

# Phase-Space

## Features

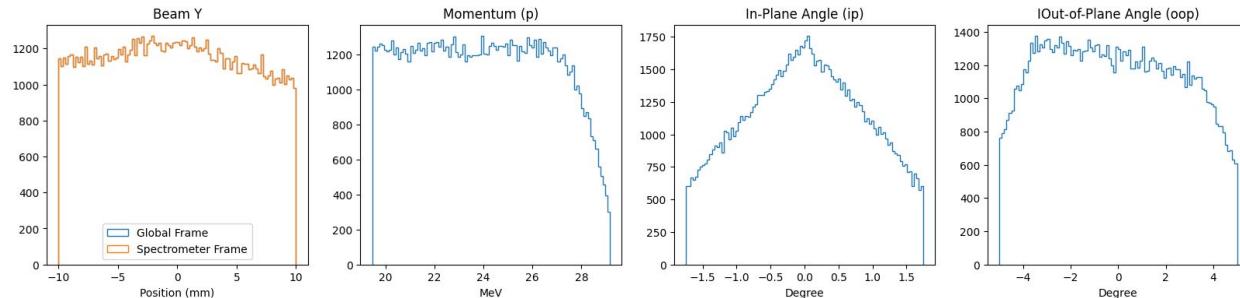
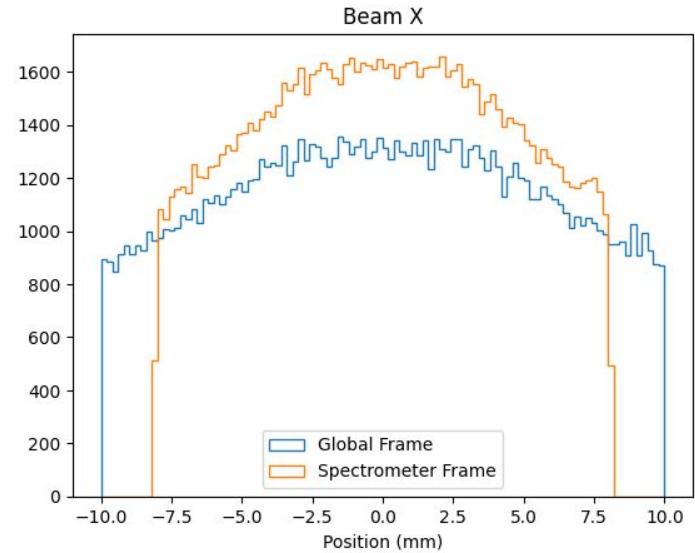
- Lower GEM hit coord. along x axis (**x**)
- Lower GEM coordinate along y axis (**y**)
- Difference between GEM hits on upper and lower GEM hits along x axis (**dx**)
- Difference between GEM hits on upper and lower GEM hits along y axis (**dy**)

## Targets

- Momentum (**p**)  $\in [-x, x]$  mm
- In-Plane Angle (**ip**)  $\in [-x, x]$  degrees
- Out-of-Plane Angle (**oop**)  $\in [-x, x]$  degrees
- Beam X (**beam\_x**)  $\in [-x, x]$  mm
- Beam Y (**beam\_y**)  $\in [-x, x]$  mm

# 0. Test-Set (eC 25 MeV)

- Constant:
  - Momentum ( $\mathbf{p}$ ) (very small variation!)
- Variable:
  - Beam X (**beam\_x**)
  - In-Plane Angle (**ip**)
  - Of-of-Plane Angle (**oop**)
- Number of events: 114,989
- **beam\_x** range
  - Global Frame: (-10, 10) mm
  - Spectrometer Frame: (-8.1, 8.1) mm

