# How to compile mbed platform

mbed CLI Compiler

Step 1 - Install Python, Git, Mercurial and GCC

- I. Install python
- 1) Go to download page for python (<a href="https://www.python.org/downloads/">https://www.python.org/downloads/</a>)
- 2) During installation, Add Python to system path
- 3) Wait for Python to install
- II. Install Git
- 1) Go to download page for git(<a href="https://git-scm.com/download/win">https://git-scm.com/download/win</a>)
- Wait for Git to install

III. Install Mercurial

- 1) Go to download page for git(https://www.mercurial-scm.org/downloads/)
- Wait for Git to install after click 'Add the installation path to the search path' during installation

#### IV. Install GCC

- Go to download page(<a href="https://launchpad.net/gcc-arm-embedded">https://launchpad.net/gcc-arm-embedded</a> (GNU ARM Embedded Toolchain)
- Wait for GCC to install after adding path to the environment, i.e., click'Launch gccvar.bat' during installation

http://d2.naver.com/helloworld/1011 (Comparison between Git and Mercurial)

#### Step 2 Verify installation

```
명령 프롬프트
Microsoft Windows [Version 10.0.15063]
(c) 2017 Microsoft Corporation, All rights reserved.
C:\Users\user>arm-none-eabi-gcc --version
arm-none-eabi-gcc (GNU Tools for ARM Embedded Processors) 5.4.1 20160919 (release) [ARM/embedded-5-branch revision 24049
Copyright (C) 2015 Free Software Foundation, Inc.
This is free software; see the source for copying conditions. There is NO warranty; not even for MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.
C:\Users\user>python --version
Python 2.7.13
C:\Users\user>pip --version
pip 9.0.1 from c:\python27\lib\site-packages (python 2.7)
C:₩Users₩user>hg --version
Mercurial Distributed SCM (version 4.2+4)
 (see https://mercurial-scm.org for more information)
Copyright (C) 2005-2017 Matt Mackall and others
This is free software; see the source for copying conditions. There is NO
warranty; not even for MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE.
```

Step 2 install mbed CLI from pip

Step 1 Import

: copy URL of

repository(<a href="https://developer.mbed.org/mbed\_demo/code/mbed\_blinky">https://developer.mbed.org/mbed\_demo/code/mbed\_blinky</a>

```
E:\|Heedong\|Work\|mbed\|Src\|dev_directory>mbed import https://developer.mbed.org/users/mbed_demo/code/mbed_blinky/
[mbed] Importing program "mbed_blinky" from "https://developer.mbed.org/users/mbed_demo/code/mbed_blinky" at latest revi
sion in the current branch
[mbed] Adding library "mbed" from "http://mbed.org/users/mbed_official/code/mbed/builds" at rev #f9eeca106725
[mbed] Downloading library build "f9eeca106725" (might take a minute)
[mbed] Unpacking library build "f9eeca106725" in "E:\|Heedong\|Work\|mbed\|Src\|dev_directory\|mbed_blinky\|mbed\|
[mbed] Couldn't find build tools in your program. Downloading the mbed 2.0 SDK tools...
[mbed] Auto-installing missing Python modules...
```

#### Step 2 toolchain and target

- 1) Go to program folder
- 2) Detect toolchain and target options after connecting the dev board to the PC

via USB

3) compile

```
C:\Users\ARM\mbed_blinky>mbed detect

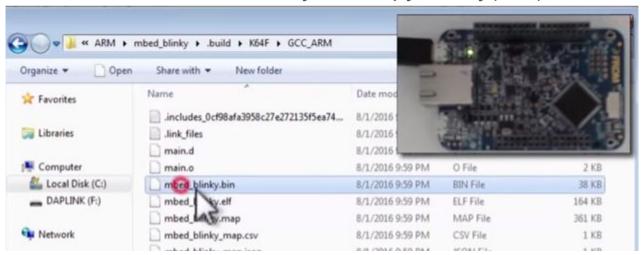
[mbed] Detected K64F, port None, mounted F:
[mbed] Supported toolchains for K64F

! Target | mbed OS 2 | mbed OS 5 | ARM | GCC_ARM | uARM | GCC_CR |
! K64F | - | - | Supported | Supported | - | - |
Supported targets: 1
Supported toolchains: 3

C:\Users\ARM\mbed_blinky>mbed toolchain GCC_ARM
[mbed] GCC_ARM now set as default toolchain in program "mbed_blinky"

C:\Users\ARM\mbed_blinky>mbed target K64F
[mbed] K64F now set as default target in program "mbed_blinky"
```

Step 3 Find .bin in .build directory and copy binary(.bin) to board



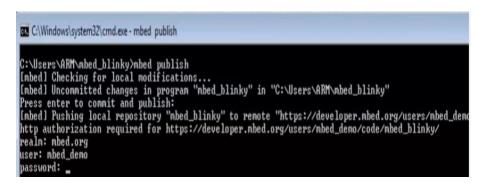
Step 4 Reset board to run the code

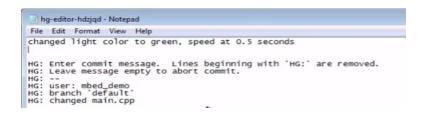
Step 5 Modify code in main.cpp

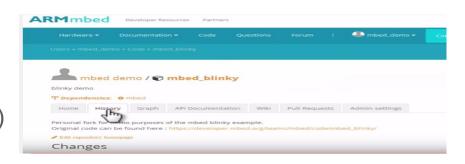
Step 6 Change blink speed and LED colors and Compile and Flash new binary to Board

#### Step 7 publish

- publish code back to server and press enter and fill in change message
- close window to continue
- enter mbed username and mbed password
- see changes on website (History tab)







Step 8 Reset board to run the code

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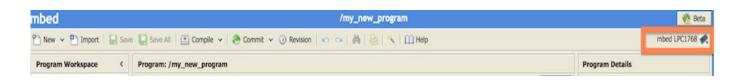
mbed online compiler

## Importing blinky

Selecting a target board and Adding a board to your list

Go to the board's page on mbed.com(<a href="https://developer.mbed.org/platforms/">https://developer.mbed.org/platforms/</a>) and click the Add to your mbed compiler button

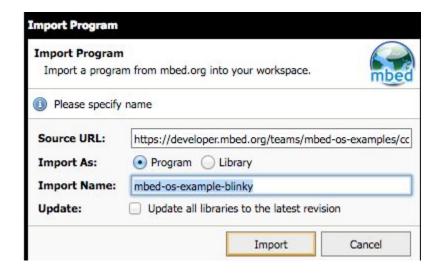




## Importing blinky

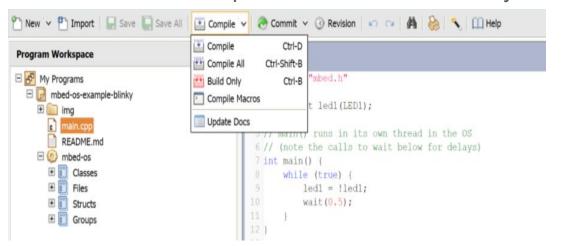
To get blinky into the mbed online compiler, click the Import into mbed IDE button





## Compile and install

The mbed online compiler builds a .bin file that you can install on your board



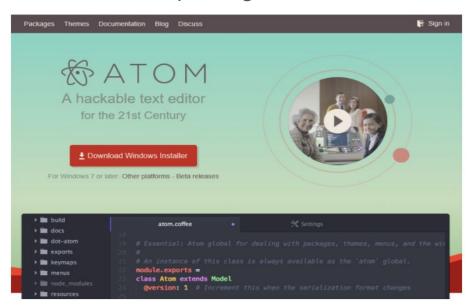


Connect your board to your computer over USB. mbed boards are shown as "removable storage"

Drag and drop your program to the board / The board installs the program and Reset the board and see the LED blink

## How to install platform io

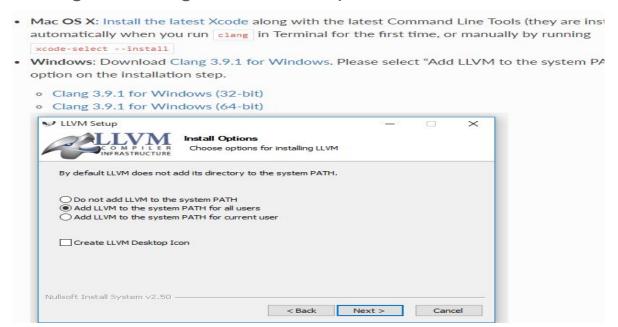
1. Install atom package





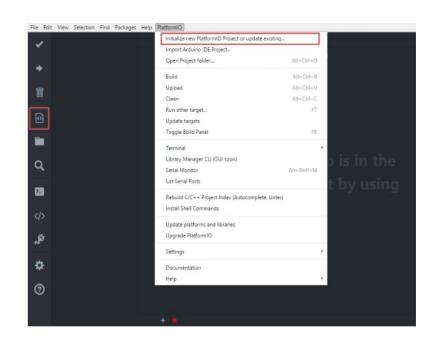
#### How to install platform io

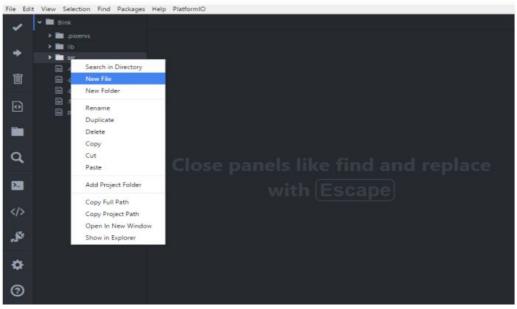
#### 2. Clang for intelligent code completion



