# STAT406- Methods of Statistical Learning Lecture 13

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- In general, we have n observations (training)
- $(g_1, \mathbf{x}_1), (g_2, \mathbf{x}_2), \ldots, (g_n, \mathbf{x}_n)$
- we would like to build a classifier, a function  $\hat{g}(\mathbf{x})$  to predict the true class g of a future observation  $(g, \mathbf{x})$  (for which g is unknown)

- In general, there are K possible classes,  $c_1, c_2, \ldots, c_K$ . In other words  $g \in \{c_1, c_2, \ldots, c_K\}$
- Consider the following loss function

$$L(a,b) = \begin{cases} 0 & \text{if } a = b \\ 1 & \text{if } a \neq b \end{cases}$$

• Find a classifier  $\hat{g}(\mathbf{x})$  such that

$$E_{(G,\mathbf{X})}[L(G,\hat{g}(\mathbf{X}))] \leq E_{(G,\mathbf{X})}[L(G,h(\mathbf{X}))]$$

for any other function *h* 

$$E_{(G,\mathbf{X})}\left[L\left(G,\hat{\mathbf{g}}(\mathbf{X})\right)\right] = E_{\mathbf{X}}\left\{E_{G|\mathbf{X}}\left[L\left(G,\hat{\mathbf{g}}(\mathbf{X})\right)\right]\right\}$$
$$= E_{\mathbf{X}}\left\{\sum_{j=1}^{K}L\left(c_{j},\hat{\mathbf{g}}(\mathbf{X})\right)P\left(G=c_{j}|\mathbf{X}\right)\right\}$$

• It is sufficient to find  $\hat{g}(\mathbf{X})$  that minimizes

$$\begin{split} \sum_{j=1}^{K} L\left(c_{j}, \hat{g}(\mathbf{X})\right) P\left(G = c_{j} | \mathbf{X}\right) \\ &= \sum_{c_{j} \neq \hat{g}(\mathbf{X})} P\left(G = c_{j} | \mathbf{X}\right) \\ &= 1 - P\left(G = \hat{g}(\mathbf{X}) | \mathbf{X}\right) \end{split}$$

• Hence, the optimal classifier satisfies

$$P(G = \hat{g}(\mathbf{X})|\mathbf{X}) \geq P(G = c_i|\mathbf{X})$$
 for all  $c_i$ 

## More than 2 groups

• In other words,  $\hat{g}(\mathbf{X})$  should be the class with the highest probability

$$\hat{g}(\mathbf{X}) = \arg \max_{\mathbf{g} \in \{c_1, \dots, c_K\}} P(G = \mathbf{g} | \mathbf{X})$$

 "Assign X to the class with largest posterior probability given X"

 Most classifiers can be thought of as different ways to estimate or model

$$\mathbf{f_j}(\mathbf{x}) = P(G = \mathbf{c_j} | \mathbf{X} = \mathbf{x})$$

 For example, logistic classifiers propose a model for f<sub>i</sub>:

$$\mathbf{f_j}(\mathbf{x}) = rac{\exp\left(eta_{\mathbf{j}}\,\mathbf{x}
ight)}{1+\exp\left(eta_{\mathbf{j}}\,\mathbf{x}
ight)}$$

- Vaso example Logistic linear model
- Data  $(y_1, \mathbf{x}_1)$ ,  $(y_2, \mathbf{x}_2)$ , ...,  $(y_n, \mathbf{x}_n)$
- $y_j = 0, 1, \mathbf{x} = (rate, volume)'$
- A possible model is

$$P\left(y_{j}=1\big|\,\mathbf{x}_{j}
ight) \,=\, rac{\exp\left(eta^{\prime}\,\mathbf{x}_{j}
ight)}{1+\exp\left(eta^{\prime}\,\mathbf{x}_{j}
ight)}$$

- We can estimate β using MLE
- Function glm in R
- Given values of rate and volume we predict a 1 if

$$\hat{P}(y_j = 1 | \text{rate}, \text{volume}) > 0.5$$

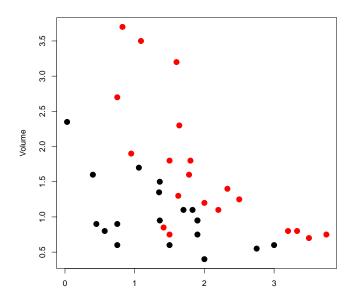
These posterior probabilities

$$P(G = \mathbf{c}_j \mid \mathbf{X} = \mathbf{x})$$

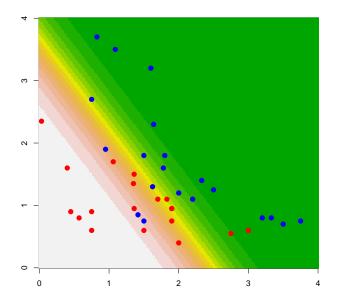
can also be used

- to quantify uncertainty in the classification for a particular value of x
- to identify regions of the feature space where classification isn't so clear

## Example - Vaso data



## Logistic based probabilities



## A model for $\mathbf{X}|g$

If we **model** the feature **distribution** in each **group**:

$$f(\mathbf{X}|G=c_{\mathbf{k}})=f_{\mathbf{k}}(\mathbf{X})$$
  $\mathbf{k}=1,\ldots,\mathbf{K}$ 

then

$$P(G = c_{\mathbf{k}} | \mathbf{X}) = \frac{f(\mathbf{X} | G = c_{\mathbf{k}}) p_{\mathbf{k}}}{f(\mathbf{X})} = \frac{f_{\mathbf{k}}(\mathbf{X}) p_{\mathbf{k}}}{f(\mathbf{X})}$$

thus

$$\hat{\mathbf{g}}(\mathbf{X}) = \arg \max_{1 \le \mathbf{k} \le \mathbf{K}} f_{\mathbf{k}}(\mathbf{X}) p_{\mathbf{k}}$$

## A model for $\mathbf{X}|g$

For example, we can assume that

$$\left| \mathbf{X} 
ight| G = c_{\mathbf{k}} \, \sim \, \mathcal{N} \left( \mu_{\mathbf{k}}, \mathbf{\Sigma} 
ight)$$

then, we can estimate

$$\hat{f}_{f k}({f X}) \sim \mathcal{N}\left(\hat{\mu}_{f k},\widehat{f \Sigma}
ight)$$

using the sample mean of each group and the pooled sample covariance matrix.