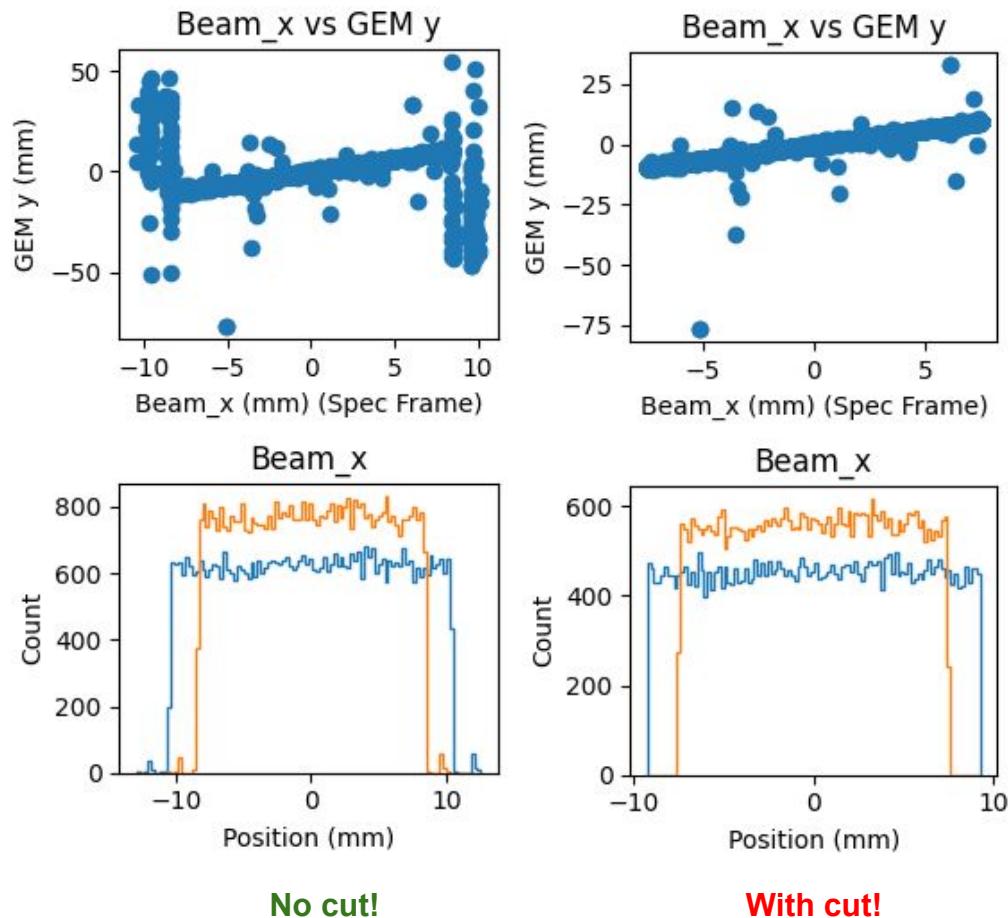


# 1. One DOF: beam\_x

- Constant:
  - Momentum (**p**) = Nominal
  - In-Plane Angle (**ip**) =  $0^\circ$
  - Out-of-Plane Angle (**oop**) =  $0^\circ$
  - Beam Y (**beam\_y**) = 0 mm
- Variable:
  - Beam X (**beam\_x**)  $\sim \mathcal{U}(-20, +20)$  mm
- Number of events: 100k

# 1. One DOF: beam\_x

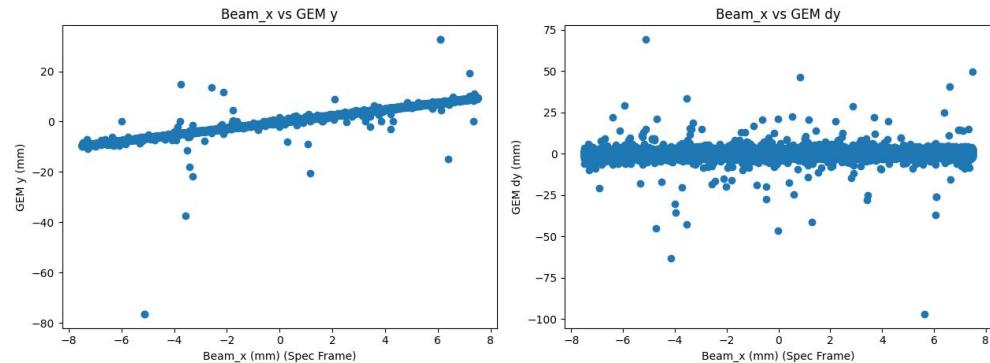
- Constant:
  - Momentum (**p**) = Nominal
  - In-Plane Angle (**ip**) =  $0^\circ$
  - Out-of-Plane Angle (**oop**) =  $0^\circ$
  - Beam Y (**beam\_y**) = 0 mm
- Variable:
  - Beam X (**beam\_x**)  $\sim \mathcal{U}(-20, +20)$  mm
- Number of events: 100k
- **beam\_x** range (we have put a hard cut)
  - Global Frame: (-9.3, 9.3) mm
  - Spectrometer Frame: (-7.5, 7.5) mm



