Package 'VLTimeCausality'

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Title Variable-Lag Time Series Causality Inference Frames	vork
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Version 0.1.0

Description A framework to infer causality on a pair of time series of real numbers based on variable-lag Granger causality and transfer entropy. Typically, Granger causality and transfer entropy have an assumption of a fixed and constant time delay between the cause and effect. However, for a non-stationary time series, this assumption is not true. For example, considering two time series of velocity of person A and person B where B follows A. At some time, B stops tying his shoes, then running to catch up A. The fixed-lag assumption is not true in this case. We propose a framework that allows variable-lags between cause and effect in Granger causality and transfer entropy to allow them to deal with variable-lag non-stationary time series. Please see Chainarong Amornbunchornvej, Elena Zheleva, and Tanya Berger-Wolf (2019) https://www.cs.uic.edu/~elena/pubs/amornbunchornvej-dsaa19.pdf> when referring to this package in publications.

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URL https://github.com/DarkEyes/VLTimeSeriesCausality

BugReports https://github.com/DarkEyes/VLTimeSeriesCausality/issues

Language en-US **Encoding** UTF-8

LazyData true

Depends R (>= 3.5.0),

dtw, tseries,

RTransferEntropy

Imports ggplot2 (>= 3.0)

Suggests knitr, rmarkdown

VignetteBuilder knitr

RoxygenNote 7.0.0

R topics documented:

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check Multiple Simulation VL time series

check Multiple Simulation VL time series

Description

 $check Multiple Simulation VL time series \ is \ a \ support \ function \ that \ can \ compare \ two \ adjacency \ matrices: \ ground truth \ and \ inferred \ matrices. \ It \ re$

Usage

checkMultipleSimulationVLtimeseries(trueAdjMat, adjMat)

Arguments

trueAdjMat a groundtruth matrix.
adjMat an inferred matrix.

Value

This function returns a list of precision prec , recall rec , and F1 score F1 of inferred vs. groundtruth matrices.

```
\label{eq:generate_simulation} \begin{array}{l} \# \ Generate \ simulation \ data \\ G<-matrix(FALSE,10,10) \ \# \ groundtruth \\ G[1,c(4,7,8,10)]<-TRUE \\ G[2,c(5,7,9,10)]<-TRUE \\ G[3,c(6,8,9,10)]<-TRUE \\ TS<- \ MultipleSimulationVL timeseries() \\ out<-multipleVLG ranger Func(TS) \\ checkMultipleSimulationVL timeseries(trueAdjMat=G,adjMat=out\$adjMat) \end{array}
```

following Relation 3

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Description

followingRelation is a function that infers whether Y follows X.

Usage

```
followingRelation(Y, X, timeLagWindow, lagWindow = 0.2)
```

Arguments

Y is a numerical time series of a follower X is a numerical time series of a leader

timeLagWindow is a maximum possible time delay in the term of time steps.

lagWindow is a maximum possible time delay in the term of percentage of length(X). If

timeLagWindow is missing, then timeLagWindow=ceiling(lagWindow*length(X)).

The default is 0.2.

Value

This function returns a list of following relation variables below.

follVal is a following-relation value s.t. if follVal is positive, then Y follows X. If

follVal is negative, then X follows Y. Otherwise, if follVal is zero, there is no

following relation between X,Y.

nX is a time series that is rearranged from X by applying the lags optIndexVec in

order to imitate Y.

optDelay is the optimal time delay inferred by cross-correlation of X,Y. It is positive if Y

is simply just a time-shift of X (e.g. Y[t]=X[t-optDelay]).

 optCor is the optimal correlation of Y[t] = X[t-optDelay] for all t.

optIndexVec is a time series of optimal warping-path from DTW that is corrected by cross

correlation. It is approximately that Y[t]=X[t-optIndexVec[t]]).

VLval is a percentage of elements in optIndexVec that is not equal to optDelay.

ccfout is an output object of ccf function.

Examples

```
# Generate simulation data
```

TS <- SimpleSimulationVLtimeseries()

Run the function

out<-followingRelation(Y=TS\$Y,X=TS\$X)

4 GrangerFunc

|--|

Description

GrangerFunc is a Granger Causality function. It tests whether X Granger-causes Y.

