

SuperLU Users' Guide

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Chapter 1

	Sequential SuperLU	SuperLU_MT	SuperLU_DIST
Platform	serial		

1.3.2 Tuning Parameters for BLAS

1.3.6 Iterative Refinement

Step 6 of the expert driver algorithm, iterative refinement,

Here $\|x\|_\infty = \max_i |x_i|$. Thus, if $\text{FERR} = 10^{-6}$ then each component of x has an error bounded by about 10^{-6} .

1.4 How the three libraries differ

Chapter 2

Sequential SuperLU (Version 4.1)


```
/* De-allocate storage */  
SUPERLU_FREE (rhs);  
SUPERLU_FREE (perm_r);  
SUPERLU_FREE (perm_c);  
Destroy_CompCol_Matrix(&A);  
Destroy_SuperMatrix_Store(&B);  
Destroy_SuperNode_Matrix(&L);  
Destroy_CompCol_Matrix(&U);  
StatFree(&stat);  
}
```

2.3 Matrix data structures

```
typedef struct {  
    Stype_t Stype; /* Storage type: indicates the storage format of *Store. */  
    Dtype_t Dtype; /* Data type. */  
    Mtype_t Mtype; /* Mathematical type */  
    int  nrow;      /* number of rows */  
    int  ncol;      /* number of columns */  
}
```



```
                                which column j belongs */  
int  *sup_to_col;  /* sup_to_col[s] points to the starting column
```

- A = { Stype = SLU_NC; Dtype = SLU_D; Mtype = SLU_GE; nrow = 5; ncol = 5;
*Store = { nnz = 12;
nzval = [19.00, 12.00, 12.00, 21.00, 12.00, 12.00, 21.00,

- Equi I { YES | NO }
Specifies whether to equilibrate the system (scale A 's rows and columns to have unit norm).
- Col Perm
Specifies how to permute the columns of the matrix for sparsity preservation.
 - NATURAL: **natural ordering.**

– DROP_PROWS:

2.5 Permutations

Furthermore, we incorporated several heuristics for adapt

2.9.1 Driver routines

We provide two types of driver routines for solving systems o

- `dgscon()`

```
/* Convert the compressed row format to the compressed column format. */  
dCompRow_to_CompCol(int m, int n, int nnz,
```


`[L,U,prow,pcol] = superlu(A)` preorders the columns of A by min degree,

using a supernodal LU factorization that is faster than Matlab's

$$FERR = \frac{\| |A^{-1}| \mathbf{f} \|_{\infty}}{\| \mathbf{x} \|_{\infty}} .$$

Here, \mathbf{f}

--	--	--


```
printf("No of nonzeros in L+U = %d\n", Lstore->nnz + Ustore->nnz);  
dQuerySpace(L, U, &mem_usage);
```


*

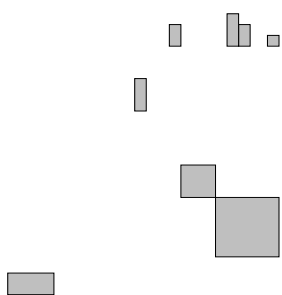
enddo


```

typedef struct {
    int nnz; /* number of nonzeros in the matrix */
    int nsuper; /* number of supernodes */
    void *nzval; /* pointer to array of nonzero values,
                 packed by column */
    int *nzval_colbeg; /* nzval_colbeg[j] points to beginning of column j
                       in nzval[] */
    int *nzval_colend; /* nzval_colend[j] points to one past the last
                       element of column j in nzval[] */
    int *rowind; /* pointer to array of compressed row indices of
                 the supernodes */
    int *rowind_colbeg; /* rowind_colbeg[j] points to beginning of column j
                       in rowind[] */
    int *rowind_colend; /* rowind_colend[j] points to one past the last
                       element of column j in rowind[] */
    int *col_to_sup; /* col_to_sup[j] is the supernode number to which
                     column j belongs */
    int *sup_to_colbeg; /* sup_to_colbeg[s] points to the first column
                       of the s-th supernode /
    int *sup_to_colend; /* sup_to_colend[s] points to one past the last
                       column of the s-th supernode */
} SCPformat;

```


Chapter 4



This process grid will use the first nprow

NOTE: All processes in the base group, including those not in

any other ordering in place of the ones provided in the librar

- Refine initialized { YES | NO }

- * 4. Call `pdgssvx`
- * 5. Release the process grid and terminate the MPI environment
- *
- * On the Cray T3E, the program may be


```

PStatInit(&stat);

/* Call the linear equation solver. */
pdgssvx(&options, &A, &ScalePermstruct, b, ldb, nrhs, &grid,
        &LUstruct, &SOLVEstruct, berr, &stat, &info);

/* Check the accuracy of the solution. */
pdinf_norm_error(iam, ((NRformat_loc *)A.Store)->m_loc,
                 nrhs, b, ldb, xtrue, ldx, &grid);

PStatPrint(&options, &stat, &grid);          /* Print the statistics. */

/* -----

```

`superlu_gri di ni t()`. In this example, the communication domain for SuperLU is built upon the MPI default communicator `MPI_COMM_WORLD`. In general, it can be built upon any MPI communicator. Section 4.4 contains the details about this step.


```
ScalePermstructFree(ScalePermstruct_t *ScalePermstruct);

/* Allocate storage in LUstruct. */
LUstructInit(const int_t m, const int_t n, LUstruct_t *LUstruct);

/* Deallocate the distributed L & U factors in LUstruct. */
Destroy_LU(int_t n, gridinfo_t *grid, LUstruct_t *LUstruct);

/* Deallocate LUstruct. */
LUstructFree(LUstruct_t *LUstruct);

/* Initialize the statistics variable. */
```

SuperLU_DIST


```

parameter ( maxn = 10000, maxnz = 100000, maxnrhs = 10 )
integer rowind(maxnz), colptr(maxn)
real*8 values(maxnz), b(maxn), berr(maxnrhs)
integer n, m, nnz, nrhs, ldb, i, ierr, info, iam
integer nprow, npcol
integer init

integer(superlu_ptr) :: grid
integer(superlu_ptr) :: options
integer(superlu_ptr) :: ScalePermstruct
integer(superlu_ptr) :: LUstruct
integer(superlu_ptr) :: SOLVEstruct
integer(superlu_ptr) :: A
integer(superlu_ptr) :: stat

```

```

! Create Fortran handles for the C structures used in SuperLU_DIST

```

```

call f_create_gridinfo(grid)
call f_create_options(options)
call f_create_ScalePermstruct(ScalePermstruct)
call f_create_LUstruct(LUstruct)
call f_create_SOLVEstruct(SOLVEstruct)
call f_create_SuperMatrix(A)
call f_create_SuperLUStat(stat)

```

```

! Initialize MPI environment

```

```

call mpi_f47 [(c)-3(a)-3(l)-3-519.993(e)-3(e)-2.)cactacl(l)-((d)-2.99886())519.993a)-3(

```



```
subroutine set_SuperMatrix(A, nrow, ncol)
  integer(superlu_ptr) :: A
  integer, optional :: nrow, ncol
```



```
fptr *SOLVEstruct, double *berr, fptr *stat, int *info)
```

Bibliography

[1] E. Anderson, Z. Bai, C. Bischof, J. Demmel, J. Dongarra, J

[27] Message Passing Interface (MPI) forum. <http://www.mp>