

Machine Intelligence

Assignment 1

(Chapters Questions)

Team 1

Mohamed Shawky Zaky, Sec : **2**, BN : **15**

Remonda Talaat Eskarous, Sec : **1**, BN : **19**

Mohamed Ahmed Mohamed Ahmed, Sec : **2**, BN : **10**

Mohamed Ramzy Helmy, Sec : **2**, BN : **13**

Chapter (13)

- 1) Using a full joint probability distribution table is an efficient and scalable way to calculate posteriors. (False)
 - 2) [d] Bayes Rule can help doctors calculating $P(\text{corona} \mid \text{high_body_temp} \wedge \text{dry_cough})$ because
 - a) calculating Diagnosis probability using Causal probability is reasonable.
 - b) calculating Causal probability using Diagnosis probability is reasonable.
 - c) conditional independence makes calculations faster and more scalable.
 - d) a and c.
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Chapter (14)

- 1) A Bayesian Network's graph can have directed cycles. (False)
 - 2) [c] is the probability distribution that is represented by a Bayesian Network that has a set of $\{x_1, x_2, x_3, x_4\}$ nodes.
 - a) $p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2)p(x_3)p(x_4)$
 - b) $p(x_1, x_2, x_3, x_4) = p(x_1) + p(x_2) + p(x_3) + p(x_4)$
 - c) $p(x_1, x_2, x_3, x_4) = p(x_1|\text{parents}(x_1))p(x_2|\text{parents}(x_2))p(x_3|\text{parents}(x_3))p(x_4|\text{parents}(x_4))$
 - d) $p(x_1, x_2, x_3, x_4) = p(x_1)p(x_2|\text{parents}(x_2))p(x_3|\text{parents}(x_3))p(x_4|\text{parents}(x_4))$
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Chapter (15)

- 1) Extended Kalman Filter (EKF) is an addition over regular Kalman Filter (KF) to overcome nonlinearities in the system being modeled. (True)
- 2) [b] is the task of computing the belief state (the posterior distribution over the most recent state) given all evidence to date.
 - a) Learning.
 - b) Filtering.
 - c) Smoothing.
 - d) Prediction

Chapter (21)

- 1) The main difference between passive reinforcement learning and policy evaluation is that the passive learning agent doesn't know the transition model nor the reward function. (True)
- 2) [c] The task of reinforcement learning is to use rewards to learn an optimal (or nearly optimal) policy from the environment.
 - a) scattered.
 - b) potential.
 - c) observed.
 - d) predicted.