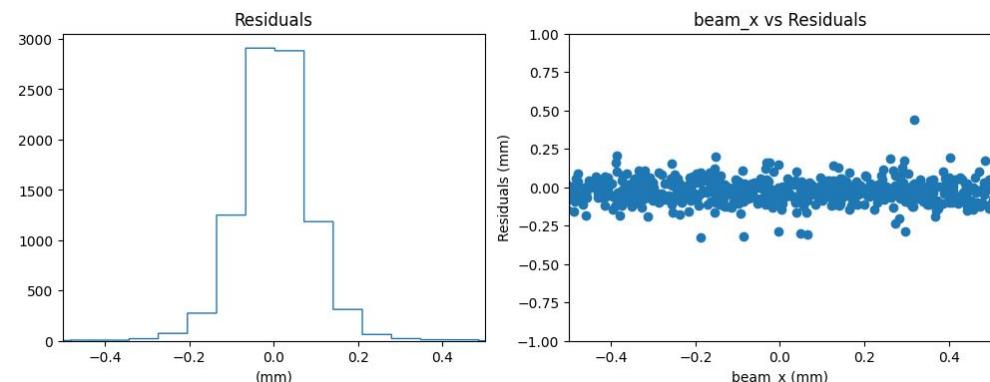
# 1. One DOF: beam\_x

- Constant:
  - Momentum (**p**) = Nominal
  - In-Plane Angle (**ip**) =  $0^\circ$
  - Out-of-Plane Angle (**oop**) =  $0^\circ$
  - Beam Y (**beam\_y**) = 0 mm
- Variable:
  - Beam X (**beam\_x**)  $\sim \mathcal{U}(-20, +20)$  mm
- Number of events: 100k
- **beam\_x** range (we have put a hard cut!)
  - Global Frame: (-9.3, 9.3) mm
  - Spectrometer Frame: (-7.5, 7.5) mm

beam_x Correlations	
GEM y	1.0
GEM dy	0.17

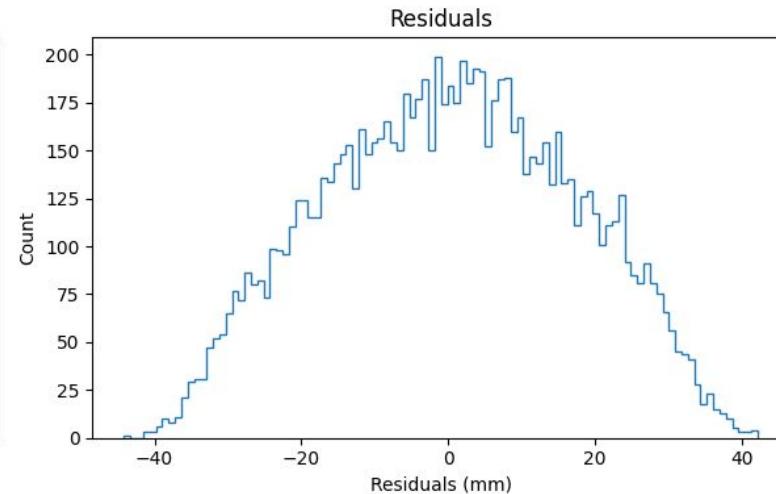
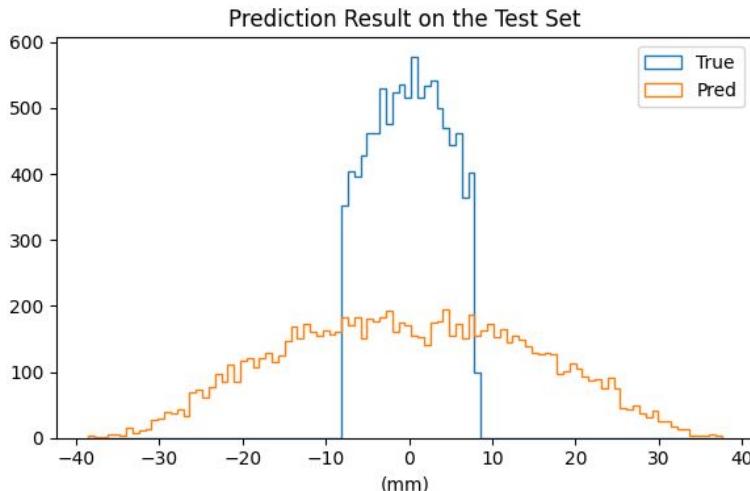


- **OLS Model:**  $\text{beam}_x = 0.09 + 0.79 \square y + 0.05 \square dy$
- Out-of-Sample:
  - RMSE: 0.82
  - Standard Deviation: 4.33
  - $R^2$ : 0.96