We can then find the class **k** that has the largest  $\hat{f}_{\mathbf{k}}(\mathbf{X}) p_{\mathbf{k}}$ 

## Gaussian populations

Note that if  $f_j \sim \mathcal{N}_p\left(\mu_j, \mathbf{\Sigma}\right)$ , j=1,2

$$\begin{split} f_1(\mathbf{x}) \, \rho_1 \, > \, f_2(\mathbf{x}) \, \rho_2 & \Leftrightarrow \\ \log \left( \frac{f_1(\mathbf{x}) \, \rho_1}{f_2(\mathbf{x}) \, \rho_2} \right) > 0 & \Leftrightarrow \\ \mathbf{a}' \mathbf{x} + \mathbf{b} \, > \, 0 \end{split}$$

for some  $\mathbf{a} \in \mathbb{R}^p$  and  $\mathbf{b} \in \mathbb{R}$ .

In other words, boundaries between classes are **linear**.

## Gaussian populations

We can also write this in term of class probabilities

$$\frac{P(G=c_1|\mathbf{X})}{P(G=c_2|\mathbf{X})} > 1 \quad \Leftrightarrow \quad f_1(\mathbf{x}) p_1 > f_2(\mathbf{x}) p_2$$

$$\Leftrightarrow \log\left(\frac{f_1(\mathbf{x})\,\rho_1}{f_2(\mathbf{x})\,\rho_2}\right) > 0 \quad \Leftrightarrow \quad \mathbf{a}'\mathbf{x} + \mathbf{b} \,>\, 0$$

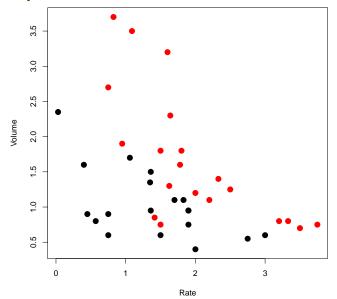
## Gaussian populations

In fact, for normally distributed features we have

$$egin{aligned} \log\left(rac{P\left(G=c_1|\mathbf{X}
ight)}{P\left(G=c_2|\mathbf{X}
ight)}
ight) &= \\ \log\left(rac{P\left(G=c_1|\mathbf{X}
ight)}{1-P\left(G=c_1|\mathbf{X}
ight)}
ight) &= \mathbf{a}'\mathbf{x}+\mathbf{b} \end{aligned}$$

With two classes, we have also estimated a and b using logistic regression.

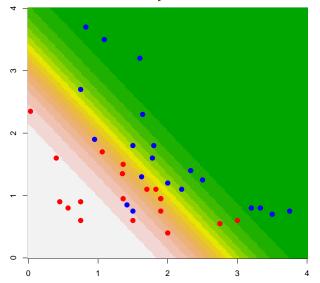
## Example - Vaso data



## Example - Vaso data

```
library (MASS)
data(vaso, package='robustbase')
plot(Volume ~ Rate, pch=19, col=c('red', 'blue')[Y+1],
      data=vaso, cex=1.3)
a.lda \leftarrow lda(Y \sim Volume + Rate, prior = c(.5, .5),
     data=vaso)
aa <- seq(0, 4, length=200)
bb < - seg(0, 4, length=200)
dd <- expand.grid(aa, bb)
names(dd) <- c('Volume', 'Rate')</pre>
pr.lda <- predict(a.lda, newdata=dd)$posterior[,1]</pre>
image (aa, bb, matrix (pr.1da, 200, 200),
     col=terrain.colors(15), xlab='', vlab='')
points(Volume ~ Rate, pch=19, col=c('red', 'blue')[Y+1],
     data=vaso, cex=1.3)
```

## Gaussian-based probabilities



## Example - Vaso data

 Note that if we do not assume Gaussian features but insist that

$$\log \left( \frac{P(G=1|\mathbf{X})}{P(G=2|\mathbf{X})} \right) =$$
 $\log \left( \frac{P(G=1|\mathbf{X})}{1 - P(G=1|\mathbf{X})} \right) =$ 

we can use glm to estimate  $\hat{a}$  and  $\hat{b}$ :

$$\hat{\mathbf{a}} = (-3.88, -2.65)'$$
 and  $\hat{\mathbf{b}} = 9.53$ 

## Logistic-based probabilities

```
data(vaso, package='robustbase')
a <- glm(Y ~ Volume + Rate, data=vaso, family=binomial
aa <- seg(0, 4, length=200)
bb < - seq(0, 4, length=200)
dd <- expand.grid(aa, bb)</pre>
names(dd) <- c('Volume', 'Rate')</pre>
yy <- predict(a, newdata=dd, type='response')</pre>
image(aa, bb, matrix(1-yy, 200, 200),
     col=terrain.colors(15), xlab='', ylab='')
points(Volume ~ Rate, pch=19, col=c('red', 'blue')[Y+1]
     data=vaso, cex=1.3)
```

## Logistic-based probabilities

