

100m Dual Laser Calibration Laser Range Finder Module

Key Properties

- Measuring Range: 0.06m ~ 30m/60m/100m

- Measure Accuracy: ±3.0 mm @ 25°C

- Measure Frequency: $1^{\sim}10$ Hz

- Laser Wavelength: 620~690 nm

- Eye Safety: Class 2 (<1mW)

- Communication Interface: TTL (UART)

- Dual Laser Calibration



Application

Measurement / Industrial / Robot / Auto Control Applications

Product Code

| Product | Measure Range | Frequency | Туре | Communication Interface | | | | |
|------------------------|-----------------|-----------|----------------------|-------------------------|--|--|--|--|
| LRF: Laser Rang Finder | 30M: 30 meter | 10: 10Hz | PH: Precise High-end | Default: TTL (UART) | | | | |
| | 60M: 60 meter | | | USB: TTL to USB cable | | | | |
| | 100M: 100 meter | | | BT: Bluetooth | | | | |
| Example: LRF30M10PH | | | | | | | | |

Introduction

LRF100M10PH is a high precision laser rangefinder module with dual calibration design to maintain absolute accuracy when operating under different environmental conditions. The small-size and lightweight feature is convenient for OEM users to integrate into systems and equipment, and the TTL UART communication interface provides users to develop and program their own application.

The LRF100M10PH offers measuring ranges from 30 up to 100 meters. The compact units with small dimensions: only 37.5 x 45.3 x 19.2 mm. They are designed for users to easily connect the Laser measurement unit to a PC or an MCU through TTL(UART) communication . A Bluetooth option is also available, please refer to the IADIY Laser Distance measuring BT-series. The unit has a 1mm resolution and an accuracy of ±3.0mm along with a high sampling rate. (up to 10 samples / second)

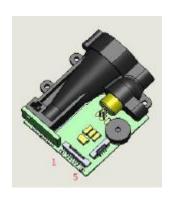


1. Specifications

| Model Name | LRF30M10PH | LRF60M10PH | LRF100M10PH | | | |
|-------------------------|------------------|-----------------------|-------------------|--|--|--|
| Measuring Range | 0.06 ~ 30 meters | 0.06 ~ 60 meters | 0.06 ~ 100 meters | | | |
| Measure Accuracy | | ± 3.0 mm @ 25°C | | | | |
| Measure Rate | | 1 ~ 10 Hz | | | | |
| Mechanical Dimension | | 37.5 x 45.3 x 19.2 mm | | | | |
| Distance Resolution | | 1 mm | | | | |
| Starting Current | N | Min. 300mA, Typ. 500m | Α | | | |
| Operating Current | | <200 mA | | | | |
| Operating Voltage(DC) | | 2.5 ~ 3.0 V | | | | |
| Transmission Mode | | TTL (UART) | | | | |
| Transmission Interfaces | Fer | nale USB type-B conne | ctor | | | |
| Baud Rate | | 9600 | | | | |
| Operating Temperature | | 0~50 ℃ | | | | |
| Storage Temperature | | -20~70 ℃ | | | | |
| Buzzer Sound | | 60 ± 20 dB | | | | |
| Weight | | ~16 g | | | | |
| Laser Beam Size | 2.5 | x 5 mm @ 3 meter (FW | /HM) | | | |
| Laser Wavelength | 620~690 nm | | | | | |
| Laser Safety | | <1 mW (Class 2) | | | | |

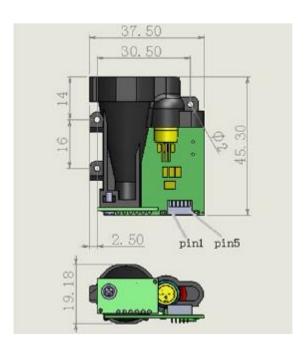
2. Pin Assignment

| Pin | Function | Description |
|-----|----------|---|
| 1 | Vin | Vcc |
| 2 | RxD | UART Rx, TTL level |
| 3 | TxD | UART Tx, TTL level |
| 4 | PWREN | Power Enable, used for system ON (High) and |
| | | OFF(Low) or can be used as Reset pin |
| 5 | GND | Ground |