# 1. One DOF: beam\_x Test Set Result

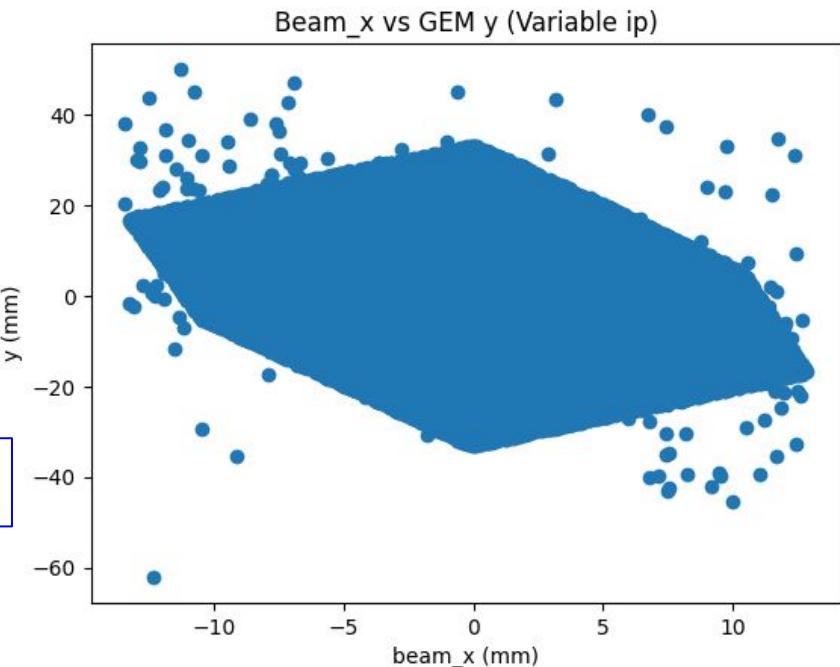
RMSE	16.9645
STD	4.404
$R^2$	-13.83

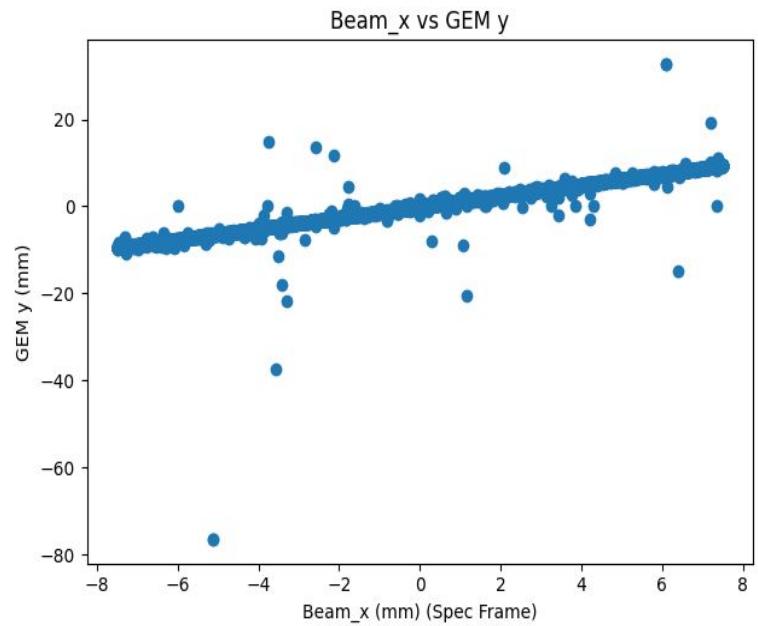


## 2. Two DOF: ip, beam\_x

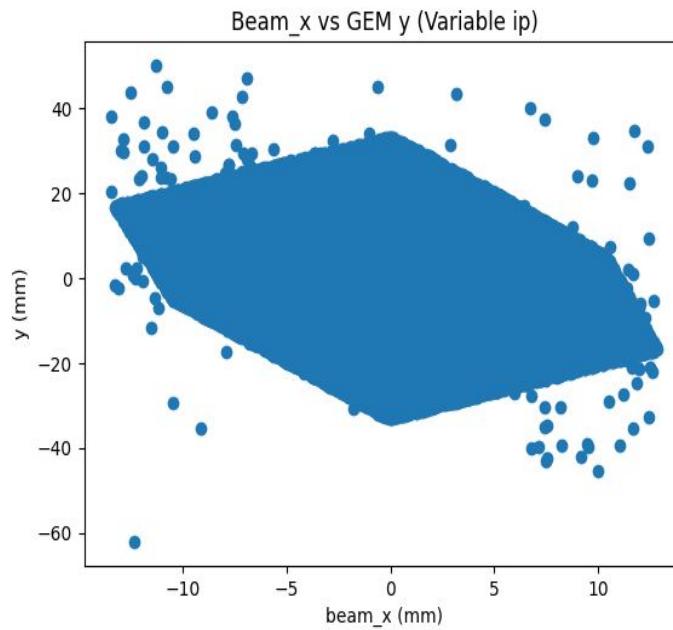
- Constant:
  - Momentum (**p**) = Nominal
  - Out-of-Plane Angle (**oop**) =  $0^\circ$
  - Beam Y (**beam\_y**) = 0 mm
- Variable:
  - Beam X (**beam\_x**)  $\sim \mathcal{U}(-20, +20)$  mm
  - In-Plane Angle (**ip**)  $\sim \mathcal{U}(-1.35^\circ, +1.35^\circ)$
- Number of events: 100k
- Model 1: 
$$\boxed{\text{beam}_x = \beta_0 + \beta_1 y + \beta_2 dy}$$

RMSE	5.68
STD	5.99
$R^2$	0.101

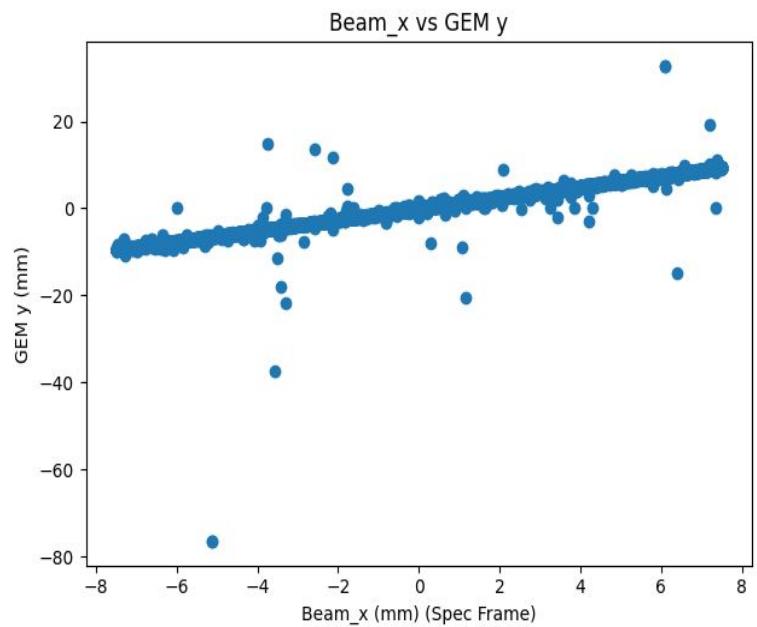




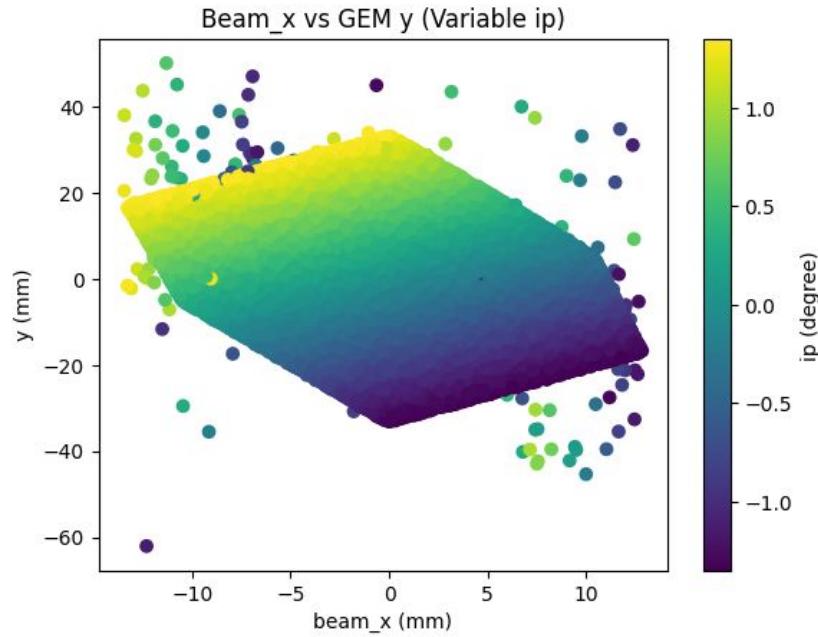
ip fixed!



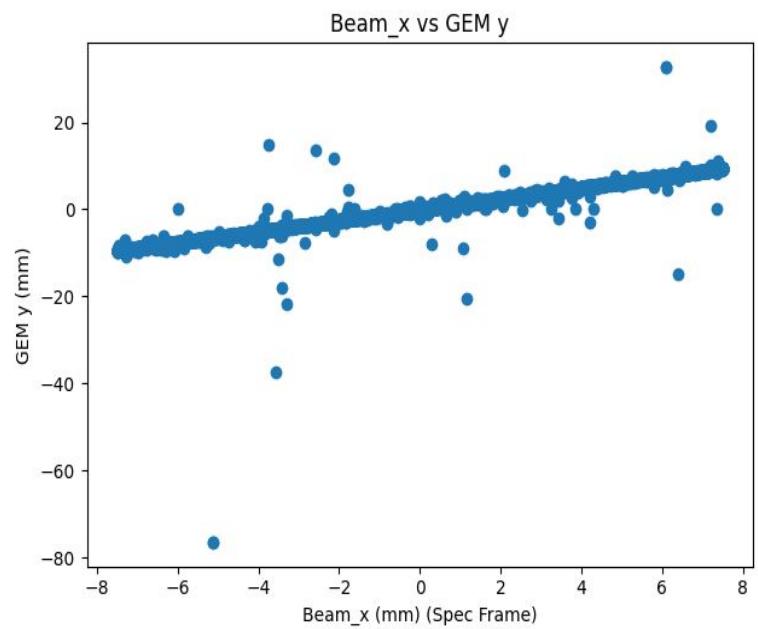
ip free!



ip fixed!



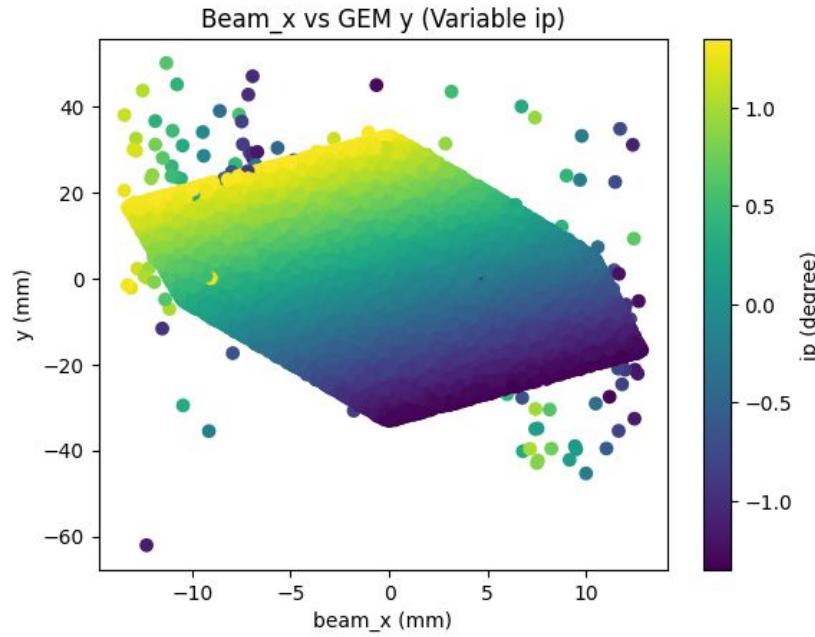
ip free!



ip fixed!

$$\hat{ip} = f(y, dy)$$

$$\text{beam\_x} = g(y, dy, \hat{ip})$$

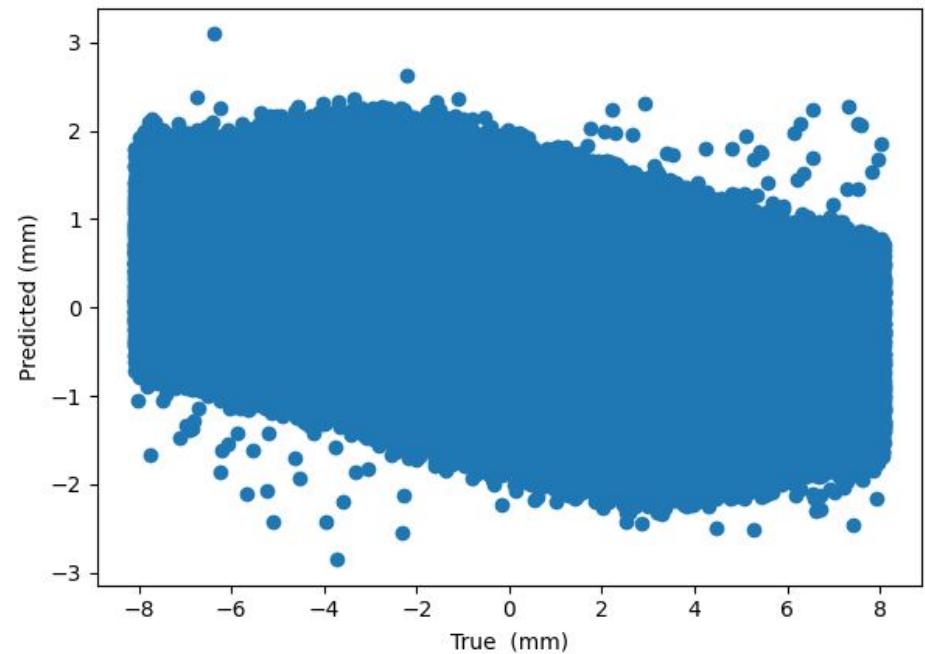


ip free!

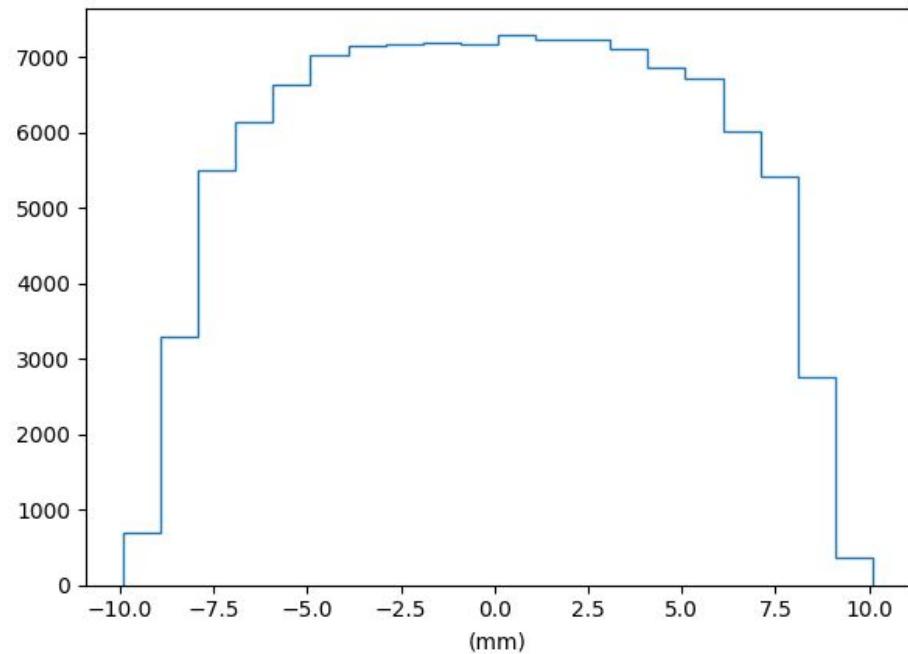
$$\Rightarrow \text{beam\_x} = g(y, dy, f(y, dy))$$

