(42)
         n, d = 100, 50
         X = np.random.randn(n, d)
         y = np.random.randn(n)
         lambda_ = 10
         m = 2 * d
         Q = 0.5 * np.eye(n)
         p = -y
         A = np.vstack([X.T, -X.T])
         b = lambda_* np.ones(2 * d)
         v0 = np.zeros(n)
         eps = 1e-6
         mu_values = [2, 5, 15, 50, 100, 200, 500]
         final_v_per_mu, _ , t_per_mu, gap_per_mu, _ =_
      →test_barrier_method_dual(mu_values, Q, p, A, b, v0, eps)
         plt.figure(figsize=(12, 6))
         for i, mu in enumerate(mu_values):
             plt.semilogy(gap_per_mu[i], label=f"gap for = {mu}", color=f"C{i}")
             plt.semilogy(m / np.array(t_per_mu[i]), label=f"precision criterion for_

    = {mu}", linestyle='dashed', color=f"C{i}")

         plt.xlabel("Iteration")
         plt.ylabel("Gap f(vt) - f*")
         plt.title("Convergence of Barrier Method for Different Values")
         plt.legend()
         plt.grid(True)
         plt.show()
         for i, mu in enumerate(mu_values):
             print(f" = {mu}, Final solution v: {final_v_per_mu[i]}")
         print("\nAn appropriate balances convergence speed and accuracy. Thus, ⊔
      ⇔the best value is 200.")
         return 0
```

```
[6]: main()
```



```
= 2, Final solution v: [-1.18072194e-01 -4.27466288e-01 -1.18794296e+00
-1.76276279e-01
 3.12986137e-01 -8.18743422e-01 1.32829831e+00 6.60167758e-01
-3.33210203e-01 -2.41249234e-01 1.09181755e+00 6.62416167e-01
 1.75751911e-01 -2.04102271e-01 -1.34522220e-01 -3.88193561e-02
 -1.69438574e+00 1.73789076e+00 4.84316313e-01 -7.37811688e-02
-3.62251744e-01 -1.07482684e+00 -3.45064199e-01 -1.25764657e+00
  1.87225680e+00 -7.86261154e-01 -6.27575892e-01 -6.73290447e-01
 5.84813645e-01 1.05212695e-01 -7.32913709e-01 1.05518116e+00
 3.53917416e-01 1.02780344e-01 4.98509762e-01 1.66789107e+00
 2.03288345e+00 -4.24244643e-01 8.57389576e-01 4.89054483e-01
  6.97388113e-01 -1.20639883e+00 3.83675595e-01 -1.94236703e-01
  1.06765972e+00 8.02024719e-01 -1.89817562e+00 -1.84532636e-01
  1.37430528e+00 -3.39303957e-01 4.07298951e-01 3.61229750e-01
 3.06354064e-01 -2.42400666e-01 -2.62677838e-01 -1.39157526e+00
 5.56755905e-01 -6.45380598e-02 -4.20337238e-01 -2.98104655e-01
 -2.72176552e-01 8.64065716e-01 -3.70144608e-01 -9.93135879e-01
  1.08354511e-01 -3.86338808e-01 1.60897134e-01 8.18382866e-01
 4.68803204e-02 -1.48749800e-02 -9.60411509e-01 -2.01449174e-01
  1.10206379e-01 -1.25491409e+00 2.75819509e-01 3.01000138e-01
 4.84897539e-01 9.90198223e-01 9.42638319e-01 1.15412026e+00
 -3.29618618e-01 3.29775115e-01 4.00422786e-02 -7.00011717e-01
 4.05639451e-01 1.92779201e+00 -1.58174251e-03 -1.37015217e-01
 2.18616545e-01 -3.81398309e-01 -1.17878369e+00 -5.81943520e-01
-9.05911513e-01 1.45191302e+00 3.16507267e-01 2.58062036e-01
 7.92308150e-01 -6.66403311e-01 -3.03226632e-01 -1.75662311e-01]
 = 5, Final solution v: [-1.18072338e-01 -4.27466329e-01 -1.18794300e+00
-1.76276243e-01
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 1.75751782e-01 -2.04102247e-01 -1.34522172e-01 -3.88193376e-02
 -1.69438580e+00 1.73789096e+00 4.84316329e-01 -7.37811042e-02
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 6.97388162e-01 -1.20639881e+00 3.83675577e-01 -1.94236644e-01
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 4.84897494e-01 9.90198219e-01 9.42638319e-01 1.15412038e+00
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-9.05911656e-01 1.45191301e+00 3.16507207e-01 2.58062068e-01
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 = 15, Final solution v: [-1.18072263e-01 -4.27466308e-01 -1.18794298e+00
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 -1.69438577e+00 1.73789086e+00 4.84316320e-01 -7.37811380e-02
 -3.62251755e-01 -1.07482689e+00 -3.45064183e-01 -1.25764659e+00
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 1.10206409e-01 -1.25491412e+00 2.75819508e-01 3.01000141e-01
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 4.05639384e-01 1.92779208e+00 -1.58172173e-03 -1.37015206e-01
 2.18616462e-01 -3.81398343e-01 -1.17878370e+00 -5.81943508e-01
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 = 50, Final solution v: [-1.18072376e-01 -4.27466340e-01 -1.18794301e+00]
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 -3.62251772e-01 -1.07482697e+00 -3.45064155e-01 -1.25764663e+00
 1.87225678e+00 - 7.86261133e-01 - 6.27575715e-01 - 6.73290431e-01
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 3.53917455e-01 1.02780363e-01 4.98509770e-01 1.66789088e+00
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  6.97388175e-01 -1.20639881e+00 3.83675572e-01 -1.94236628e-01
  1.06765965e+00 8.02024520e-01 -1.89817565e+00 -1.84532658e-01
  1.37430530e+00 -3.39304072e-01 4.07299002e-01 3.61229790e-01
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 4.05639271e-01 1.92779220e+00 -1.58168723e-03 -1.37015188e-01
 2.18616324e-01 -3.81398400e-01 -1.17878372e+00 -5.81943487e-01
 -9.05911694e-01 1.45191301e+00 3.16507191e-01 2.58062077e-01
 7.92308213e-01 -6.66403279e-01 -3.03226550e-01 -1.75662397e-01]
 = 100, Final solution v: [-1.18072086e-01 -4.27466257e-01 -1.18794293e+00
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 1.75752010e-01 -2.04102290e-01 -1.34522256e-01 -3.88193702e-02
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  1.87225681e+00 -7.86261167e-01 -6.27575997e-01 -6.73290457e-01
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 3.53917393e-01 1.02780333e-01 4.98509757e-01 1.66789119e+00
 2.03288340e+00 -4.24244663e-01 8.57389678e-01 4.89054518e-01
  6.97388076e-01 -1.20639884e+00 3.83675609e-01 -1.94236748e-01
  1.06765976e+00 8.02024838e-01 -1.89817560e+00 -1.84532622e-01
  1.37430527e+00 -3.39303888e-01 4.07298921e-01 3.61229727e-01
  3.06354036e-01 -2.42400677e-01 -2.62677889e-01 -1.39157529e+00
 5.56755972e-01 -6.45379287e-02 -4.20337300e-01 -2.98104655e-01
 -2.72176394e-01 8.64065680e-01 -3.70144548e-01 -9.93135905e-01
 1.08354508e-01 -3.86338800e-01 1.60897117e-01 8.18382792e-01
 4.68803151e-02 -1.48749907e-02 -9.60411556e-01 -2.01449304e-01
  1.10206332e-01 -1.25491405e+00 2.75819511e-01 3.01000134e-01
```