Usage

```
\begin{aligned} & GrangerFunc(\\ & Y,\\ & X,\\ & maxLag = 1,\\ & alpha = 0.05,\\ & autoLagflag = TRUE,\\ & gamma = 0.5,\\ & family = gaussian \end{aligned}
```

Arguments

Y is a numerical time series of effect X is a numerical time series of cause

maxLag is a maximum possible time delay. The default is 1.

alpha is a significance level of F-test to determine whether X Granger-causes Y. The

default is 0.05.

autoLagflag is a flag for enabling the automatic lag inference function. The default is true.

If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to

infer Granger causality.

gamma is a parameter to determine whether X Granger-causes Y using BIC difference

ratio.

family is a parameter of family of function for Generalized Linear Models function

(glm). The default is gaussian.

Value

This function returns of whether X Granger-causes Y.

ftest F-statistic of Granger causality.

p. val A p-value from F-test.

BIC_H0 Bayesian Information Criterion (BIC) derived from Y regressing on Y past.

BIC_H1 Bayesian Information Criterion (BIC) derived from Y regressing on Y,X past.

XgCsY The flag is true if X Granger-causes Y using BIC difference ratio where BICDiffRatio

>= gamma.

 $XgCsY_ftest$ The flag is true if X Granger-causes Y using F-test where p.val>=alpha. $XgCsY_BIC$ The flag is true if X Granger-causes Y using BIC where BIC H0>=BIC H1.

```
maxLag A maximum possible time delay.

H0 glm object of Y regressing on Y past.

H1 glm object of Y regressing on Y,X past.
```

BICDiffRatio Bayesian Information Criterion difference ratio: (BIC H0-BIC H1)/BIC H0.

Examples

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
# Run the function
out<-GrangerFunc(Y=TS$Y,X=TS$X)
```

MultipleSimulationVLtimeseries

MultipleSimulationVLtimeseries

Description

MultipleSimulationVLtimeseries is a support function for generating a set of time series TS[,1],...TS[,10]. TS[,1],TS[,2],TS[,3] are causes X time series that are generated independently. The rest of time series are Y time series that are effects of some causes TS[,1],TS[,2],TS[,3]. TS[,1] causes TS[,4],TS[,7],TS[,8], and TS[,10]. TS[,2] causes TS[,5],TS[,7],TS[,9], and TS[,10].

Usage

```
\begin{split} & \text{MultipleSimulationVL timeseries}(\\ & n = 200, \\ & \text{lag} = 5, \\ & \text{YstFixInx} = 111, \\ & \text{YfnFixInx} = 150, \\ & \text{XpointFixInx} = 100, \\ & \text{arimaFlag} = \text{TRUE} \\ & ) \end{split}
```

Arguments

n is length of time series.

lag is a time lag between X and Y s.t. Y[t] is approximately X[t-lag].

YstFixInx is the starting point of variable lag part.
YfnFixInx is the end point of variable lag part.

 $XpointFixInx \qquad \text{is a point in } X \text{ s.t. } Y[YstFixInx:YfnFixInx] = X[XpointFixInx] \ .$

arimaFlag is ARMA model flag. If it is true, then X is generated by ARMA model. If it is

false, then X is generated by sampling of the standard normal distribution.

Value

This function returns a list of time series TS.

Examples

```
# Generate simulation data
TS <- MultipleSimulationVLtimeseries()
```

multipleVLGrangerFunc multipleVLGrangerFunc

Description

multiple VLGranger Func is a function that infers Variable-lag Granger Causality of all pairwises of m time series TS[,1],...TS[,m].

Usage

```
multipleVLGrangerFunc(
 TS,
 maxLag,
 alpha = 0.05,
 gamma = 0.3,
 autoLagflag = TRUE,\\
 causalFlag = 0,
 VLflag = TRUE,
 family = gaussian
```

Arguments TS

	time series.
$\max Lag$	is a maximum possible time delay. The default is 0.2*length(Y).
alpha	is a significance level of F-test to determine whether \boldsymbol{X} Granger-causes $\boldsymbol{Y}.$ The default is $0.05.$
gamma	is a parameter to determine whether \boldsymbol{X} Granger-causes \boldsymbol{Y} using BIC difference ratio. The default is 0.3.
autoLagflag	is a flag for enabling the automatic lag inference function. The default is true. If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to infer Granger causality.
${\it causalFlag}$	is a choice of criterion for inferring causality: causalFlag=0 for BIC difference

is a numerical time series of effect where $\mathrm{TS}[t,k]$ is an element at time t of kth

ratio, causalFlag=1 for f-test, or causalFlag=2 for BIC.

VLflag is a flag of Granger causality choice: either VLflag=TRUE for VL-Granger or

VLflag=FALSE for Granger causality.

family is a parameter of family of function for Generalized Linear Models function

(glm). The default is gaussian.

Value

This function returns of a list of an adjacency matrix of causality where adjMat[i,j] is true if TS[,i] causes TS[,j].

Examples