3. Dimensions

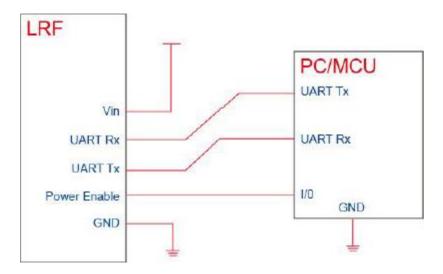


4. Electrical Characteristics

| Value | Symbol | Min | Typical | Max | Unit |
|----------------------|--------|------|---------|---------|------|
| Voltage Input | Vin | 2.5 | 3.0 | 3.1 | V |
| Current Input | lin | 300 | 500 | - | mA |
| UART Rx Logic 1 | Vuth | 3.0 | 3.3 | 3.4 | V |
| UART Rx Logic 0 | Vutl | -0.3 | 0 | 0.8 | V |
| UART Tx Logic 1 | Vurh | 3.0 | 3.3 | 3.4 | V |
| UART Tx Logic 0 | Vurl | -0.3 | 0 | 0.3 | V |
| Power Enable Logic 1 | Vpeh | 3.0 | 3.3 | Vin+0.3 | V |
| Power Enable Logic 0 | Vpel | -0.3 | 0 | 0.1 | V |



5. Connection



Note

- 1. UART configuration parameters: 8N1 with 9600 baud rate.
- 2. Users should check their OS version (Operating System) to confirm that RS232 data transmission is available.



6. Communication Format

| Master (PC/ | Master (PC/MCU) Read/Write | | | | | | | | | | | |
|--------------|--------------------------------------|---------|--------|--------|--------|-----------|--------|--|--|--|--|--|
| Initiate | Address | Command | Data 1 | ••••• | Data N | Check Sum | End | | | | | |
| 1 Byte | 1 Byte | 1 Byte | 1 Byte | 1 Byte | 1 Byte | 1 Byte | 1 Byte | | | | | |
| Slave (Laser | Slave (Laser Distance Measuring Kit) | | | | | | | | | | | |
| Initiate | Address | Command | Data 1 | | Data N | Check Sum | End | | | | | |
| 1 Byte | 1 Byte | 1 Byte | 1 Byte | 1 Byte | 1 Byte | 1 Byte | 1 Byte | | | | | |

Initiate: 0xAA End: 0xA8

Address: 0 is the master, 1-127 are the slave/devices on the Bus.

The master can communicate with all the slave devices on the Bus.

Data: Some commands may have no response.

Check Sum: Only Bit 7 to avoid conflict with Initiate or End. The highest level is set at 0.

Check Sum = (Address+Command+Data 1+···+Data n) & 0x7F.

7. Commands

| 0x08 | Read Status |
|------|-----------------------------|
| 0x04 | Read Address |
| 0x41 | Set Address |
| 0x42 | Laser ON |
| 0x43 | Laser OFF |
| 0x44 | Single measurement |
| 0x45 | Continuous measurement |
| 0x46 | Stop continuous measurement |



8. Commands details (Set slave as 0x01)

| Read Device status | | | | | | | | | | |
|--------------------|----------|---------|---------|--------|-----------|------|--|--|--|--|
| Master | End | | | | | | | | | |
| | 0xAA | 0x09 | 0xA8 | | | | | | | |
| Slave | Initiate | Address | Command | Data 1 | Check Sum | End | | | | |
| | 0xAA | 0x01 | 0x08 | 0x00 | 0x09 | 0xA8 | | | | |

[※]Slave response: 0x00 as Not ready yet; 0x01 as Standby; 0x31 as Error. When an error message is displayed, we suggest to the user to reset the system by following the procedure below:

- 1. Set the Power Enable pin level low for 200ms and then back high, and check if the system works.
- 2. If not, please contact IADIY for further service.