```
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 4.05639560e-01 1.92779189e+00 -1.58177565e-03 -1.37015234e-01
  2.18616678e-01 -3.81398254e-01 -1.17878367e+00 -5.81943540e-01
-9.05911405e-01 1.45191303e+00 3.16507312e-01 2.58062012e-01
 7.92308113e-01 -6.66403330e-01 -3.03226681e-01 -1.75662259e-01]
 = 200, Final solution v: [-1.18072486e-01 -4.27466371e-01 -1.18794304e+00
-1.76276205e-01
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 -3.62251790e-01 -1.07482705e+00 -3.45064128e-01 -1.25764667e+00
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  1.37430532e+00 -3.39304142e-01 4.07299033e-01 3.61229814e-01
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 4.84897448e-01 9.90198216e-01 9.42638318e-01 1.15412050e+00
 -3.29618472e-01 3.29775259e-01 4.00422306e-02 -7.00011774e-01
 4.05639161e-01 1.92779231e+00 -1.58165374e-03 -1.37015170e-01
 2.18616190e-01 -3.81398456e-01 -1.17878374e+00 -5.81943467e-01
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 7.92308250e-01 -6.66403259e-01 -3.03226501e-01 -1.75662450e-01
 = 500, Final solution v: [-1.18072171e-01 -4.27466282e-01 -1.18794295e+00
-1.76276285e-01
 3.12986143e-01 -8.18743420e-01 1.32829830e+00 6.60167759e-01
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 1.75751933e-01 -2.04102275e-01 -1.34522228e-01 -3.88193592e-02
 -1.69438573e+00 1.73789073e+00 4.84316310e-01 -7.37811794e-02
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  3.53917412e-01 1.02780342e-01 4.98509761e-01 1.66789110e+00
  2.03288344e+00 -4.24244647e-01 8.57389598e-01 4.89054491e-01
  6.97388105e-01 -1.20639883e+00 3.83675598e-01 -1.94236712e-01
  1.06765973e+00 8.02024744e-01 -1.89817561e+00 -1.84532633e-01
  1.37430528e+00 -3.39303942e-01 4.07298945e-01 3.61229745e-01
  3.06354058e-01 -2.42400668e-01 -2.62677849e-01 -1.39157526e+00
  5.56755919e-01 -6.45380315e-02 -4.20337251e-01 -2.98104655e-01
```

An appropriate balances convergence speed and accuracy. Thus, the best value is 200.

[6]: 0

[]: