Link to github: <a href="https://github.com/Darkat-X/Rutgers-CS428-523-Social-Force">https://github.com/Darkat-X/Rutgers-CS428-523-Social-Force</a> Links to videos:

Part1: <a href="https://www.youtube.com/watch?v=De91X7eJXwU">https://www.youtube.com/watch?v=De91X7eJXwU</a>

Part2:

Pursue and Evade: <a href="https://www.youtube.com/watch?v=7RXhgQ\_DSqw">https://www.youtube.com/watch?v=7RXhgQ\_DSqw</a>
Growing Spiral: <a href="https://www.youtube.com/watch?v=yWICk4CxBck">https://www.youtube.com/watch?v=yWICk4CxBck</a>
Leader Following: <a href="https://www.youtube.com/watch?v=u68432yYVsQ">https://www.youtube.com/watch?v=u68432yYVsQ</a>
Queueing: <a href="https://www.youtube.com/watch?v=RpMiH\_qdiOE">https://www.youtube.com/watch?v=RpMiH\_qdiOE</a>

Fundamental Social Force Components:

### Part 1:

Social Force = Goal Force + Agent Force + Wall Force Agent Force = Proximity Force + Repulsion Force + Sliding Friction Wall Force = Proximity Force + Repulsion Force + Sliding Friction

# Part 2:

# Pursue and Evade:

Pursuer Social Force = Goal Force From Pursuer to Evader + Agent Force + Wall Force Evader Social Force = - Goal Force From Evader to Pursuer + Agent Force + Wall Force If Evader is too close to the Wall:

Evader Social Force += The Tangential Force + Goal Force So that if Evader approaches the corner, they will spin away (The center of spin should be Vector3.zero)

#### Growing Spiral:

Social Force = The Tangential Force + Goal Force + Agent Force + Wall Force After a period of time:

Social Force = The Tangential Force - Goal Force + Agent Force + Wall Force

# Leader Following:

Leader Social Force = Goal Force + Agent Force + Wall Force Follower Social Force = Goal Force to the Leader + Agent Force + Wall Force If Follower may block the way of leader:

Follower Social Force += The Tangential Force + Goal Force The direction of the tangent is dependent on the angle

### Queueing:

Social Force = Goal Force to their queue position + Agent Force + Wall Force

The queue position is the position that is a little behind the position that is next one agent closer to the destination than this agent.

The queue order is dependent on the distance from agent to the destination, after a period of time, the order will not change any more. So that the queue will form a line that goes to the destination and will not change the shape of line after a period of time.

# Hints:

1. There is a private int, named "Mode" in Agent.cs. By changing the value of "Mode", you can choose different modes. You can change it in Agent script, in start().

```
/* Mode
1 = Pursue and Evade
2 = Growing Spiral
3 = Leader Following
4 = Queueing
other number = Normal Mode for Part one */
```

2. FreeCam Keys:

wasd / arrows - movement

q/e - up/down (local space)
r/f - up/down (world space)
pageup/pagedown - up/down (world space)
hold shift - enable fast movement mode

right mouse - enable free look

mouse - free look / rotation