2 DOF: beam\_x, ip

Beam X Reconstruction



Residuals



RMSE	4.79
STD	4.39
$R^2$	-0.18

### 3. Three DOF: ip, oop, beam\_x

- Constant:
  - Momentum (**p**) = Nominal
  - Beam Y (**beam\_y**) = 0 mm
- Variable:
  - Beam X (**beam\_x**)  $\sim \mathcal{U}(-20, +20)$  mm
  - In-Plane Angle (**ip**)  $\sim \mathcal{U}(-1.8^\circ, +1.8^\circ)$
  - Out-of-Plane Angle (**oop**)  $\sim \mathcal{U}(-5^\circ, +5^\circ)$
- Number of events: 500k

$$\hat{ip} = \alpha_1 + \alpha_2 \cdot y + \alpha_3 \cdot dy$$

$$\hat{oop} = \beta_1 + \beta_2 \cdot y + \beta_3 \cdot dy + \beta_4 \cdot x + \beta_5 \cdot dx$$

$$\hat{\text{beam\_x}} = \gamma_1 + \gamma_2 x + \gamma_3 dx + \gamma_4 y + \gamma_5 dy$$

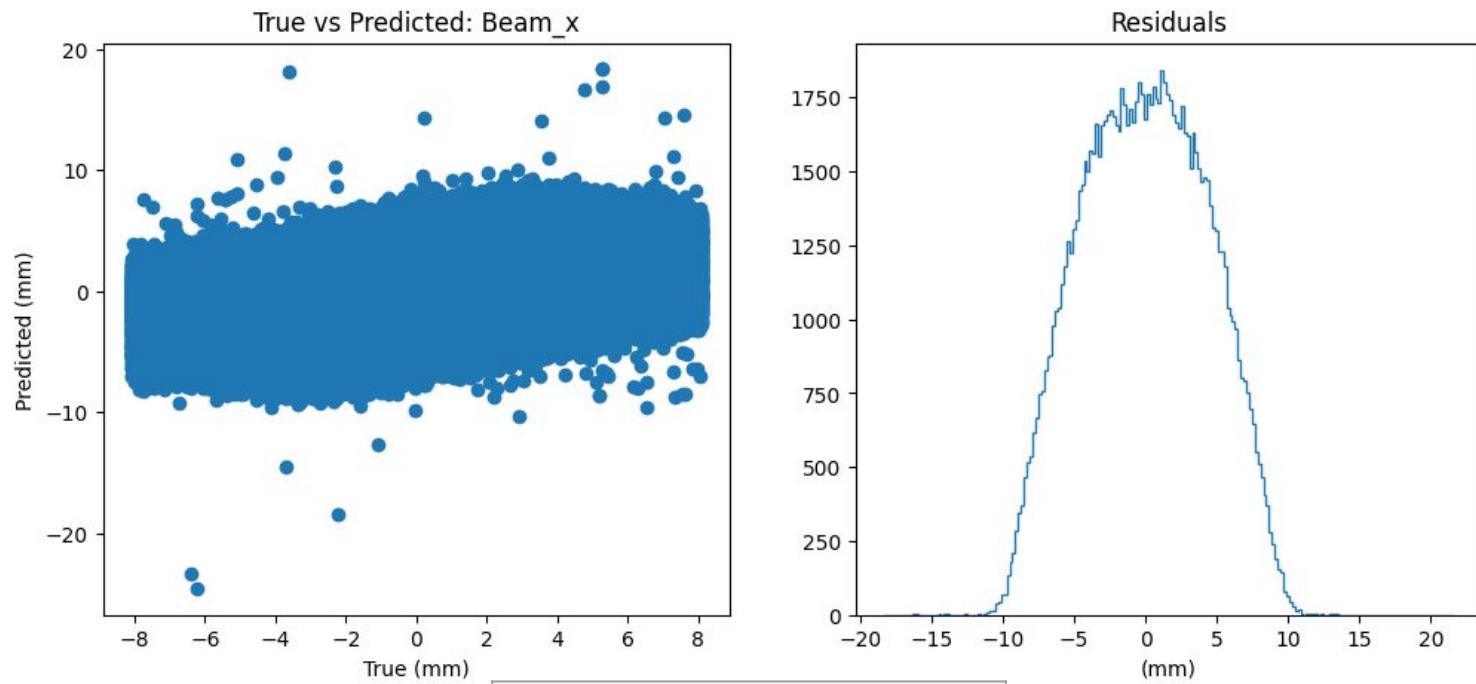
### 3. Three DOF: ip, oop, beam\_x

- Constant:
  - Momentum (**p**) = Nominal
  - Beam Y (**beam\_y**) = 0 mm