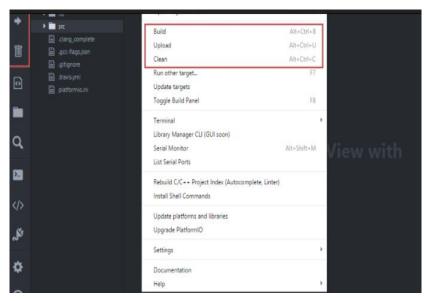
## How to build platform io

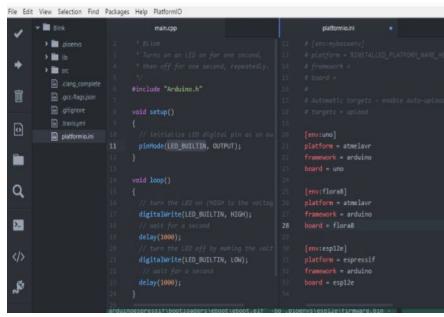
#### Set up new project



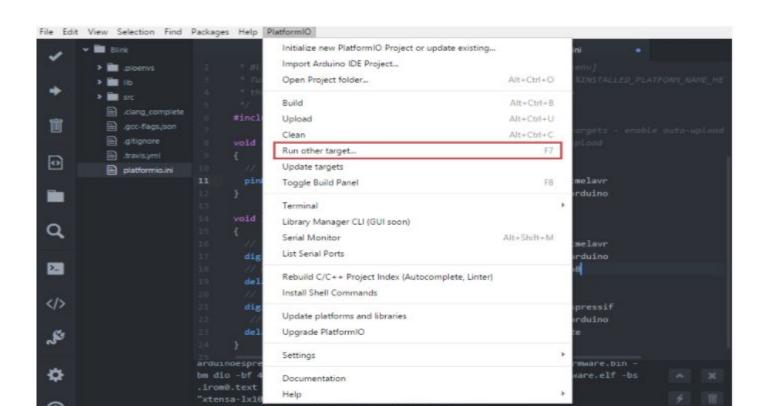


## How to build platform io

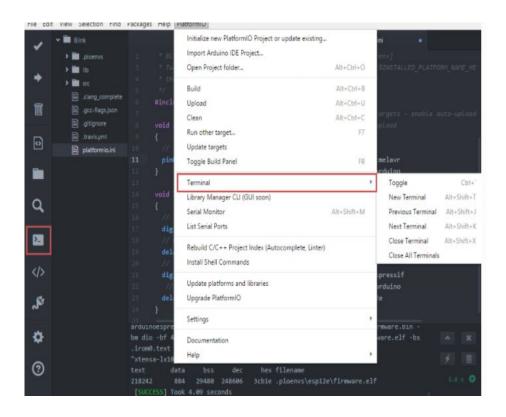


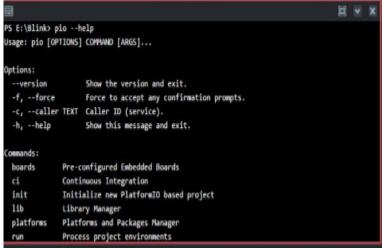


## How to run platform io

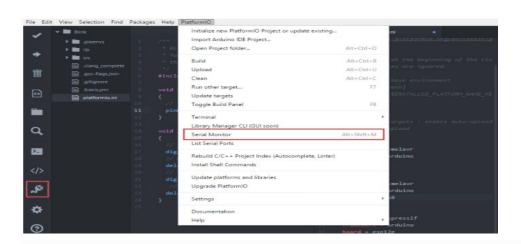


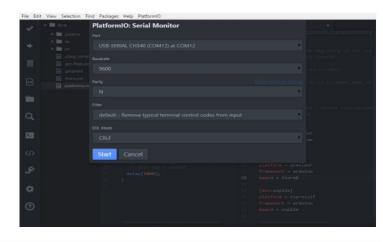
## How to install platform io





## How to install platform io



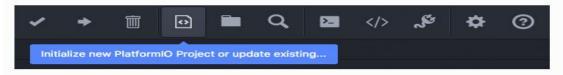




#### Platform IO Toolbar

#### PlatformIO Toolbar

PlatformIO IDE Toolbar contains quick access buttons for the popular commands. Each button contains hint (delay mouse on it).



- · PlatformIO: Build
- · PlatformIO: Upload
- · PlatformIO: Clean
- |
- · Initialize new PlatformIO Project or update existing...
- · Add/Open Project Folder...
- Find in Project...
- II
- Terminal
- Library Manager
- Serial Monitor
- ||
- Settings
- PlatformIO Documentation

## How to build platform IO CLI

Install shell commands on platform io

#### How to build PlatformIO based project

- 1. Install PlatformIO Core
- 2. Download examples source code
- 3. Extract ZIP archive
- 4. Run these commands:

```
# Change directory to example
> cd platformio-examples/mbed/mbed-blink

# Build project
> platformio run

# Upload firmware
> platformio run --target upload

# Build specific environment
> platformio run -e lpc1768

# Upload firmware for the specific environment
> platformio run -e lpc1768 --target upload

# Clean build files
> platformio run --target clean
```