```
# Generate simulation data
TS <- MultipleSimulationVLtimeseries()
# Run the function
out<-multipleVLGrangerFunc(TS)
```

multipleVLTransferEntropy

multiple VLT ransfer Entropy

Description

multiple VLT ransfer Entropy is a function that infers Variable-lag Transfer Entropy of all pairwises of m time series TS[,1],...TS[,m].

Usage

```
\begin{split} & multiple VLT ransfer Entropy (\\ & TS,\\ & max Lag,\\ & nboot = 0,\\ & lx = 1,\\ & ly = 1,\\ & VL flag = TRUE,\\ & auto Lag flag = TRUE \end{split}
```

Arguments

TS	is a numerical time series of effect where TS[t,k] is an element at time t of kth
1.5	is a numerical time series of effect where I SIt kl is an element at time t of kth

time series.

 $\max \text{Lag}$ is a maximum possible time delay. The default is 0.2*length(Y).

nboot is a number of times of bootstrapping for RTransferEntropy::transfer_entropy()

function.

lx, ly are lag parameters of RTransferEntropy::transfer_entropy().

VLflag is a flag of Granger causality choice: either VLflag=TRUE for VL-Granger or

VLflag=FALSE for Granger causality.

autoLagflag is a flag for enabling the automatic lag inference function. The default is true.

If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to

infer Granger causality.

Value

This function returns of a list of an adjacency matrix of causality where $\operatorname{adjMat}[i,j]$ is true if $\operatorname{TS}[,i]$ causes $\operatorname{TS}[,j]$.

8 plotTimeSeries

Examples

```
\label{eq:continuous} \begin{array}{l} \# \ Generate \ simulation \ data \\ out1<-SimpleSimulationVL timeseries() \\ TS<-cbind(out1\$X,out1\$Y) \\ \# \ Run \ the \ function \\ out2<-multipleVLTransferEntropy(TS,maxLag=1) \end{array}
```

plotTimeSeries

plotTimeSeries

Description

plotTimeSeries is a function for visualizing time series

Usage

```
plotTimeSeries(X, Y, strTitle = "Time Series Plot", TSnames)
```

Arguments

X is a 1st numerical time series

Y is a 2nd numerical time series. If it is not supplied, the function plots only X.

strTitle is a string of the plot title

TSnames is a list of legend of X,Y where TSnames[1] is a legend of X and TSnames[2]

is a legend of Y.

Value

This function returns an object of ggplot class.

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
# Run the function
plotTimeSeries(Y=TS$Y,X=TS$X)
```

SimpleSimulationVLtimeseries

SimpleSimulationVLtimeseries

Description

SimpleSimulationVL timeseries is a support function for generating time series X,Y where X VL-Granger-causes Y.

Usage

```
\begin{array}{l} Simple Simulation VL time series (\\ n=200,\\ lag=5,\\ Yst Fix Inx=110,\\ Yfn Fix Inx=170,\\ Xpoint Fix Inx=100,\\ arima Flag=TRUE \end{array}
```

Arguments

n is length of time series.

lag is a time lag between X and Y s.t. Y[t] is approximately X[t-lag].

YstFixInx is the starting point of variable lag part.

YfnFixInx is the end point of variable lag part.

XpointFixInx is a point in X s.t. Y[YstFixInx:YfnFixInx] = X[XpointFixInx].

arimaFlag is ARMA model flag. If it is true, then X is generated by ARMA model. If it is

false, then X is generated by sampling of the standard normal distribution.

