(b) PREEMPTIVE PRIORITY SCHEDULING

Aim - To implement Preemptive priority scheduling algorithm

THEORY -

Preemptive Priority Scheduling is a **CPU scheduling algorithm** in which each process is assigned a **priority value**. The **CPU is allocated** to the process with the **highest priority** (usually, smaller numerical value = higher priority).

If a new process arrives with a **higher priority** than the currently running one, the CPU **preempts (stops)** the current process and assigns the CPU to the new, higher-priority process.

How It Works

- 1. Each process has a priority number.
- 2. The scheduler always checks if a new process with higher priority arrives.
- 3. If so, the **running process is preempted** (paused and moved to the ready queue).
- 4. The higher-priority process executes first.
- 5. Once it completes or gets blocked, the CPU returns to the next highest-priority process.

Characteristics

- Preemptive: CPU can be taken away if a higher-priority process arrives.
- **Efficient for real-time systems**, where urgent tasks must be executed immediately.
- Starvation (Indefinite Blocking): Low-priority processes might never get CPU time if high-priority processes keep arriving.
- **Aging Technique:** Used to reduce starvation gradually **increasing the priority** of waiting processes over time.

PRIORITY MECHANISM

Each process has a priority number.

Lower number = Higher priority (in most systems).

Example: Priority 1 is higher than Priority 3.

CPU is allocated to the waiting process with the highest priority.

If two processes have the same priority, then First-Come-First-Serve (FCFS) is used as a tie-breaker.

IMPORTANT TERMS

1. Arrival Time (AT)

The time at which a process arrives in the ready queue.

Example: If Process P1 has AT = 2, it means it comes to the system at time unit 2.

2. Burst Time (BT)

The total execution time a process needs to complete on the CPU.

Example: If BT = 5, the process requires 5 units of CPU time.

3. Completion Time (CT)

The time at which a process finishes execution.

Example: If a process starts at time 4 and runs for 5 units, its CT = 9.

4. Turnaround Time (TAT)

The total time a process spends in the system (from arrival to completion).

Formula:

TAT = CT - AT

5. Waiting Time (WT)

The time a process spends waiting in the ready queue before getting CPU.

Formula:

WT = TAT - BT

6. Average Turnaround Time (Avg TAT)

Average of turnaround times of all processes.

7. Average Waiting Time (Avg WT)

Average of waiting times of all processes.

Example -

Process Name	Arrival Time	Burst Time	Priority
А	2	2	3
В	0	8	4
С	3	16	1
D	7	1	2

Gantt Chart -

В		A C		D	А	В
0	2	3	19	20	21	27

Table -

Process Name	Arrival Time	Burst Time	Priority	Completion Time	Turn Around Time (TAT)	Wait Time
A	2	2	3	21	19	17
В	0	8	4	27	27	19
С	3	16	1	19	16	0
D	7	1	2	20	13	12

AVERAGE TURN AROUND TIME IS 18.75 AND AVERAGE WAIT TIME IS 12

PROGRAM

#include <iostream> #include <iomanip> #include <vector> #include <algorithm> using namespace std; struct Process { string name;</algorithm></vector></iomanip></iostream>	<pre>while (completed != n) { int idx = -1; int highestPriority = 1e9; for (int i = 0; i < n;</pre>	<pre>p[idx].ct = time; p[idx].tat = p[idx].ct - p[idx].at; p[idx].wt = p[idx].tat - p[idx].bt; p[idx].done = true; completed++;</pre>
<pre>int at, bt, ct, tat, wt, pr; int remainingTime; bool done; };</pre>	i++) {	<pre>currentProcess = ""; } } else {</pre>
,	highestPriority) {	time++;
int main() {	highestPriority	if (currentProcess
int n;	= p[i].pr;	!= "IDLE") {
cout << "Enter number	idx = i;	currentProcess =
of processes: ";	} else if (p[i].pr	"IDLE";
cin >> n;	== highestPriority) {	ganttProcess.pu sh_back(currentProcess
vector <process> p(n);</process>	if (p[i].at < p[idx].at));
for (int $i = 0$; $i < n$; $i++$) {	idx = i;	ganttTime.push_
cout << "Enter	}	back(time - 1);
Process Name, Arrival	}	}
Time, Burst Time,	}	}
Priority for P" << i + 1 <<		}
". ",	if (idx != -1) {	
cin >> p[i].name >>	if (currentProcess	ganttTime.push_back(
p[i].at >> p[i].bt >>	!= p[idx].name) {	time);
p[i].pr;	currentProcess =	
p[i].remainingTime =	p[idx].name;	int totalTAT = 0,
p[i].bt;	ganttProcess.pu	totalWT = 0;
p[i].done = false; }	sh_back(currentProcess);	for (int i = 0; i < n; i++) { totalTAT += p[i].tat;
I	ganttTime.push_	totatiAi += p[i].tat; totalWT += p[i].wt;
int time = 0,	back(time);	}
completed = 0;	}	,
vector <string></string>	•	cout << "
ganttProcess;	p[idx].remainingTi	
vector <int> ganttTime;</int>	me;	\n";
ganttTime.push_back(time++;	cout <<
0);		"Process\tAT\tBT\tPR\tC
	if	T\tTAT\tWT\n";
string currentProcess = "";	(p[idx].remainingTime == 0) {	

```
cout << "-----
-----
----\n";
 for (int i = 0; i < n; i++) {
   cout << p[i].name <<
"\t" << p[i].at << "\t" <<
p[i].bt << "\t"
     << p[i].pr << "\t"
<< p[i].ct << "\t" <<
p[i].tat << "\t" << p[i].wt
<< "\n";
 }
 cout << "-----
-----
----\n";
 cout << "Total
Turnaround Time = " <<
```

totalTAT << "\n";

```
cout << "Average
Turnaround Time = " <<
(float)totalTAT / n <<
"\n";
  cout << "Average
Waiting Time = " <<
(float)totalWT / n <<
"\n\n";
  cout << "Gantt
Chart:\n";
  cout << "-----\n|";
  for (size_t i = 0; i <
ganttProcess.size(); i++)
{</pre>
```

```
cout << " " <<
setw(2) <<
ganttProcess[i] << " | ";
}
cout << "\n-----\n";
for (size_t i = 0; i <
ganttTime.size(); i++) {
   cout << setw(7) <<
ganttTime[i];
}
cout << "\n";
return 0;
}</pre>
```

OUTPUT-

```
ubconeurumentite l , in (4:) ( ·/cembconeurumentite l
Enter number of processes: 4
Enter Process Name, Arrival Time, Burst Time, Priority for P1: A
3
Enter Process Name, Arrival Time, Burst Time, Priority for P2: B
8
4
Enter Process Name, Arrival Time, Burst Time, Priority for P3: C
16
1
Enter Process Name, Arrival Time, Burst Time, Priority for P4: D
1
Process AT BT PR CT TAT WT
______
A 2 2 3 21 19 17
B 0 8 4 27 27 19
C 3 16 1 19 16 0
D 7 1 2 20 13 12
Total Turnaround Time = 75
Average Turnaround Time = 18.75
Average Waiting Time = 12
Gantt Chart:
   B | A | C | D | A | B |
0 0 2 3 19 20 21 27
```

CONCLUSION - Preemptive Priority Scheduling is highly effective for systems that require strict adherence to priority levels and fast response times for critical tasks.