| Read Slave Address | | | | | | | | | | |
|--------------------|-------------------------------|---------|---------|-----------|-----------|-----|--|--|--|--|
| Master | Initiate | Address | Command | Check Sum | End | | | | | |
| | 0xAA | 0x00 | 0x04 | 0x04 | 0xA8 | | | | | |
| Slave | Initiate | Address | Command | Data 1 | Check Sum | End | | | | |
| | 0xAA 0x01 0x04 0x01 0x06 0xA8 | | | | | | | | | |
| | | | | | | | | | | |

| Set Slave Add | Set Slave Address | | | | | | | | | | |
|-----------------------------|---|---------|-----------|--------|-----------|-----|--|--|--|--|--|
| Master | Initiate | Address | Command | Data 1 | Check Sum | End | | | | | |
| 0xAA 0x00 0x41 0x02 0x43 0x | | | | | | | | | | | |
| Slave | Initiate | Data 1 | Check Sum | End | | | | | | | |
| | 0xAA 0x02 0x41 0x01 0x44 0xA8 | | | | | | | | | | |
| ※Master comn | ※Master command: Set slave Address as 0x02; Slave response: 1-Success, 0-Failed | | | | | | | | | | |

| Laser ON | | | | | | |
|----------|----------|---------|---------|-----------|-----------|------|
| Master | Initiate | Address | Command | Check Sum | End | |
| | 0xAA | 0x01 | 0x42 | 0x43 | 0xA8 | |
| Slave | Initiate | Address | Command | Data 1 | Check Sum | End |
| | 0xAA | 0x01 | 0x42 | 0x01 | 0x44 | 0xA8 |

[%]This Command is for user to easily aim at the target, but is not a necessary procedure for the measurement
%Slave response: 1-Success, 0-failed



| Laser OFF | | | | | | | | | |
|-------------------------------|--------------------------------------|---------|---------|-----------|-----------|-----|--|--|--|
| Master | Initiate | Address | Command | Check Sum | End | | | | |
| | 0xAA | 0x01 | 0x43 | 0x44 | 0xA8 | | | | |
| Slave | Initiate | Address | Command | Data 1 | Check Sum | End | | | |
| 0xAA 0x01 0x43 0x01 0x45 0xA8 | | | | | | | | | |
| *Slave respons | %Slave response: 1-Success, 0-failed | | | | | | | | |

| Single m | Single measurement | | | | | | | | | | | |
|------------------|--------------------|--------------|---------------|-----------|------------------|------------------|-----------------|------------------|------------------|-----------|------|--|
| Master | Initiate | Address | Command | Check Sum | End | | | | | | | |
| | 0xAA | 0x01 | 0x44 | 0x45 | 0xA8 | | | | | | | |
| Slave | Initiate | Address | Command | Data1 | Data2 | Data3 | Data4 | Data5 | Data6 | Check Sum | End | |
| Cond.1 | 0xAA | 0x01 | 0x44 | 0x30'0' | 0x32 ′2 ′ | 0x33 ′3 ′ | 0x34 ′4′ | 0x35 ′5 ′ | 0x36 ′6 ′ | 0x79 | 0xA8 | |
| Cond.2 | 0xAA | 0x01 | 0x44 | 0x45'E' | 0x52'R' | 0x52' R ' | 0x32'2' | 0x35 ′5 ′ | 0x35 ′5 ′ | 0x74 | 0xA8 | |
| ※ 1. Slav | e response | e: Data Byte | coding with A | SCII | | | | | | | | |

| Continuous Measurement | | | | | | | | | | | |
|------------------------|----------|---------|---------|------------------|------------------|------------------|---------|------------------|------------------|-----------|------|
| Master | Initiate | Address | Command | Check Sum | End | | | | | | |
| | 0xAA | 0x01 | 0x45 | 0x46 | 0xA8 | | | | | | |
| Slave | Initiate | Address | Command | Data 1 | Data2 | Data3 | Data4 | Data5 | Data6 | Check Sum | End |
| Cond.1 | 0xAA | 0x01 | 0x44 | 0x30 ′0 ′ | 0x32 ′2 ′ | 0x33 ′3 ′ | 0x34'4' | 0x35 ′5 ′ | 0x36' 6 ' | 0x79 | 0xA8 |
| Cond.2 | 0xAA | 0x01 | 0x44 | 0x45' E ' | 0x52'R' | 0x52'R' | 0x32'2' | 0x35 ′5 ′ | 0x35 ′5 ′ | 0x74 | 0xA8 |

[☆]The Continuous measurement command allows the Laser Distance Measuring kit to feedback measurement data continuously. There are 2 ways to stop the continuous mode: 1. STOP Continuous measurement command, and 2: Level Low the supply power, such as system OFF.