- Variable:
  - Beam X (**beam\_x**)  $\sim \mathcal{U}(-20, +20)$  mm
  - In-Plane Angle (**ip**)  $\sim \mathcal{U}(-1.8^\circ, +1.8^\circ)$
  - Out-of-Plane Angle (**oop**)  $\sim \mathcal{U}(-5^\circ, +5^\circ)$
- Number of events: 500k

$$\hat{ip} = \alpha_1 + \alpha_2 \cdot y + \alpha_3 \cdot dy$$
$$\hat{oop} = \beta_1 + \beta_2 \cdot y + \beta_3 \cdot dy + \beta_4 \cdot x + \beta_5 \cdot dx$$
$$\hat{beam\_x} = \gamma_1 + \gamma_2 x + \gamma_3 dx + \gamma_4 y + \gamma_5 dy$$

Model 1: Predicting ip	
RMSE	0.29
STD	0.88
R <sup>2</sup>	0.88

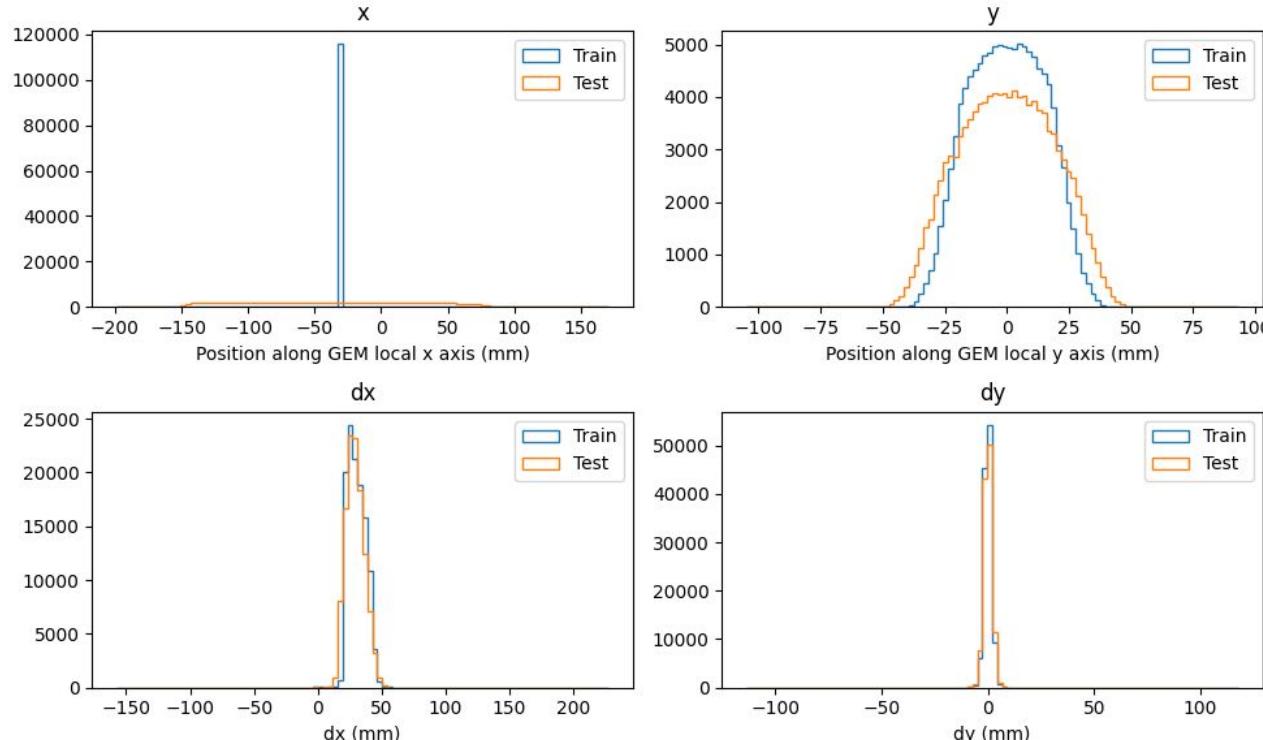
Model 2: Predicting oop	
RMSE	2.24
STD	2.7
R <sup>2</sup>	0.32



Model 3: Predicting beam\_x

RMSE	4.38
STD	4.39
R <sup>2</sup>	0.005

# Data Distribution in 3 DOF Case (Features)



# Data Distribution in 3 DOF Case (Targets)