Value

This function returns a list of time series X,Y where X VL-Granger-causes Y.

```
# Generate simulation data
TS <- SimpleSimulationVLtimeseries()
```

10 VLGrangerFunc

${ m VLGrangerFunc}$	VLGrangerFunc
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Description

 $\label{lem:VLGrangerFunc} VLGrangerFunc \ is \ a \ Variable-lag \ Granger \ Causality \ function. \ It tests \ whether \ X \ VL-Granger-causes \ Y.$

Usage

```
\begin{array}{l} VLGrangerFunc (\\ Y,\\ X,\\ alpha=0.05,\\ maxLag,\\ gamma=0.5,\\ autoLagflag=TRUE,\\ family=gaussian \end{array}
```

Arguments

Y is a numerical time series of effect X is a numerical time series of cause

alpha is a significance level of f-test to determine whether X Granger-causes Y. The

default is 0.05.

 $\max \text{Lag}$ is a maximum possible time delay. The default is 0.2*length(Y).

gamma is a parameter to determine whether X Granger-causes Y using BIC difference

ratio. The default is 0.5.

autoLagflag is a flag for enabling the automatic lag inference function. The default is true.

If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to

infer Granger causality.

family is a parameter of family of function for Generalized Linear Models function

(glm). The default is gaussian.

Value

This function returns of whether X Granger-causes Y.

ftest	F-statistic of Granger causality.
p. val	A p-value from F-test.
$\mathrm{BIC}_{-}\mathrm{H0}$	Bayesian Information Criterion (BIC) derived from Y regressing on Y past.
$\mathrm{BIC}_{-}\mathrm{H1}$	Bayesian Information Criterion (BIC) derived from Y regressing on Y,X past.
XgCsY	The flag is true if X Granger-causes Y using BIC difference ratio where BICDiffRatio
	>= gamma.
$\rm XgCsY_ftest$	The flag is true if X Granger-causes Y using f-test where p.val>=alpha.
${\rm XgCsY_BIC}$	The flag is true if X Granger-causes Y using BIC where BIC_H0>=BIC_H1.

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```
maxLag A maximum possible time delay.

H0 glm object of Y regressing on Y past.

H1 glm object of Y regressing on Y,X past.
```

follOut is a list of variables from function following Relation.

BICDiffRatio Bayesian Information Criterion difference ratio: (BIC H0-BIC H1)/BIC H0.

Examples

```
\label{eq:continuity} \begin{array}{l} \# \mbox{ Generate simulation data} \\ TS <- \mbox{ SimpleSimulationVL timeseries()} \\ \# \mbox{ Run the function} \\ out<- \mbox{VLGrangerFunc}(Y=TS\$Y,X=TS\$X) \end{array}
```

VLTransferEntropy

VLTransferEntropy

Description

VLTransferEntropy is a Variable-lag Transfer Entropy function. It tests whether X VL-Transfer-Entropy-causes Y.

Usage

```
\label{eq:VLTransferEntropy} \begin{split} &Y,\\ &Y,\\ &X,\\ &\max Lag,\\ &\operatorname{nboot} = 0,\\ &\ln x = 1,\\ &\ln y = 1,\\ &\operatorname{VLflag} = \operatorname{TRUE},\\ &\operatorname{autoLagflag} = \operatorname{TRUE} \end{split}
```

Arguments

Y is a numerical time series of effect X is a numerical time series of cause

 $\max \operatorname{Lag}$ is a maximum possible time delay. The default is $0.2*\operatorname{length}(Y)$.

nboot is a number of times of bootstrapping for RTransferEntropy::transfer_entropy()

function.

lx, ly are lag parameters of RTransferEntropy::transfer_entropy().

VLflag is a flag of Transfer Entropy choice: either VLflag=TRUE for VL-Transfer

Entropy or VLflag=FALSE for Transfer Entropy.

autoLagflag is a flag for enabling the automatic lag inference function. The default is true.

If it is set to be true, then maxLag is set automatically using cross-correlation. Otherwise, if it is set to be false, then the function takes the maxLag value to

infer Granger causality.

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Value

This function returns of whether X (VL-)Transfer-Entropy-causes $\Upsilon.$

res is an object of output from RTransferEntropy::transfer_entropy()

follOut is a list of variables from function following Relation.

XgCsY_trns The flag is true if X (VL-)Transfer-Entropy-causes Y using Transfer Entropy

ratio ratio where TEratio >1 if X causes Y.

```
\label{eq:continuity} \begin{array}{l} \# \mbox{ Generate simulation data} \\ TS <- \mbox{ SimpleSimulationVL timeseries()} \\ \# \mbox{ Run the function} \\ out<- \mbox{VLTransferEntropy}(\mbox{Y=TS$Y,X=TS$X}) \end{array}
```

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