※The slave response is shown above.

For example: If the measuring distance is 23456mm, Data will be shown as above Cond.1;

But if the system fails, the error code will be 255, the response data will be shown as Cond. 2, other error codes will display "ERRxxx".

| Error code | Problem | Description | | | | |
|------------|-------------------------|--|--|--|--|--|
| ERR204 | calculate error | The Target moved too fast | | | | |
| EDDAEE | Mode signal reception | Use a reflective film on the target, or find a more adapted | | | | |
| ERR255 | Weak signal reception | measurement point on the target | | | | |
| 500056 | Character al according | Use a reflective film on the target ,or move the target away | | | | |
| ERR256 | Strong signal reception | from any light source | | | | |



| STOP Continuous Measurement | | | | | | | | | |
|-----------------------------|----------|---------|---------|-----------|-----------|------|--|--|--|
| Master | Initiate | Address | Command | Check Sum | End | | | | |
| | 0xAA | 0x01 | 0x46 | 0x47 | 0xA8 | | | | |
| Slave | Initiate | Address | Command | Data 1 | Check Sum | End | | | |
| | 0xAA | 0x01 | 0x46 | 0x01 | 0x48 | 0xA8 | | | |
| | | | | | | | | | |

| ON/OFF Buzzer | | | | | | | | | |
|---------------|----------|-----------------|---------|------------------|-----------|------|--|--|--|
| Master | Initiate | Address Command | | Data 1 Check Sum | | End | | | |
| | 0xAA | 0x01 | 0x47 | 0x01 | 0x49 | 0xA8 | | | |
| Slave | Initiate | Address | Command | Data 1 | Check Sum | End | | | |
| | 0xAA | 0x01 | 0x47 | 0x01 | 0x49 | 0xA8 | | | |

[★]Users can use this command to turn ON or OFF the Buzzer on the Laser Distance measuring kit by sending 0 for OFF or 1 for ON. The example above shows a command to turn the Buzzer ON, and Slave response is: 1- Success, 0-failed.

Notice

- 1. User should always remember to turn OFF the power of the Laser Distance Measuring Kit when the measurement is complete, as keeping the power on might reduce the life-time of the Laser and of the light receiving element inside the Laser Distance Measuring Kit.
- 2. Resistors of a few hundred Ohm are preferentially added between the pins UART Rx, UART Tx and the user's MCU in order to limit the voltage discrepancy between the two systems that would lead to current loss.
- 3. Measure Accuracy ± 3.0 mm @ 25°C, room environment.

The outdoor measurement accuracy can be roughly calculated using the following formula.

Accuracy reference (mm) = $(L-20) \times C \times 0.3 + 2$

L: measure distance (M), C: constant=1

- 4. The measure rate changes automatically based on reflectance and environmental conditions.
- 5. Continuous testing at low temperatures (0°) should not exceed 30 minutes.
- 6. Measurement targets should avoid direct light exposure



Laser Safety

The light emitted from these devices has been set in accordance with IEC60825. However, staring into the beam, whether directly or indirectly, must be avoided.

Class I

The maximum permissible exposure (MPE) cannot be exceeded, it includes High-power lasers within an enclosure that prevents exposure to the radiation and that cannot be opened without shutting down the laser. For example, a continuous laser at 600nm can emit up to 0.39mW, but for shorter wavelengths, the maximum emission is lower.

Class II

"Caution", visible laser light less than 1.0mW. Considered eye safe, normal exposure to this type of beam will not cause permanent damage to the retina.

Class IIIA

"Danger", visible laser light between 1.0mW and 5.0mW. Considered eye safe with caution. Focusing of this light into the eye could cause some damage.

Class IIIB

"Danger", infrared(IR), and high power visible lasers considered dangerous to the retina if exposed. NB: it is important to note that while complying with the above classifications, unless otherwise stated. Our laser diode products are not certified and are designed solely for use in OEM products. The way in which device is used in the final product may alter its original design classification, and it is the responsibility of the OEM to ensure compliance with the relevant standards.

Specifications are subject to change without notice.





